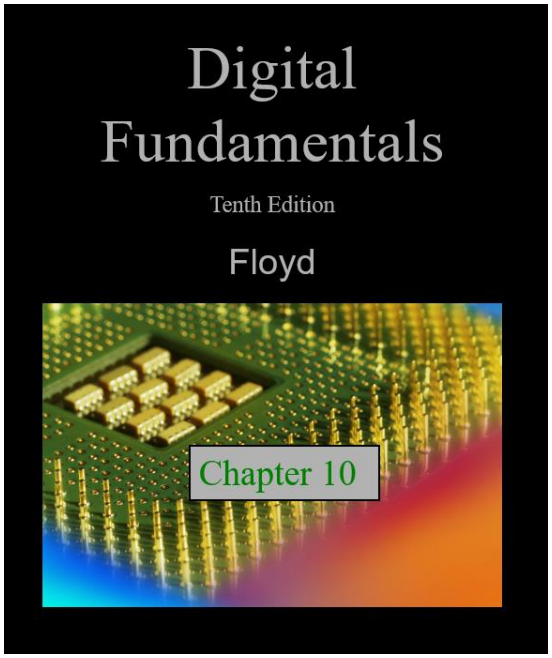
최신디지털공학

Digital Fundamentals

Thomas L. Floyd



Chapter 10

메모리

Memory

Summary

Memory Units

Memories store data in units from one to eight bits. The most common unit is the **byte**, which by definition is 8 bits.

Computer memories are organized into multiples of bytes called words. Generally, a word is defined as the number of bits handled as one entity by a computer. By this definition, a word is equal to the internal register size (usually 16, 32, or 64 bits).

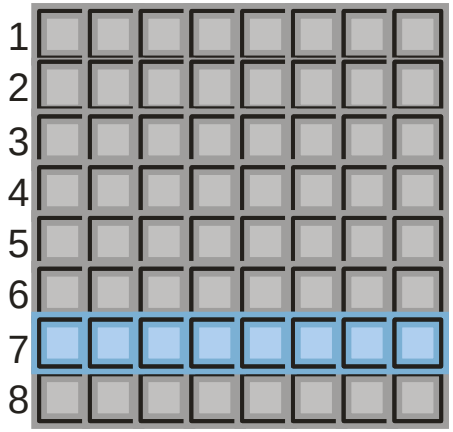
For historical reasons, assembly language defines a word as exactly two bytes. In assembly language, a 32 bit entity is called a double-word and 64 bits is defined as a quad-word.

Summary

Memory Units

The location of a unit of data in a memory is called the **address**. In PCs, a byte is the smallest unit of data that can be accessed.

In a 2-dimensional array, a byte is accessed by supplying a row number. For example the blue byte is located in row 7.

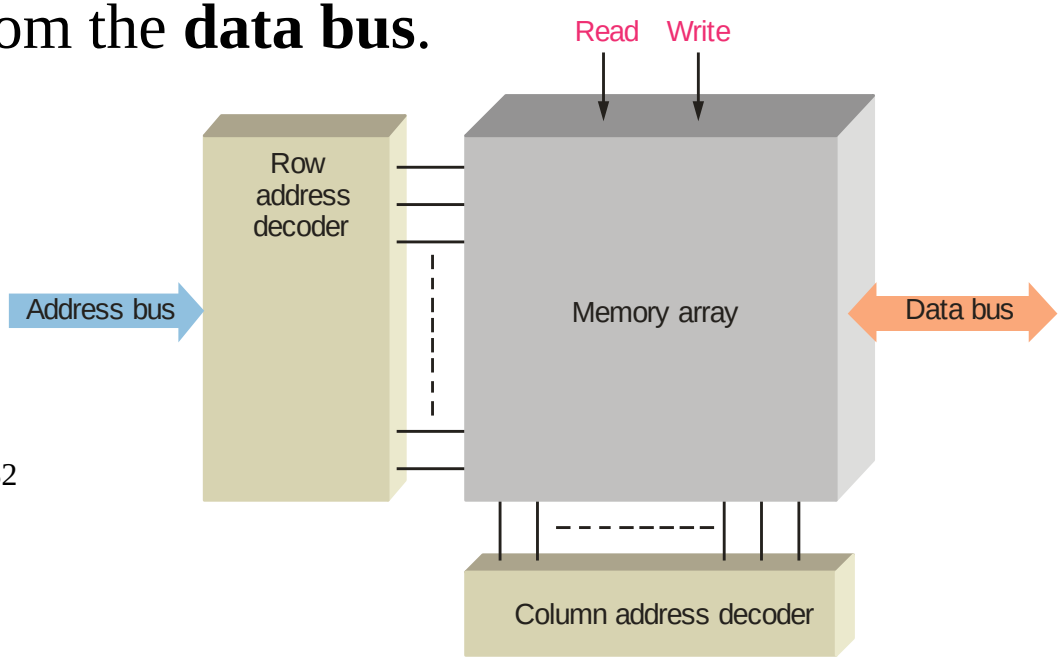


Summary

Memory Addressing

In order to read or write to a specific memory location, a binary code is placed on the **address bus**. Internal decoders decode the address to determine the specific location. Data is then moved to or from the **data bus**.

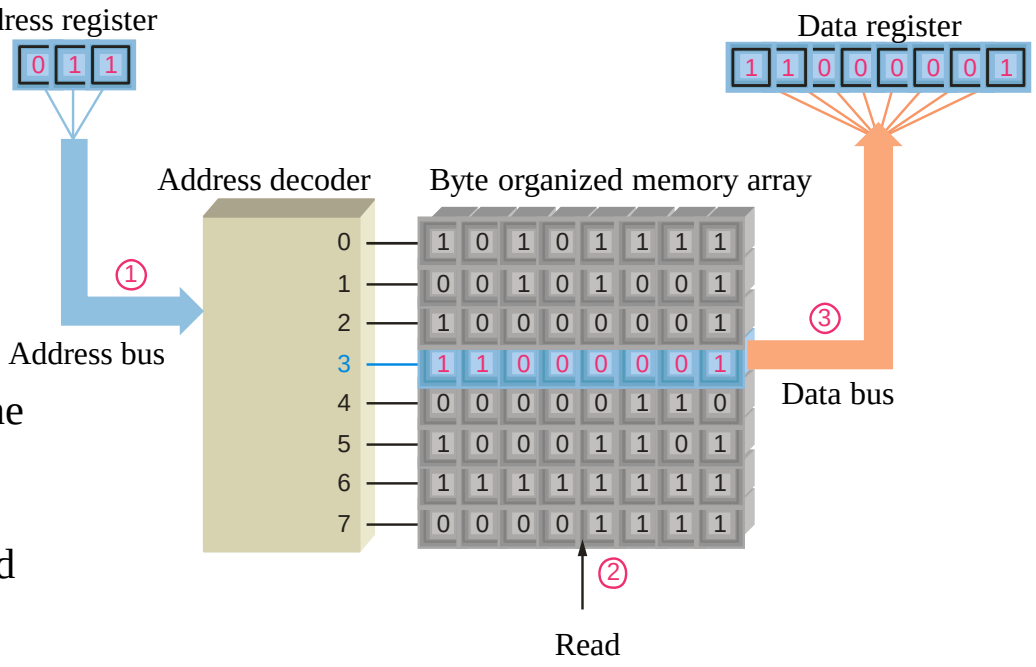
The address bus is a group of conductors with a common function. Its size determines the number of locations that can be accessed. A 32 bit address bus can access 2^{32} locations, which is approximately 4G.



Summary

Read and Write Operations

The read operation is actually a “copy” operation, as the original data is not changed. The data bus is a “two-way” path; data moves *from* the memory during a read operation.

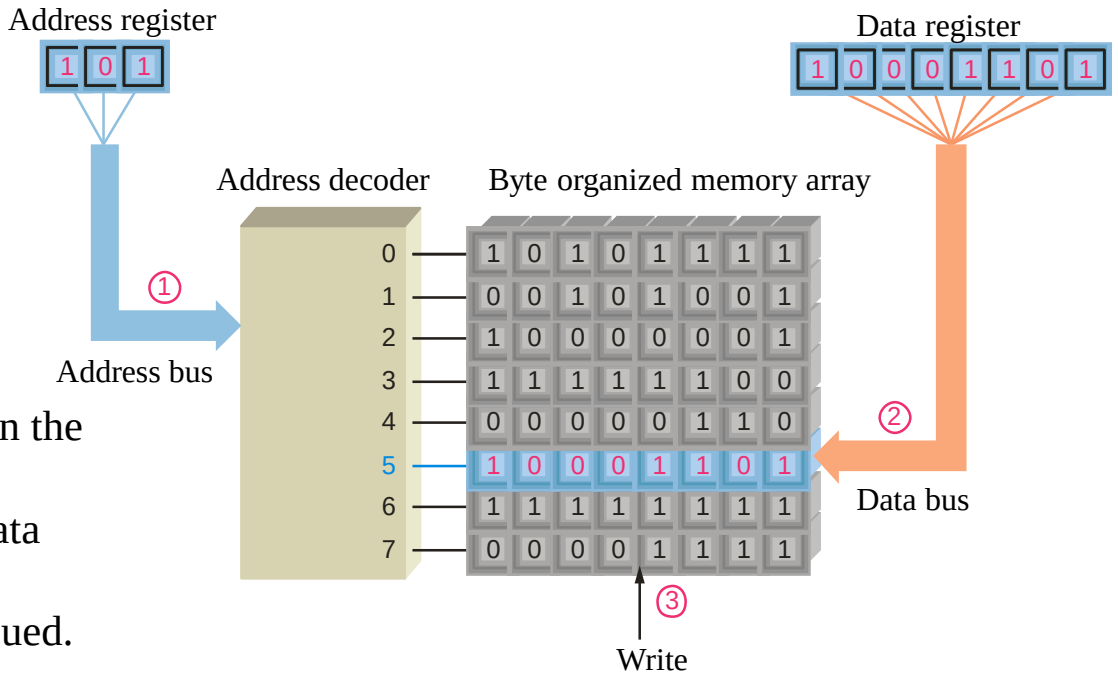


1. The address is placed on the address bus.
2. A read command is issued.
3. A copy of the data is placed in the data bus and shifted into the data register.

Summary

Read and Write Operations

The two main memory operations are called **read** and **write**. A simplified write operation is shown in which new data overwrites the original data. Data moves *to* the memory.

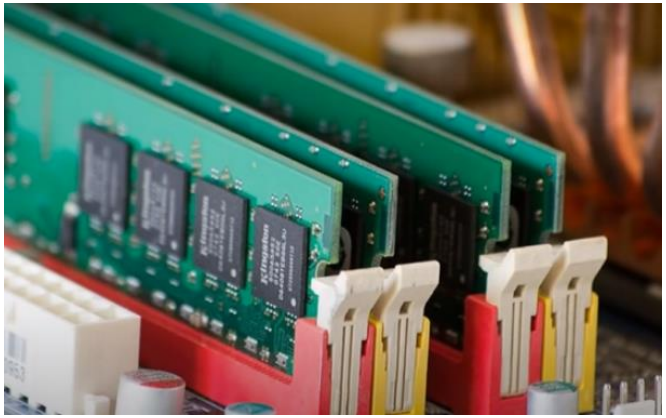


1. The address is placed on the address bus.
2. Data is placed on the data bus.
3. A write command is issued.

Summary

RAM(Random Access Memory)

- Volatile (contents lost when the power is turned off)
- Read and write
- Large in comparison to ROM



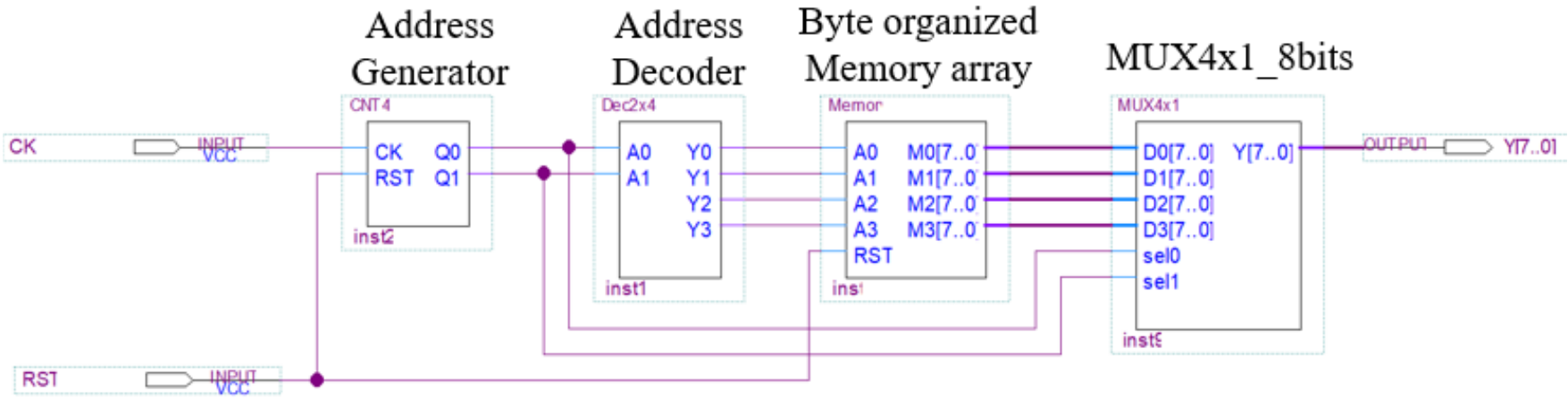
ROM(Read Only Memory)

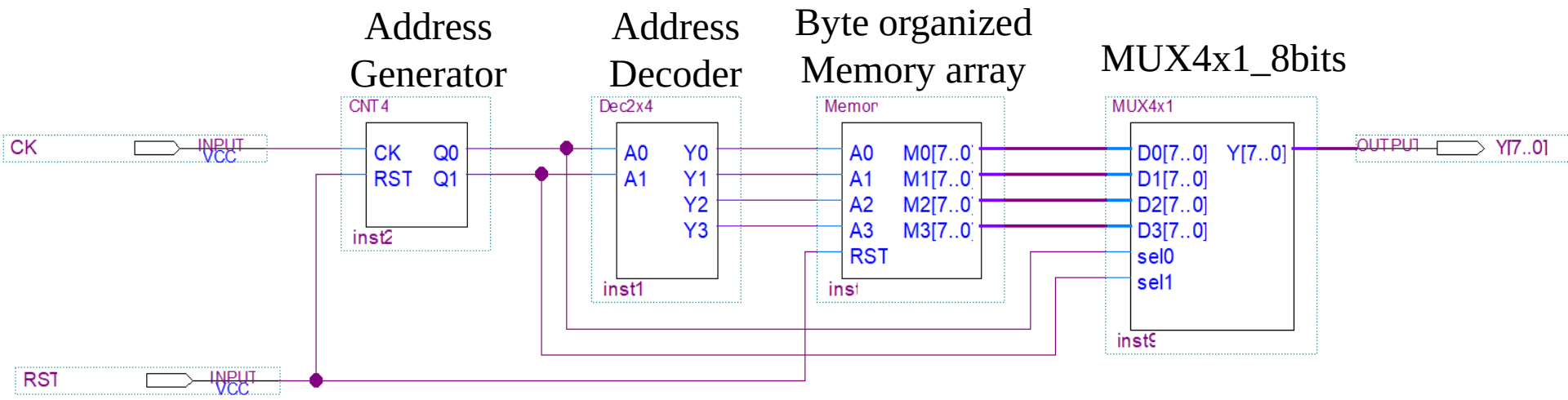
- Non-volatile (contents remains when power is turned off)
- Read only
- Small in comparison to RAM

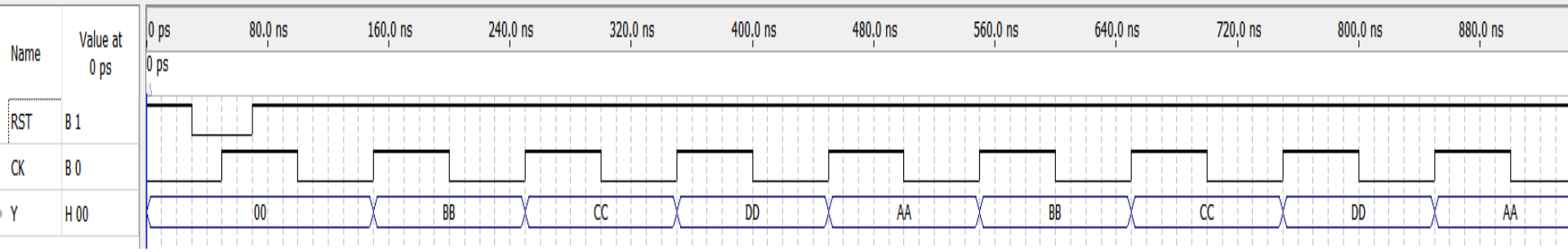
H/W #1

아래의 Memory controller 회로를 설계하고

그 내용을 설명하시오.







Memory 출력 data

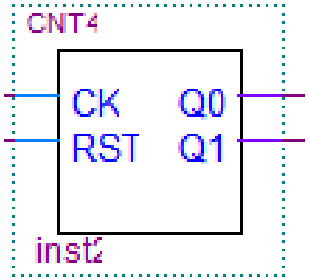
Address 0 : AA

Address 1 : BB

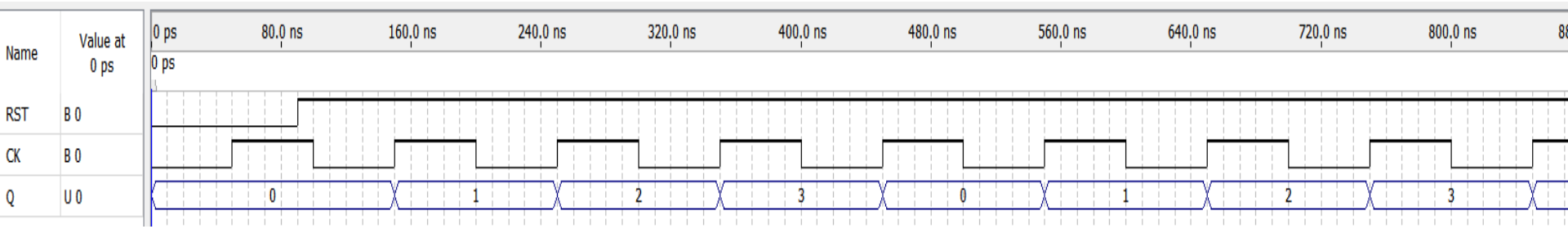
Address 2 : CC

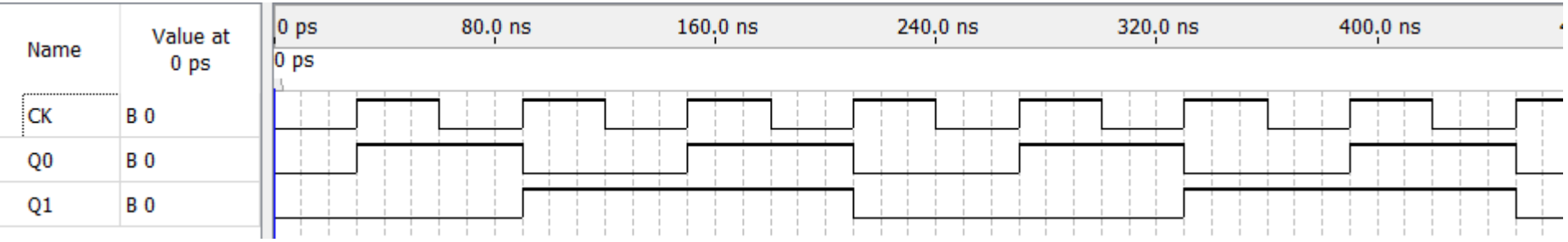
Address 3 : DD

Address Generator

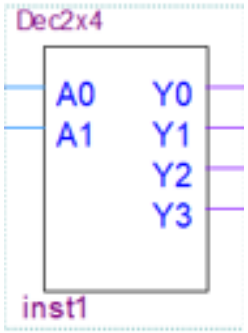


4진 Counter

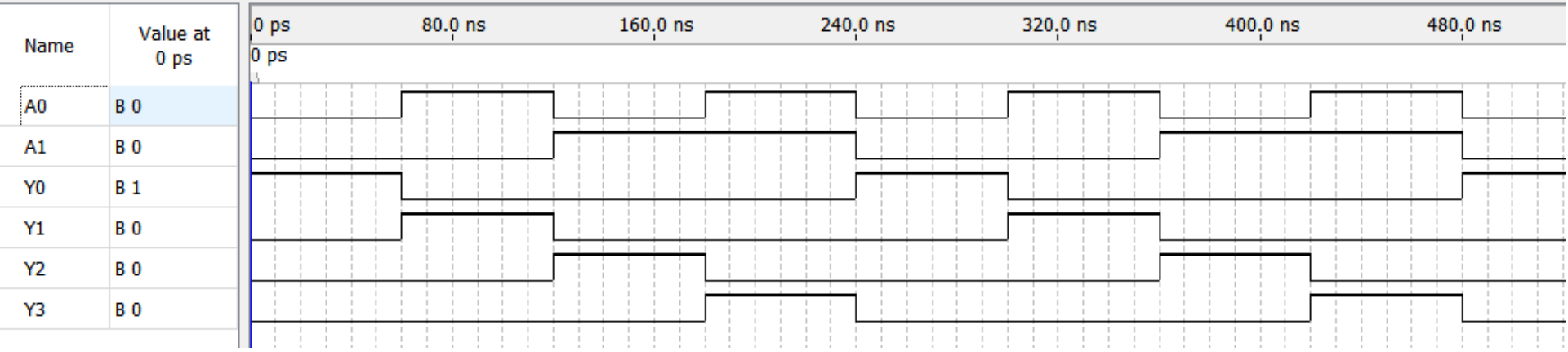




Address Decoder

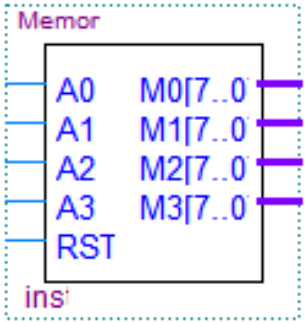


2X4 Decoder



Byte organized Memory array

4-byte Memory array



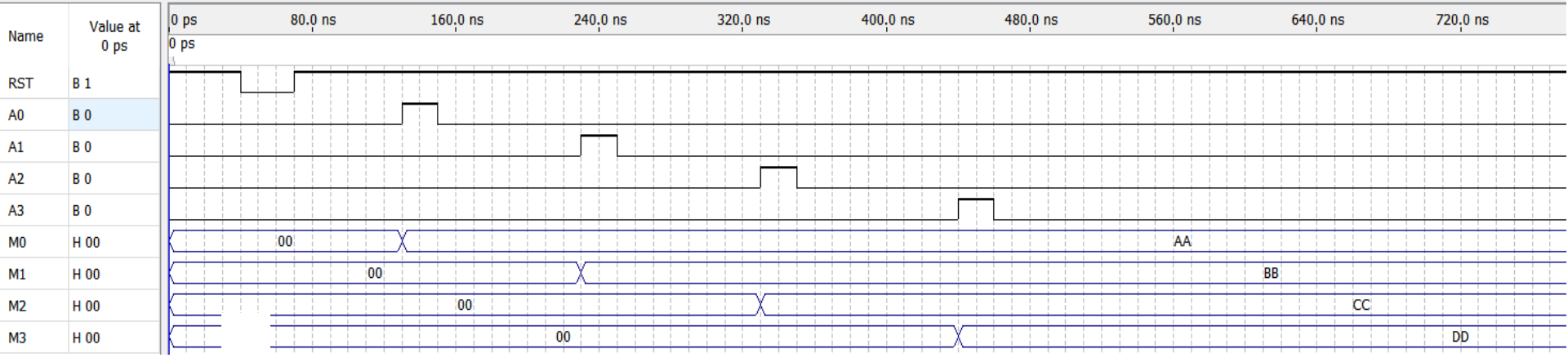
Memory 출력 data

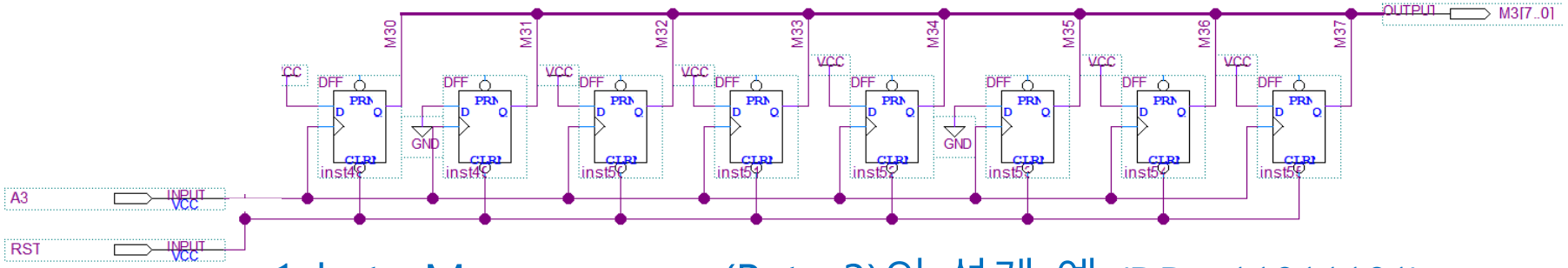
Byte 0 : AA

Byte 1 : BB

Byte 2 : CC

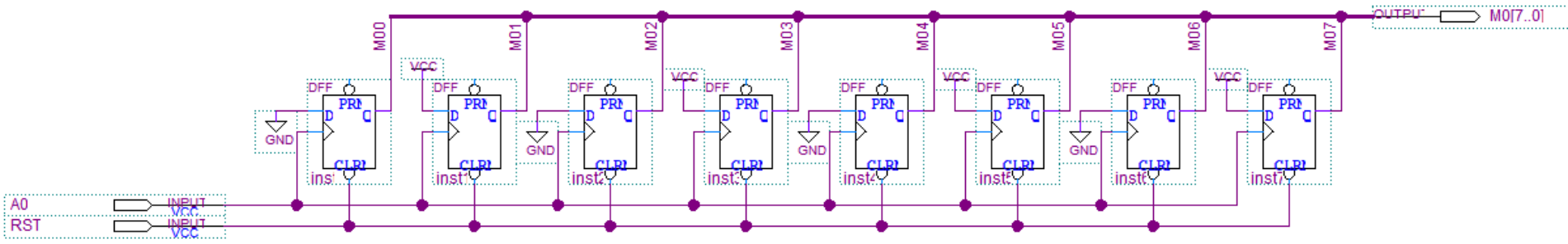
Byre 3 : DD





1-byte Memory array(Byte 3)의 설계 예 (DD : 11011101)

1-byte Memory array의 설계 예 (AA : 10101010)



Q0 Q1 Q2 Q3 Q4 Q5 Q6 Q7

0 1 0 1 0 1 0 1 : AA

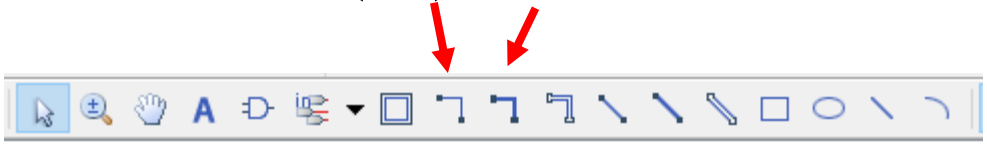
LSB

MSB

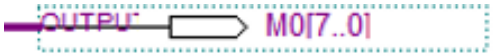
Quartus에서 BUS 사용법

1) 선이 굵은 BUS ICON을 눌러 드래그 하면 굵은 선의 BUS가 그려진다

Wire(bit) BUS

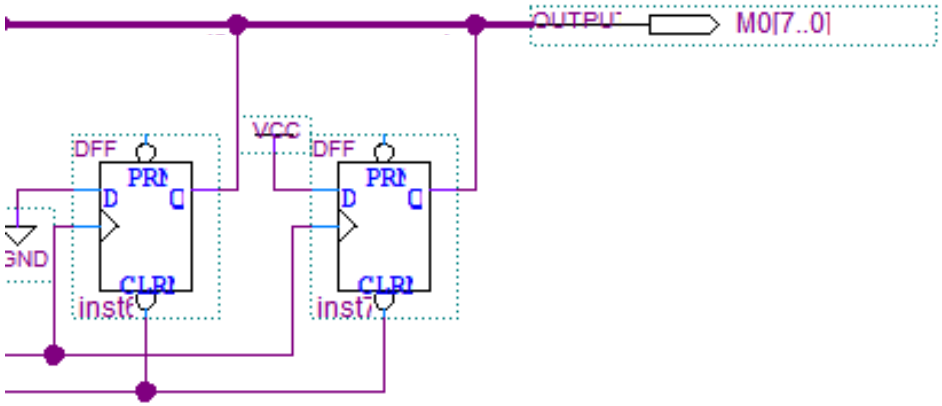


2) Input, Output pad에 BUS의 크기를 적는다. M0[7..0] : 8bit Bus

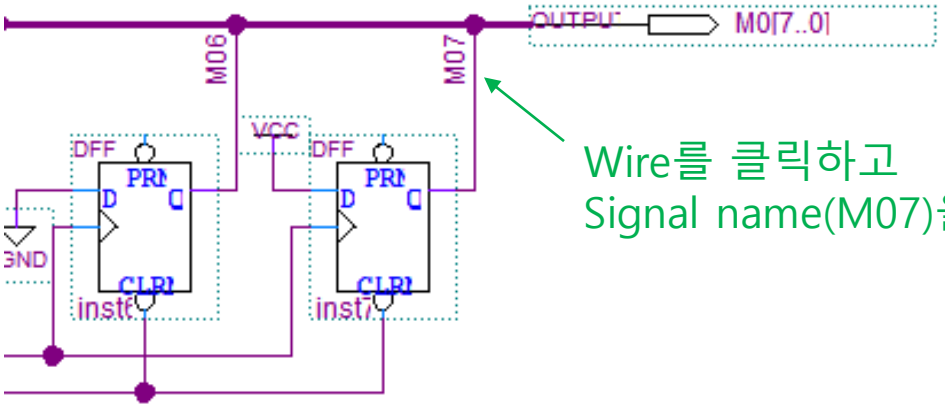


[7..0] 형식에 유의할 것

3) D F/F을 BUS에 wire로 연결한다.

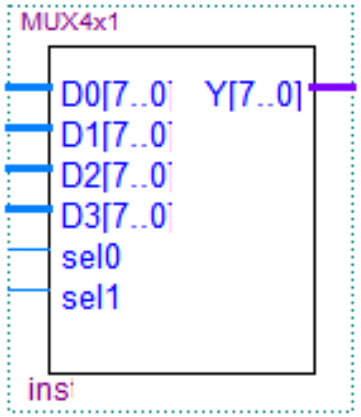


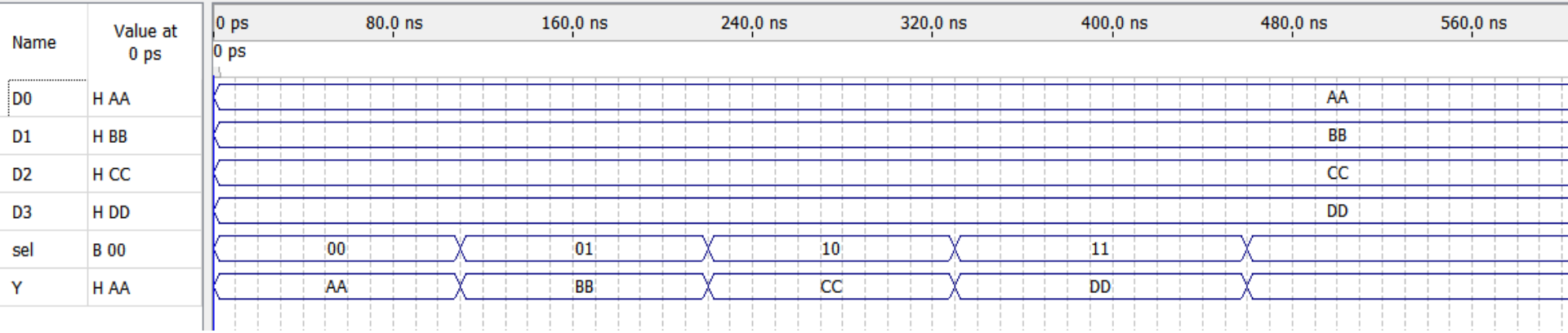
4) BUS에 연결한 각각의 wire에 name을 추가한다.(M00 ~ M07)



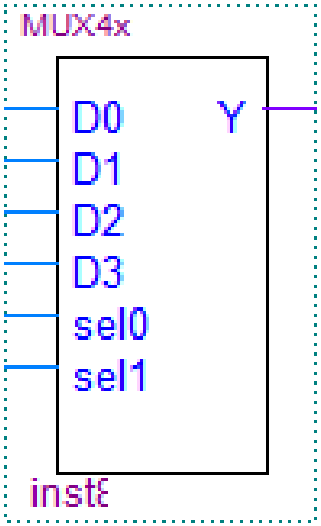
Wire를 클릭하고
Signal name(M07)을 타이핑 한다.

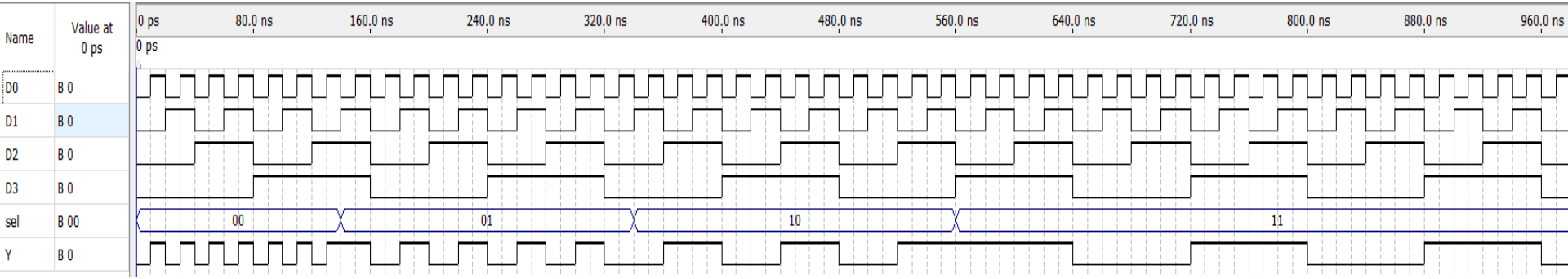
MUX4x1_8bits

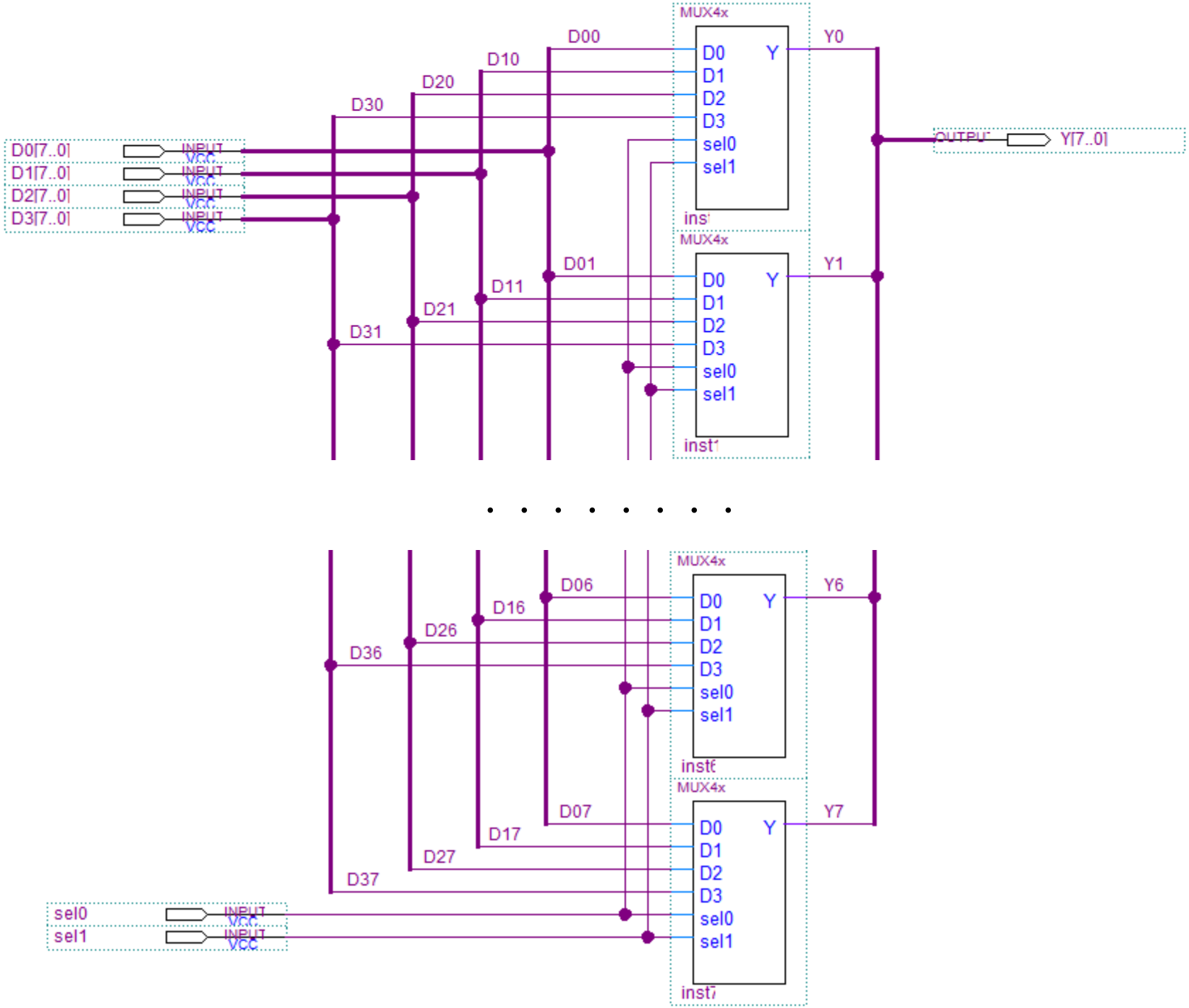




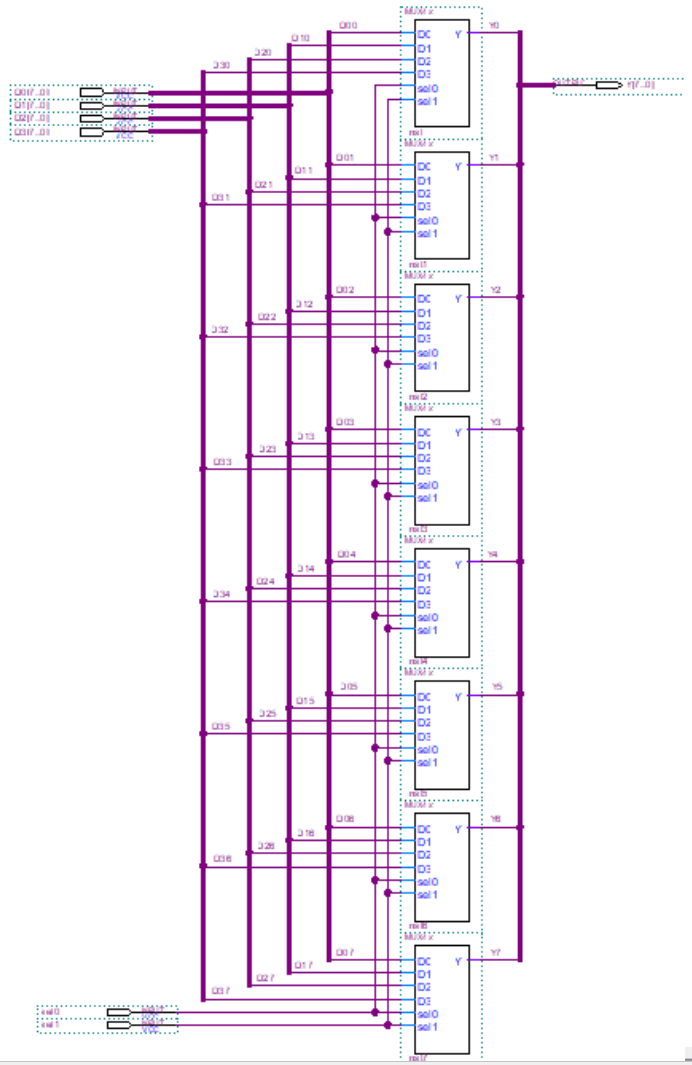
MUX4x1_1bit

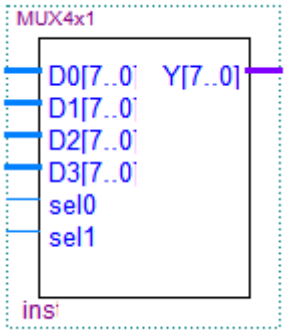

MUX4x
D0
D1
D2
D3
sel0
sel1
Y
inst8

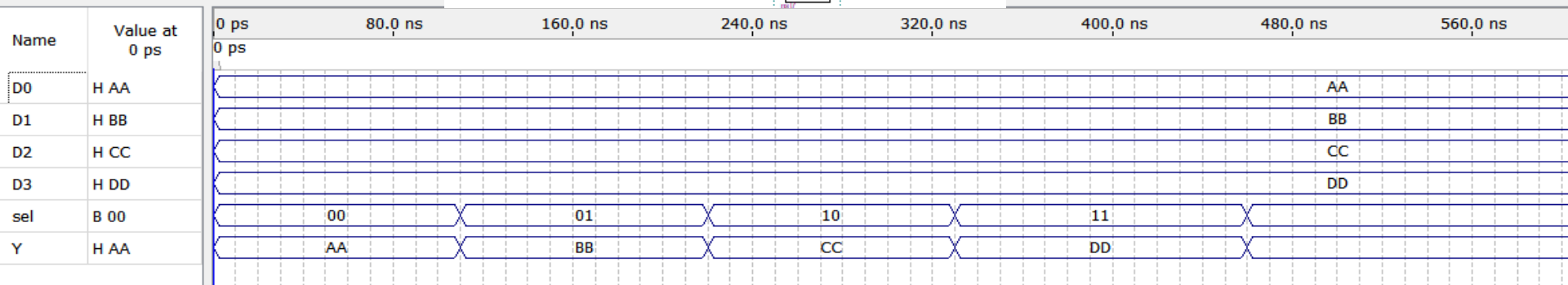

Name
Value at
0 ps
0 ps
80.0 ns
160.0 ns
240.0 ns
320.0 ns
400.0 ns
480.0 ns
560.0 ns
640.0 ns
720.0 ns
800.0 ns
880.0 ns
960.0 ns
D0
B 0
D1
B 0
D2
B 0
D3
B 0
sel
B 00
00
01
10
11
Y
B 0


D0[7..0]
D1[7..0]
D2[7..0]
D3[7..0]
INPUT
VCC
D00
D10
D20
D30
D01
D11
D21
D31
D06
D16
D26
D36
D07
D17
D27
D37
sel0
sel1
MUX4x
D0
D1
D2
D3
sel0
sel1
Y
Y0
Y1
Y6
Y7
OUTPUT
Y[7..0]

MUX4x1_8bits

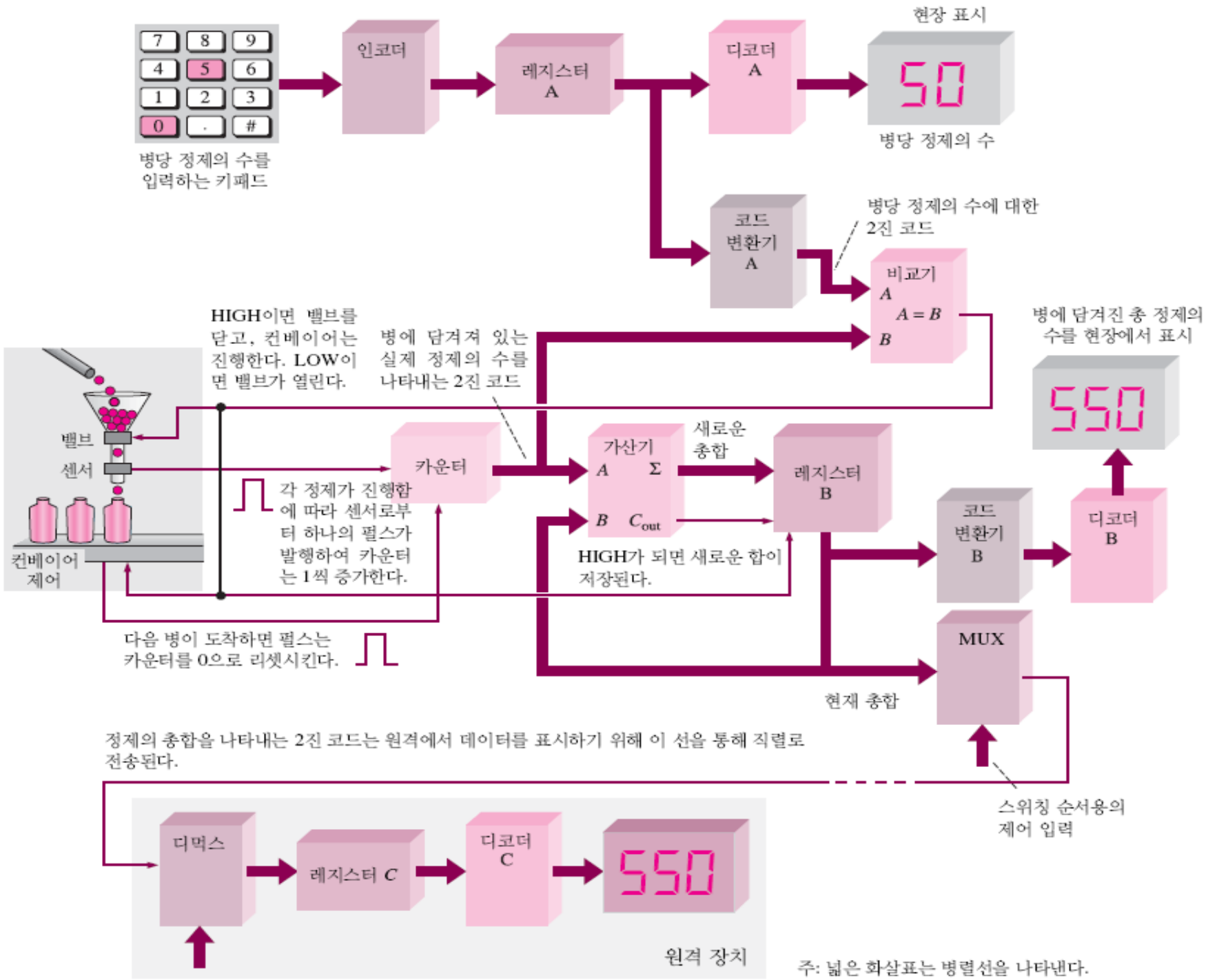







제약회사 직무용어 탐방기

50


7 8 9
4 5 6
1 2 3
0 . #
병당 정제의 수를 입력하는 키패드
인코더
레지스터 A
디코더 A
현장 표시
50
병당 정제의 수
코드 변환기 A
병당 정제의 수에 대한 2진 코드
비교기
A
A = B
B
HIGH이면 밸브를 닫고, 컨베이어는 진행한다. LOW이면 밸브가 열린다.
병에 담겨져 있는 실제 정제의 수를 나타내는 2진 코드
병에 담겨진 총 정제의 수를 현장에서 표시
550
밸브
센서
컨베이어 제어
카운터
각 정제가 진행함에 따라 센서로부터 하나의 펄스가 발행하여 카운터는 1씩 증가한다.
가산기
A Σ
B C_{out}
새로운 총합
레지스터 B
HIGH가 되면 새로운 합이 저장된다.
코드 변환기 B
디코더 B
다음 병이 도착하면 펄스는 카운터를 0으로 리셋시킨다.
MUX
현재 총합
정제의 총합을 나타내는 2진 코드는 원격에서 데이터를 표시하기 위해 이 선을 통해 직렬로 전송된다.
스위칭 순서용의 제어 입력
디먹스
레지스터 C
디코더 C
550
원격 장치
주: 넓은 화살표는 병렬선을 나타낸다.

수고하셨습니다!!!