DYNAMIC PROGRAMMING

- · Dynamic programming is a technique for solving problems. with overlapping subproblens.
- · Typically, these subproblems alise from a reculrence relating a solution to a given problem with solution to its smaller Subproblems of the same type.
- Dynamic programming suggests solving each smaller subproplem once and recording the results in a table from which a solution. to the original problem can be obtained.
- = Recussion + Common Sense. · Dynamic programming = memoization [remembering results
 of a few states]

Eg: the Fibonacci Series. trace: fib(6) pule reculsion. \$ if (n<2).

retwin 1.

retwin fib(n-1) + fib(n-2).

fib(4) fib(3)

fib(4) fib(3)

fib(4) fib(3)

fib(4) fib(3)

fib(4) fib(4)

fib(5) fib(4)

fib(6)

Fib (i) is colculated multiple times in reculsion method Time complexity: 0 (2n) Lynamic programming Cadding memby to recussion method) void fib(). {
fibresult[0] = 1; fibresult[1] = 1. for (int- i=2; i<n; i++). fibresult[i] = fibresult[i-1] + fibresult[i-2]; Time complexity = 0(n) space complexity = 0(n) · Two major proporties of Dynamic programming. I to decide whether a problem can be solved by applying dynamic programming we have to sheck two. Properties. (a) overlapping Sub-problems (b) Optimal Substructure.

- (a) Overlapping sub-problems.
 - -) suggests that the subproblem needs to be solved again and again.
 - -) In reculsion we solve those problems every time. Eq: fibonacci with pule reculsion method.
 - In dynamic programming we solve these subproblems.

 only once and store it for fullule use.

 Eq: Fibonacci with dynamic programming.

(b) Optimal Substructure.

- -) It- a problem can be solved using the solutions. of- the sub problems then we say that problem has a Optimal Substructure Property.
- · Dynamic Programming Approaches:
 - (a) Boltom-up. approach. [Tabular]
 - -) suppose we need to solve the problem for N, we start solving the problem with the smallest possible inputs and state it for future.
 - _) Now as you calculate for the bigget values use the stored salutions (solution for smaller problems)
 - (b) Top-down approach. [memoization]
 - -> Break the problem into sub-problem and solve them as needed and stole the solution for future:



Problems on DP EDynamic programming) Approach

- 1) 0/1 Knapsack.
- 2) Worshall's Algerithm. [all possible paths]
- 3) Floyd Washall Algorithm [all pairs shortest distances]
- 4) Longest common subsequence.

Examples for all the above have been done. NOTE: in class. Refer class notes.

(1) O/1 KNAPSACK T Algorithm For 0/1 knapsack. ν [i, ω+] = max & ν[i-1, ω+], ν[i-1, ω-ω+[i]] + P[i] II. Time complexity = 0(2n) 2) WARSHALL'S ALGORITHM.

Thoughthm for Worshall's
Input: Adjacency matrix A of a directed graph with n' Output: The transitive closure of the directed graph. $R^{(0)} \leftarrow A$. for k < 1 to n do. For i < 1 to n do fajetton do. RCK)[i,j] + RCK-1)[i,j] & R(K-1)[i,k] and R(K-1)[K,i]) Return R(n). Time complexity Time complexity = O(n3)

(3) FLOYD WARSHALL ALGORITHM 1 Algrithm Input: The weight matrix W of- a graph with. no negative length cycle regule with weights that sum to negative of the shortest path's number length. D ~ W for K < 1 ton do. for i < 1 to n do. for je 1 to n do. D[i,i] < min {D[i,j], D[i,k] + D[k,j]g return D. 11 Time complexity. Time complexity = O(n3) 4 LONGEST COMMON SUBSEQUENCE. T Algorithm ([]B = [iJA) 7i LCS [i, j] = 1+ LCS [i-1, j-1]

else. Les [i,j] = max { Les [i-1,j], Les [i,j-1] } Time complexity = O(mn)
Space complexity = O(mn)

0/1 knapsack problems.

1) wh pt.

2

3 5

Capacity = 10.

3 5

4 9

6 4

2). W- pt

3 (00)

2 20

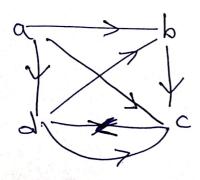
capacity = 5

4 60

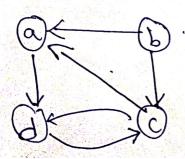
1 40

Washall's Algerithm problems

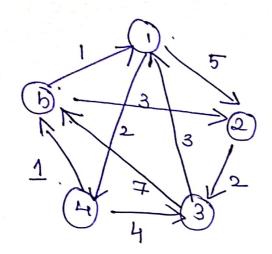


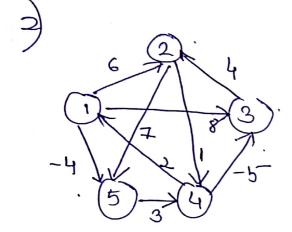






Floyd Washall algorithm Problems





Longest common subsequence Problems

- 1) A stone B - longest
- 3) A lesson B - leagnt.
- 3) A Engineer. B - Edition