# Shubham Agrawal

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#### **EDUCATION**

### Columbia University in the City of New York

New York, NY

Master of Science in Computer Science; Vision, Graphics, Interaction and Robotics track; CGPA: 3.8/4.0

Aug 2019 - May 2021

**Indian Institute of Technology Kanpur** 

Kanpur, India

Bachelor of Technology in Computer Science; CGPA: 8.7/10.0

Jul 2013 - Apr 2017

## **EXPERIENCE**

#### Samsung Research America

New York, NY, USA March 2023 - Present

Senior Researcher, Machine Learning Engineer Machine Learning Research

Jun 2021 - March 2023

- Led perception team for the inter-team table-clearing benchmark competition. Key components: (a) In-house 6DoF Perception Data collection and labeling tool **Video** C, (b) instance segmentation, (c) 6DoF pose estimation, (d) glass detection, (e) stereo depth prediction, and (f) fusion of single view predictions into a coherent world map
- Research on 3D scene understanding for robotics tasks. Relevant papers: Real-time simultaneous multi-object 3D Shape Reconstruction, 6DoF Pose Estimation, and Dense Grasp Prediction arXiv 🖒, Simultaneous object reconstruction and grasp prediction arXiv 🖒 arXiv 🖒

Tesla Inc Palo Alto, USA (remote)

Autopilot Intern (Non Disclosure Agreement)

Jun 2020 - Aug 2020

· Worked on identifying and associating the same objects visible in multiple cameras to create object tracks across time.

Adobe Inc

Noida, India

Member of Technical Staff (C++, JavaScript Software Developer)

Jul 2017 - Jan 2019

• Implemented CRUD operations for highlight/underline/sticky notes for next generation PDF webview using Javascript.

Research Intern (Machine Learning)

May 2016 - Aug 2016 (voluntarily working till Jun 2017)

• Created a novel end-to-end system for automated design of affinity (user's interest) based smart geo-fences for selective targeting. US Patent US20180232767A1 2 . ACM SIGSPATIAL'17 conference paper 2

# PROJECTS AND PUBLICATIONS

- [2023 IEEE IROS] Real-time simultaneous multi-object 3D Shape Reconstruction, 6DoF Pose Estimation and Dense Grasp Prediction: Shubham Agrawal, Nikhil Chavan-Dafle, Isaac Kasahara, Selim Engin, Jinwook Huh, and Volkan Isler. arXiv ©
- [2023 (under review)] RIC: Rotate-Inpaint-Complete for Generalizable Scene Reconstruciton: Isaac Kasahara, Shubham Agrawal, Selim Engin, Nikhil Chavan-Dafle, Shuran Song, and Volkan Isler. arXiv 🗗
- [2022 IEEE IROS] SEaT: Scene Editing as Teleoperation: Shubham Agrawal\*, Yulong Li\*, Jen-Shuo Liu, Steven K. Feiner, and Shuran Song. Scene Editing as Teleoperation: A Case Study in 6DoF Kit Assembly. (\* = equal contributions). arXiv C\*, Website C\*.
- [2021 PMLR CoRL] Fit2Form: 3D Generative Model for Robot Gripper Form Design: Shubham Agrawal\*, Huy Ha\*, and Shuran Song. PMLR CoRL &, Website &.
- [2021 IEEE ICRA] AdaGrasp: Learning an Adaptive Gripper-Aware Grasping Policy: Zhenjia Xu, Beichun Qi, Shubham Agrawal, Shuran Song. arXiv &, Website &.
- [2022 IEEE IROS] Simultaneous object reconstruction and grasp prediction using camera-centric object shell representation: Nikhil Chavan Dafle, Sergiy Popovich, Shubham Agrawal, Daniel Lee, Volkan Isler. IROS ♂
- [2021 US Patent] Smart geo-fencing using location sensitive product affinity: Ankur Garg, Sweta Agrawal, Shubham Agrawal, Payal Bajaj, Abhishek Kedia. Google patents 🖒
- [2021 arXiv] Automatic differentiation and continuous sensitivity analysis of rigid body dynamics: David Millard, Eric Heiden, Shubham Agrawal, Gaurav S Sukhatme. arXiv ♂

#### SKILLS

- Languages | Libraries: C++, Python, Pytorch, Ray, ROS, (Isaac Sim, Pybullet, Gazebo) simulators
- Hardware Experience: (UR5, Panda, Kinova, Ridgeback) Robots, (WSG50, RG2, BHand) Grippers, RGB-D Cameras, Raspberry Pi

#### ACHIEVEMENTS & EXTRACIRRICULAR

- Course Assistant Fellowship, Columbia University: awarded for stellar academic performance and outstanding work as a TA
- Selected for Advanced Master Research Specialization at Columbia University offering one fully funded semester of research
- All India Rank 191, IIT-JEE Advanced 2013 (among 150K candidates)
- Course assistantships: Computational Aspects of Robotics (Head TA) [2], Applied Machine Learning [2], Advanced Database Systems [2]
- Research assistantships: Shuran Song Columbia University & (Sept 2019 present), Gaurav Sukhatame USC & (May 2019 Aug 2019)
- · Received Academic Excellence Award for excellent academic performance during 2013-14 curriculum at IIT Kanpur
- Served as CS Department Senator at Viterbi Graduate Student Association, University of Southern California for spring semester, 2019
- Co-created TOEFL Infinite &, an android application for TOEFL and GRE exam preparation with 150K downloads on Google Play