Instructions

- · Some parts of the code are already done for you
- You need to execute all the cells
- You need to add the code where ever you see "#### Add your code here ####"
- · Marks are mentioned along with the cells

Face detection

Task is to predict the boundaries(mask) around the face in a given image.

Dataset

Faces in images marked with bounding boxes. Have around 500 images with around 1100 faces mar

- Mount Google drive if you are using google colab
 - · We recommend using Google Colab as you can face memory issues and longer runtimes while

```
from google.colab import drive
drive.mount('/content/drive')

Go to this URL in a browser: https://accounts.google.com/o/oauth2/auth?client_id=9473189

Enter your authorization code:
...........
Mounted at /content/drive
```

Change current working directory to project folder (1 mark)

```
import os
import tensorflow as tf
#### Add your code here ####
project_dir = "/content/drive/My Drive/greatlakes/Projects/Advanced_Computer_Vision/Project1/
os.chdir(project_dir)
```

The default version of TensorFlow in Colab will soon switch to TensorFlow 2.x.

We recommend you <u>upgrade</u> now or ensure your notebook will continue to use TensorFlow 1.x via the %tens 1.x magic: <u>more info</u>.

▼ Load the "images.npy" file (2 marks)

This file contains images with details of bounding boxes

```
import numpy as np
data = np.load('images.npy', allow_pickle=True)
```

▼ Check one sample from the loaded "images.npy" file (2 marks)

```
#### Add your code here ####
print(data[10][1])
```

[{'label': ['Face'], 'notes': '', 'points': [{'x': 0.48, 'y': 0.10385756676557864}, {'x'

Set image dimensions (1 mark)

Initialize image height, image width with value: 224

```
IMAGE_WIDTH = 224
IMAGE_HEIGHT = 224
```

Hint - print data[10][1]

Create features and labels

- Here feature is the image
- The label is the mask
- Images will be stored in "X_train" array
- Masks will be stored in "masks" array

```
import cv2
from tensorflow.keras.applications.mobilenet import preprocess_input

masks = np.zeros((int(data.shape[0]), IMAGE_HEIGHT, IMAGE_WIDTH))
X_train = np.zeros((int(data.shape[0]), IMAGE_HEIGHT, IMAGE_WIDTH, 3))
for index in range(data.shape[0]):
    img = data[index][0]
    img = cv2.resize(img, dsize=(IMAGE_HEIGHT, IMAGE_WIDTH), interpolation=cv2.INTER_CUBIC)
    try:
        img = img[:, :, :3]
    except:
        continue
    X_train[index] = preprocess_input(np.array(img, dtype=np.float32))
    for i in data[index][1]:
        x1 = int(i["points"][0]['x'] * IMAGE_WIDTH)
        x2 = int(i["noints"][1]['x'] * TMAGE_WIDTH)
```

```
y1 = int(i["points"][0]['y'] * IMAGE_HEIGHT)
y2 = int(i["points"][1]['y'] * IMAGE_HEIGHT)
masks[index][y1:y2, x1:x2] = 1
```

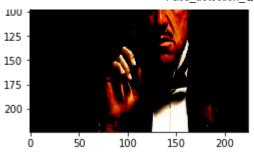
▼ Print the shape of X_train and mask array (1 mark)

Print a sample image and image array

```
from matplotlib import pyplot
n = 10
print(X_train[n])
pyplot.imshow(X_train[n])
```

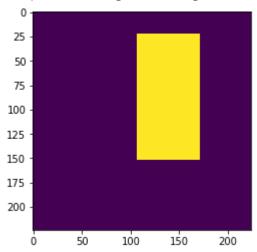
```
Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [6]
[[[-0.98431373 -0.98431373 -0.98431373]
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  [-0.96078432 -0.96078432 -0.96078432]]]
<matplotlib.image.AxesImage at 0x7f69f3cef5f8>
  0
  25
  50
```

75



pyplot.imshow(masks[n])

← <matplotlib.image.AxesImage at 0x7f69fcf48f60>



Create the model (10 marks)

- Add MobileNet as model with below parameter values
 - input_shape: IMAGE_HEIGHT, IMAGE_WIDTH, 3
 - include_top: False
 - o alpha: 1.0
 - weights: "imagenet"
- Add UNET architecture layers
 - This is the trickiest part of the project, you need to research and implement it correctly

```
from tensorflow.keras.applications.mobilenet import MobileNet
from tensorflow.keras.layers import Concatenate, UpSampling2D, Conv2D, Reshape
from tensorflow.keras.models import Model
```

ALPHA = 1.0 # Width hyper parameter for MobileNet (0.25, 0.5, 0.75, 1.0). Higher width means

def create_model(trainable=True):
 model = model = MobileNet(input_shape=(IMAGE_WIDTH, IMAGE_HEIGHT, 3), include_top=False,
 for layer in model.layers:
 layer.trainable = trainable

```
# Add all the UNET layers here

block1 = model.get_layer("conv_pw_1_relu").output
block2 = model.get_layer("conv_pw_3_relu").output
block3 = model.get_layer("conv_pw_5_relu").output
block4 = model.get_layer("conv_pw_11_relu").output
block5 = model.get_layer("conv_pw_13_relu").output

x = Concatenate()([UpSampling2D()(block5), block4])
x = Concatenate()([UpSampling2D()(x), block3])
x = Concatenate()([UpSampling2D()(x), block2])
x = Concatenate()([UpSampling2D()(x), block1])
x = UpSampling2D()(x)

x = Conv2D(1, kernel_size=1, activation="sigmoid")(x)
x = Reshape((IMAGE_WIDTH, IMAGE_HEIGHT))(x)

return Model(inputs=model.input, outputs=x) #### Add your code here ####
```

▼ Call the create_model function

```
# Give trainable=False as argument, if you want to freeze lower layers for fast training (but model = create_model()

# Print summary model.summary()
```

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow_core/python/or Instructions for updating:

If using Keras pass *_constraint arguments to layers.

Model: "model"

Layer (type)	Output Shape	Param #	Connected to
input_1 (InputLayer)	[(None, 224, 224,	3) 0	
conv1_pad (ZeroPadding2D)	(None, 225, 225, 3	0	input_1[0][0]
conv1 (Conv2D)	(None, 112, 112, 32	2) 864	conv1_pad[0][0]
conv1_bn (BatchNormalization)	(None, 112, 112, 32	2) 128	conv1[0][0]
conv1_relu (ReLU)	(None, 112, 112, 3	2) 0	conv1_bn[0][0]
conv_dw_1 (DepthwiseConv2D)	(None, 112, 112, 3	2) 288	conv1_relu[0][0]
conv_dw_1_bn (BatchNormalizatio	(None, 112, 112, 3	2) 128	conv_dw_1[0][0]
conv_dw_1_relu (ReLU)	(None, 112, 112, 3	2) 0	conv_dw_1_bn[0][0]
conv_pw_1 (Conv2D)	(None, 112, 112, 64	1) 2048	conv_dw_1_relu[0][0]
conv_pw_1_bn (BatchNormalizatio	(None, 112, 112, 64	1) 256	conv_pw_1[0][0]
conv_pw_1_relu (ReLU)	(None, 112, 112, 64	1) 0	conv_pw_1_bn[0][0]
conv_pad_2 (ZeroPadding2D)	(None, 113, 113, 64	1) 0	conv_pw_1_relu[0][0]
conv_dw_2 (DepthwiseConv2D)	(None, 56, 56, 64)	576	conv_pad_2[0][0]
conv_dw_2_bn (BatchNormalizatio	(None, 56, 56, 64)	256	conv_dw_2[0][0]
conv_dw_2_relu (ReLU)	(None, 56, 56, 64)	0	conv_dw_2_bn[0][0]
conv_pw_2 (Conv2D)	(None, 56, 56, 128	8192	conv_dw_2_relu[0][0]
conv_pw_2_bn (BatchNormalizatio	(None, 56, 56, 128	512	conv_pw_2[0][0]
conv_pw_2_relu (ReLU)	(None, 56, 56, 128	0	conv_pw_2_bn[0][0]
conv_dw_3 (DepthwiseConv2D)	(None, 56, 56, 128	1152	conv_pw_2_relu[0][0]
conv_dw_3_bn (BatchNormalizatio	(None, 56, 56, 128	512	conv_dw_3[0][0]
conv_dw_3_relu (ReLU)	(None, 56, 56, 128	0	conv_dw_3_bn[0][0]
conv_pw_3 (Conv2D)	(None, 56, 56, 128	16384	conv_dw_3_relu[0][0]
conv_pw_3_bn (BatchNormalizatio	(None, 56, 56, 128	512	conv_pw_3[0][0]
conv_pw_3_relu (ReLU)	(None, 56, 56, 128	0	conv_pw_3_bn[0][0]

Face_detection	_Questions	s_Proje	ect_CV	_AIML_C	Inline.ipynb - Colab	oratory
<pre>conv_pad_4 (ZeroPadding2D)</pre>	(None,	57,	57,	128)	0	conv_pw_3_relu[0][0]
conv_dw_4 (DepthwiseConv2D)	(None,	28,	28,	128)	1152	conv_pad_4[0][0]
conv_dw_4_bn (BatchNormalizatio	(None,	28,	28,	128)	512	conv_dw_4[0][0]
conv_dw_4_relu (ReLU)	(None,	28,	28,	128)	0	conv_dw_4_bn[0][0]
conv_pw_4 (Conv2D)	(None,	28,	28,	256)	32768	conv_dw_4_relu[0][0]
conv_pw_4_bn (BatchNormalizatio	(None,	28,	28,	256)	1024	conv_pw_4[0][0]
conv_pw_4_relu (ReLU)	(None,	28,	28,	256)	0	conv_pw_4_bn[0][0]
conv_dw_5 (DepthwiseConv2D)	(None,	28,	28,	256)	2304	conv_pw_4_relu[0][0]
conv_dw_5_bn (BatchNormalizatio	(None,	28,	28,	256)	1024	conv_dw_5[0][0]
conv_dw_5_relu (ReLU)	(None,	28,	28,	256)	0	conv_dw_5_bn[0][0]
conv_pw_5 (Conv2D)	(None,	28,	28,	256)	65536	conv_dw_5_relu[0][0]
conv_pw_5_bn (BatchNormalizatio	(None,	28,	28,	256)	1024	conv_pw_5[0][0]
conv_pw_5_relu (ReLU)	(None,	28,	28,	256)	0	conv_pw_5_bn[0][0]
conv_pad_6 (ZeroPadding2D)	(None,	29,	29,	256)	0	conv_pw_5_relu[0][0]
conv_dw_6 (DepthwiseConv2D)	(None,	14,	14,	256)	2304	conv_pad_6[0][0]
conv_dw_6_bn (BatchNormalizatio	(None,	14,	14,	256)	1024	conv_dw_6[0][0]
conv_dw_6_relu (ReLU)	(None,	14,	14,	256)	0	conv_dw_6_bn[0][0]
conv_pw_6 (Conv2D)	(None,	14,	14,	512)	131072	conv_dw_6_relu[0][0]
conv_pw_6_bn (BatchNormalizatio	(None,	14,	14,	512)	2048	conv_pw_6[0][0]
conv_pw_6_relu (ReLU)	(None,	14,	14,	512)	0	conv_pw_6_bn[0][0]
conv_dw_7 (DepthwiseConv2D)	(None,	14,	14,	512)	4608	conv_pw_6_relu[0][0]
conv_dw_7_bn (BatchNormalizatio	(None,	14,	14,	512)	2048	conv_dw_7[0][0]
conv_dw_7_relu (ReLU)	(None,	14,	14,	512)	0	conv_dw_7_bn[0][0]
conv_pw_7 (Conv2D)	(None,	14,	14,	512)	262144	conv_dw_7_relu[0][0]
conv_pw_7_bn (BatchNormalizatio	(None,	14,	14,	512)	2048	conv_pw_7[0][0]
conv_pw_7_relu (ReLU)	(None,	14,	14,	512)	0	conv_pw_7_bn[0][0]
conv_dw_8 (DepthwiseConv2D)	(None,	14,	14,	512)	4608	conv_pw_7_relu[0][0]
conv_dw_8_bn (BatchNormalizatio	(None,	14,	14,	512)	2048	conv_dw_8[0][0]
conv_dw_8_relu (ReLU)	(None,	14,	14,	512)	0	conv_dw_8_bn[0][0]

Face_detection	_Questions_F	-roject_cv_AliviL_	Online.ipyrib - Colab	oratory
conv_pw_8 (Conv2D)	(None, 1	.4, 14, 512)	262144	conv_dw_8_relu[0][0]
conv_pw_8_bn (BatchNormalizatio	(None, 1	.4, 14, 512)	2048	conv_pw_8[0][0]
conv_pw_8_relu (ReLU)	(None, 1	.4, 14, 512)	0	conv_pw_8_bn[0][0]
conv_dw_9 (DepthwiseConv2D)	(None, 1	.4, 14, 512)	4608	conv_pw_8_relu[0][0]
conv_dw_9_bn (BatchNormalizatio	(None, 1	.4, 14, 512)	2048	conv_dw_9[0][0]
conv_dw_9_relu (ReLU)	(None, 1	.4, 14, 512)	0	conv_dw_9_bn[0][0]
conv_pw_9 (Conv2D)	(None, 1	.4, 14, 512)	262144	conv_dw_9_relu[0][0]
conv_pw_9_bn (BatchNormalizatio	(None, 1	.4, 14, 512)	2048	conv_pw_9[0][0]
conv_pw_9_relu (ReLU)	(None, 1	.4, 14, 512)	0	conv_pw_9_bn[0][0]
conv_dw_10 (DepthwiseConv2D)	(None, 1	.4, 14, 512)	4608	conv_pw_9_relu[0][0]
conv_dw_10_bn (BatchNormalizati	(None, 1	.4, 14, 512)	2048	conv_dw_10[0][0]
conv_dw_10_relu (ReLU)	(None, 1	.4, 14, 512)	0	conv_dw_10_bn[0][0]
conv_pw_10 (Conv2D)	(None, 1	.4, 14, 512)	262144	conv_dw_10_relu[0][0]
conv_pw_10_bn (BatchNormalizati	(None, 1	.4, 14, 512)	2048	conv_pw_10[0][0]
conv_pw_10_relu (ReLU)	(None, 1	.4, 14, 512)	0	conv_pw_10_bn[0][0]
conv_dw_11 (DepthwiseConv2D)	(None, 1	.4, 14, 512)	4608	conv_pw_10_relu[0][0]
conv_dw_11_bn (BatchNormalizati	(None, 1	.4, 14, 512)	2048	conv_dw_11[0][0]
conv_dw_11_relu (ReLU)	(None, 1	.4, 14, 512)	0	conv_dw_11_bn[0][0]
conv_pw_11 (Conv2D)	(None, 1	.4, 14, 512)	262144	conv_dw_11_relu[0][0]
conv_pw_11_bn (BatchNormalizati	(None, 1	.4, 14, 512)	2048	conv_pw_11[0][0]
conv_pw_11_relu (ReLU)	(None, 1	.4, 14, 512)	0	conv_pw_11_bn[0][0]
conv_pad_12 (ZeroPadding2D)	(None, 1	.5, 15, 512)	0	conv_pw_11_relu[0][0]
conv_dw_12 (DepthwiseConv2D)	(None, 7	7, 7, 512)	4608	conv_pad_12[0][0]
conv_dw_12_bn (BatchNormalizati	(None, 7	7, 7, 512)	2048	conv_dw_12[0][0]
conv_dw_12_relu (ReLU)	(None, 7	7, 7, 512)	0	conv_dw_12_bn[0][0]
conv_pw_12 (Conv2D)	(None, 7	7, 7, 1024)	524288	conv_dw_12_relu[0][0]
conv_pw_12_bn (BatchNormalizati	(None, 7	7, 7, 1024)	4096	conv_pw_12[0][0]
conv_pw_12_relu (ReLU)	(None, 7	7, 7, 1024)	0	conv_pw_12_bn[0][0]
conv_dw_13 (DepthwiseConv2D)	(None, 7	7, 7, 1024)	9216	conv_pw_12_relu[0][0]

conv_dw_13_bn (BatchNormalizati	(None,	7, 7, 1024)	4096	conv_dw_13[0][0]
conv_dw_13_relu (ReLU)	(None,	7, 7, 1024)	0	conv_dw_13_bn[0][0]
conv_pw_13 (Conv2D)	(None,	7, 7, 1024)	1048576	conv_dw_13_relu[0][0]
conv_pw_13_bn (BatchNormalizati	(None,	7, 7, 1024)	4096	conv_pw_13[0][0]
conv_pw_13_relu (ReLU)	(None,	7, 7, 1024)	0	conv_pw_13_bn[0][0]
up_sampling2d (UpSampling2D)	(None,	14, 14, 1024)	0	conv_pw_13_relu[0][0]
concatenate (Concatenate)	(None,	14, 14, 1536)	0	up_sampling2d[0][0] conv_pw_11_relu[0][0]
up_sampling2d_1 (UpSampling2D)	(None,	28, 28, 1536)	0	concatenate[0][0]
concatenate_1 (Concatenate)	(None,	28, 28, 1792)	0	up_sampling2d_1[0][0] conv_pw_5_relu[0][0]
up_sampling2d_2 (UpSampling2D)	(None,	56, 56, 1792)	0	concatenate_1[0][0]
concatenate_2 (Concatenate)	(None,	56, 56, 1920)	0	up_sampling2d_2[0][0] conv_pw_3_relu[0][0]
up_sampling2d_3 (UpSampling2D)	(None,	112, 112, 192	0	concatenate_2[0][0]
concatenate_3 (Concatenate)	(None,	112, 112, 198	0	up_sampling2d_3[0][0] conv_pw_1_relu[0][0]
up_sampling2d_4 (UpSampling2D)	(None,	224, 224, 198	0	concatenate_3[0][0]
conv2d (Conv2D)	(None,	224, 224, 1)	1985	up_sampling2d_4[0][0]
reshape (Reshape)	(None,	224, 224)	0	conv2d[0][0]
=======================================	======	=========	-========	

Total params: 3,230,849 Trainable params: 3,208,961 Non-trainable params: 21,888

Define dice coefficient function (5 marks)

· Create a function to calculate dice coefficient

▼ Dice Coefficient (F1 Score) Explanation

The Dice Coefficient is 2 * the Area of Overlap divided by the total number of pixels in both images

```
def dice_coefficient(y_true, y_pred):
    #### Add your code here ####
    numerator = 2 * tf.reduce_sum(y_true * y_pred)
    denominator = tf.reduce_sum(y_true + y_pred)
```

```
return numerator / (denominator + tf.keras.backend.epsilon())
```

Define loss

```
from tensorflow.keras.losses import binary_crossentropy
from tensorflow.keras.backend import log, epsilon
def loss(y_true, y_pred):
    return binary_crossentropy(y_true, y_pred) - log(dice_coefficient(y_true, y_pred) + epsil
```

Compile the model (2 marks)

- Complie the model using below parameters
 - loss: use the loss function defined above
 - o optimizers: use Adam optimizer
 - metrics: use dice_coefficient function defined above

```
#### Add your code here ####
from tensorflow.keras.optimizers import Adam
optimizer = Adam(lr=1e-4, beta_1=0.9, beta_2=0.999, epsilon=None, decay=0.0, amsgrad=False)
model.compile(loss=loss, optimizer=optimizer, metrics=[dice_coefficient])
```

Define checkpoint and earlystopping

▼ Fit the model (2 marks)

- · Fit the model using below parameters
 - o epochs: you can decide
 - batch_size: 1
 - o callbacks: checkpoint, reduce_lr, stop

```
#### Add your code here ####
EPOCHS = 10
BATCH SIZE =1
```

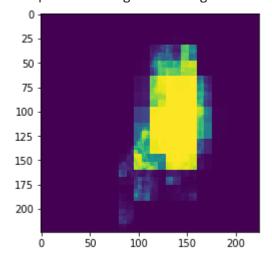
```
WARNING:tensorflow:The `nb epoch` argument in `fit` has been renamed `epochs`.
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow core/python/or
Instructions for updating:
Use tf.where in 2.0, which has the same broadcast rule as np.where
Train on 409 samples
Epoch 1/10
Epoch 00001: loss improved from inf to 1.32828, saving model to model-1.33.h5
Epoch 2/10
Epoch 00002: loss improved from 1.32828 to 0.78870, saving model to model-0.79.h5
409/409 [=================== ] - 16s 40ms/sample - loss: 0.7887 - dice_coeffic
Epoch 3/10
Epoch 00003: loss improved from 0.78870 to 0.62350, saving model to model-0.62.h5
Epoch 4/10
Epoch 00004: loss improved from 0.62350 to 0.55947, saving model to model-0.56.h5
Epoch 00005: loss improved from 0.55947 to 0.51682, saving model to model-0.52.h5
Epoch 6/10
Epoch 00006: loss improved from 0.51682 to 0.48293, saving model to model-0.48.h5
409/409 [========================== ] - 17s 42ms/sample - loss: 0.4829 - dice coeffic
Epoch 7/10
Epoch 00007: loss improved from 0.48293 to 0.46742, saving model to model-0.47.h5
409/409 [================== ] - 16s 40ms/sample - loss: 0.4674 - dice coeffic
Epoch 8/10
Epoch 00008: loss improved from 0.46742 to 0.44828, saving model to model-0.45.h5
409/409 [================== ] - 17s 41ms/sample - loss: 0.4483 - dice coeffic
Epoch 9/10
Epoch 00009: loss improved from 0.44828 to 0.43255, saving model to model-0.43.h5
Epoch 10/10
Epoch 00010: loss improved from 0.43255 to 0.42149, saving model to model-0.42.h5
409/409 [================== ] - 16s 40ms/sample - loss: 0.4215 - dice coeffic
<tensorflow.python.keras.callbacks.History at 0x7f69e00464a8>
```

Get the predicted mask for a sample image (3 marks)

▼ Impose the mask on the image (3 marks)

```
#### Add your code here ####
#pyplot.imshow(masks[n])
pyplot.imshow(predicted_mask_reshaped)
```

← <matplotlib.image.AxesImage at 0x7f677d94e2b0>



pyplot.imshow(masks[n])

С→

<matplotlib.image.AxesImage at 0x7f677d926f28>

