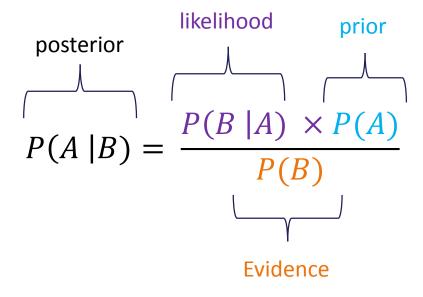




Sequential
Model-Based
Optimization

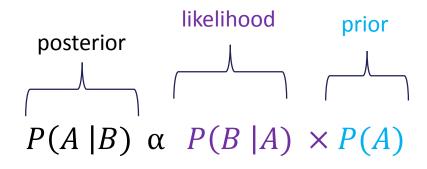
Bayes' Rule



With Bayes' Rule we infer a posterior P(A | B) from a Prior (A)



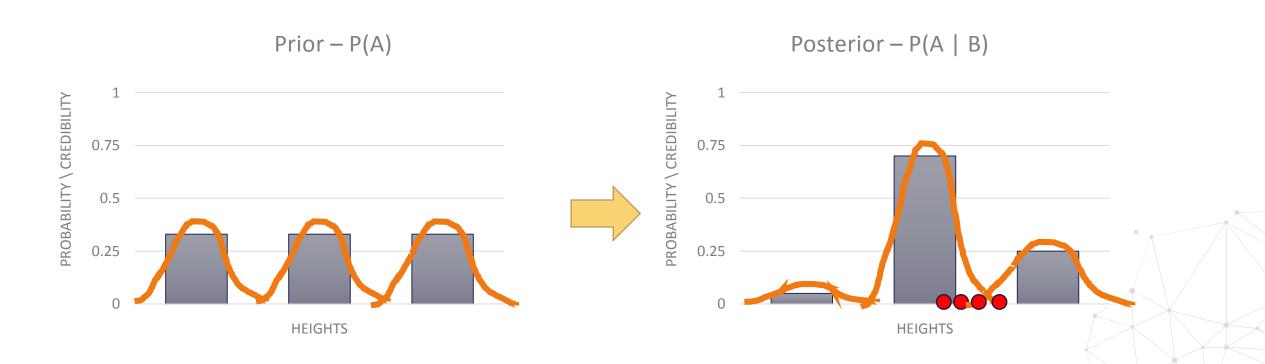
Bayes' Rule



With **Bayes' Rule** we infer a posterior P(A | B) from a Prior (A)



Probability reallocation



We **hypothesize** a range of possible distributions, models or generators (priors), and from data we determine their credibility (posterior).



Mathematically, we want to find the global maximizer (or minimizer) of an unknown (black-box) objective function *f*:

$$\mathbf{x}^{\star} = \arg\max_{\mathbf{x} \in \mathcal{X}} f(\mathbf{x})$$

where x are the hyperparameters.



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$$\mathbf{x}^{\star} = \arg\max_{\mathbf{x} \in \mathcal{X}} f(\mathbf{x})$$

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Response surface

- A: Algorithm
 - A_{λ} : Hyperparameters
- X: Dataset
- L: Function to optimise
 - Performance metric

Black Box



- Let \mathbf{w} be $f(\mathbf{x})$ and \mathbf{D} be the available data
- w is unknown, so we treat it as a random function and place a prior over it \rightarrow P(w)
- P(w) captures our beliefs about the possible values of w
- Given D and the likelihood model P(D | w), we can infer the posterior P(w | D)
 using Bayes' rule



$$P(w | D) = \frac{P(D | w) \times P(w)}{P(D)}$$

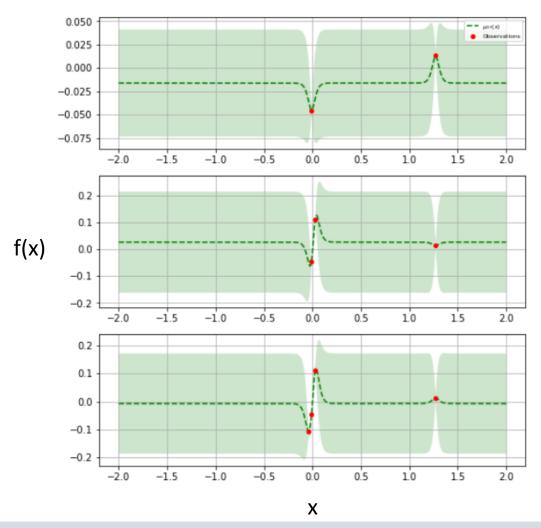
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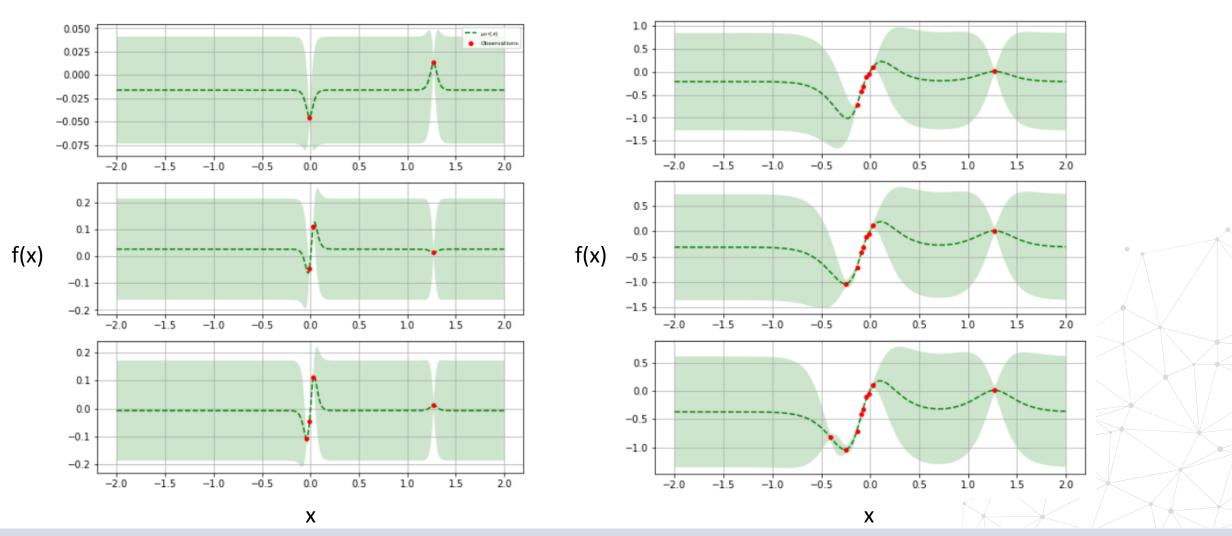
- The posterior $P(w \mid D)$ represents our updated belief of w after contemplating D.
- Given the posterior distribution **P(w | D)**, we construct an acquisition function to determine the next query point to sample w.



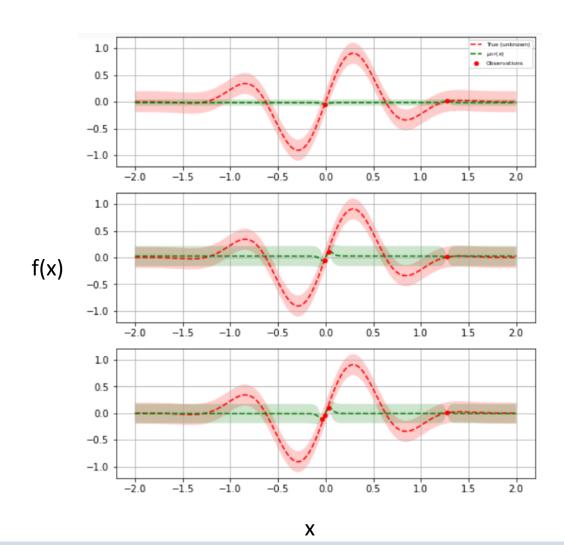


- The green area is our Prior, P(w)
- D is the red dots, where we evaluate f(x)
- We adjust the posterior P(w | D) based on D.
- The uncertainty decreases around the evidence.



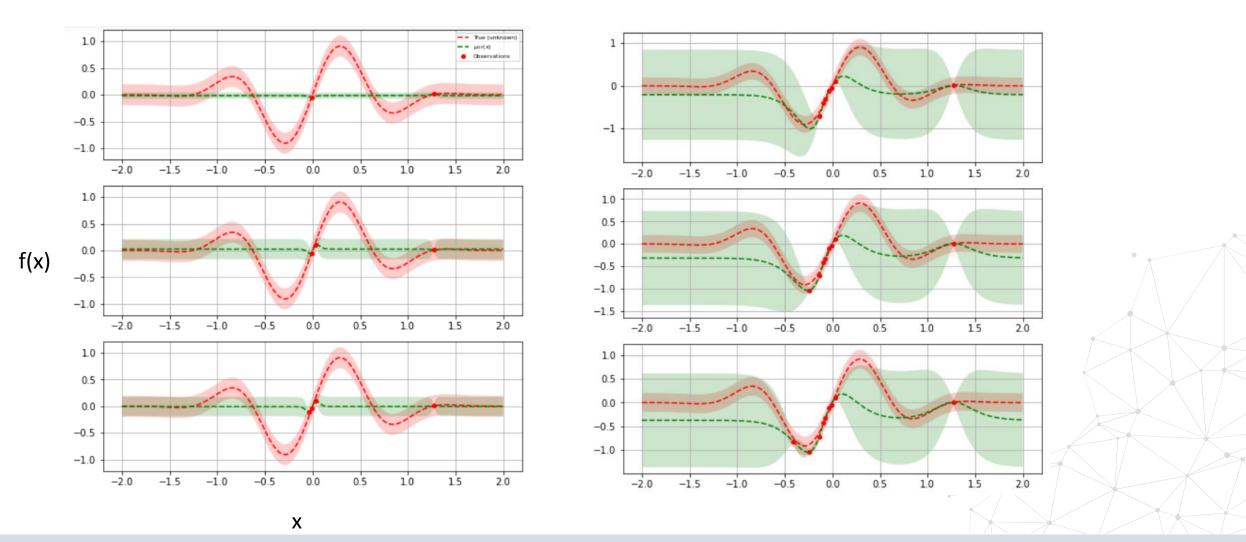






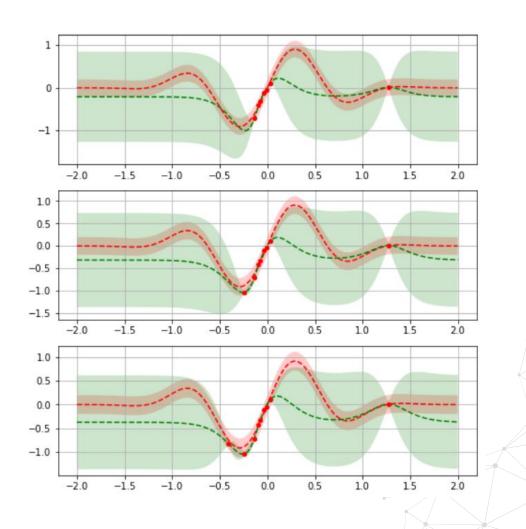
- Red is f(x)
- The green area is our Prior, P(w)
- D is the red dots, where we evaluate f(x)
- We adjust the posterior P(w | D) based on D.
- Note how with Bayes Optimization we find the minimum of f(x).







- Red is f(x)
- As we gather more data, the posterior
 P(w | D) increases its uncertainty in unexplored areas and decreases its uncertainty in explored areas

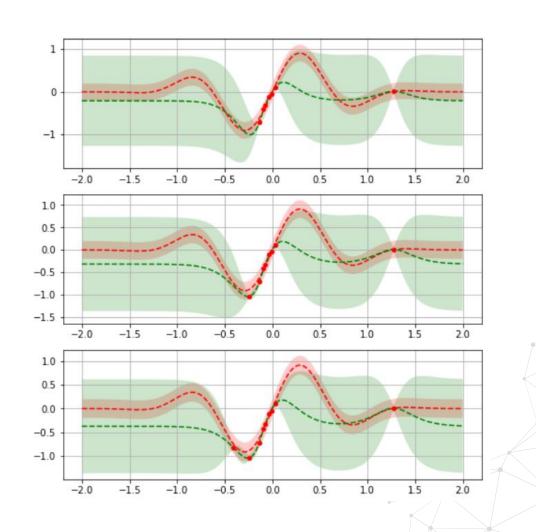




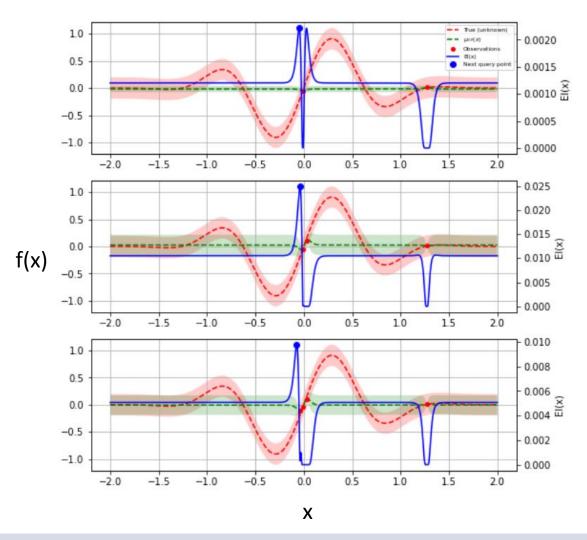
 f(x) is unknown, we do not know its shape

 We need a way to produce a prior, and a posterior → Surrogate model for f(x)

Gaussian Process Regression



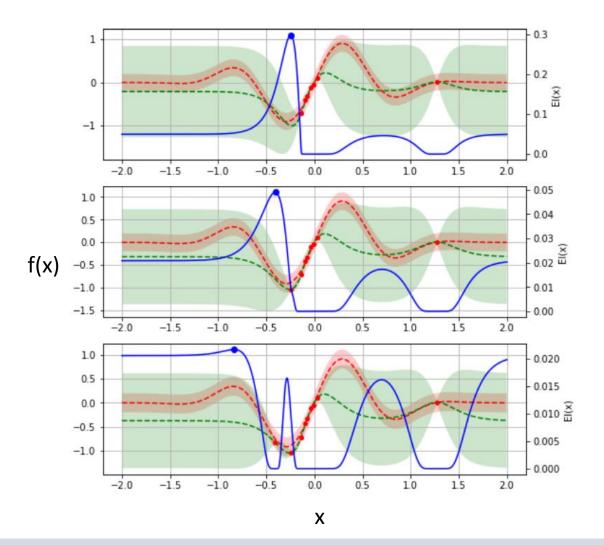




 We also need a way to estimate where to sample next → acquisition function



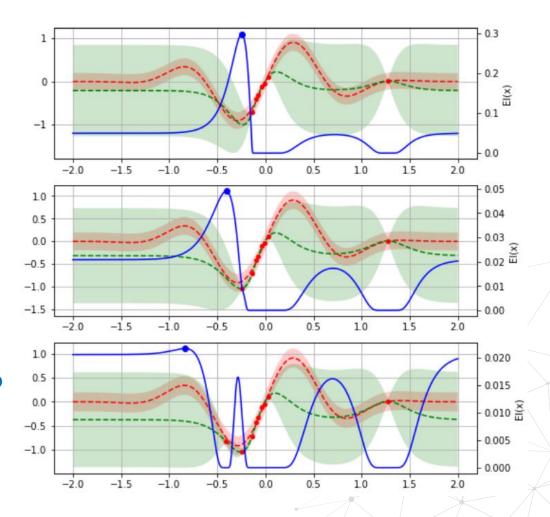




- We also need a way to estimate where to sample next → acquisition function
- Acquisition function values are high where the mean of f(x) is low (or high) → exploitation.
- Acquisition function values are high when the variance of f(x) is high → exploration.



- f(x) is unknown, we do not know its shape
- We need a way to produce a prior, and a posterior → Surrogate model for f(x)
 - Gaussian Process Regression
- We need an acquisition function to determine where to sample next
- The surrogate and the acquisition function need to be cheaper to evaluate than f(x)







THANK YOU

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