# Shubham Agrawal

agshubh191@gmail.com ♂ | 213-446-5430 | Website: agshubh.com ♂ | New York City, NY

#### **EDUCATION**

#### Columbia University in the City of New York

Master of Science in Computer Science; Advanced Masters Research Specialization in Vision and Robotics; GPA: 3.8/4.0

Aug 2019 - May 2021

New York, NY

**Indian Institute of Technology Kanpur** 

Kanpur, India

Bachelor of Technology in Computer Science; GPA: 8.7/10.0

Jul 2013 - Apr 2017

#### EXPERIENCE

#### Samsung Research America

New York, NY, USA March 2023 - Present

Senior Researcher, Machine Learning Engineer, Machine Learning Research

Jun 2021 - March 2023

- <u>3D computer vision research</u>: Simultaneous scene understanding and grasp estimation, leveraging foundational visual language models for generalizable scene reconstruction. The research led to <u>multiple publications and patents</u> ( SceneGrasp 2 , RIC 2 ).
- Lidar to floorplan: Generated a visually pleasing rectilinear floor plan from a noisy lidar-scan image. (video 🗗). The research technology is now in the production phase for the Samsung Robot Vaccum Cleaner.
- Autonomous table clearing and dishwasher loading Key components: (a) in-house 6DoF perception data labeling tool (video 🖸 ), (b) instance segmentation, (c) 6DoF pose estimation, (d) glass detection, (e) stereo depth prediction, and (f) sensor fusion.

Tesla Inc
Palo Alto, USA (remote)
Autopilot Intern
Jun 2020 - Aug 2020

(Non Disclosure Agreement) Identify and associate the same objects visible in multiple cameras to create object tracks across time.

Adobe Inc Noida, India

*Member of Technical Staff (C++, JavaScript Software Developer)* 

Jul 2017 - Jan 2019

Research Intern (Machine Learning)

May 2016 - Aug 2016

• Implemented CRUD operations for highlight/underline/sticky notes for Adobe PDF Liquid mode C. Shipped fixes for multiple critical security vulnerabilities (null pointer dereferencing, buffer overflow, JavaScript parameter tampering).

#### PROJECTS AND PUBLICATIONS

• Real-time Simultaneous Multi-object 3D Shape Reconstruction, 6DoF Pose, and Dense Grasp Prediction Project page 2, Video 2, Code 2 IROS 2023 | Patent pending | S. Agrawal, N. Dafle, I. Kasahara, S. Engin, J. Huh, V. Isler

RIC: Rotate-Inpaint-Complete for Generalizable Scene Reconstruction
 2023 (in review) | Patent pending | I. Kasahara, <u>S. Agrawal</u>, S. Engin, N. Dafle, S. Song, V. Isler
 Recognized as a strategically important patent in the Generative AI domain by Samsung's IP team.

Project page 갑 , Video 갑

 SEaT: Scene Editing as Teleoperation IROS 2022 | S. Agrawal\*, Y. Li\*, J. Liu, S. Feiner, S. Song (\* equal contributions) Project page ♂, Video ♂, Code ♂

• Camera-centric Object Shell Representation for Simultaneous Object Reconstruction and Grasp Prediction IROS 2022 | Patent pending | N. Dafle, S. Popovich, S. Agrawal, D. Lee, V. Isler

ArXiv ♂ , Video ♂

 Fit2Form - 3D Generative Model for Robot Gripper Form Design CoRL 2021 | S. Agrawal\*, H. Ha\*, S. Song Project page ♂ , Video ♂ , Code ♂

 AdaGrasp: Learning an Adaptive Gripper-Aware Grasping Policy ICRA 2021 | Z. Xu, B. Qi, <u>S. Agrawal</u>, S. Song Project page ♂, Video ♂, Code ♂

Smart Geo-fencing with Location-Sensitive Product Affinity
 SIGSPATIAL 2017 | Patent ♂ | A. Garg, S. Agrawal, S. Agrawal, P. Bajaj, A. Kedia

Patent 🗗 , ArXiv 🗗

## SKILLS

- Languages | Libraries: C++, Python, Java, PyTorch, Spark, XGBoost, scikit-learn, ROS, Docker, SQL, GPU, Distributed Systems, GCP
- Techniques: Single/Multi-view geometry, Pose estimation, SLAM, Visual Inertial Odometry, Sensor Fusion, GAN/VAE/Diffusion models
- Hardware Experience: Robots (UR5, Panda, Kinova, Ridgeback), Grippers (WSG50, RG2, BHand), RGB-D Cameras, Raspberry Pi

### ACHIEVEMENTS & EXTRACURRICULAR

- Course Assistant Fellowship, Columbia University: awarded for stellar academic performance and outstanding work as a TA
- Co-founded TOEFL Infinite C, an android application for TOEFL and GRE exam preparation with 150K downloads on Google Play
- Ranked 191 (99.8 percentile) among 150K candidates in IIT-JEE Advanced 2013 entrance exam for premium engineering colleges in India
- Teaching: Computational Aspects of Robotics (Head TA) &, Applied Machine Learning &, Advanced Database Systems &
- Research assistantships: Shuran Song Columbia University & (Sept 2019 Apr 2021), Gaurav Sukhatame USC & (May 2019 Aug 2019)
- CS Department Senator, University of Southern California
- Ran TCS New York City Marathon 2023. Love music and playing flute in my free time.