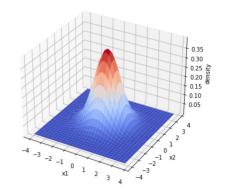
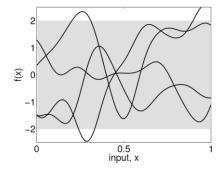


Gaussian Distribution → probability distribution of scalars

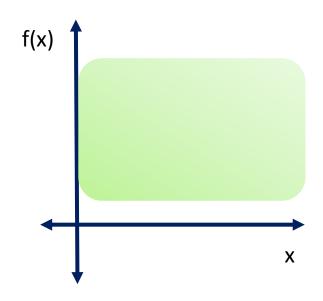


Multivariate Gaussian → probability distribution of vectors



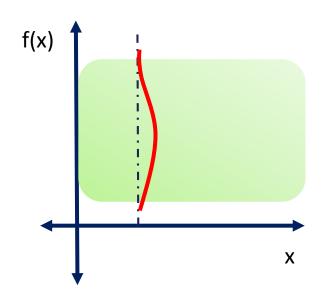
- Gaussian Process → Probability distribution of functions
 - Hyperparameter response function





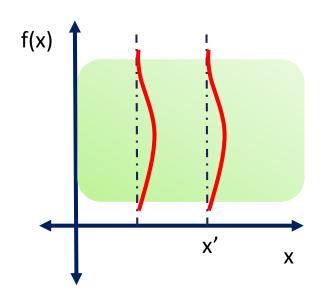
- Gaussian Process = GP = f(x)
- GP = Gaussian Distribution over functions
- X are functions
- Think of a function, X, as a very long vector, each entry in the vector specifying the function value f(x).



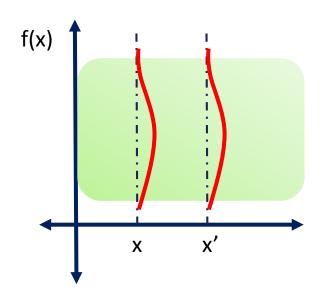


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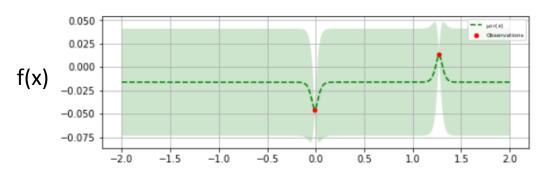


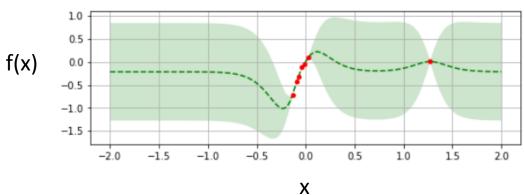
- GP = Gaussian Distribution over functions, f(x)
- x are functions
- Think of a function, x, as a very long vector, each entry in the vector specifying the function value f(x).
- The distribution of a Gaussian Process is the joint distribution of all those (infinitely many) random variables / functions.



- GP = Gaussian Distribution over functions
- $f(x) \sim GP(m(x), K(x, x'))$
- $\bullet \ \mathsf{m}(\mathsf{x}) = \mathsf{E}[\mathsf{f}(\mathsf{x})]$
- $K(x, x') = E[(f(x) m(x)) \times (f(x') m(x'))]$
- Computationally → infinitely dimensional







If we evaluate f(x) for a finite number of x, we can predict f(x) for all other values with an estimate plus an uncertainty.

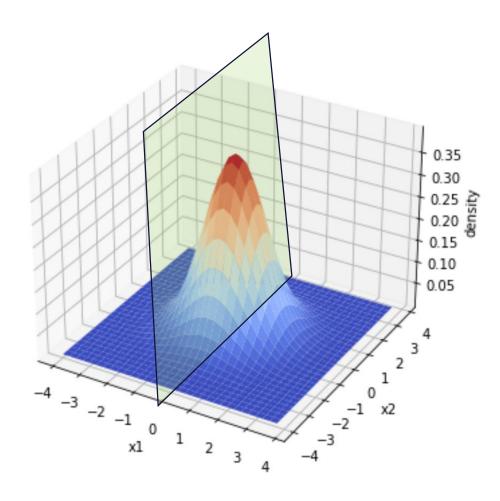
GP → prior

f(x) evaluations → Data

Update $f(x) \rightarrow$ the posterior



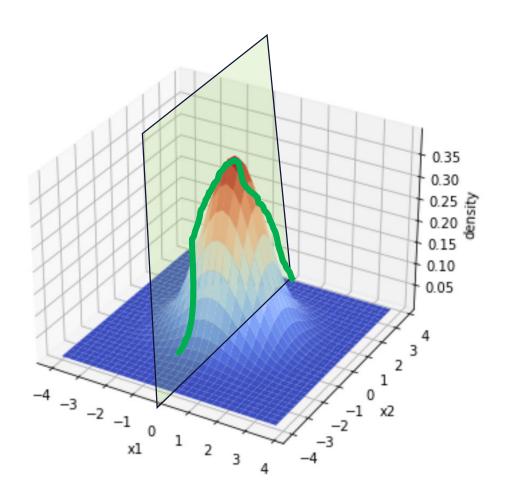
Joint Probability







Joint Probability

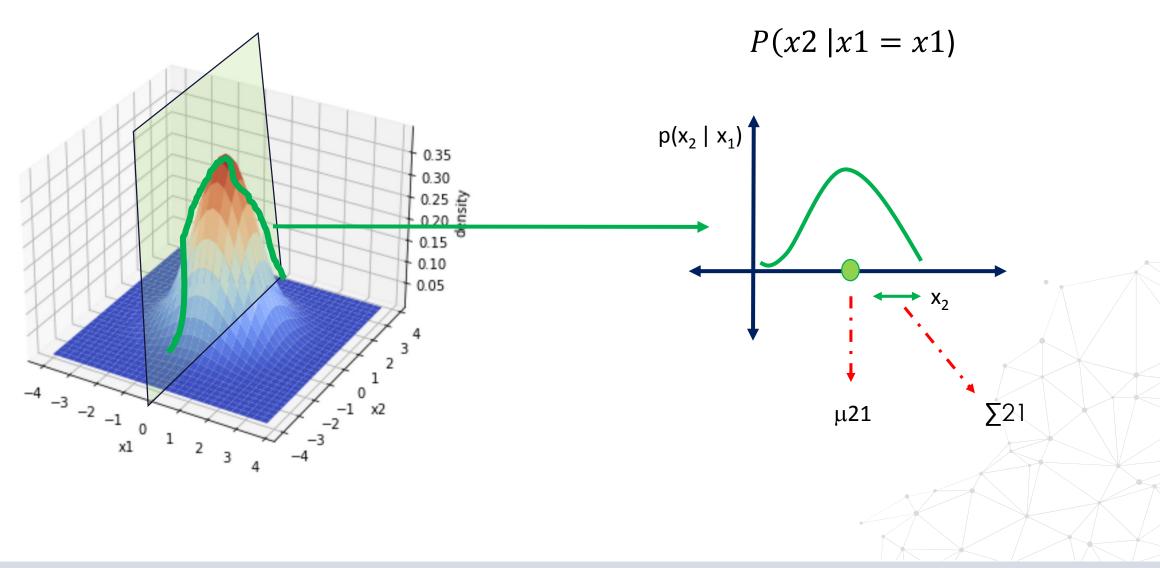


$$P(x2 \mid x1 = x1)$$





Joint Probability



Multivariate Gaussian Theorem

If
$$X = \begin{bmatrix} x1\\ x2 \end{bmatrix} \sim N(\mu = \begin{bmatrix} m1\\ m2 \end{bmatrix}, \Sigma = \begin{bmatrix} \sum_{11} & \sum_{12}\\ \sum_{21} & \sum_{22} \end{bmatrix})$$

The marginal:

- $P(x1) \sim N(\mu 1, \sum 11)$
- $P(x2) \sim N(\mu 2, \Sigma 22)$

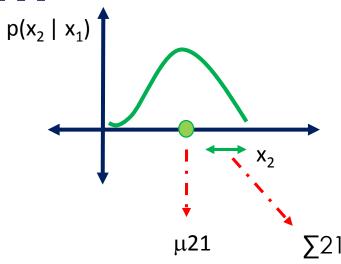
The posterior:

$$p(\mathbf{x}_1|\mathbf{x}_2) = \mathcal{N}(\mathbf{x}_1|\boldsymbol{\mu}_{1|2}, \boldsymbol{\Sigma}_{1|2})$$
 $\boldsymbol{\mu}_{1|2} = \boldsymbol{\mu}_1 + \boldsymbol{\Sigma}_{12}\boldsymbol{\Sigma}_{22}^{-1}(\mathbf{x}_2 - \boldsymbol{\mu}_2)$
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Multivariate Gaussian Theorem

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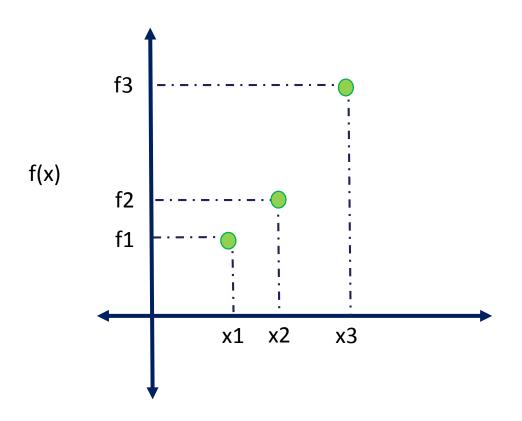


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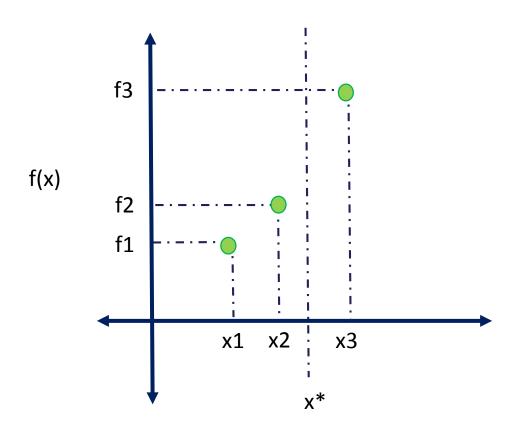
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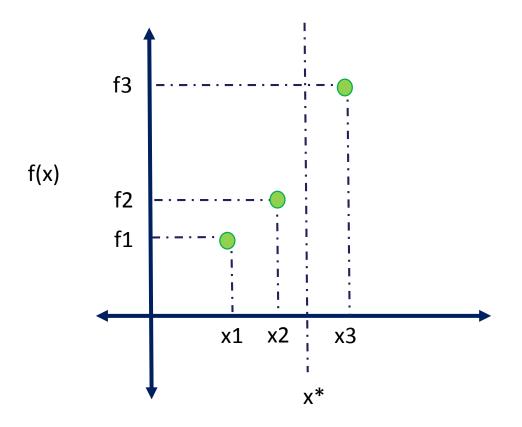
$$\begin{bmatrix} f1 \\ f2 \\ f3 \end{bmatrix} \sim N(\mu = \begin{bmatrix} m1 \\ m2 \\ m3 \end{bmatrix}, \Sigma = \begin{bmatrix} K11 & K12 & K13 \\ K21 & K22 & K23 \\ K31 & K32 & K33 \end{bmatrix})$$





$$\begin{bmatrix} f1 \\ f2 \\ f3 \end{bmatrix} \sim N(\mu = \begin{bmatrix} m1 \\ m2 \\ m3 \end{bmatrix}, \Sigma = \begin{bmatrix} K11 & K12 & K13 \\ K21 & K22 & K23 \\ K31 & K32 & K33 \end{bmatrix})$$

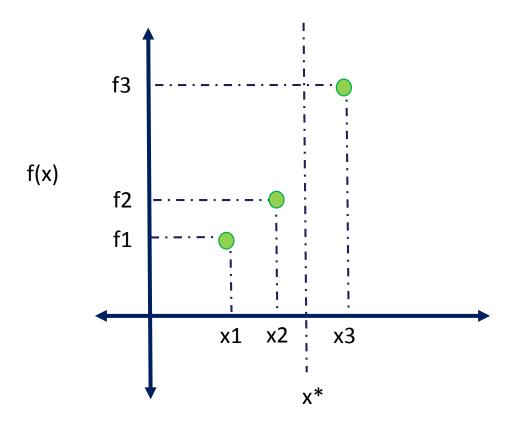




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$$\begin{bmatrix} f1 \\ f2 \\ f3 \\ f* \end{bmatrix} \sim N(\mu = \begin{bmatrix} m1 \\ m2 \\ m3 \\ m* \end{bmatrix}, \Sigma = \begin{bmatrix} K11 & K12 & K13 & K1* \\ K21 & K22 & K23 & K2* \\ K31 & K32 & K33 & K3* \\ K*1 & K*2 & K*3 & K** \end{bmatrix})$$





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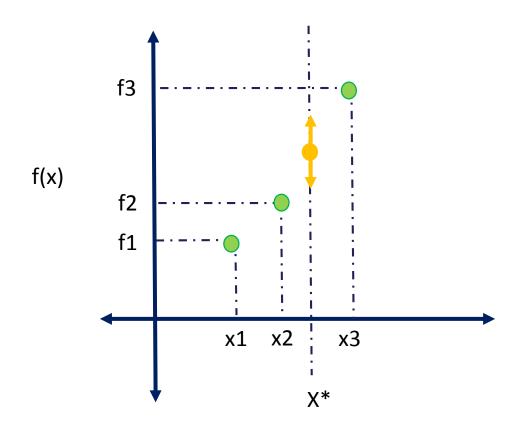
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$$\begin{bmatrix} f \\ f * \end{bmatrix} \sim N(\mu = \begin{bmatrix} m \\ m * \end{bmatrix}, \Sigma = \begin{bmatrix} K & K * \\ K * & K * * \end{bmatrix}$$

$$m^* = \mu(x^*) + K_*K^{-1}(f - \mu(f))$$

$$\sum = K_{**} - K_* K^{-1} K_*$$





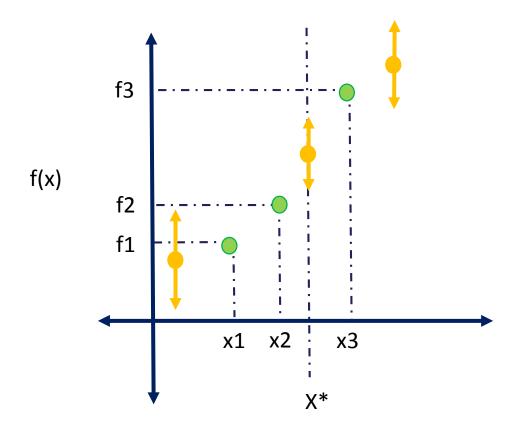
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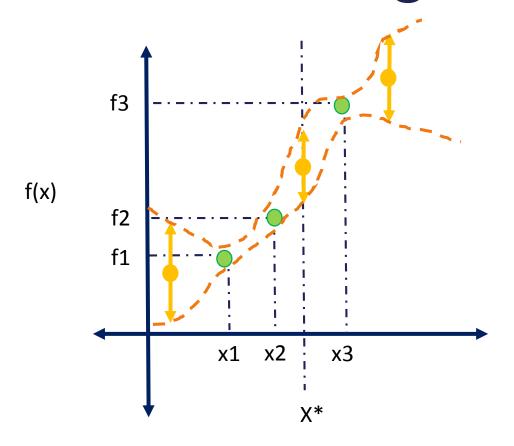
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THANK YOU

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