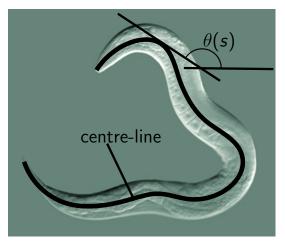
Rejected headsweep

Accepted headsweep

Eigen-worms



s = fractional distance along centre-line.

Parameterise posture as $\theta(s) - \int \theta(s') ds'$

 $PCA \implies 4 \text{ modes}.$

[Stephens et al.]

Eigen-larvae?



Posture not captured by centre-line.

Length is dynamical.

Principal Component Analysis (PCA)

Our data-set consists of vectors (each member from one frame of the videos):

$$x_1, x_2, x_3, \dots$$

Make change of variables (describe each frame by α^n):

$$\mathbf{x}_i = \langle \mathbf{x} \rangle + \sum_n \alpha_i^n \mathbf{u}_n.$$

Choose directions \mathbf{u}_n to be of decreasing importance so we can ignore all but first few α^n .

Principal Component Analysis (cont'd)

- ullet Choose direction $oldsymbol{u}_1$ to account for the maximum variance possible.
- ullet Choose direction $oldsymbol{u}_2$ to account for as much of the remaining variance as possible.
- And so on.

 \implies **u**_n are eigenvectors of the covariance matrix:

$$\mathbf{C} = \langle (\mathbf{x} - \langle \mathbf{x} \rangle) \cdot (\mathbf{x} - \langle \mathbf{x} \rangle)^{\mathrm{T}} \rangle, \qquad \mathbf{C} \cdot \mathbf{u}_n = \sigma_n^2 \mathbf{u}_n.$$

where σ_n^2 are decreasing – variance accounted for by n^{th} direction.

PCA with constraints

Suppose each datum satisfies a linear constraint:

$$\mathbf{b} \cdot \mathbf{x}_i = \beta$$
.

We have

$$\mathbf{b} \cdot \langle \mathbf{x} \rangle = \beta,$$

$$\mathbf{b} \cdot \mathbf{C} = 0 \qquad \Longrightarrow \mathbf{b} \cdot \mathbf{u}_n = 0 \quad \text{if} \quad \sigma_n^2 \neq 0.$$

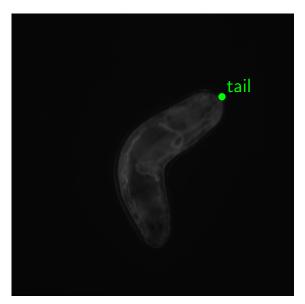
So, if we choose $\alpha^n = 0$ in null directions:

$$\mathbf{b} \cdot \left[\langle \mathbf{x} \rangle + \sum_{n} \alpha^{n} \mathbf{u}_{n} \right] = \beta.$$

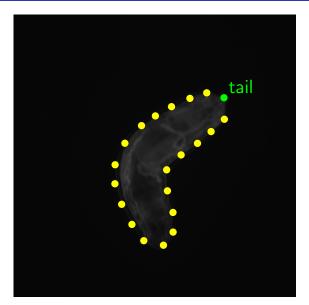
i.e. the constraint is satisfied for any choice of $\{\alpha^n\}$ in non-null directions.



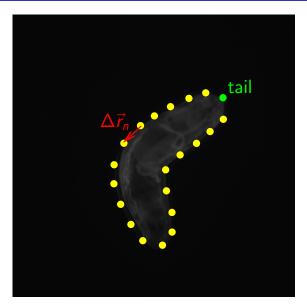
Extract boundary



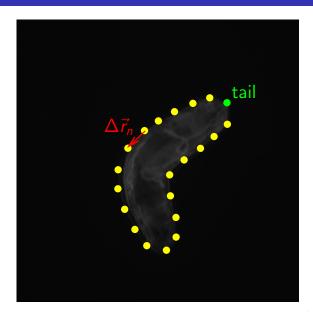
- Extract boundary
- Find tail



- Extract boundary
- Find tail
- Mark N points along boundary



- Extract boundary
- Find tail
- Mark N points along boundary
- Record difference vectors



- Extract boundary
- Find tail
- Mark N points along boundary
- Record difference vectors
- Rotate so that tangent horizontal at tail

Parameterising posture

We record:

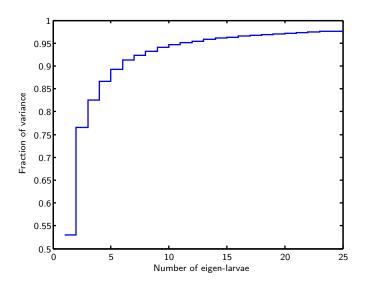
$$\mathbf{x} = (\Delta x_1, \dots, \Delta x_N, \Delta y_1, \dots, \Delta y_N)^{\mathrm{T}}$$

Constraints:

- $\sum_n \Delta x_n = 0$
- $\sum_n \Delta y_n = 0$ (closed curve)
- $\Delta y_1 + \Delta y_N = 0$. (overall rotations)

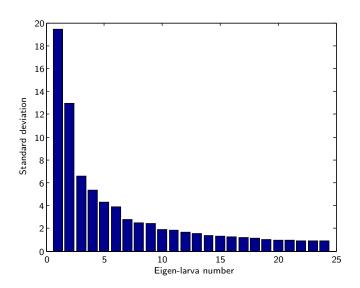
All linear \implies respected by PCA.

Dimensionality reduction

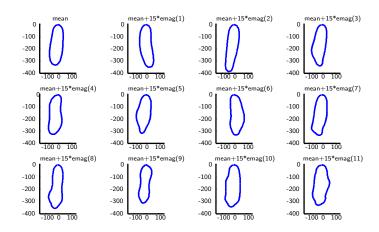


cf. for C.elegans, 95% of variance from 4 eigen-worms.

Dimensionality reduction



Eigen-larvae



Trajectories for accepted headsweeps

