

## ▼ Bounding box detection - Racoon data

### Data files

- images\_racoon.rar: contain images of racoons
- train\_labels.csv: contains coordinates for bounding box for every image

```
from google.colab import drive
drive.mount('/content/drive')
```

➞ Go to this URL in a browser: [https://accounts.google.com/o/oauth2/auth?client\\_id=9473189](https://accounts.google.com/o/oauth2/auth?client_id=9473189)

```
Enter your authorization code:
.....
Mounted at /content/drive
```

## ▼ Import the necessary libraries

```
# IMPORT LIBRARIES AND PACKAGES
import tensorflow as tf
import csv
import numpy as np
from PIL import Image

from keras import Model
from keras.applications.mobilenet import MobileNet, preprocess_input
from keras.callbacks import ModelCheckpoint, EarlyStopping, ReduceLROnPlateau, Callback
from keras.layers import Conv2D, Reshape
from keras.utils import Sequence
from keras.backend import epsilon
```

➞ The default version of TensorFlow in Colab will soon switch to TensorFlow 2.x.  
We recommend you [upgrade](#) now or ensure your notebook will continue to use TensorFlow 1.x via the %tensorflow1.x magic: [more info](#).

```
%tensorflow1.x
Using TensorFlow backend
```

## ▼ Change directory

```
import os

DATASET_FOLDER = "/content/drive/My Drive/greatlakes/Residency9/InternalLab/"
os.chdir(DATASET_FOLDER)
```

## ▼ Load the training data from train.csv file

```
↳ 173
```

## ▼ Print the shape of the train dataset

```
batch_images.shape
```

```
↳ (173, 128, 128, 3)
```

## ▼ Declare a variable IMAGE\_SIZE = 128 as we will be using MobileNet which will be

```
IMAGE_SIZE = 128 # MobileNet takes images of size 128*128*3
```

## ▼ With the help of csv.reader write a for loop which can load the train.csv file and store x0,y0,x1,y1 in individual variables.

1. Create a list variable known as 'path' which has all the path for all the training images
2. Create an array 'coords' which has the resized coordinates of the bounding box for the training images

Note: All the training images should be downsampled to 128 \* 128 as it is the input shape of MobileNet (for object detection). Hence the corresponding coordinates of the bounding boxes should be changed to match

```
TRAIN_CSV = DATASET_FOLDER+"train_labels.csv"
images_path = DATASET_FOLDER + "images/"
```

```
import csv
with open(TRAIN_CSV, 'r') as csvfile:
```

```
    paths = []
    coords = np.zeros((sum(1 for line in csvfile)-1, 4))
    reader = csv.reader(csvfile, delimiter=',')
    csvfile.seek(0)
    next(csvfile)
    for col, row in enumerate(reader):

        path = images_path + row[0]
        image_width,image_height,xmin, ymin, xmax, ymax = int(row[1]),int(row[2]),int(row[4]),int(row[5]),int(row[6]),int(row[7])
        #print(image_width,image_height,xmin, ymin, xmax, ymax)
        coords[col, 0] = xmin * IMAGE_SIZE / image_width # Normalize bounding box by image size
        coords[col, 1] = ymin * IMAGE_SIZE / image_height # Normalize bounding box by image height
        coords[col, 2] = xmax * IMAGE_SIZE / image_width # Normalize bounding box by image width
        coords[col, 3] = ymax * IMAGE_SIZE / image_height # Normalize bounding box by image height
        paths.append(path)
```

```

coords[col, 2] = (xmax - xmin) * IMAGE_SIZE / image_width # Normalize bounding box by
coords[col, 3] = (ymax - ymin) * IMAGE_SIZE / image_height
paths.append(path)

```

```

print(len(paths))
print(len(coords))

```

```

↳ 173
   173

```

Write a for loop which can load all the training images into a variable 'batch\_images' variable

Note: Convert the image to RGB scale as the MobileNet accepts 3 channels as inputs

```

batch_images = np.zeros((len(paths), IMAGE_SIZE, IMAGE_SIZE, 3), dtype=np.float32)
for i, f in enumerate(paths):
    img = Image.open(f) # Read image
    img = img.resize((IMAGE_SIZE, IMAGE_SIZE)) # Resize image
    img = img.convert('RGB')
    batch_images[i] = preprocess_input(np.array(img, dtype=np.float32))

```

Import MobileNet and load MobileNet into a variable named 'model' which takes Freeze all the layers. Add convolution and reshape layers at the end to ensure the

```

model = MobileNet(input_shape=(IMAGE_SIZE, IMAGE_SIZE, 3), include_top=False) # Load pre-trained
# Do not include classification (top) layer

```

```

# to freeze layers, except the new top layer, of course, which will be added below
for layer in model.layers:
    layer.trainable = False

```

```

# Add new top layer which is a conv layer of the same size as the previous layer so that only
x = model.layers[-1].output
x = Conv2D(4, kernel_size=4, name="coords")(x)
# In the line above kernel size should be 3 for img size 96, 4 for img size 128, 5 for img size 160
x = Reshape((4,))(x) # These are the 4 predicted coordinates of one BBox

```

```

model = Model(inputs=model.input, outputs=x)

```

Define a custom loss function IoU which calculates Intersection Over Union

```

def loss(gt, pred):
    intersections = 0
    unions = 0

```

```

unions = 0
diff_width = np.minimum(gt[:,0] + gt[:,2], pred[:,0] + pred[:,2]) - np.maximum(gt[:,0], p
diff_height = np.minimum(gt[:,1] + gt[:,3], pred[:,1] + pred[:,3]) - np.maximum(gt[:,1],
intersection = diff_width * diff_height

# Compute union
area_gt = gt[:,2] * gt[:,3]
area_pred = pred[:,2] * pred[:,3]
union = area_gt + area_pred - intersection

# Compute intersection and union over multiple boxes
for j, _ in enumerate(union):
    if union[j] > 0 and intersection[j] > 0 and union[j] >= intersection[j]:
        intersections += intersection[j]
        unions += union[j]

# Compute IOU. Use epsilon to prevent division by zero
iou = np.round(intersections / (unions + epsilon()), 4)
iou = iou.astype(np.float32)
return iou

def IoU(y_true, y_pred):
    iou = tf.py_func(loss, [y_true, y_pred], tf.float32)
    return iou

model.summary()

```



Model: "model\_2"

Layer (type)	Output Shape	Param #
=====		
input_2 (InputLayer)	(None, 128, 128, 3)	0
conv1_pad (ZeroPadding2D)	(None, 129, 129, 3)	0
conv1 (Conv2D)	(None, 64, 64, 32)	864
conv1_bn (BatchNormalization)	(None, 64, 64, 32)	128
conv1_relu (ReLU)	(None, 64, 64, 32)	0
conv_dw_1 (DepthwiseConv2D)	(None, 64, 64, 32)	288
conv_dw_1_bn (BatchNormaliza)	(None, 64, 64, 32)	128
conv_dw_1_relu (ReLU)	(None, 64, 64, 32)	0
conv_pw_1 (Conv2D)	(None, 64, 64, 64)	2048
conv_pw_1_bn (BatchNormaliza)	(None, 64, 64, 64)	256
conv_pw_1_relu (ReLU)	(None, 64, 64, 64)	0
conv_pad_2 (ZeroPadding2D)	(None, 65, 65, 64)	0
conv_dw_2 (DepthwiseConv2D)	(None, 32, 32, 64)	576
conv_dw_2_bn (BatchNormaliza)	(None, 32, 32, 64)	256
conv_dw_2_relu (ReLU)	(None, 32, 32, 64)	0
conv_pw_2 (Conv2D)	(None, 32, 32, 128)	8192
conv_pw_2_bn (BatchNormaliza)	(None, 32, 32, 128)	512
conv_pw_2_relu (ReLU)	(None, 32, 32, 128)	0
conv_dw_3 (DepthwiseConv2D)	(None, 32, 32, 128)	1152
conv_dw_3_bn (BatchNormaliza)	(None, 32, 32, 128)	512
conv_dw_3_relu (ReLU)	(None, 32, 32, 128)	0
conv_pw_3 (Conv2D)	(None, 32, 32, 128)	16384
conv_pw_3_bn (BatchNormaliza)	(None, 32, 32, 128)	512
conv_pw_3_relu (ReLU)	(None, 32, 32, 128)	0
conv_pad_4 (ZeroPadding2D)	(None, 33, 33, 128)	0
conv_dw_4 (DepthwiseConv2D)	(None, 16, 16, 128)	1152
conv_dw_4_bn (BatchNormaliza)	(None, 16, 16, 128)	512

conv_dw_4_relu (ReLU)	(None, 16, 16, 128)	0
conv_pw_4 (Conv2D)	(None, 16, 16, 256)	32768
conv_pw_4_bn (BatchNormaliza	(None, 16, 16, 256)	1024
conv_pw_4_relu (ReLU)	(None, 16, 16, 256)	0
conv_dw_5 (DepthwiseConv2D)	(None, 16, 16, 256)	2304
conv_dw_5_bn (BatchNormaliza	(None, 16, 16, 256)	1024
conv_dw_5_relu (ReLU)	(None, 16, 16, 256)	0
conv_pw_5 (Conv2D)	(None, 16, 16, 256)	65536
conv_pw_5_bn (BatchNormaliza	(None, 16, 16, 256)	1024
conv_pw_5_relu (ReLU)	(None, 16, 16, 256)	0
conv_pad_6 (ZeroPadding2D)	(None, 17, 17, 256)	0
conv_dw_6 (DepthwiseConv2D)	(None, 8, 8, 256)	2304
conv_dw_6_bn (BatchNormaliza	(None, 8, 8, 256)	1024
conv_dw_6_relu (ReLU)	(None, 8, 8, 256)	0
conv_pw_6 (Conv2D)	(None, 8, 8, 512)	131072
conv_pw_6_bn (BatchNormaliza	(None, 8, 8, 512)	2048
conv_pw_6_relu (ReLU)	(None, 8, 8, 512)	0
conv_dw_7 (DepthwiseConv2D)	(None, 8, 8, 512)	4608
conv_dw_7_bn (BatchNormaliza	(None, 8, 8, 512)	2048
conv_dw_7_relu (ReLU)	(None, 8, 8, 512)	0
conv_pw_7 (Conv2D)	(None, 8, 8, 512)	262144
conv_pw_7_bn (BatchNormaliza	(None, 8, 8, 512)	2048
conv_pw_7_relu (ReLU)	(None, 8, 8, 512)	0
conv_dw_8 (DepthwiseConv2D)	(None, 8, 8, 512)	4608
conv_dw_8_bn (BatchNormaliza	(None, 8, 8, 512)	2048
conv_dw_8_relu (ReLU)	(None, 8, 8, 512)	0
conv_pw_8 (Conv2D)	(None, 8, 8, 512)	262144
conv_pw_8_bn (BatchNormaliza	(None, 8, 8, 512)	2048
conv_pw_8_relu (ReLU)	(None, 8, 8, 512)	0

conv_dw_9 (DepthwiseConv2D)	(None, 8, 8, 512)	4608
conv_dw_9_bn (BatchNormaliza	(None, 8, 8, 512)	2048
conv_dw_9_relu (ReLU)	(None, 8, 8, 512)	0
conv_pw_9 (Conv2D)	(None, 8, 8, 512)	262144
conv_pw_9_bn (BatchNormaliza	(None, 8, 8, 512)	2048
conv_pw_9_relu (ReLU)	(None, 8, 8, 512)	0
conv_dw_10 (DepthwiseConv2D)	(None, 8, 8, 512)	4608
conv_dw_10_bn (BatchNormaliz	(None, 8, 8, 512)	2048
conv_dw_10_relu (ReLU)	(None, 8, 8, 512)	0
conv_pw_10 (Conv2D)	(None, 8, 8, 512)	262144
conv_pw_10_bn (BatchNormaliz	(None, 8, 8, 512)	2048
conv_pw_10_relu (ReLU)	(None, 8, 8, 512)	0
conv_dw_11 (DepthwiseConv2D)	(None, 8, 8, 512)	4608
conv_dw_11_bn (BatchNormaliz	(None, 8, 8, 512)	2048
conv_dw_11_relu (ReLU)	(None, 8, 8, 512)	0
conv_pw_11 (Conv2D)	(None, 8, 8, 512)	262144
conv_pw_11_bn (BatchNormaliz	(None, 8, 8, 512)	2048
conv_pw_11_relu (ReLU)	(None, 8, 8, 512)	0
conv_pad_12 (ZeroPadding2D)	(None, 9, 9, 512)	0
conv_dw_12 (DepthwiseConv2D)	(None, 4, 4, 512)	4608
conv_dw_12_bn (BatchNormaliz	(None, 4, 4, 512)	2048
conv_dw_12_relu (ReLU)	(None, 4, 4, 512)	0
conv_pw_12 (Conv2D)	(None, 4, 4, 1024)	524288
conv_pw_12_bn (BatchNormaliz	(None, 4, 4, 1024)	4096
conv_pw_12_relu (ReLU)	(None, 4, 4, 1024)	0
conv_dw_13 (DepthwiseConv2D)	(None, 4, 4, 1024)	9216
conv_dw_13_bn (BatchNormaliz	(None, 4, 4, 1024)	4096
conv_dw_13_relu (ReLU)	(None, 4, 4, 1024)	0
conv_pw_13 (Conv2D)	(None, 4, 4, 1024)	1048576

conv_pw_13 (Conv2D)	(None, 4, 4, 1024)	1048576
conv_pw_13_bn (BatchNormaliz	(None, 4, 4, 1024)	4096
conv_pw_13_relu (ReLU)	(None, 4, 4, 1024)	0
coords (Conv2D)	(None, 1, 1, 4)	65540
reshape_2 (Reshape)	(None, 4)	0

=====

Total params: 3,294,404  
 Trainable params: 65,540  
 Non trainable params: 3,228,864

## ▼ Write model.compile function & model.fit function with:

1. Optimizer = Adam, Loss = 'mse' and metrics = IoU
2. Epochs = 30, batch\_size = 32, verbose = 1

```
len(coords)
```

```
174
```

```
EPOCHS = 30 # Number of epochs. I got decent performance with just 5.
```

```
BATCH_SIZE = 32 # Depends on your GPU or CPU RAM.
```

```
ground_truth = coords
```

```
model.compile(optimizer='Adam', loss='mse', metrics=[IoU]) # Regression loss is MSE
```

```
#checkpoint = ModelCheckpoint("model-{val_iou:.2f}.h5", verbose=1, save_best_only=True,
#                               save_weights_only=True, mode="max", period=1) # Checkpoint best
#stop = EarlyStopping(monitor="val_iou", patience=PATIENCE, mode="max") # Stop early, if the
#reduce_lr = ReduceLROnPlateau(monitor="val_iou", factor=0.2, patience=10, min_lr=1e-7, verbose=1)
# Reduce learning rate if Validation IOU does not improve
```

```
model.fit(batch_images, ground_truth,
          epochs=EPOCHS, batch_size = BATCH_SIZE,
          verbose=1)
```



WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_

Epoch 1/30

173/173 [=====] - 6s 33ms/step - loss: 2887.0585 - IoU: 0.0774

Epoch 2/30

173/173 [=====] - 5s 26ms/step - loss: 699.2910 - IoU: 0.4297

Epoch 3/30

173/173 [=====] - 5s 27ms/step - loss: 652.4600 - IoU: 0.5381

Epoch 4/30

173/173 [=====] - 5s 27ms/step - loss: 586.4492 - IoU: 0.5254

Epoch 5/30

173/173 [=====] - 5s 28ms/step - loss: 343.5283 - IoU: 0.5862

Epoch 6/30

173/173 [=====] - 5s 27ms/step - loss: 274.0325 - IoU: 0.5791

Epoch 7/30

173/173 [=====] - 5s 27ms/step - loss: 241.8863 - IoU: 0.6143

Epoch 8/30

173/173 [=====] - 5s 27ms/step - loss: 199.9005 - IoU: 0.6554

Epoch 9/30

173/173 [=====] - 5s 27ms/step - loss: 165.8996 - IoU: 0.7029

Epoch 10/30

173/173 [=====] - 5s 27ms/step - loss: 156.4762 - IoU: 0.7159

Epoch 11/30

173/173 [=====] - 5s 27ms/step - loss: 146.9060 - IoU: 0.7208

Epoch 12/30

173/173 [=====] - 5s 27ms/step - loss: 119.1781 - IoU: 0.7342

Epoch 13/30

173/173 [=====] - 5s 27ms/step - loss: 113.4647 - IoU: 0.7321

Epoch 14/30

173/173 [=====] - 5s 27ms/step - loss: 100.2294 - IoU: 0.7453

Epoch 15/30

173/173 [=====] - 5s 27ms/step - loss: 93.0235 - IoU: 0.7731

Epoch 16/30

173/173 [=====] - 5s 27ms/step - loss: 89.4955 - IoU: 0.7780

Epoch 17/30

173/173 [=====] - 5s 27ms/step - loss: 82.8049 - IoU: 0.7824

Epoch 18/30

173/173 [=====] - 5s 27ms/step - loss: 81.1191 - IoU: 0.7942

Epoch 19/30

173/173 [=====] - 5s 27ms/step - loss: 78.1954 - IoU: 0.7929

Epoch 20/30

173/173 [=====] - 5s 27ms/step - loss: 70.5219 - IoU: 0.8061

Epoch 21/30

173/173 [=====] - 5s 27ms/step - loss: 67.6122 - IoU: 0.8128

Epoch 22/30

173/173 [=====] - 5s 27ms/step - loss: 68.0727 - IoU: 0.8158

Epoch 23/30

173/173 [=====] - 5s 27ms/step - loss: 67.7651 - IoU: 0.8114

Epoch 24/30

173/173 [=====] - 5s 27ms/step - loss: 66.3373 - IoU: 0.8090

Epoch 25/30

173/173 [=====] - 5s 27ms/step - loss: 66.5067 - IoU: 0.8176

Epoch 26/30

173/173 [=====] - 5s 27ms/step - loss: 61.7543 - IoU: 0.8223

Epoch 27/30

```

173/173 [=====] - 5s 26ms/step - loss: 61.7269 - IoU: 0.8313
Epoch 28/30
173/173 [=====] - 5s 27ms/step - loss: 59.2167 - IoU: 0.8316
Epoch 29/30
173/173 [=====] - 5s 27ms/step - loss: 60.2528 - IoU: 0.8427
Epoch 30/30
173/173 [=====] - 5s 27ms/step - loss: 58.2374 - IoU: 0.8436
<keras.callbacks.History at 0x7f3aa7334198>

```

### ▼ Pick a test image from the given data

```

import cv2
filename = './images/raccoon-16.jpg'
unscaled = cv2.imread(filename) # Original image for display

```

### ▼ Resize the image to 128 \* 128 and preprocess the image for the MobileNet model

```

image_height, image_width, _ = unscaled.shape
image = cv2.resize(unscaled, (IMAGE_SIZE, IMAGE_SIZE)) # Rescaled image to run the network
feat_scaled = preprocess_input(np.array(image, dtype=np.float32))

```

### ▼ Predict the coordinates of the bounding box for the given test image

```

region = model.predict(x=np.array([feat_scaled]))[0]
print(region)

```

```

[ 30.74896  29.288248  85.985504 107.34286 ]

```

### ▼ Plot the test image using .imshow and draw a boundary box around the image with the model

```

x0 = int(region[0] * image_width / IMAGE_SIZE) # Scale the BBox
y0 = int(region[1] * image_height / IMAGE_SIZE)

x1 = int((region[2]) * image_width / IMAGE_SIZE)
y1 = int((region[3]) * image_height / IMAGE_SIZE)

```

```

import matplotlib.pyplot as plt
import matplotlib.patches as patches
from PIL import Image
import numpy as np

```

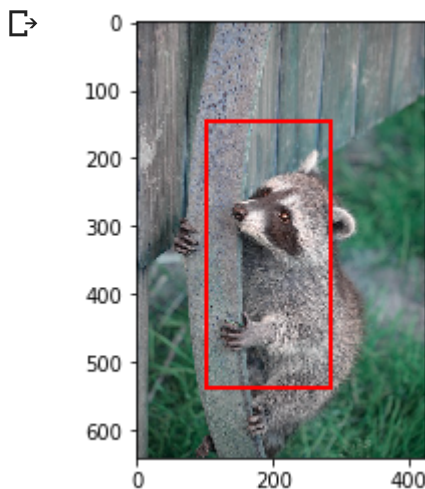
```
# Create figure and axes
fig,ax = plt.subplots(1)

# Display the image
ax.imshow(unscaled)

# Create a Rectangle patch
rect = patches.Rectangle((x0, y0), (x1 - x0) , (y1 - y0) , linewidth=2, edgecolor='r', facecc

# Add the patch to the Axes
ax.add_patch(rect)

plt.show()
```



## ▼ Time Series Prediction using LSTM

### ▼ Download Data

Link: <https://datamarket.com/data/set/2324/daily-minimum-temperatures-in-melbourne-australia-19>

#### Description

Daily minimum temperatures in Melbourne, Australia, 1981-1990

Units: Degrees Celcius

#### Steps before loading

- Rename the column name with temprature values to "Temprature"
- In the last, there is one extra row in the data, remove it by opening the file and save it again.
- There are some values in Temprature column which have a "?" before them, they will give error,
- If you don't want to do these steps, just load the data file given by Great Learning.

## ▼ Mount google drive

## ▼ Change your present working directory

## ▼ Load your data file

```
import pandas as pd
df = pd.read_csv('/content/drive/My Drive/greatlakes/Residency9/Internallab/daily-minimum-ten
df.sort_index(inplace=True)
df.head()
```

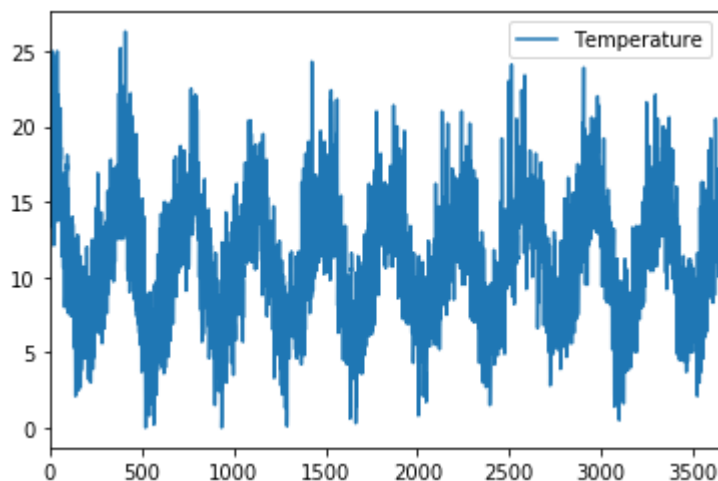
```
↗
```

	Date	Temperature
0	1981-01-01	20.7
1	1981-01-02	17.9
2	1981-01-03	18.8
3	1981-01-04	14.6
4	1981-01-05	15.8

## ▼ Plot data

```
df.plot()
```

```
↗ <matplotlib.axes._subplots.AxesSubplot at 0x7f3a9c61b128>
```



## ▼ Describe your dataframe

```
df.describe().T
```

```
↳
```

	count	mean	std	min	25%	50%	75%	max
Temperature	3650.0	11.177753	4.071837	0.0	8.3	11.0	14.0	26.3

## ▼ Check for null values

```
df.isnull().sum()
```

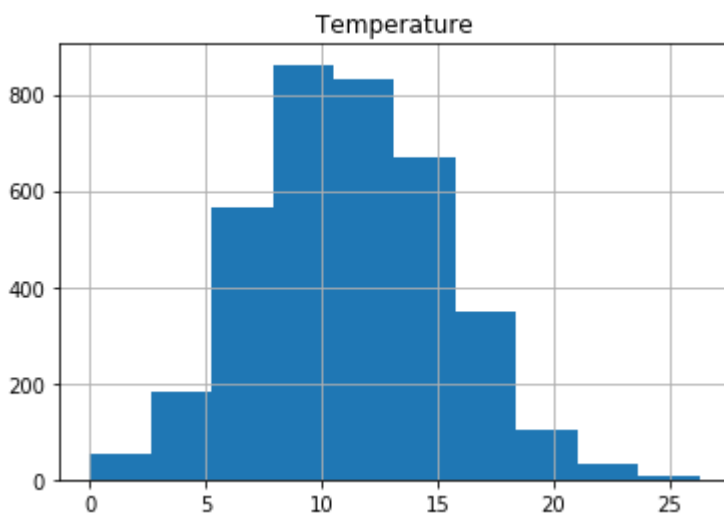
```
↳ Date      0
   Temperature  0
   dtype: int64
```

## ▼ Drop null values

## ▼ Get the representation of the distribution of data in the form of histogram

```
df.hist()
```

```
↳ array([[<matplotlib.axes._subplots.AxesSubplot object at 0x7f3aa7cc5198>]],
      dtype=object)
```



## ▼ Check the maximum and minimum values

```
#Check Data Range
```

```
print('Min', np.min(df))
print('Max', np.max(df))
```

```

↳ Min Date      1981-01-01
   Temperature    0
   dtype: object
   Max Date      1990-12-31
   Temperature   26.3
   dtype: object

```

## ▼ Normalize the data

```
df.drop("Date", axis=1, inplace=True)
from sklearn.preprocessing import MinMaxScaler
#Normalize the data
scaler = MinMaxScaler(feature_range=(0, 1))
scaled = scaler.fit_transform(df)
```

## ▼ Check the maximum and minimum values of scaled data

```
#Check Data Range
print('Min', np.min(scaled))
print('Max', np.max(scaled))
```

```

↳ Min 0.0
   Max 1.0

```

## ▼ Look into some of the scaled values

```
scaled[:10]
```

```

↳ array([[0.78707224],
        [0.68060837],
        [0.7148289 ],
        [0.55513308],
        [0.60076046],
        [0.60076046],
        [0.60076046],
        [0.66159696],
        [0.82889734],
        [0.76045627]])

```

## ▼ Split data into Training and Testing

```
#70% examples will used for training
train_size = int(len(scaled) * 0.70)
#30% will be used for Test
```

```
test_size = len(scaled) - train_size)
```

```
#Split the data
```

```
train, test = scaled[0:train_size, :], scaled[train_size: len(scaled), :]
```

### ▼ Print train and test size

```
print('train: {} \ntest: {}'.format(len(train), len(test)))
```

```
↳ train: 2555
   test: 1095
```

### ▼ Create the sequential data

Map the temperature at a particular time  $t$  to the temperature at time  $t+n$ , where  $n$  is any number you de

For example: to map tempratures of consecutive days, use  $t+1$ , i.e. `loop_back = 1`

### ▼ Define your function to create dataset

```
#window - how long the sequence will be
```

```
def create_dataset(dataset, window=1):
```

```
    dataX, dataY = [], []
```

```
    for i in range(len(dataset)-window):
```

```
        a = dataset[i:(i+window), 0]
```

```
        dataX.append(a)
```

```
        dataY.append(dataset[i + window, 0])
```

```
    return np.array(dataX), np.array(dataY)
```

### ▼ Use function to get training and test set

```
#Create Input and Output
```

```
window_size = 1
```

```
X_train, y_train = create_dataset(train, window_size)
```

```
X_test, y_test = create_dataset(test, window_size)
```

### ▼ Transform the prepared train and test input data into the expected structure using numpy.

```
#Make it 3 Dimensional Data - needed for LSTM
```

```
X_train = np.reshape(X_train, (X_train.shape[0], X_train.shape[1], 1))
```

```
X_test = np.reshape(X_test, (X_test.shape[0], X_test.shape[1], 1))
```

```
print(X_train.shape)
print(X_test.shape)
```

```
↳ (2554, 1, 1)
   (1094, 1, 1)
```

## ▼ Define Model

### ▼ Define sequential model, add LSTM layer and compile the model

```
import tensorflow as tf
tf.keras.backend.clear_session()
model = tf.keras.Sequential()
model.add(tf.keras.layers.LSTM(32,input_shape=(window_size,1)))
model.add(tf.keras.layers.Dense(1))
model.compile(optimizer='adam',loss='mse')
```

```
↳ WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow_core/python/op
Instructions for updating:
If using Keras pass *_constraint arguments to layers.
```

### ▼ Summarize your model

```
model.summary()
```

```
↳ Model: "sequential"
```

Layer (type)	Output Shape	Param #
=====		
lstm (LSTM)	(None, 32)	4352
=====		
dense (Dense)	(None, 1)	33
=====		
Total params: 4,385		
Trainable params: 4,385		
Non-trainable params: 0		
=====		

### ▼ Train the model

```
model.fit(X_train, y_train, epochs=200, validation_data=(X_test, y_test), batch_size=32)
```

```
↳
```



```
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow_core/python/op
Instructions for updating:
Use tf.where in 2.0, which has the same broadcast rule as np.where
Train on 2554 samples, validate on 1094 samples
Epoch 1/200
2554/2554 [=====] - 1s 292us/sample - loss: 0.1092 - val_loss: 
Epoch 2/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0192 - val_loss: 0
Epoch 3/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0150 - val_loss: 0
Epoch 4/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0141 - val_loss: 0
Epoch 5/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0132 - val_loss: 0
Epoch 6/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0124 - val_loss: 0
Epoch 7/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0117 - val_loss: 0
Epoch 8/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0111 - val_loss: 0
Epoch 9/200
2554/2554 [=====] - 0s 100us/sample - loss: 0.0107 - val_loss: 
Epoch 10/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0104 - val_loss: 0
Epoch 11/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0102 - val_loss: 0
Epoch 12/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0101 - val_loss: 0
Epoch 13/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0101 - val_loss: 0
Epoch 14/200
2554/2554 [=====] - 0s 96us/sample - loss: 0.0101 - val_loss: 0
Epoch 15/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0101 - val_loss: 0
Epoch 16/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0
Epoch 17/200
2554/2554 [=====] - 0s 96us/sample - loss: 0.0100 - val_loss: 0
Epoch 18/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0
Epoch 19/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0
Epoch 20/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0100 - val_loss: 0
Epoch 21/200
2554/2554 [=====] - 0s 88us/sample - loss: 0.0100 - val_loss: 0
Epoch 22/200
2554/2554 [=====] - 0s 88us/sample - loss: 0.0100 - val_loss: 0
Epoch 23/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0
Epoch 24/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0
Epoch 25/200
2554/2554 [=====] - 0s 95us/sample - loss: 0.0101 - val_loss: 0
Epoch 26/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0
Epoch 27/200
```

```
2554/2554 [=====] - 0s 95us/sample - loss: 0.0101 - val_loss: 0.0101
Epoch 28/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 29/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 30/200
2554/2554 [=====] - 0s 99us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 31/200
2554/2554 [=====] - 0s 95us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 32/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 33/200
2554/2554 [=====] - 0s 88us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 34/200
2554/2554 [=====] - 0s 96us/sample - loss: 0.0101 - val_loss: 0.0101
Epoch 35/200
2554/2554 [=====] - 0s 95us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 36/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0101 - val_loss: 0.0101
Epoch 37/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0101 - val_loss: 0.0101
Epoch 38/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 39/200
2554/2554 [=====] - 0s 99us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 40/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 41/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0101 - val_loss: 0.0101
Epoch 42/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 43/200
2554/2554 [=====] - 0s 98us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 44/200
2554/2554 [=====] - 0s 95us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 45/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 46/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 47/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 48/200
2554/2554 [=====] - 0s 99us/sample - loss: 0.0101 - val_loss: 0.0101
Epoch 49/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0101 - val_loss: 0.0101
Epoch 50/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 51/200
2554/2554 [=====] - 0s 96us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 52/200
2554/2554 [=====] - 0s 96us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 53/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 54/200
2554/2554 [=====] - 0s 87us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 55/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 56/200
```

```
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 57/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 58/200
2554/2554 [=====] - 0s 87us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 59/200
2554/2554 [=====] - 0s 87us/sample - loss: 0.0101 - val_loss: 0.0100
Epoch 60/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 61/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 62/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 63/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 64/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 65/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 66/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 67/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 68/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 69/200
2554/2554 [=====] - 0s 88us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 70/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 71/200
2554/2554 [=====] - 0s 95us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 72/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 73/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 74/200
2554/2554 [=====] - 0s 88us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 75/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 76/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 77/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 78/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 79/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 80/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 81/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0101 - val_loss: 0.0100
Epoch 82/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 83/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 84/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 85/200
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```
Epoch 85/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 86/200
2554/2554 [=====] - 0s 88us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 87/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 88/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 89/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 90/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 91/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 92/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 93/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 94/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 95/200
2554/2554 [=====] - 0s 87us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 96/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 97/200
2554/2554 [=====] - 0s 95us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 98/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 99/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 100/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 101/200
2554/2554 [=====] - 0s 95us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 102/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 103/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 104/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 105/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 106/200
2554/2554 [=====] - 0s 95us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 107/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 108/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 109/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 110/200
2554/2554 [=====] - 0s 99us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 111/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 112/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0101 - val_loss: 0.0100
Epoch 113/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
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Epoch 114/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 115/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 116/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 117/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 118/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 119/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 120/200
2554/2554 [=====] - 0s 88us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 121/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 122/200
2554/2554 [=====] - 0s 98us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 123/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0101 - val_loss: 0.0100
Epoch 124/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 125/200
2554/2554 [=====] - 0s 99us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 126/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 127/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 128/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 129/200
2554/2554 [=====] - 0s 100us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 130/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 131/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 132/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 133/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 134/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 135/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 136/200
2554/2554 [=====] - 0s 87us/sample - loss: 0.0099 - val_loss: 0.0100
Epoch 137/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 138/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 139/200
2554/2554 [=====] - 0s 87us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 140/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 141/200
2554/2554 [=====] - 0s 88us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 142/200
2554/2554 [=====] - 0s 99us/sample - loss: 0.0100 - val_loss: 0.0100
```

Epoch 143/200  
2554/2554 [=====] - 0s 89us/sample - loss: 0.0099 - val\_loss: 0.0100  
Epoch 144/200  
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 145/200  
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 146/200  
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 147/200  
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 148/200  
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 149/200  
2554/2554 [=====] - 0s 102us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 150/200  
2554/2554 [=====] - 0s 105us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 151/200  
2554/2554 [=====] - 0s 103us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 152/200  
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 153/200  
2554/2554 [=====] - 0s 88us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 154/200  
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 155/200  
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 156/200  
2554/2554 [=====] - 0s 86us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 157/200  
2554/2554 [=====] - 0s 85us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 158/200  
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 159/200  
2554/2554 [=====] - 0s 95us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 160/200  
2554/2554 [=====] - 0s 93us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 161/200  
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 162/200  
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 163/200  
2554/2554 [=====] - 0s 88us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 164/200  
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 165/200  
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 166/200  
2554/2554 [=====] - 0s 87us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 167/200  
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 168/200  
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 169/200  
2554/2554 [=====] - 0s 97us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 170/200  
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val\_loss: 0.0100  
Epoch 171/200  
2554/2554 [=====] - 0s 88us/sample - loss: 0.0100 - val\_loss: 0.0100

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2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 172/200
2554/2554 [=====] - 0s 94us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 173/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 174/200
2554/2554 [=====] - 0s 87us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 175/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 176/200
2554/2554 [=====] - 0s 103us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 177/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 178/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 179/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 180/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 181/200
2554/2554 [=====] - 0s 103us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 182/200
2554/2554 [=====] - 0s 102us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 183/200
2554/2554 [=====] - 0s 103us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 184/200
2554/2554 [=====] - 0s 96us/sample - loss: 0.0099 - val_loss: 0.0100
Epoch 185/200
2554/2554 [=====] - 0s 89us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 186/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 187/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 188/200
2554/2554 [=====] - 0s 87us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 189/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 190/200
2554/2554 [=====] - 0s 92us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 191/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 192/200
2554/2554 [=====] - 0s 90us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 193/200
2554/2554 [=====] - 0s 104us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 194/200
2554/2554 [=====] - 0s 97us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 195/200
2554/2554 [=====] - 0s 101us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 196/200
2554/2554 [=====] - 0s 100us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 197/200
2554/2554 [=====] - 0s 93us/sample - loss: 0.0099 - val_loss: 0.0100
Epoch 198/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
Epoch 199/200
2554/2554 [=====] - 0s 91us/sample - loss: 0.0100 - val_loss: 0.0100
```

## ▼ Make Predictions and Evaluate your model

```
#Un-normalize the predited data
trainPredict = model.predict(X_train)
testPredict = model.predict(X_test)
trainPredict = scaler.inverse_transform(trainPredict)
testPredict = scaler.inverse_transform(testPredict)
```

## ▼ Plot the results

```
import matplotlib.pyplot as plt
trainPredictPlot = np.empty_like(scaled)
trainPredictPlot[:, :] = np.nan
trainPredictPlot[window_size:len(trainPredict)+window_size, :] = trainPredict
# shift test predictions for plotting
testPredictPlot = np.empty_like(scaled)
testPredictPlot[:, :] = np.nan
testPredictPlot[len(trainPredict)+(window_size*2):len(scaled), :] = testPredict
# plot baseline and predictions
plt.figure(figsize=(10,6))
plt.plot(scaler.inverse_transform(scaled))
plt.plot(trainPredictPlot)
plt.plot(testPredictPlot)
plt.show()
```

