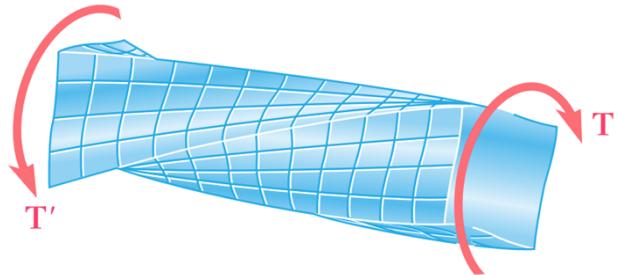
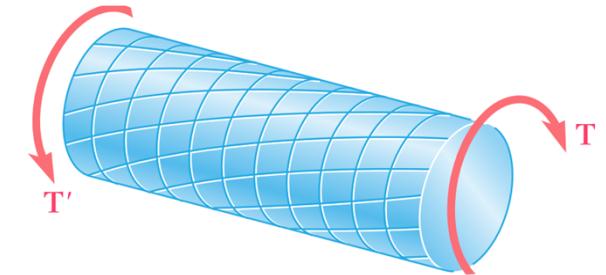


TOPIC # 4: TORSION



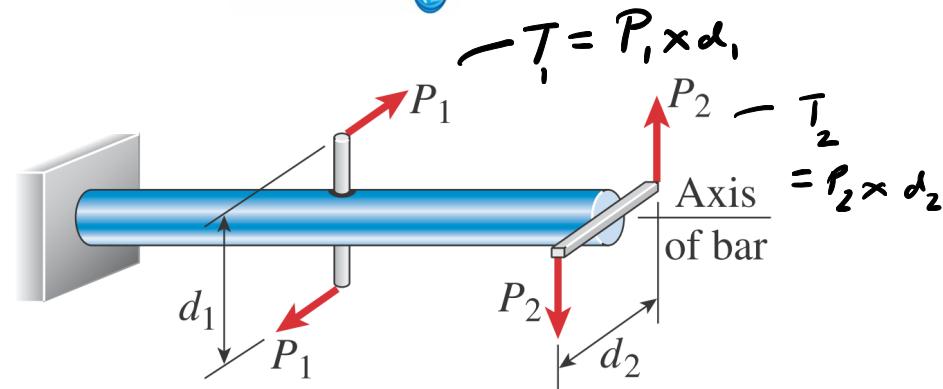
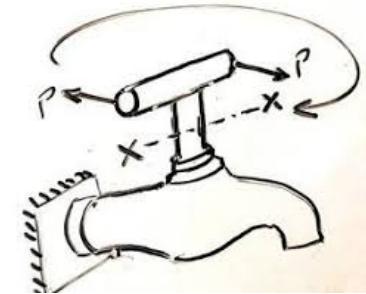
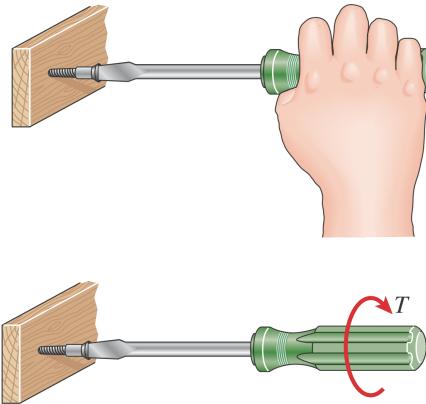
4.1 - Introduction



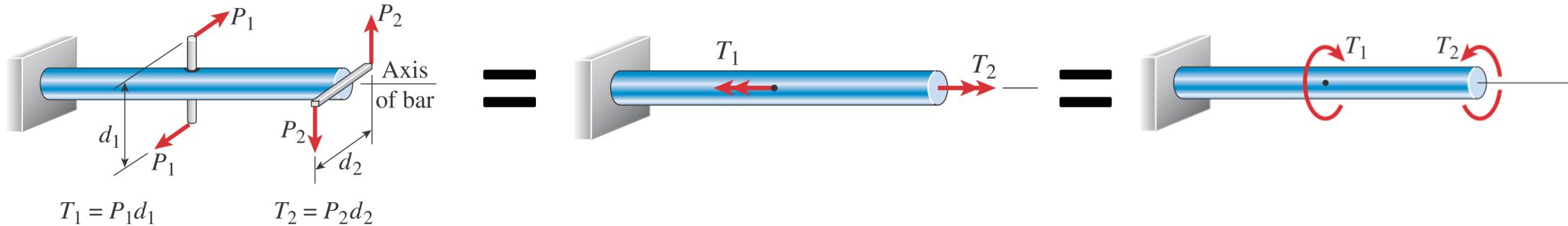
MECHANICS OF MATERIAL
(SOLID MECHANICS)



EXAMPLES OF TORSION (T)



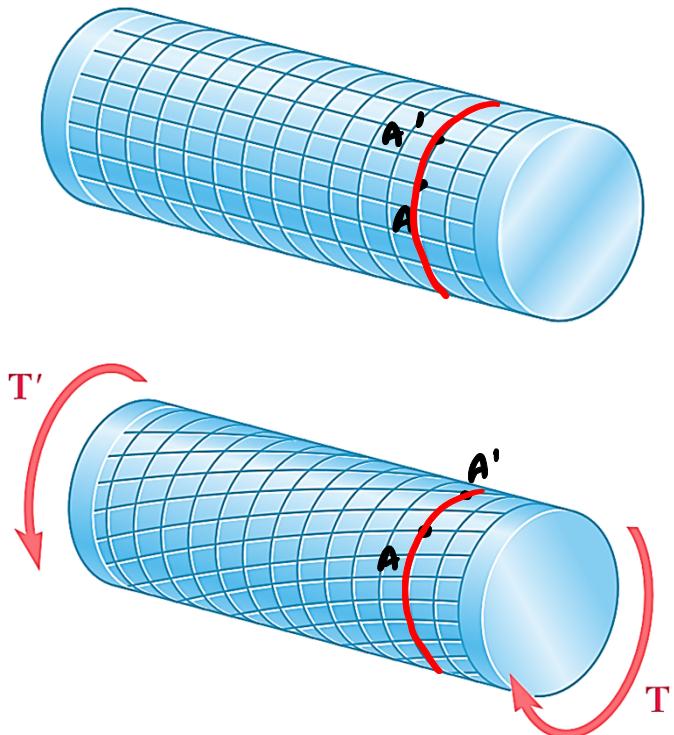
REPRESENTATION OF TORSION (T)



- Torque is a Vector quantity
- Right hand rule - Using your **right hand**, let your **fingers curl in the direction of the moment**, and then your **thumb will point in the direction of the torsion vector**

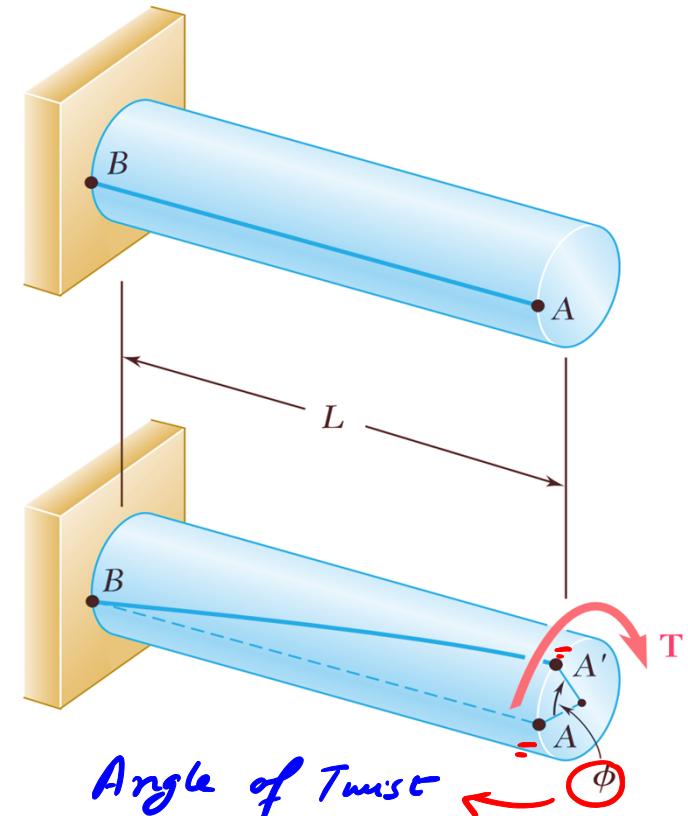
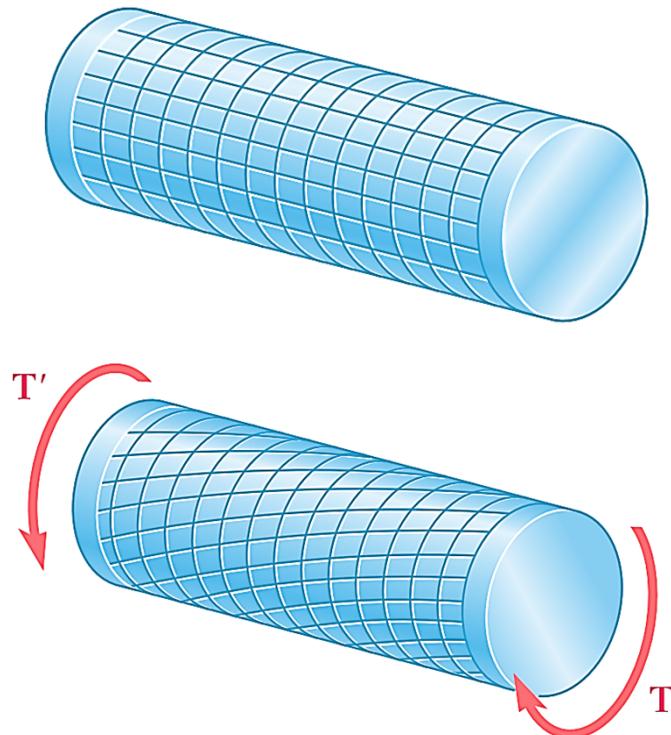
HOW DO STRUCTURES BEHAVE UNDER TORSION?

- Circular bars:

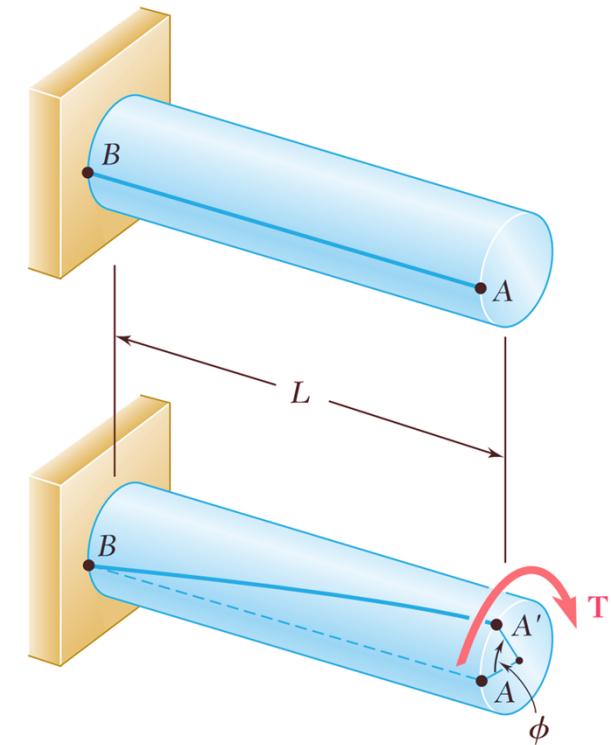
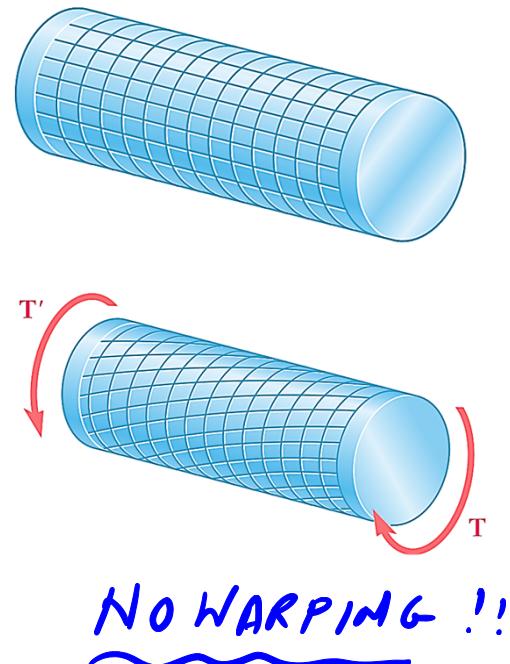
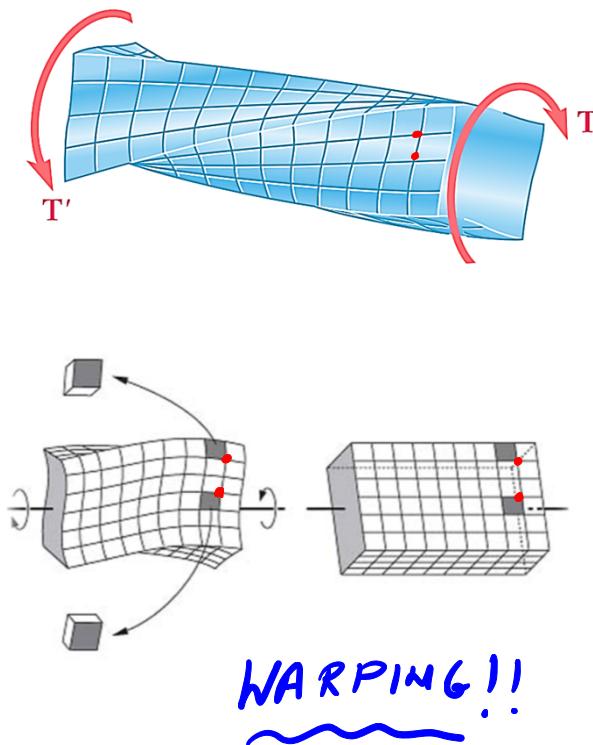


HOW DO STRUCTURES BEHAVE UNDER TORSION?

- Circular bars:

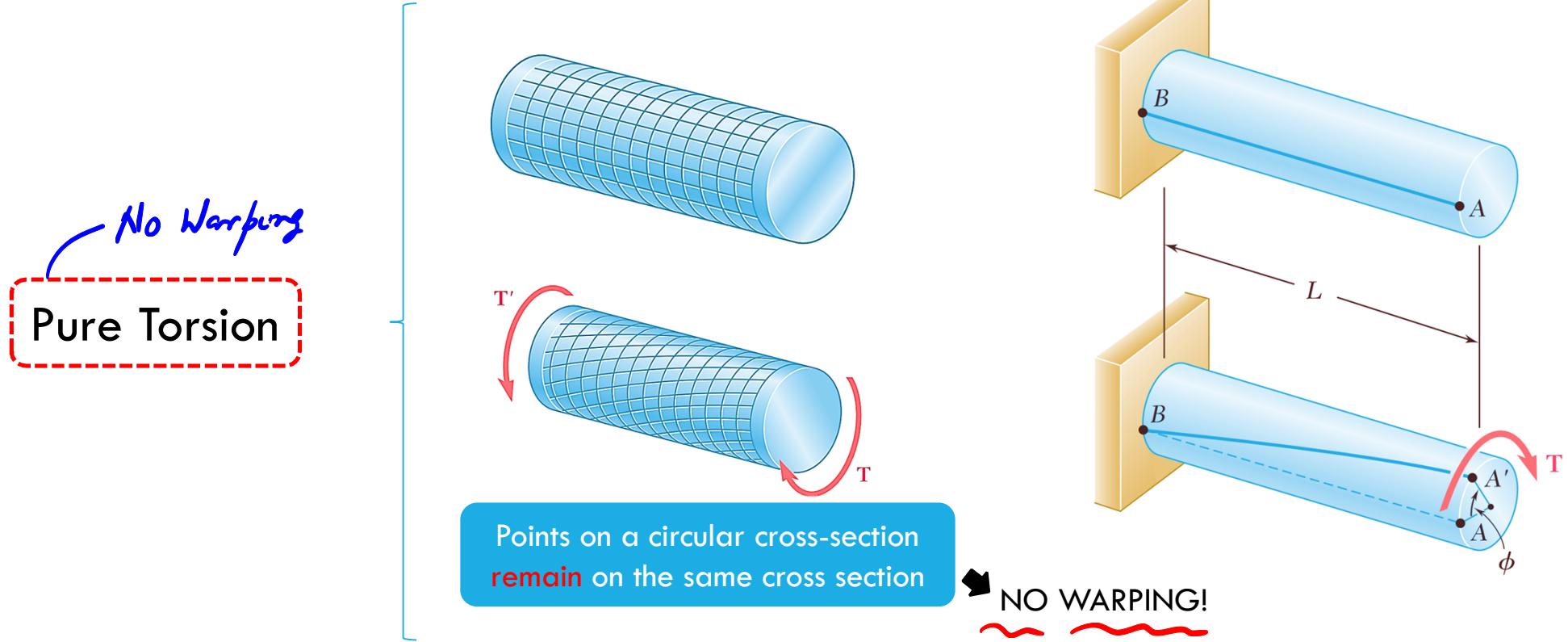


SPOT THE DIFFERENCE

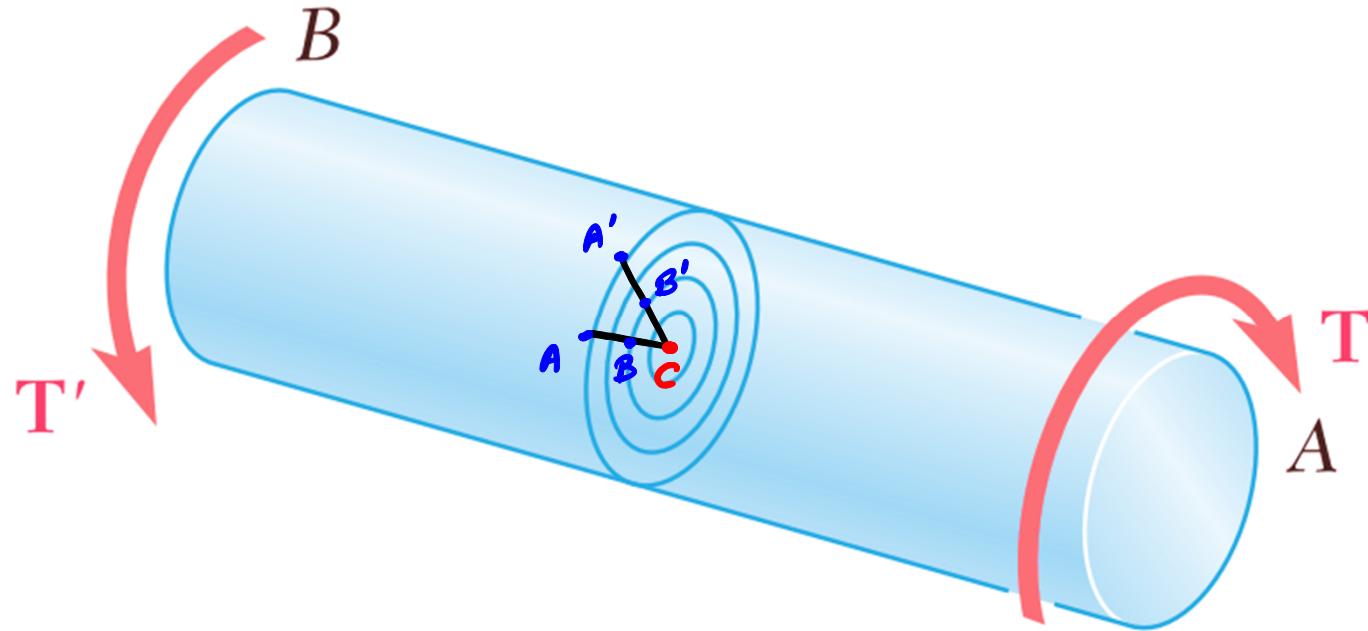


CIRCULAR SHAFTS UNDERGO: PURE TORSION

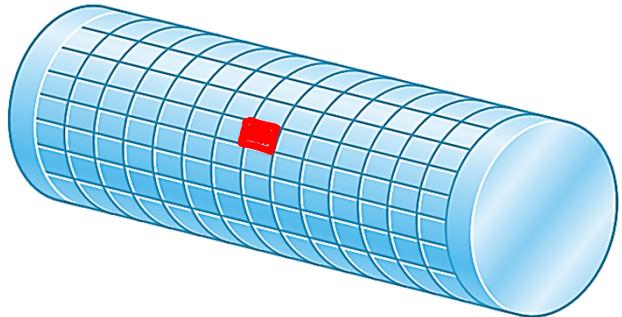
- Important Observation:



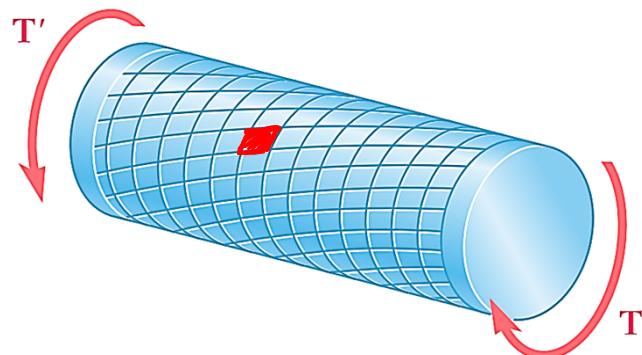
PURE TORSION



PURE SHEAR CONDITION



Elements only undergo a change in shape,
and minor contraction or elongation



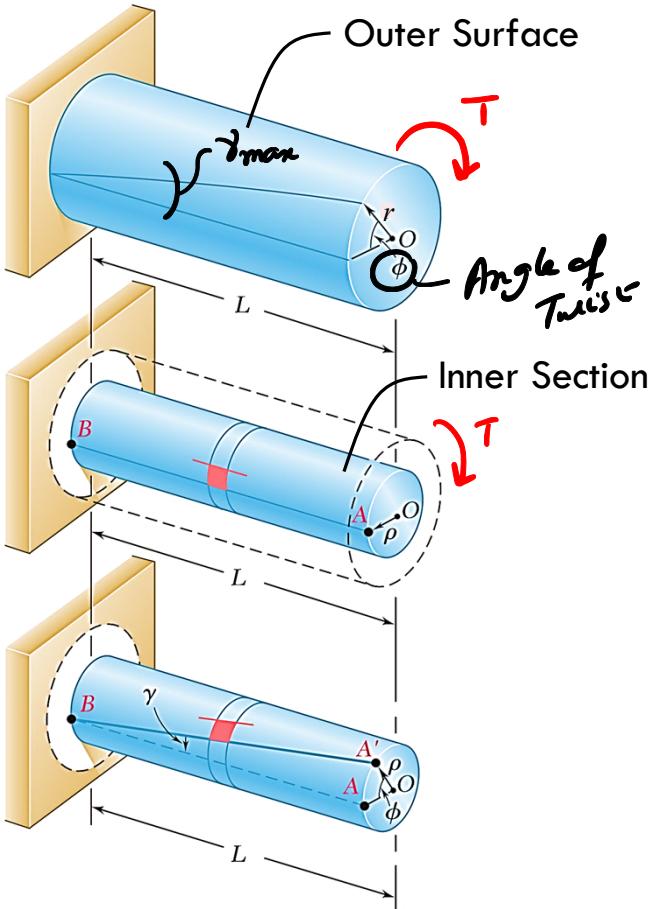
*All elements are in a state of
"PURE SHEAR"*

TOPIC # 4.2: TORSION – SHEARING STRAINS & STRESSES; TORSION FORMULA

MECHANICS OF MATERIAL
(SOLID MECHANICS)



SHEARING STRAINS



$$\tan \gamma = \frac{AA'}{L} \Rightarrow \gamma = \frac{AA'}{L} \quad \textcircled{1}$$

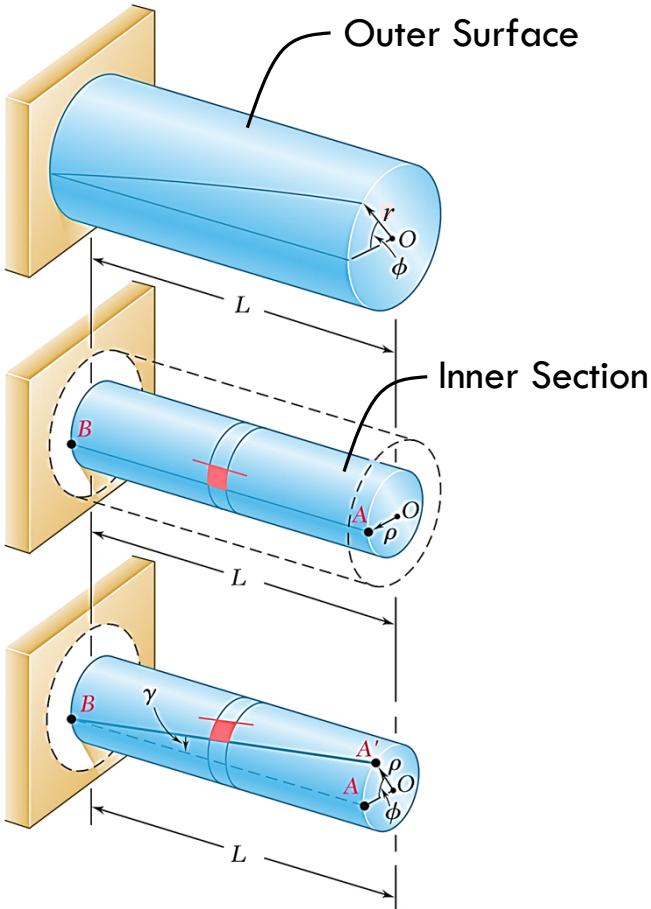
$$AA' = \rho \phi \quad \textcircled{2}$$

$$\gamma = \frac{\rho \phi}{L}$$

$$\gamma_{max} = \frac{r \phi}{L}$$

$$\gamma = \frac{\rho}{r} \gamma_{max}$$

SHEARING STRAINS



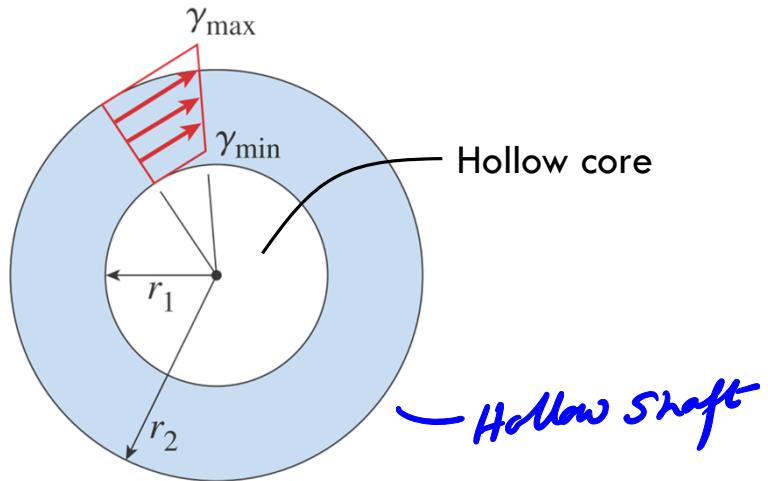
$$\gamma = \frac{\rho\phi}{L}$$

$$\gamma_{\max} = \frac{r\phi}{L}$$

$$\gamma = \frac{\rho\phi}{L} = \frac{\rho}{r} \gamma_{\max}$$

✗

CIRCULAR TUBES



$$\gamma_{\min} = \frac{r_1 \phi}{L}$$

$$\gamma_{\max} = \frac{r_2 \phi}{L}$$

$$\gamma_{\min} = \frac{r_1}{r_2} \gamma_{\max}$$

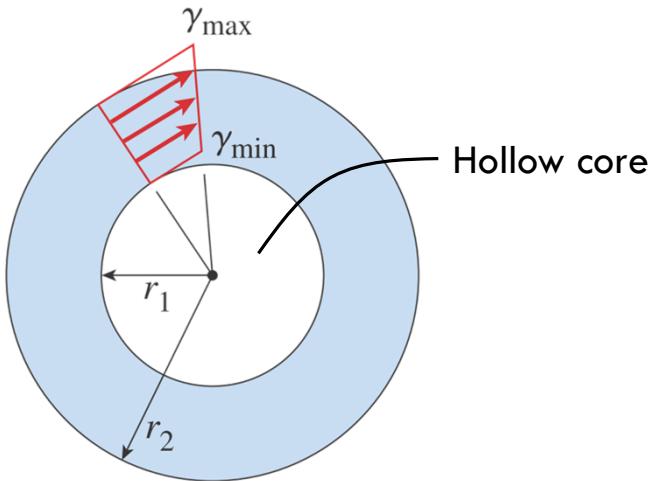
Solid Shaft

$$\gamma = \frac{\rho \phi}{L}$$

$$\gamma_{\max} = \frac{r \phi}{L}$$

$$\gamma = \frac{\rho}{r} \gamma_{\max}$$

CIRCULAR TUBES



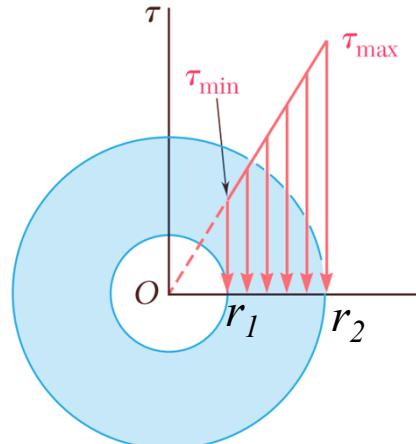
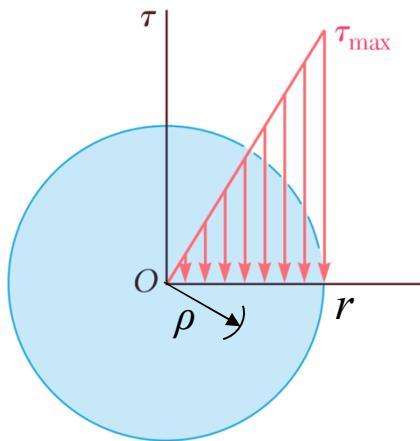
$$\gamma_{\min} = \frac{r_1}{L} \phi$$

$$\gamma_{\max} = \frac{r_2}{L} \phi$$

$$\gamma_{\min} = \frac{r_1}{L} \phi = \frac{r_1}{r_2} \gamma_{\max}$$

SHEAR STRESSES

$$\tau = G \gamma$$



$$\gamma_{\max} = \frac{r \phi}{L} \rightarrow \tau_{\max} = \frac{G r \phi}{L}$$

$$\tau = \frac{G \rho \phi}{L}$$

$$\tau = \frac{\rho}{r} \tau_{\max}$$

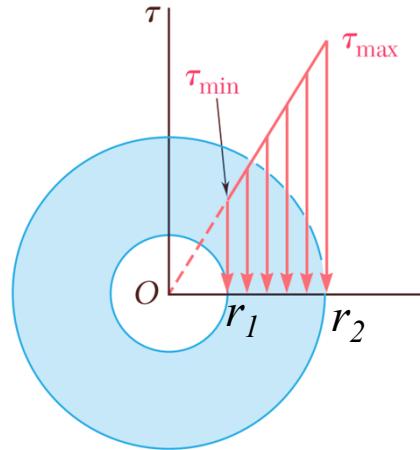
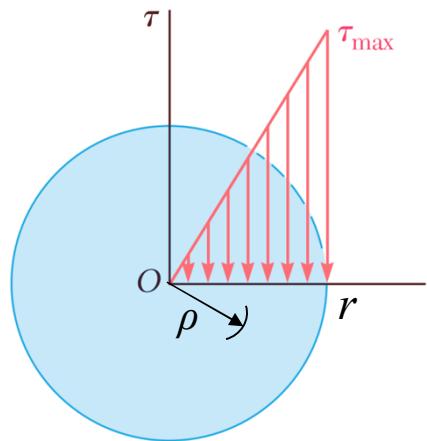
Solid Shaft

$$\begin{aligned} \tau_{\max} &= \frac{G r_2 \phi}{L} \\ \tau_{\min} &= \frac{G r_1 \phi}{L} \end{aligned}$$

HOLLOW SHAFT

$$\tau_{\min} = \frac{r_1}{r_2} \tau_{\max}$$

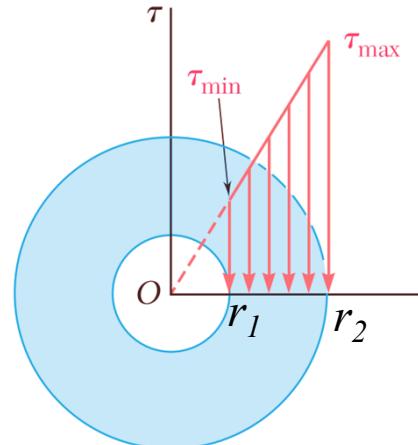
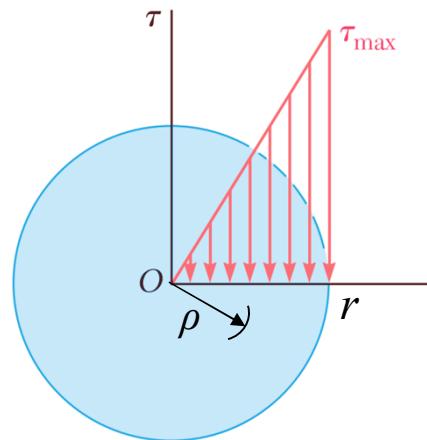
SHEAR STRESSES



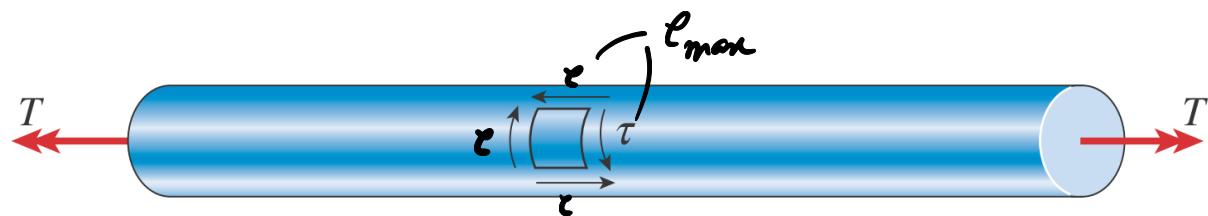
$$\tau_{\max} = G \frac{r\phi}{L}$$
$$\tau = G \frac{\rho\phi}{L} = \frac{\rho}{r} \tau_{\max}$$

$$\tau_{\min} = \frac{r_1}{r_2} \tau_{\max}$$

SHEAR STRESSES



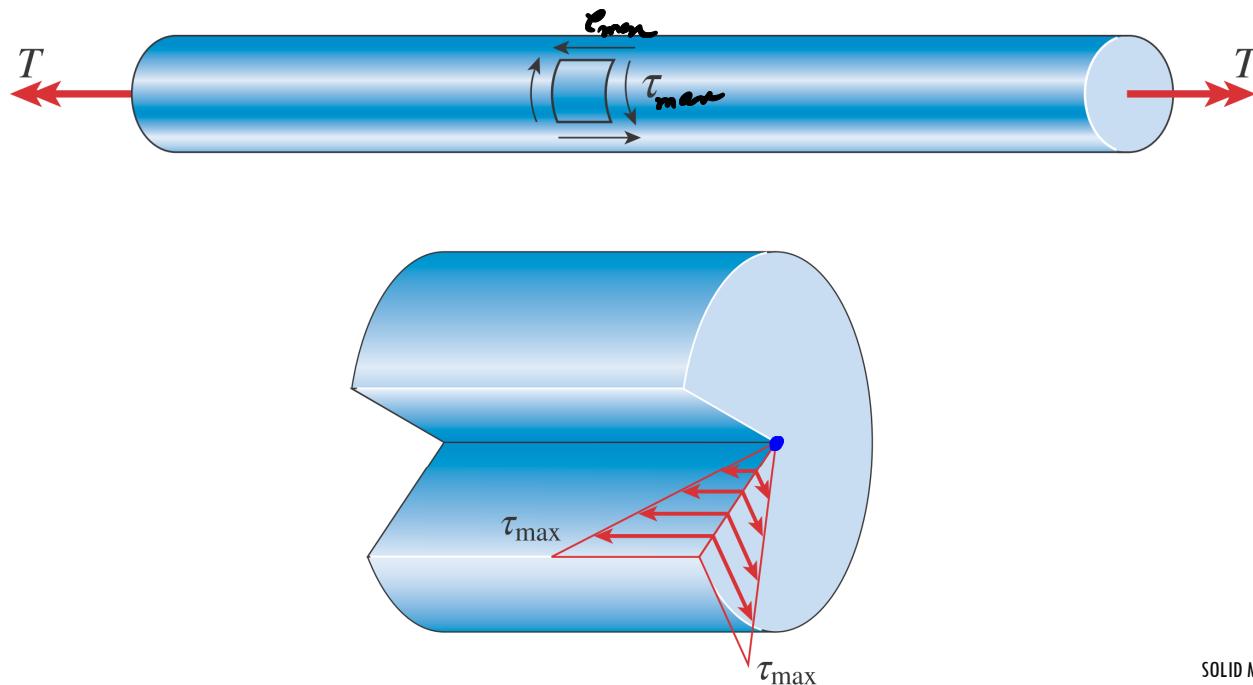
$$\tau_{\max} = G \frac{r\phi}{L}$$
$$\tau = G \frac{\rho\phi}{L} = \frac{\rho}{r} \tau_{\max}$$



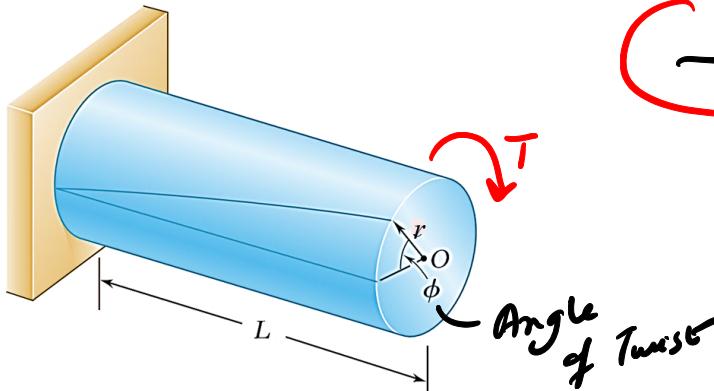
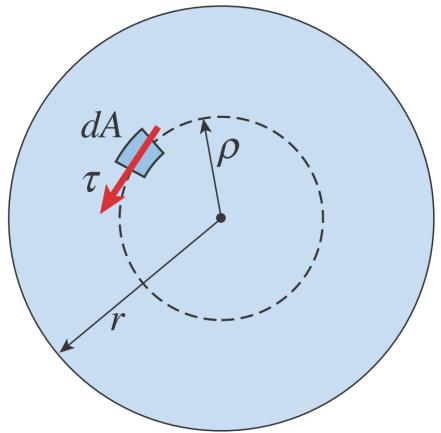
$$\tau_{\min} = \frac{r_1}{r_2} \tau_{\max}$$

SHEAR STRESSES

- Internal shear stresses



THE TORSION FORMULA



circular
J → Solid shafts

$$J = \frac{\pi r^4}{2}$$

Hollow shaft
(r_2 , r_1)

$$J = \frac{\pi r_2^4}{2} - \frac{\pi r_1^4}{2}$$

$$dM = (\tau dA) \times r$$

$$T = \int_A dM = \int \tau r dA$$

Recap

$$\tau = \frac{r}{r} \tau_{\max}$$

$$\tau_{\max} = G \frac{r \phi}{L}$$

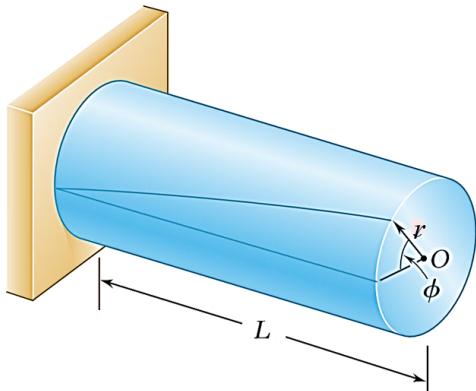
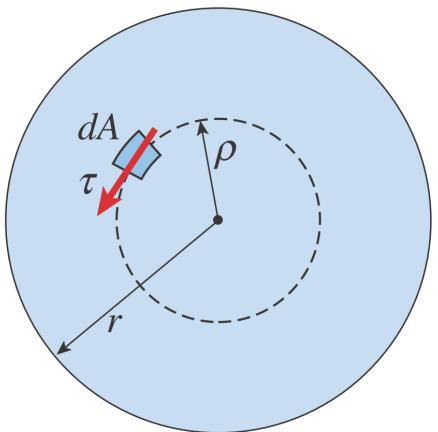
$$\Rightarrow \tau_{\max} = \frac{Tr}{J} \rightarrow \tau = \frac{Tr}{J}$$

$$\Rightarrow \frac{G r \phi}{L} = \frac{Tr}{J} \Rightarrow$$

$$\boxed{\phi = \frac{TL}{JG}}$$

TORSION
FORMULA

THE TORSION FORMULA

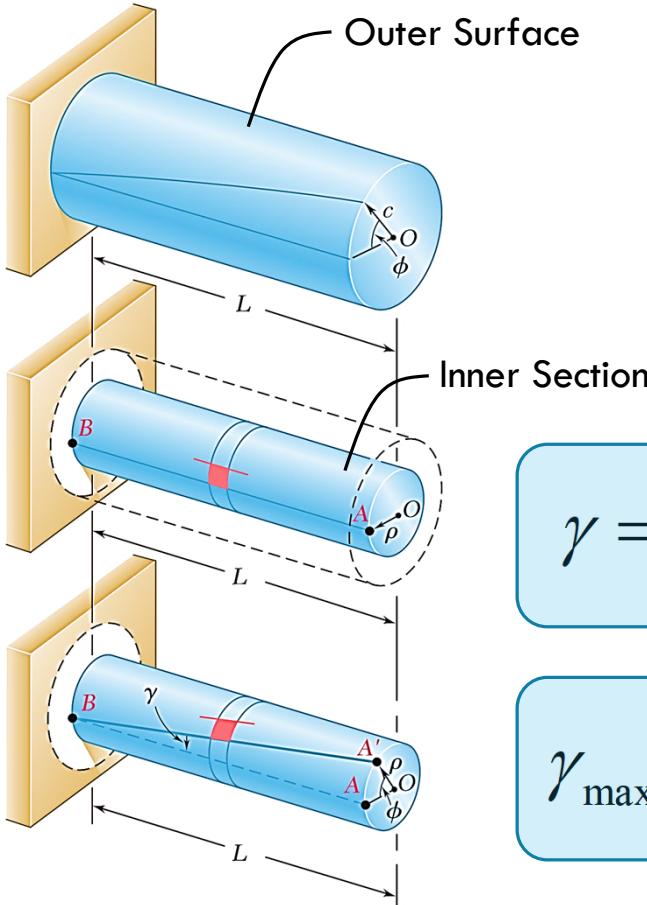


$$\tau_{\max} = \frac{Tr}{J}$$

$$\tau = \frac{T\rho}{J} = \frac{\rho}{r} \tau_{\max}$$

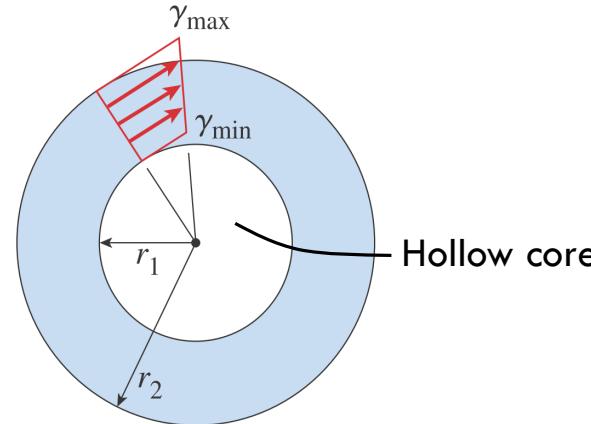
$$\phi = \frac{TL}{JG}$$

OVERALL SUMMARY



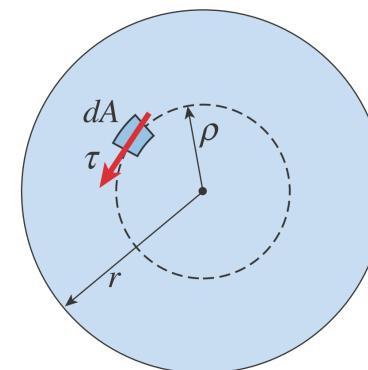
$$\gamma = \frac{\rho\phi}{L}$$

$$\gamma_{\max} = \frac{r\phi}{L}$$



$$\gamma_{\min} = \frac{r_1}{L}\phi = \frac{r_1}{r_2}\gamma_{\max}$$

$$\tau_{\min} = \frac{r_1}{r_2}\tau_{\max}$$



$$\tau_{\max} = \frac{Tr}{J}$$

$$\tau = \frac{T\rho}{J} = \frac{\rho}{r}\tau_{\max}$$

$$\phi = \frac{TL}{JG}$$

ANALOGIES WITH AXIAL LOADING

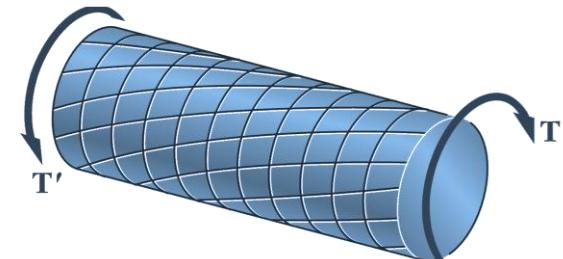
- Axial



$$\delta = \frac{PL}{AE}$$

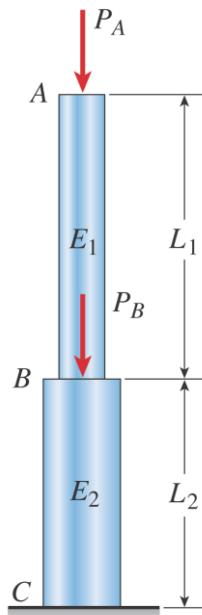
- Torsional (Pure Shear)

$$\phi = \frac{TL}{JG}$$

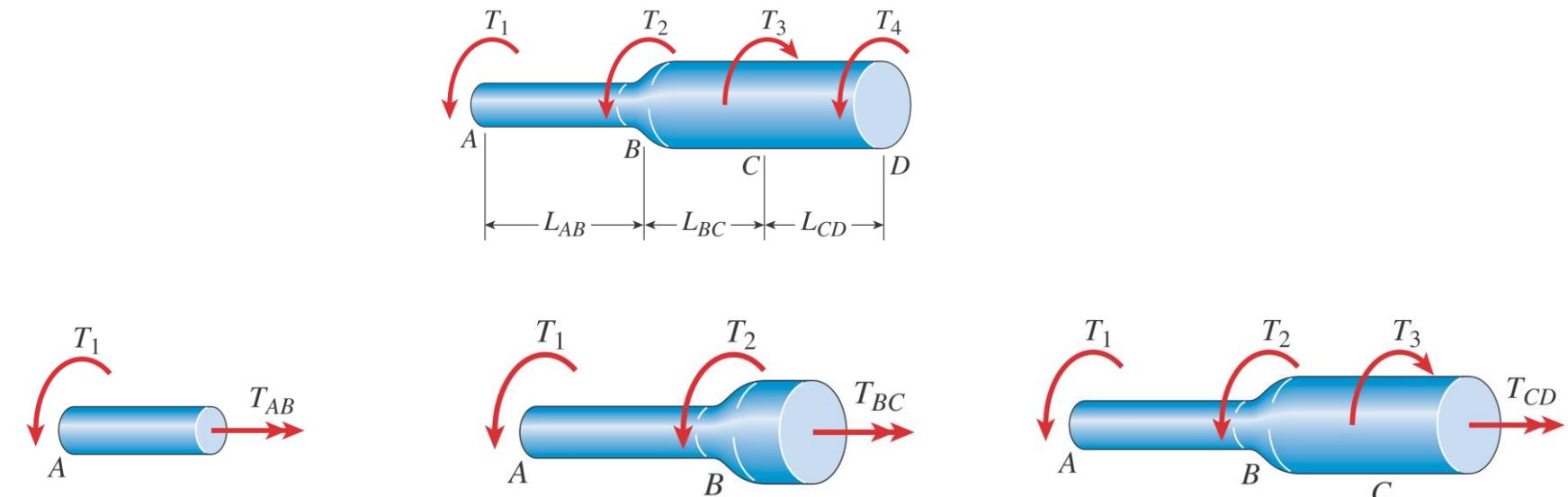


NON-UNIFORM TORSION

Remember the Axial Case ?



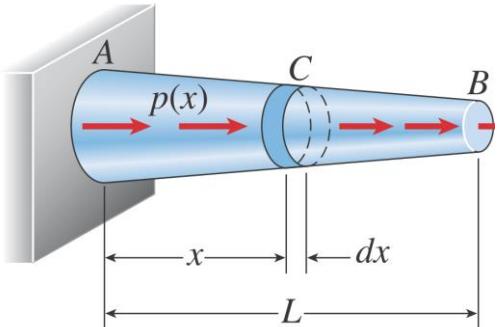
$$\delta = \sum_{i=1}^n \delta_i = \sum_{i=1}^n \frac{N_i L_i}{A_i E_i}$$



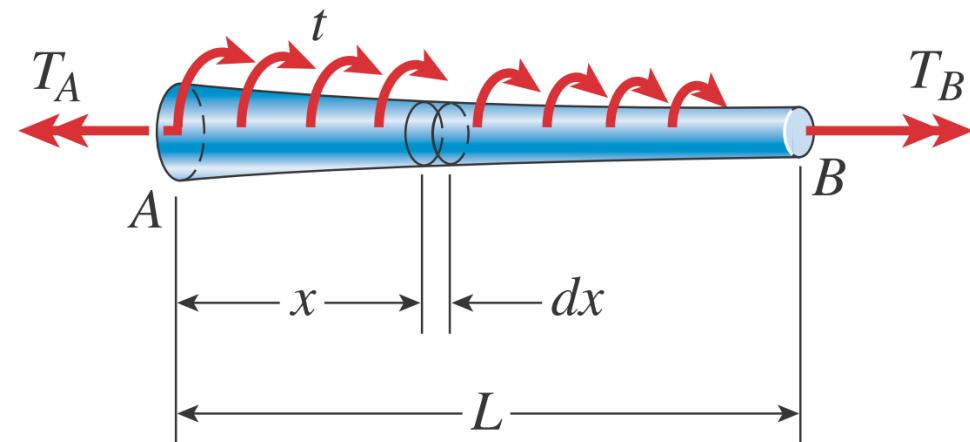
$$\phi = \sum_{i=1}^n \phi_i = \sum_{i=1}^n \frac{T_i L_i}{J_i G_i}$$

NON-UNIFORM TORSION

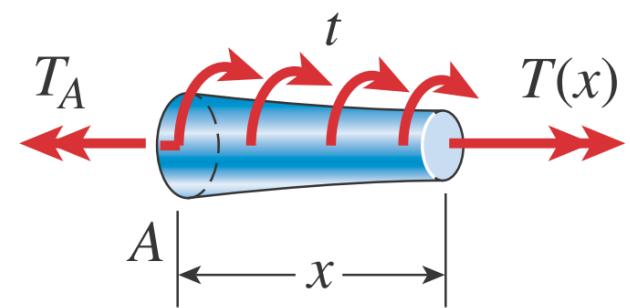
Remember the Axial Case ?



$$\delta = \int_0^L d\delta = \int_0^L \frac{N(x)dx}{EA(x)}$$

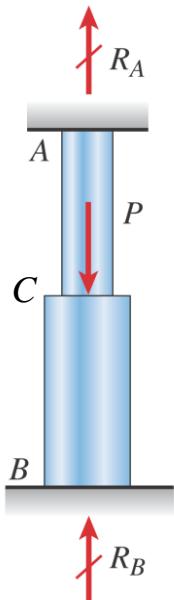


$$\phi = \int_0^L d\phi = \int_0^L \frac{T(x)dx}{GJ(x)}$$



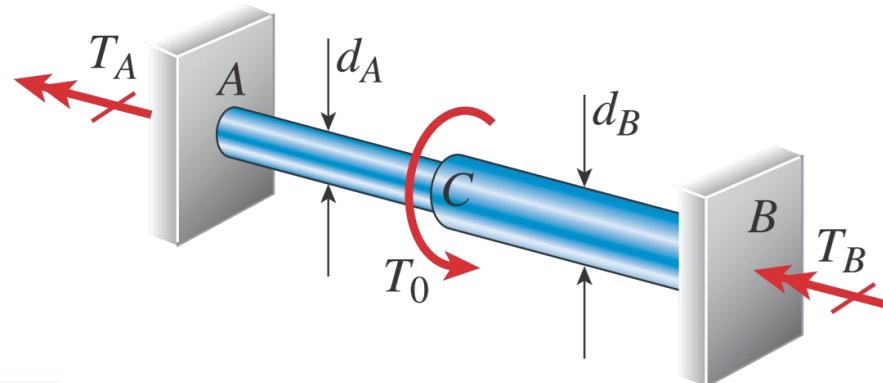
STATICALLY INDETERMINATE MEMBERS

Remember the Axial Case ?



We used Equations
of Compatibility!

$$\delta_{AB} = \delta_{AC} + \delta_{CB} = 0$$



Equilibrium $\rightarrow T_0 = T_A + T_B$

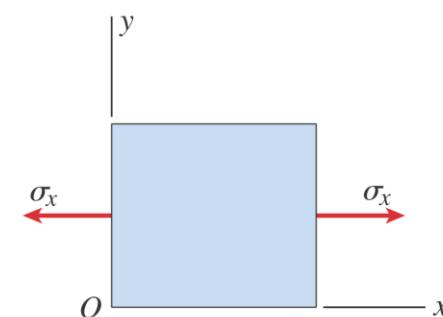
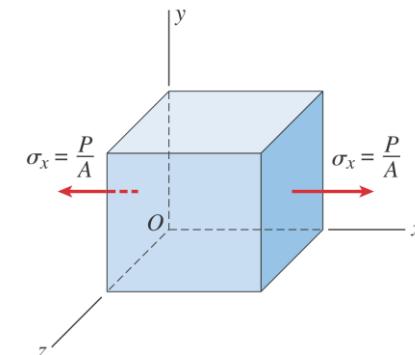
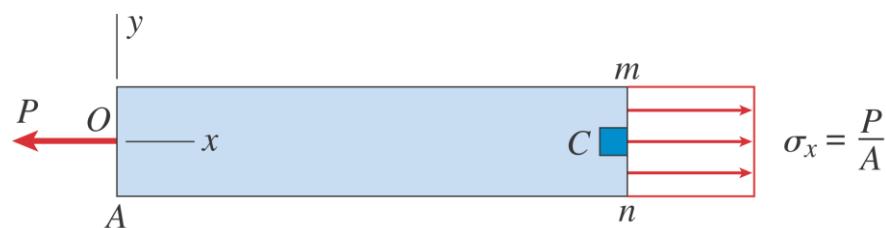
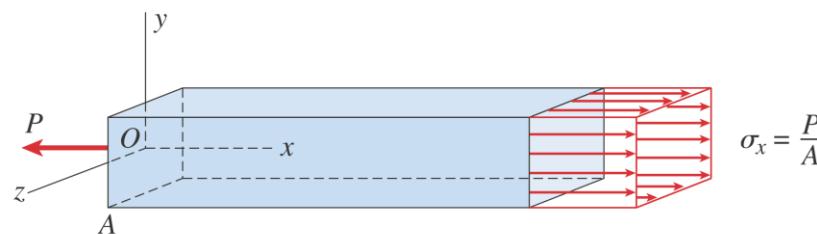
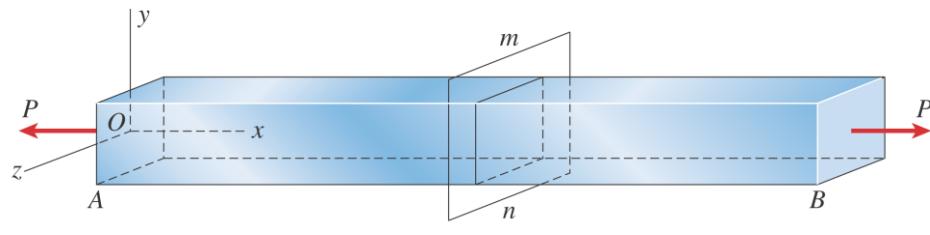
Compatibility $\rightarrow \phi_{AB} = \phi_{AC} + \phi_{CB} = 0$

$$\phi_{AC} = \frac{T_A L_{AC}}{J_{AC} G} \text{ and } \phi_{CB} = -\frac{T_B L_{CB}}{J_{CB} G}$$

Use all equations to solve for T_A and T_B

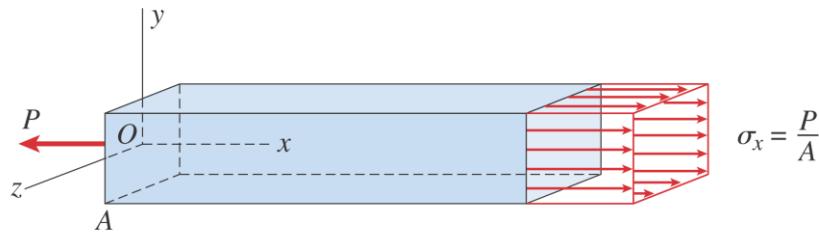
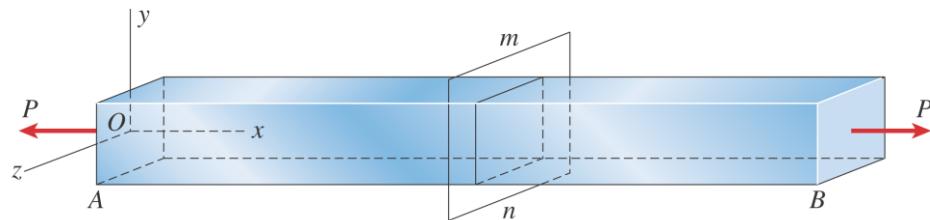
STRESSES ON INCLINED SECTIONS

Axial Loading Case

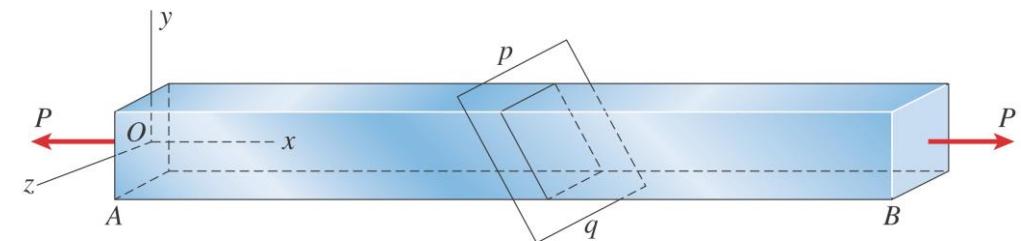


STRESSES ON INCLINED SECTIONS

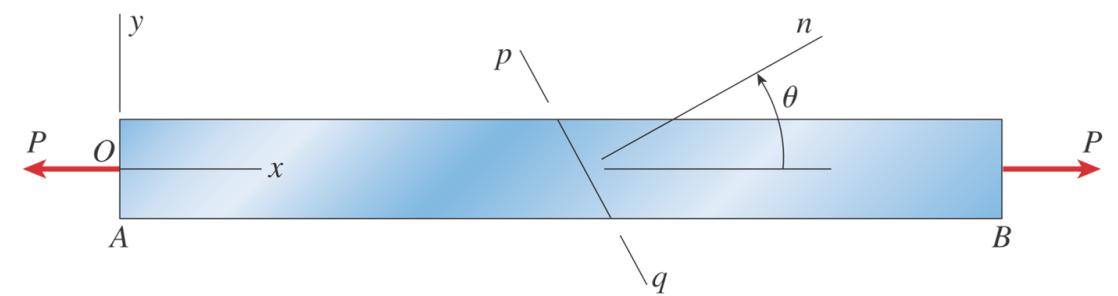
Axial Loading Case



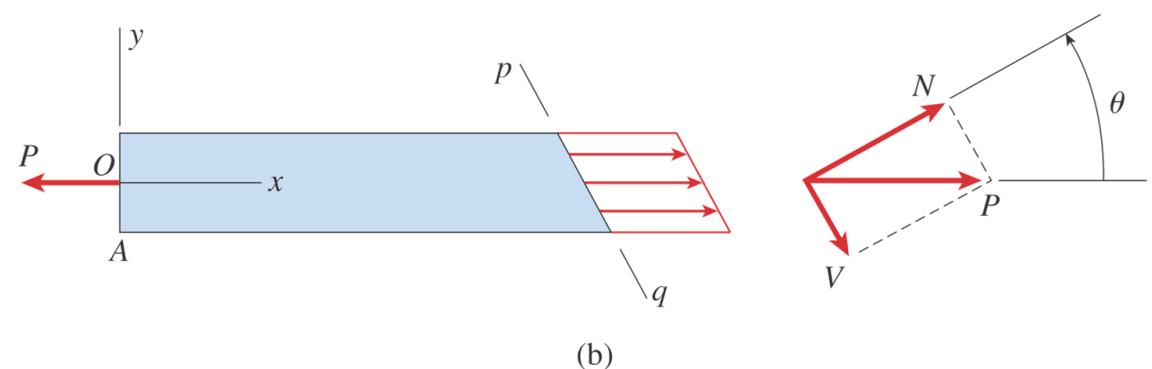
What if?



STRESSES ON INCLINED SECTIONS



(a)



(b)

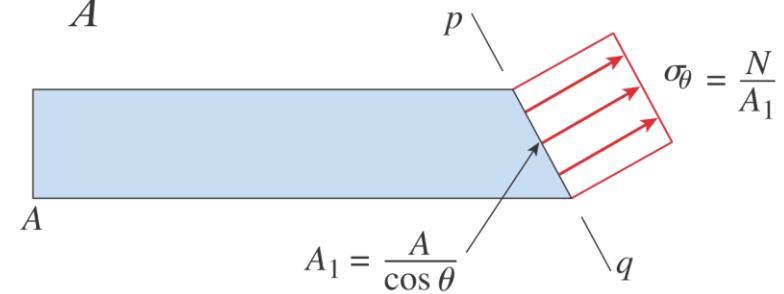
$$N = P \cos \theta$$

$$V = P \sin \theta$$



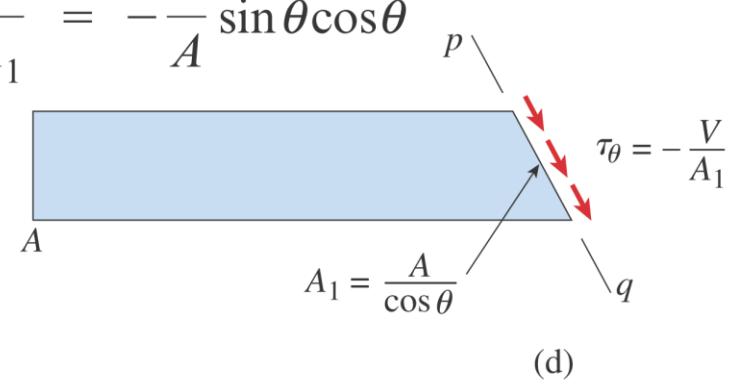
+ve sign convention

$$\sigma_\theta = \frac{N}{A_1} = \frac{P}{A} \cos^2 \theta$$



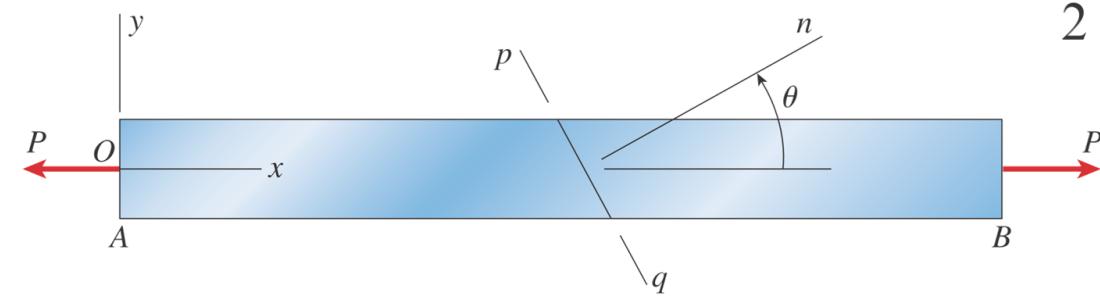
(c)

$$\tau_\theta = -\frac{V}{A_1} = -\frac{P}{A} \sin \theta \cos \theta$$



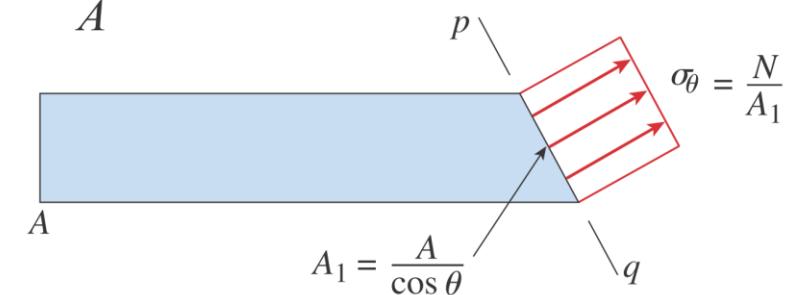
(d)

STRESSES ON INCLINED SECTIONS

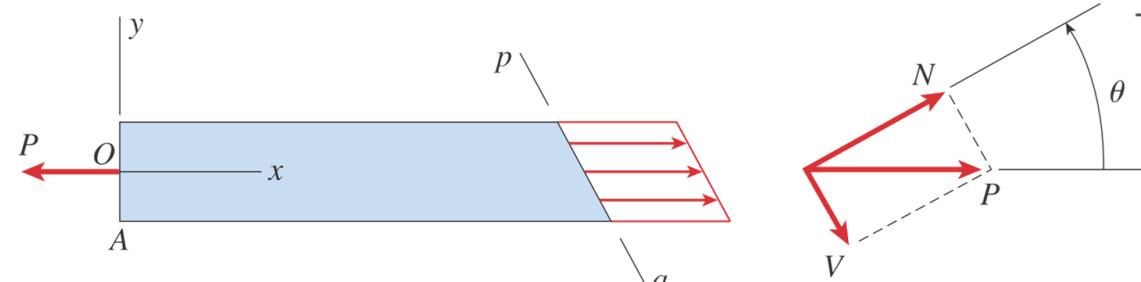


(a)

$$\frac{\sigma_x}{2} (1 + \cos 2\theta) \quad \leftarrow \quad \sigma_\theta = \frac{N}{A_1} = \frac{P}{A} \cos^2 \theta$$

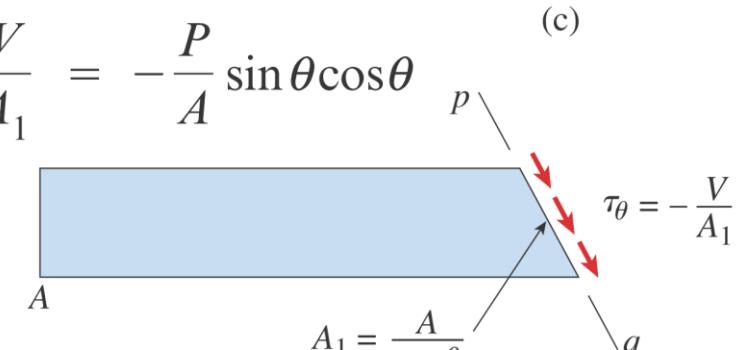


(c)



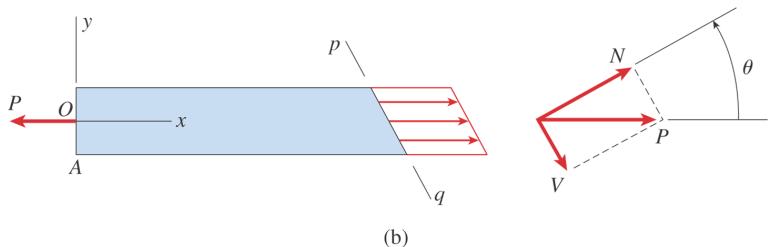
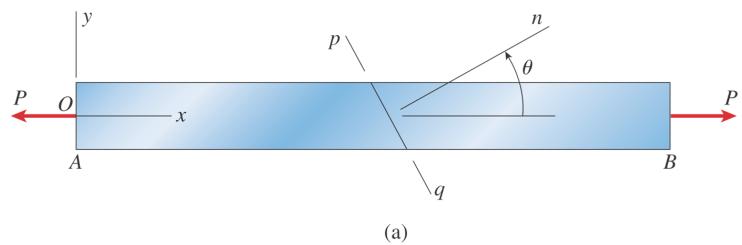
(b)

$$-\frac{\sigma_x}{2} (\sin 2\theta) \quad \leftarrow \quad \tau_\theta = -\frac{V}{A_1} = -\frac{P}{A} \sin \theta \cos \theta$$



(d)

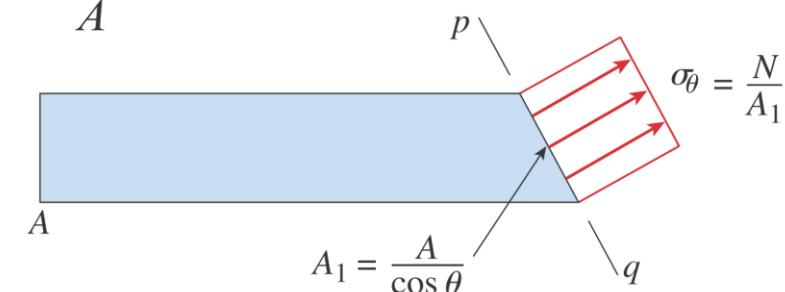
STRESSES ON INCLINED SECTIONS



$$\frac{\sigma_x}{2} (1 + \cos 2\theta) \quad \leftarrow \quad \sigma_\theta = \frac{N}{A_1} = \frac{P}{A} \cos^2 \theta$$

Maximum normal stress occurs at $\theta = 0^\circ$

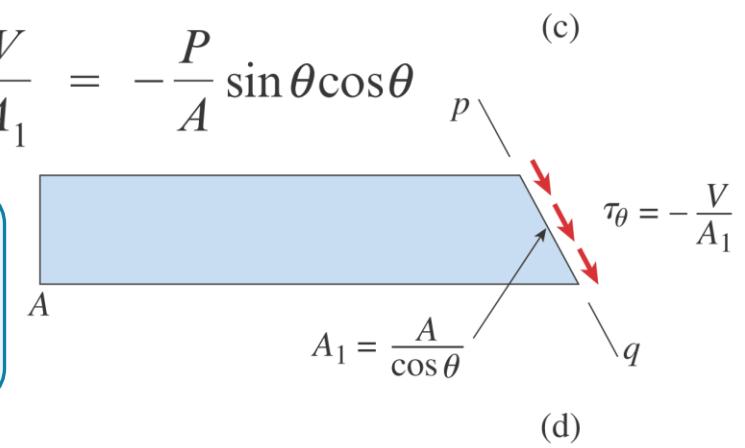
$$\sigma_{\max} = \sigma_x$$



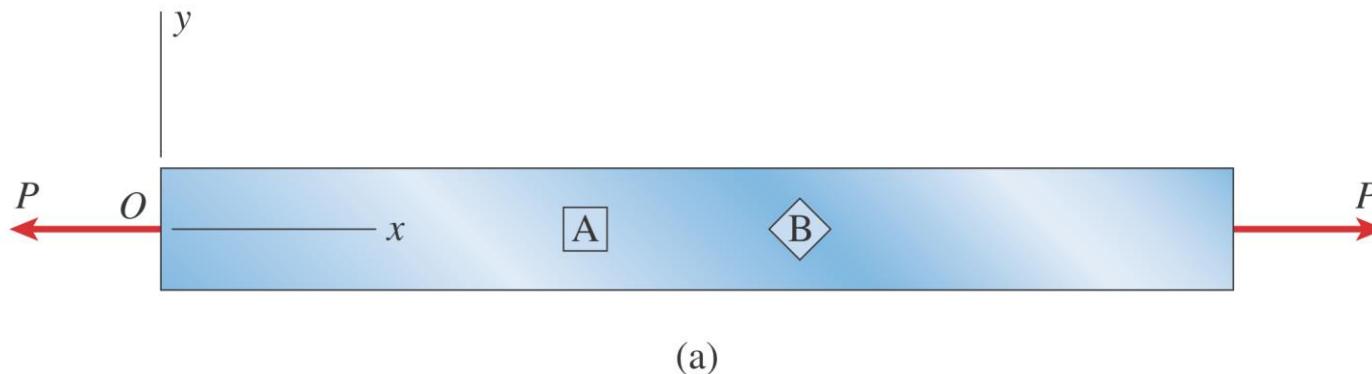
$$-\frac{\sigma_x}{2} (\sin 2\theta) \quad \leftarrow \quad \tau_\theta = -\frac{V}{A_1} = -\frac{P}{A} \sin \theta \cos \theta$$

Maximum shear stress occurs at $\theta = 45^\circ$

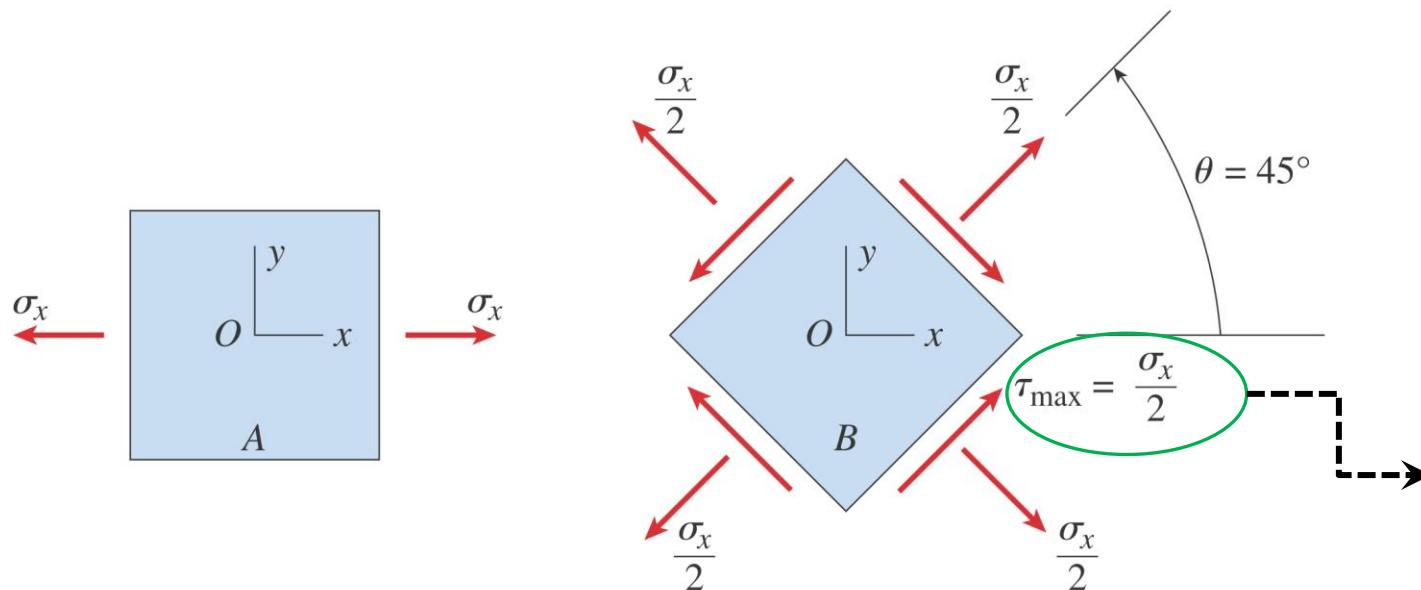
$$\tau_{\max} = \frac{\sigma_x}{2}$$



STRESSES ON INCLINED SECTIONS

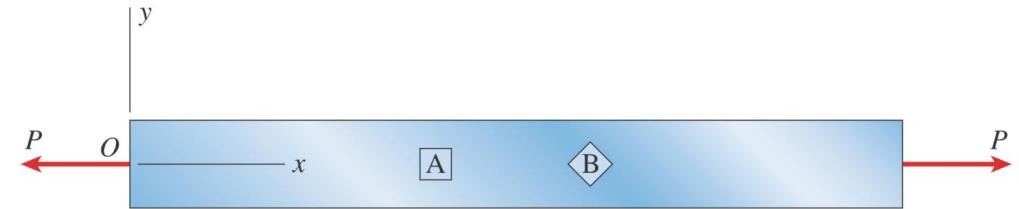


(a)

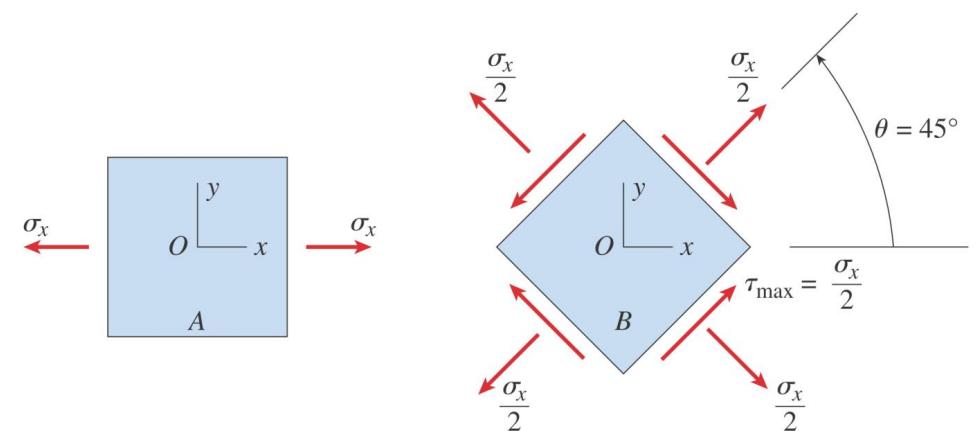


May lead to failure in
elements weak in shear,
when loaded axially!

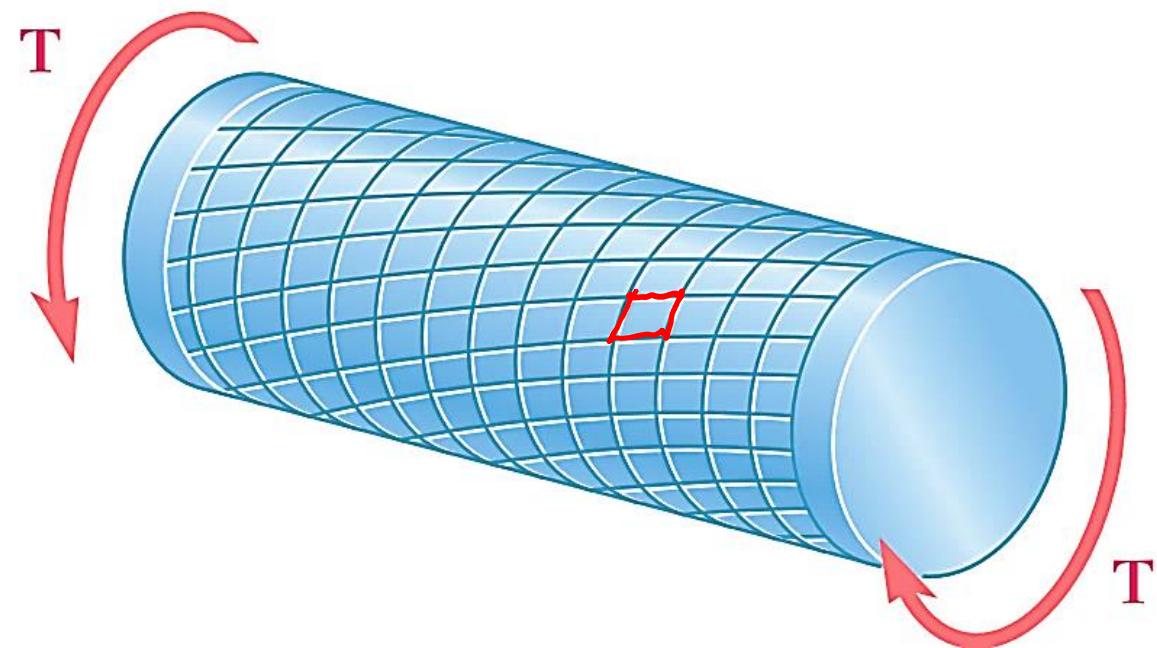
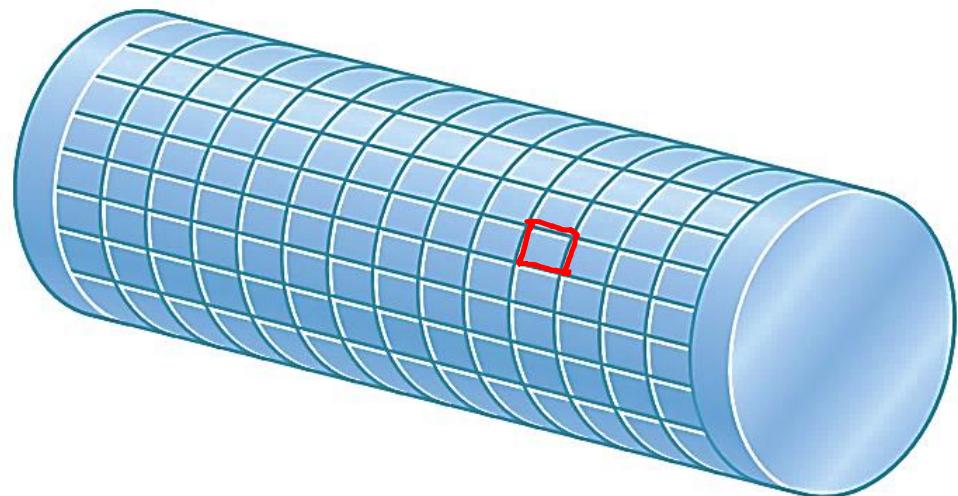
STRESSES ON INCLINED SECTIONS



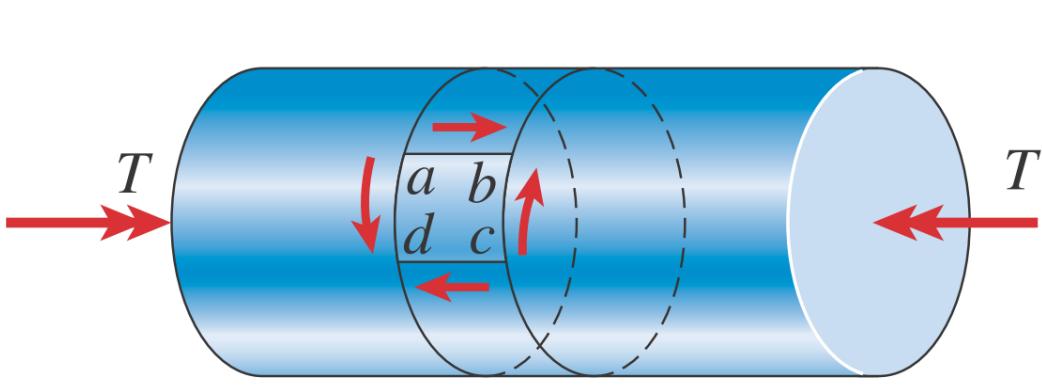
(a)



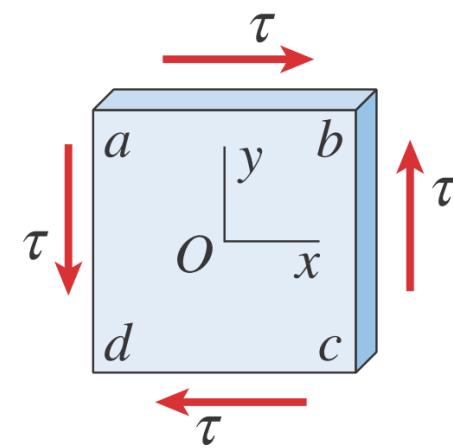
CASE OF TORSION



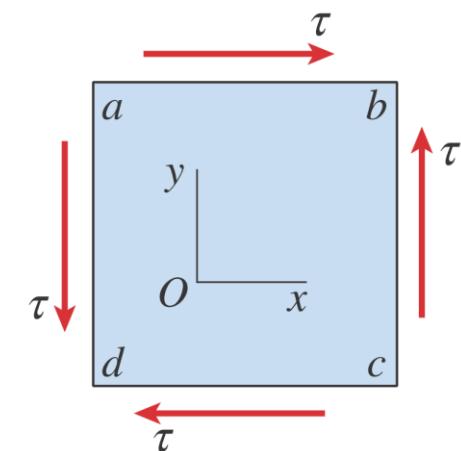
CASE OF TORSION



Pure Torsion

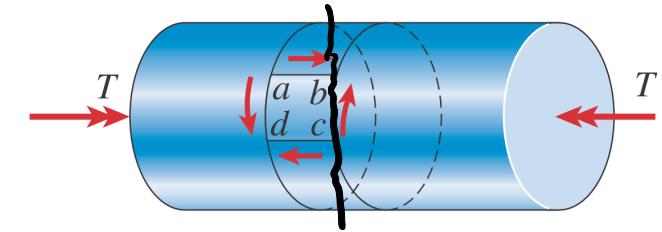
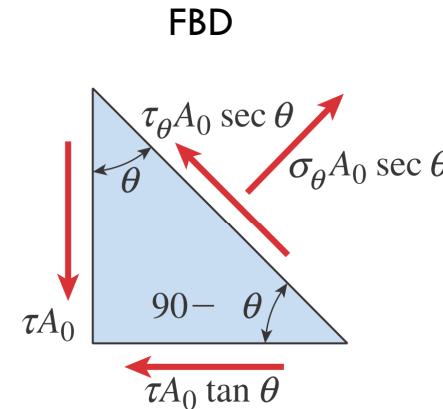
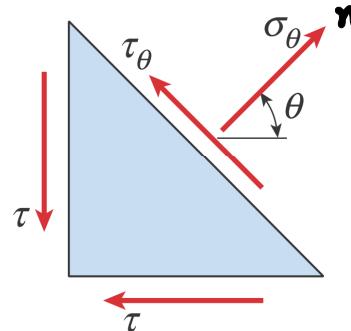
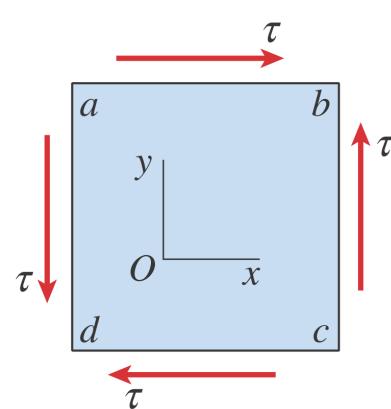


Element in Pure Shear (3D)



Element in Pure Shear (2D)

STRESSES ON INCLINED SECTIONS



Plane with Normal at angle θ

Following force balance equilibrium equations:

$$\sigma_\theta = 2\tau \sin \theta \cos \theta$$

$$\tau_\theta = \tau(\cos^2 \theta - \sin^2 \theta)$$

$$\sigma_\theta = \tau \sin 2\theta$$

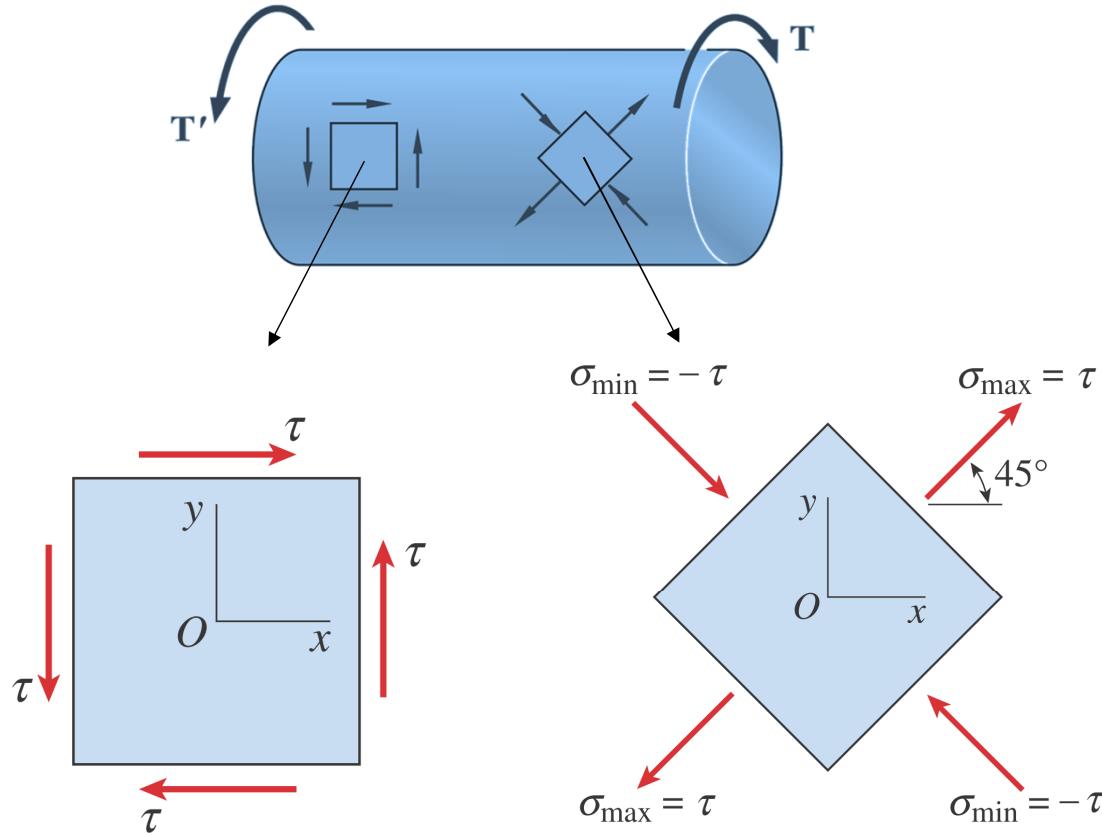
$$\tau_\theta = \tau \cos 2\theta$$

$$\sigma_\theta = \sigma_{max} \text{ at } \theta = 45^\circ$$

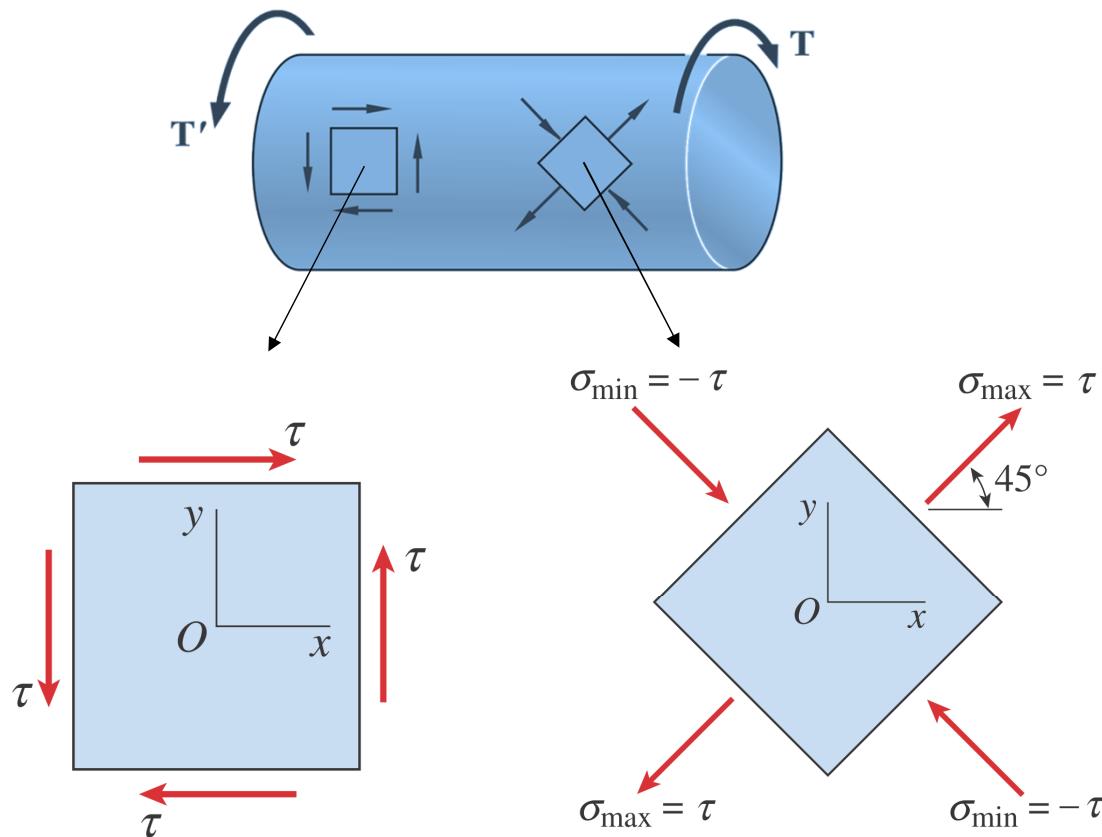
$$\sigma_{max} = \tau$$

$$\epsilon_\theta \text{ at } \theta = 45^\circ \Rightarrow \epsilon_\theta = 0$$

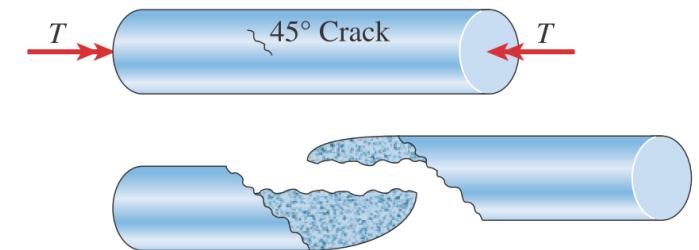
STRESSES ON INCLINED SECTIONS



STRESSES ON INCLINED SECTIONS

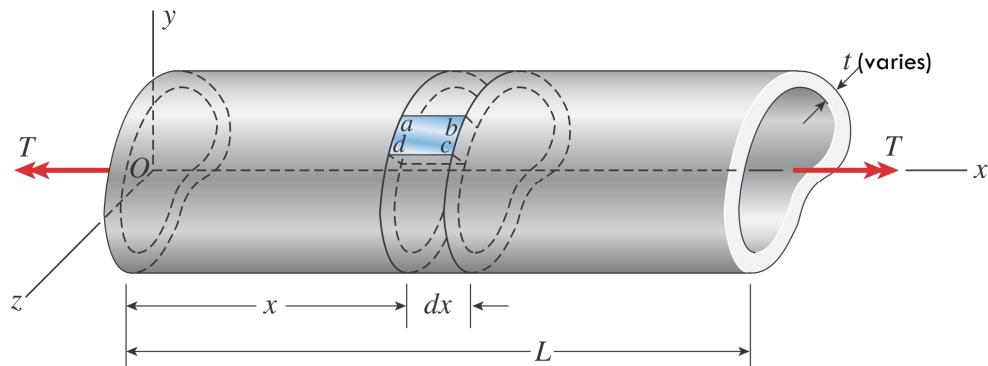


Brittle materials (eg. concrete and chalk) are weak in tension. Hence under pure torsion, it tends to fail along the 45° plane

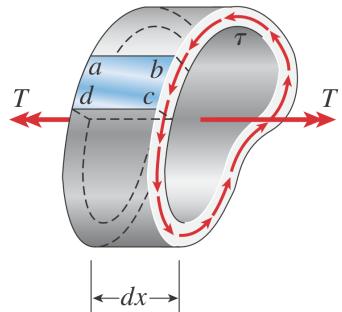


THIN WALLED TUBES

- Shear Stress and Shear Flow

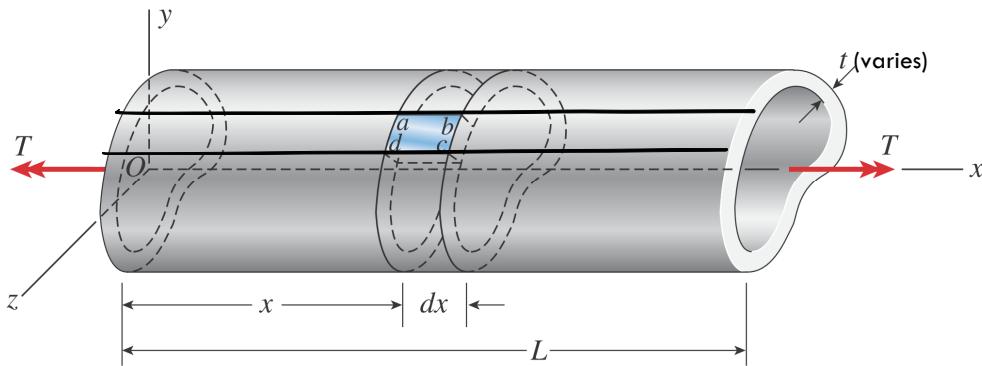


Wall is thin – Assume shear stress is constant through the thickness

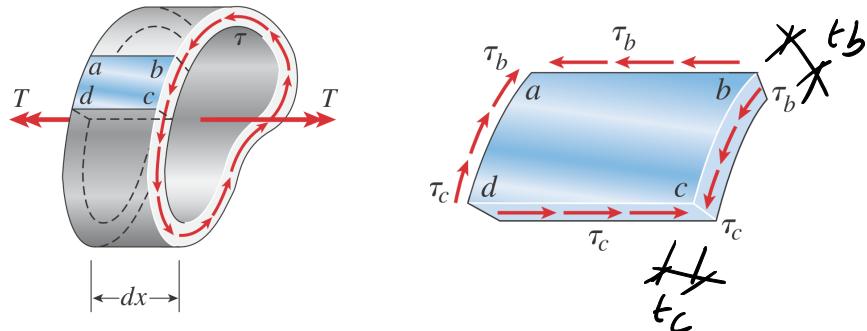


THIN WALLED TUBES

- Shear Stress and Shear Flow

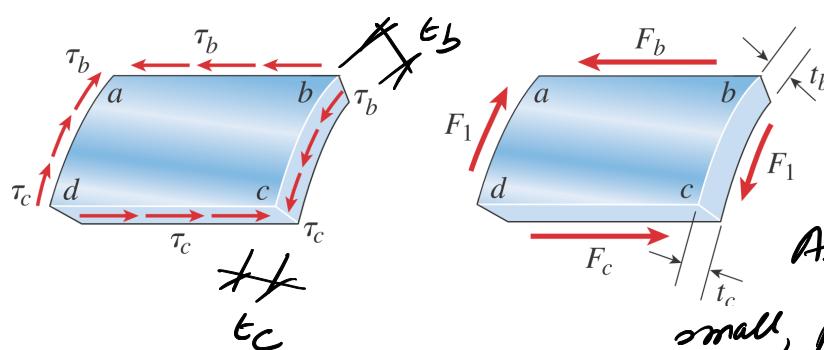
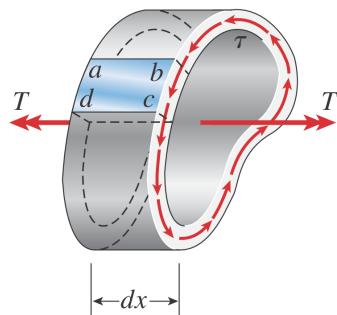
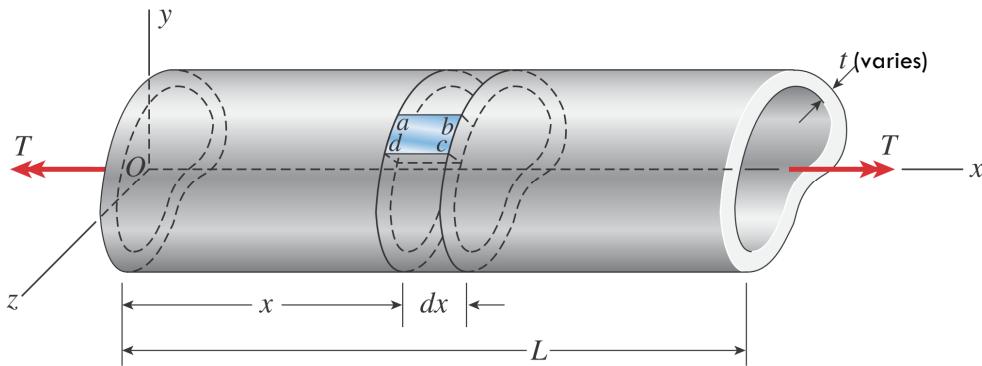


Wall is thin – Assume shear stress is constant through the thickness



THIN WALLED TUBES

- Shear Stress and Shear Flow



Wall is thin – Assume shear stress is constant through the thickness

$$F_b = c_b \times t_b \times dx \quad \text{--- 1}$$

$$F_c = c_c \times t_c \times dx \quad \text{--- 2}$$

$$\sum F_x = 0$$

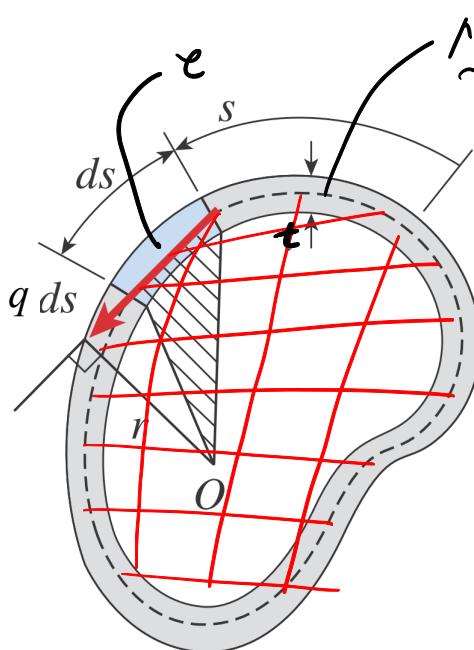
$$\Rightarrow c_b \times t_b \times dx = c_c \times t_c \times dx$$

$$\Rightarrow c_b t_b = c_c t_c = q$$

As long as the thickness is small, product of $c \times t \rightarrow$ constant

THIN WALLED TUBES

- Torsion Formula



Median line
(dm)
Length of
median line

$$dT = \int_0^L q r ds = q \int_0^L r ds$$

$A_s \rightarrow$ Area of shaded \triangle

$$\Rightarrow A_s = \frac{1}{2} \times ds \times r$$

$$\Rightarrow r ds = 2 A_s$$

$$\Rightarrow \int_0^L r ds = 2 \int_0^L A_s$$

Area enclosed by the
median line
(NOT the cross sectional
area of tube)

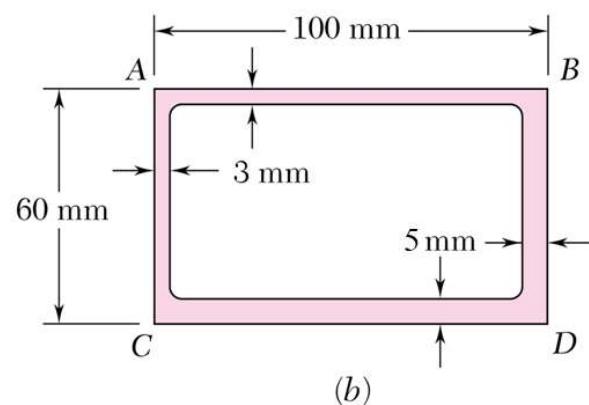
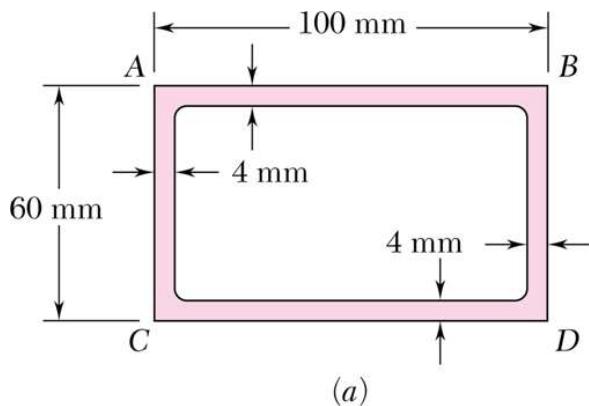
$$T = q \times 2 A_m$$

$$\Rightarrow q = \frac{T}{2 A_m} \Rightarrow \tau e = \frac{T}{2 A_m}$$

$$\boxed{\tau_e = \frac{T}{2 t A_m}}$$

Assuming 't' remains same
throughout

PROBLEM



Extruded aluminum tubing with rectangular cross-section has torque loading 2.7 kN-m.
Find shearing stress in each of four walls considering (a) uniform wall thickness of 4 mm and (b) wall thicknesses of 3 mm on AB and AC and 5 mm on CD and BD.

$$\textcircled{1} \quad A_m = (100 - 4)(60 - 4) = 5376 \text{ mm}^2.$$

$$\begin{aligned} \tau &= \frac{T}{2tA_m} \\ &= \frac{2.7 \times 10^3 \times 10^3}{2 \times 4 \times 5376} \text{ N/mm}^2 \\ &= 62.77 \text{ MPa}. \end{aligned}$$

$$\textcircled{2} \quad A_m = (100 - 1.5 - 2.5)(60 - 1.5 - 2.5) \\ = 5376 \text{ mm}^2$$

$$\begin{aligned} \tau_{AB} = \tau_{AC} &= \frac{T}{2tA_m} \\ &= \frac{2.7 \times 10^6}{2 \times 3 \times 5376} = 83.7 \text{ MPa}. \end{aligned}$$

$$\tau_{BD} = \tau_{CD} = \frac{2.7 \times 10^6}{2 \times 5 \times 5376} = 50.2 \text{ MPa}$$