

Shubham Agrawal

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EDUCATION

COLUMBIA UNIVERSITY

MS COMPUTER SCIENCE

Aug. 19 - Dec 20

UNIVERSITY OF S. CAL.

MS COMPUTER SCIENCE

(TRANSFERRED OUT)

Jan. 19 - Apr. 19

CGPA: 3.65

IIT KANPUR

B.TECH COMPUTER SCIENCE

Jul. 13 - May 17

CGPA: 8.7/10

EXPERIENCE

ADOBE | C++, JS

SOFTWARE DEVELOPER

Jul. 17 - Dec. 18

RESL, USC | ROBOTICS

RESEARCH INTERN

May 19 - Jul. 19

ADOBE | RESEARCH

INTERN

May 17 - Jul 17

COURSEWORK

Recent Advances in Vision
Bayesian Machine Learning
Artificial Intelligence
Machine Learning Tools
Optimizations Techniques
Natural Language Processing

MISCELLANEOUS

SENATOR | VITERBI

GRADUATE STUDENT

ASSOCIATION, USC

Jan. 19 - Apr. 19

ACADEMIC MENTOR |

COUNSELLING SERVICE, IIT

KANPUR

Jul. 14 - Apr. 15

CHASSIS HEAD | IITK

MOTORSPORTS, BAJA

STUDENT INDIA

Oct. 13 - Jan. 15

AWARDS

2013 All India Rank 191

2013 All India Rank 1234

2014 Academic Excellence Award

2015 BEST ROOKIE TEAM

IIT-JEE ADVANCED among 150K candidates

JEE-MAINS among 14M candidates

DOAA, IIT Kanpur

BAJA STUDENT INDIA

PUBLICATIONS

ACM SIGSPATIAL 2017

Patent #15434886

Smart Geo-fencing with Location Sensitive Product Affinity

Smart Geo-fencing with Location Sensitive Product Affinity

PROJECTS

SMART GEO-FENCING | RESEARCH PROJECT - MACHINE LEARNING

May 16 - Jul. 16 | Big Data Experience Lab, Adobe Inc.

Algorithmically designed personalized geo-fences for selective customer targeting. To unsheathe user interest from sparse location tagged browsing data, algorithm captures intrinsic interest of user, trends at semantically similar locations and similarity between products and users. Achieved precision was 5 times higher than the existing geo-fence.

DENSE CAPTIONING | RESEARCH PROJECT - COMPUTER VISION

Aug. 16 - Nov. 16 | IIT Kanpur

Analyzed the work "DenseCap" by Andrej Karpathy et. al. by experimenting with the parameters and design choices. Enhanced the mAP from 5.698 to 5.76.

DIFFERENTIABLE PHYSICS ENGINE | RESEARCH PROJECT - ROBOTICS

May 19 - ongoing | Robotics Embedded Research Laboratory, USC

Automatic task-based robot design and parameter estimation for nonlinear dynamical systems by automatically calculating gradients in Interactive Differentiable Simulation. Implemented efficient Adjoint Method for getting differentials of integrated ODEs.

VEHICLE CLASSIFICATION | COURSE PROJECT - COMPUTER VISION

Jan. 16 - Aug. 16 | IIT Kanpur

Experimented with object proposal methods (Morphological, Selective Search) and feature extractors (SURF, ConvNets) for detection and classification. Used decision tree, random forest and SVM (OVR and OVO) classifiers to predict labels.

PORN BLOCK | OPEN SOURCE PROJECT - COMPUTER VISION

Jan. 18 - Aug. 18

Chrome extension for identification and blurring of sensual contents from webpages. Implemented and Trained CNN for classification using KerasJS and scrapped data. Wrote a proxy server for bypassing CORS while generating the client side image matrix.

BAYESIAN FACTORIZATION | RESEARCH PROJECT - MACHINE LEARNING

Jan. 17 - May 17 | IIT Kanpur

Analyzed the performances of Poisson, Hierarchical Poisson, and Bayesian Non-parametric Poisson Matrix Factorization on MovieLens 1M dataset.

STICKY ANNOTATION SYNCHRONIZATION | C++ JS DEVELOPMENT

Jan. 18 - Jul. 18 | Acrobat Development Team, Adobe Inc.

Engineered the sticky annotation capability for the new HTML based PDF webview. The new view now supports CRUD operations of sticky annotations and synchronization of the annotations with the original view.