Multi-Modal Route Planning for Global Logistics Optimization

Subham Subhasis Sahoo (2020CSB1317), Aman Pankaj Adatia (2020CSB1154), Vinay Kumar (2020CSB1141)

I. Introduction

Our objective is to develop a multi-modal route planning for a global delivery fleet. With varying vehicle capacities and transportation modes at our disposal, the challenge lies in optimizing routes to ensure timely, cost-effective, and environmentally responsible deliveries. The sheer scale of possibilities - spanning air, water, rail, and road- adds complexity, necessitating an intelligent system that not only estimates travel metrics but also adheres to operational heuristics. Moreover, accommodating different vehicle capacities introduces an additional layer of intricacy. Our mission is to develop a solution that seamlessly integrates machine learning predictions, heuristic-guided optimizations, dynamic clustering, and connectivity-based objective functions, setting a new standard for efficient, sustainable, and adaptive logistics operations.

II. RESEARCH METHODOLOGY

A. Feature Estimation Through Estimation Models

We aim to enhance transportation modes through feature extraction, encompassing travel conditions, vehicle attributes, infrastructure details, and geographical constraints. Tailored estimation models will be created for each mode, using comprehensive datasets covering vehicle properties and global distances. Regression techniques will accurately forecast travel costs, providing insights into financial aspects. Additionally, a model will be developed considering road conditions, traffic patterns, and transportation choices, utilizing techniques like time series analysis and regression for precise travel time estimations. Our commitment to sustainability drives the training of a model using vehicle properties and travel conditions data. This model, employing regression techniques, will predict emissions for various transportation modes, contributing to environmental conservation and aiding informed transportation decisions.

B. Cluster Generation and Optimisation:

In our multi-modal route planning, we begin by employing the DBSCAN algorithm to cluster locations. This method utilizes spatial proximity and traffic density, providing an initial structure for the efficient organization of delivery spots. This foundational step accurately reflects the geographical distribution. Following this, we introduce a sophisticated connectivitybased objective function. It critically assesses cluster assignments, evaluating the connectivity of nodes within each cluster. This ensures a seamless interaction between locations, resulting in smoother and more efficient routes.

To further refine our clusters, we implement a Genetic Algorithm (GA). Chromosomes in the GA represent potential cluster assignments. Through operations like crossover and mutation, we fine-tune assignments to optimize the connectivity objective function. This iterative approach systematically enhances the spatial arrangement of delivery spots within clusters. We define the connectivity-based objective function to evaluate the quality of cluster assignments:

$$\label{eq:objectiveFunction} \text{ObjectiveFunction } = \sum_{c \in \text{Clusters}} \log \left(1 + \frac{\text{Connectivity } (c)}{\text{MaxConnectivity}} \right)$$

C. Integration with Route Planning

We're integrating genetic algorithms into our route planning. Each individual in the population signifies a potential route for a specific cluster, encoded with precision to include node sequences and transportation modes. This encoding takes into account the vehicle capacities within the cluster. To refine our route plans within the genetic algorithm framework, we implement two critical operations. The first is the Crossover Operation. This involves a multi-point crossover and mutation, enabling the exchange of route segments between two individuals within the same cluster while switching modes.

To evaluate the effectiveness of our route plans, we employ a composite fitness function. This function combines cost, time, and emissions, factoring in their relative importance within the context of our logistics operations. By assessing the fitness of everyone within the population, we gain crucial insights into the performance of our routes. This information is invaluable in guiding subsequent iterations of the genetic algorithm.

ObjectiveFunction =
$$\sum_{c \in \text{ constraints}} \left(H_i \cdot w_1 \log \left(1 + \frac{c}{C_{\text{max}}} \right) \right)$$

For instance, we can have a heuristic that prioritizes direct routes, minimizing intermediate stops and detours to enhance efficiency. Another heuristic focuses on minimizing mode changes, streamlining operations and reducing potential delays. By aligning our heuristics with the fitness functions, we've plan to have a holistic approach that optimizes not only based on numerical metrics but also on qualitative considerations, resulting in routes that are not only efficient but also adhere to specific operational priorities and constraints.

III. NOVELTY

We integrate machine learning models to precisely estimate travel times, costs, and emissions for different transportation modes. This predictive capability empowers our genetic algorithm, resulting in more efficient route plans. Additionally, our heuristic-driven optimizations enhance the decision-making process. These heuristics, aligned with operational priorities, guide the genetic algorithm towards routes that meet both quantitative metrics and qualitative constraints.

Furthermore, we introduce a dynamic clustering technique that groups delivery spots based on vehicle capacities. This tailors routes to the unique characteristics of each vehicle, optimizing for efficiency and resource utilization. Additionally, our connectivity-based objective function, integrated into the genetic algorithm, addresses a critical aspect often overlooked in traditional methods. It promotes well-connected clusters, enhancing the overall efficiency of the logistics operation.