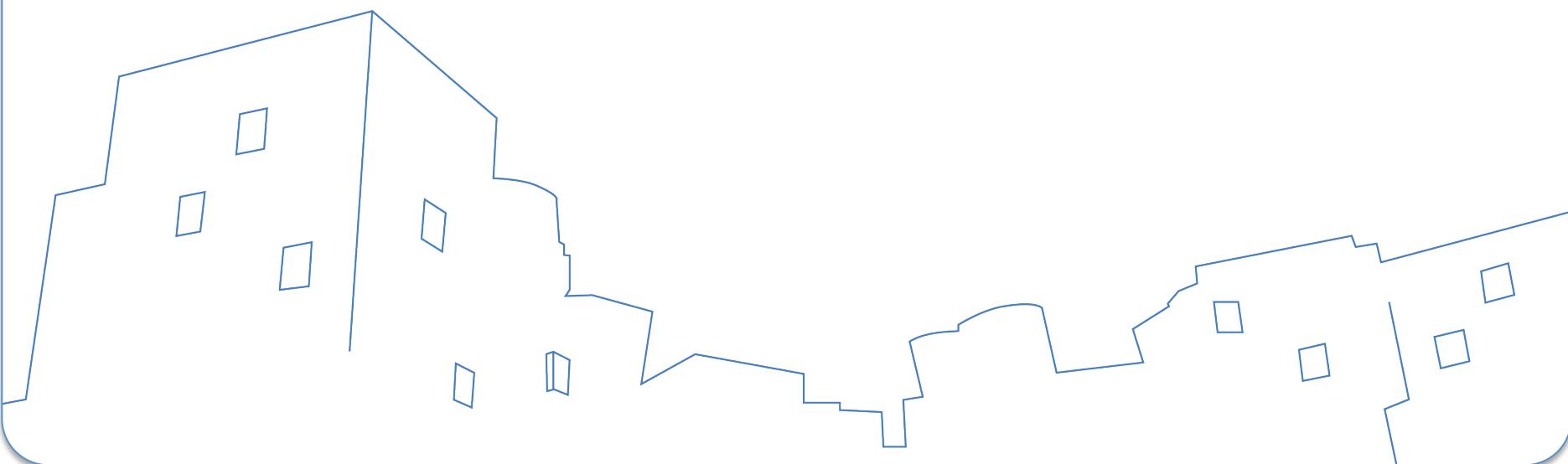


6.434/16.391 Statistics for Engineers and Scientists

Lecture 12 10/24/2012

Laboratory for Information and Decision Systems
Massachusetts Institute of Technology



Lecture 11 10/24/2011

SCORE FUNCTION AND FISHER INFORMATION

Score function

- Definition: Let X_1, X_2, \dots, X_n be random variables with joint PDF (or PMF) $f_{\mathbf{X}}(\mathbf{x}|\theta)$. The score function is defined as

$$V(\mathbf{x}, \theta) = \frac{f'(\mathbf{x}, \theta)}{f(\mathbf{x}, \theta)}, \quad \text{where } f'(\mathbf{x}, \theta) = \frac{\partial}{\partial \theta} f(\mathbf{x}, \theta)$$

- Note:
 - $V(\mathbf{X}, \theta)$ is random
 - The score function can be expressed as

$$\begin{aligned} V(\mathbf{x}, \theta) &= \frac{\partial}{\partial \theta} \ln f(\mathbf{x}, \theta) \\ &= \frac{\partial}{\partial \theta} L(\theta | \mathbf{x}) \end{aligned}$$

where $L(\theta | \mathbf{x})$ is the log likelihood function

Fisher information

- Definition: The Fisher information in the observation \mathbf{X} about the parameter θ is given by

$$\begin{aligned} I_{\mathbf{X}}(\theta) &= \mathbb{E}_{\mathbf{X}} \left\{ [V(\mathbf{X}, \theta)]^2 \right\} \\ &= \mathbb{E}_{\mathbf{X}} \left\{ \left[\frac{\partial}{\partial \theta} L(\theta | \mathbf{X}) \right]^2 \right\} \end{aligned}$$

- One should start to suspect that there is a strong connection between MLE and the Fisher information
- In fact, under so called “regularity conditions”, one can show that MLE $\hat{\theta}_n = \hat{\theta}_n(X_1, \dots, X_n)$ is a CAN estimator with

$$J^2(\theta) = \frac{1}{I_X(\theta)}$$

Example 1

- Let X be distributed as $\mathcal{N}(\mu, \sigma^2)$. Find $I(\mu)$ and $I(\sigma^2)$
- First of all, the likelihood function is

$$f(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{(x-\mu)^2}{2\sigma^2}\right\}$$

Then we have

$$\ln f(x|\mu, \sigma^2) = -\frac{1}{2} \ln(2\pi) - \frac{1}{2} \ln(\sigma^2) - \frac{1}{2\sigma^2}(x-\mu)^2$$

$$\frac{\partial}{\partial \mu} \ln f(x|\mu, \sigma^2) = +\frac{1}{\sigma^2}(x-\mu)$$

$$\frac{\partial}{\partial \sigma^2} \ln f(x|\mu, \sigma^2) = -\frac{1}{2} \frac{1}{\sigma^2} + \frac{1}{2} \frac{1}{\sigma^4}(x-\mu)^2$$

$$\begin{aligned} \frac{\partial}{\partial \sigma} \ln f(x|\mu, \sigma^2) &= -\frac{1}{2} \frac{2\sigma}{\sigma^2} + \frac{2}{2\sigma^3}(x-\mu)^2 \\ &= -\frac{1}{\sigma} + \frac{1}{\sigma^3}(x-\mu)^2 \end{aligned}$$

Example 1

- For parameter μ ,

$$V(x, \mu) = \frac{1}{\sigma^2} (x - \mu)$$

$$\begin{aligned} I_X(\mu) &= \mathbb{E} \{ V^2(X, \mu) \} \\ &= \frac{1}{\sigma^4} \mathbb{E} \{ (X - \mu)^2 \} \\ &= \frac{1}{\sigma^2} \end{aligned}$$

Example 1

- For parameter σ^2 ,

$$V(x, \sigma^2) = -\frac{1}{2} \frac{1}{\sigma^2} + \frac{1}{2} \frac{1}{\sigma^4} (x - \mu)^2$$

$$\begin{aligned} I_X(\sigma^2) &= \mathbb{E} \left\{ \frac{1}{4} \frac{1}{\sigma^4} - \frac{2}{4} \frac{1}{\sigma^6} (X - \mu)^2 + \frac{1}{4} \frac{1}{\sigma^8} (X - \mu)^4 \right\} \\ &= \frac{1}{4} \frac{1}{\sigma^4} - \frac{1}{2} \frac{1}{\sigma^6} \mathbb{E} \{(X - \mu)^2\} + \frac{1}{4\sigma^4} \mathbb{E} \left\{ \frac{(X - \mu)^4}{\sigma^4} \right\} \\ &= -\frac{1}{4\sigma^4} + \frac{1}{4\sigma_4} \alpha^4 \\ &= \frac{1}{4\sigma^4} (\alpha_4 - 1) \end{aligned}$$

where

$$\alpha_4 = \mathbb{E} \left\{ \frac{(X - \mu)^4}{\sigma^4} \right\}$$

Example 1

- For parameter σ ,

$$\begin{aligned}V(x, \sigma) &= -\frac{1}{\sigma} + \frac{1}{\sigma^3}(x - \mu)^2 \\I_X(\sigma^2) &= \mathbb{E} \left\{ \frac{1}{\sigma^2} - \frac{2}{\sigma^4}(X - \mu)^2 + \frac{1}{\sigma^6}(X - \mu)^4 \right\} \\&= \frac{1}{\sigma^2} - \frac{2}{\sigma^4} \mathbb{E} \left\{ (X - \mu)^2 \right\} + \frac{1}{\sigma^2} \mathbb{E} \left\{ \frac{(X - \mu)^4}{\sigma^4} \right\} \\&= -\frac{1}{\sigma^2} + \frac{1}{\sigma^2} \alpha_4 \\&= \frac{1}{\sigma^2} (\alpha_4 - 1)\end{aligned}$$

Example 2

- Let X be a Bernoulli random variable with p the probability of success, i.e.,

$$\mathbb{P}\{X = x|p\} = p^x(1 - p)^{1-x}, \quad x = 0, 1$$

Find the Fisher information for p

- First,

$$\ln \mathbb{P}\{X = x|p\} = x \ln p + (1 - x) \ln(1 - p)$$

The score function is

$$V(x, p) = \frac{\partial}{\partial p} \ln \mathbb{P}\{X = x|p\} = \frac{x}{p} - \frac{1 - x}{1 - p}$$

Example 2

- Finally,

$$\begin{aligned} I_X(p) &= \mathbb{E}\{V^2(X, p)\} \\ &= \mathbb{E}\left\{\frac{X^2}{p^2} - \frac{2X(1-X)}{p(1-p)} + \frac{(1-X)^2}{(1-p)^2}\right\} \\ &= \frac{1}{p(1-p)} \end{aligned}$$

- Note: Since

$$V(x, p) = \frac{(1-p)x - p(1-x)}{p(1-p)} = \frac{x-p}{p(1-p)}$$

we have $\mathbb{E}\{V(X, p)\} = 0$. Therefore,

$$I_X(p) = \mathbb{V}\{V(X, p)\} = \frac{1}{p^2(1-p)^2} \mathbb{V}\{X - p\} = \frac{1}{p(1-p)}$$

Fisher information in independent observations

- Lemma: Let X_1, X_2, \dots, X_n and Y_1, Y_2, \dots, Y_n be independent observation for θ . Then

$$I_{\mathbf{XY}}(\theta) = I_{\mathbf{X}}(\theta) + I_{\mathbf{Y}}(\theta)$$

- Proof: The score function

$$\begin{aligned} V(\mathbf{x}, \mathbf{y}, \theta) &= \frac{\partial}{\partial \theta} L(\theta | \mathbf{x}, \mathbf{y}) \\ &= \frac{\partial}{\partial \theta} \ln f(\mathbf{xy} | \theta) \\ &= \frac{\partial}{\partial \theta} \ln [f(\mathbf{x} | \theta) f(\mathbf{y} | \theta)] \\ &= \frac{\partial}{\partial \theta} \ln f(\mathbf{x} | \theta) + \frac{\partial}{\partial \theta} \ln f(\mathbf{y} | \theta) \\ &= V(\mathbf{x}, \theta) + V(\mathbf{y}, \theta) \end{aligned}$$

Fisher information in independent observations

- Therefore,

$$\begin{aligned} I_{\mathbf{X}\mathbf{Y}}(\theta) &= \mathbb{V}\{V(\mathbf{X}, \mathbf{Y}, \theta)\} \\ &= \mathbb{V}\{V(\mathbf{X}, \theta) + V(\mathbf{Y}, \theta)\} \\ &= \mathbb{V}\{V(\mathbf{X}, \theta)\} + \mathbb{V}\{V(\mathbf{Y}, \theta)\} \\ &= I_{\mathbf{X}}(\theta) + I_{\mathbf{Y}}(\theta) \end{aligned}$$

where the third equality is due to the independence between \mathbf{X} and \mathbf{Y}

- In particular, if X_1, X_2, \dots, X_n are i.i.d., then

$$I_{\mathbf{X}}(\theta) = nI_{X_1}(\theta)$$

Lecture 12 10/24/2012

INFORMATION INEQUALITY

Regularity conditions

- Satisfy certain technical conditions
 - The set of possible values of the random variable X do not depend on the unknown parameter θ
 - Integration and differentiation can be interchanged
- Mathematically
 - The set $\mathcal{A} = \{\mathbf{x} : f_{\mathbf{x}}(\mathbf{x}|\theta) > 0\}$ does not depend on θ for all $\mathbf{x} \in \mathcal{A}$ and $\theta \in \Theta$, $\frac{\partial}{\partial \theta} \ln f(\mathbf{x}, \theta)$ exists and is finite
 - If T is any statistic such that

$$\mathbb{E}_X \{|T(\mathbf{X})|\} < \infty, \quad \forall \theta \in \Theta$$

Then we require that

$$\frac{\partial}{\partial \theta} \int \cdots \int T(\mathbf{x}) f(\mathbf{x}, \theta) d\mathbf{x} = \int \cdots \int T(\mathbf{x}) \frac{\partial}{\partial \theta} f(\mathbf{x}, \theta) d\mathbf{x}$$

Regularity conditions

- Under regularity conditions,

$$\begin{aligned}\mathbb{E} \{V(\mathbf{X}, \theta)\} &= \mathbb{E} \left\{ \frac{\partial}{\partial \theta} \ln f(\mathbf{X}|\theta) \right\} \\ &= \int \cdots \int \frac{f'(\mathbf{x}|\theta)}{f(\mathbf{x}|\theta)} f(\mathbf{x}|\theta) d\mathbf{x} \\ &= \frac{\partial}{\partial \theta} \int \cdots \int f(\mathbf{x}|\theta) d\mathbf{x} \\ &= 0\end{aligned}$$

- Fisher information

$$\begin{aligned}I_{\mathbf{X}}(\theta) &= \mathbb{E} \{V^2(\mathbf{X}, \theta)\} \\ &= \mathbb{E} \{V^2(\mathbf{X}, \theta)\} - \underbrace{\mathbb{E}^2 \{V(\mathbf{X}, \theta)\}}_{=0} \\ &= \mathbb{V} \{V(\mathbf{X}, \theta)\}\end{aligned}$$

Information inequality

- Theorem (Information inequality): Let $T(\mathbf{X})$ be any estimator of some function of θ such that $\mathbb{V}\{T(\mathbf{X})\} < \infty$ for all $\theta \in \Theta$. Denote $\psi(\theta) = \mathbb{E}\{T(\mathbf{X})\}$. Suppose regularity conditions holds and the condition $0 < I_{\mathbf{X}}(\theta) < \infty$ is satisfied, then for all $\theta \in \Theta$,

$$\mathbb{E} \left\{ [T(\mathbf{X}) - g(\theta)]^2 \right\} \geq \frac{[\psi'(\theta)]^2}{I_{\mathbf{X}}(\theta)}$$

- Note
 - $\psi(\theta) = \mathbb{E}\{T(\mathbf{X})\} - g(\theta) + g(\theta) = b(\theta) + g(\theta)$
 - Information inequality gives lower bound on MSE of the estimate of $g(\theta)$

Information inequality

- Proof: We show the following relationships step by step

$$(A) \quad \mathbb{E} \{T(\mathbf{X})V(\mathbf{X}, \theta)\} = \psi'(\theta)$$

$$(B) \quad \mathbb{E} \{g(\theta)V(\mathbf{X}, \theta)\} = 0$$

$$(C) \quad \mathbb{E} \{[T(\mathbf{X}) - g(\theta)] V(\mathbf{X}, \theta)\} = \psi'(\theta)$$

$$(D) \quad \mathbb{E} \left\{ [T(\mathbf{X}) - g(\theta)]^2 \right\} \mathbb{E} \{V^2(\mathbf{X}, \theta)\} \geq [\psi'(\theta)]^2$$

$$\mathbb{E} \left\{ [T(\mathbf{X}) - g(\theta)]^2 \right\} \geq \frac{[\psi'(\theta)]^2}{I_{\mathbf{X}}(\theta)}$$

Information inequality

- Proof of (A)

$$\mathbb{E} \{T(X)V(X, \theta)\} = \int \cdots \int T(\mathbf{x})V(\mathbf{x}, \theta)f(\mathbf{x}|\theta)d\mathbf{x}$$

Using the relationship

$$V(\mathbf{x}, \theta) = \frac{\partial}{\partial \theta} \ln f(\mathbf{x}|\theta) = \frac{f'(\mathbf{x}|\theta)}{f(\mathbf{x}|\theta)}$$

we have

$$\begin{aligned}\mathbb{E} \{T(\mathbf{X})V(\mathbf{X}, \theta)\} &= \int \cdots \int T(\mathbf{x}) \frac{\partial}{\partial \theta} f(\mathbf{x}|\theta)d\mathbf{x} \\ &= \frac{\partial}{\partial \theta} \int \cdots \int T(\mathbf{x}) f(\mathbf{x}|\theta)d\mathbf{x} \\ &= \frac{\partial}{\partial \theta} \mathbb{E} \{T(\mathbf{X})\}\end{aligned}$$

i.e., $\mathbb{E} \{T(\mathbf{X})V(\mathbf{X}, \theta)\} = \psi'(\theta)$

Information inequality

- Proof of (B)

$$\mathbb{E} \{g(\theta)V(\mathbf{X}, \theta)\} = g(\theta)\mathbb{E} \{V(\mathbf{X}, \theta)\} = 0$$

where the second equality is due to

$$\begin{aligned}\mathbb{E} \{V(\mathbf{X}, \theta)\} &= \mathbb{E} \left\{ \frac{\partial}{\partial \theta} \ln f(\mathbf{X}|\theta) \right\} \\ &= \int \cdots \int \frac{f'(\mathbf{x}|\theta)}{f(\mathbf{x}|\theta)} f(\mathbf{x}|\theta) d\mathbf{x} \\ &= \frac{\partial}{\partial \theta} \underbrace{\int \cdots \int f(\mathbf{x}|\theta) d\mathbf{x}}_1 \\ &= 0\end{aligned}$$

Information inequality

- Proof of (C)

(A) – (B) gives $\mathbb{E} \{ [T(\mathbf{X}) - g(\theta)] V(\mathbf{X}, \theta) \} = \psi'(\theta)$

Information inequality

- Proof of (D)

We use the Cauchy-Schwarz inequality

$$\left[\int a(z)b(z)dz \right]^2 \leq \left[\int a(z)^2 dz \right] \left[\int b(z)^2 dz \right]$$

where equality holds if and only if $b(z) = c a(z)$. Following this inequality, we have

$$\mathbb{E}^2\{XY\} \leq \mathbb{E}\{X^2\}\mathbb{E}\{Y^2\}$$

where equality holds if and only if $Y = c X$. Therefore,

$$\mathbb{E} \left\{ [T(\mathbf{X}) - g(\theta)]^2 \right\} \mathbb{E} \{ V^2(\mathbf{X}, \theta) \} \geq \mathbb{E}^2 \{ [T(\mathbf{X}) - g(\theta)] V(\mathbf{X}, \theta) \} = [\psi'(\theta)]^2$$

i.e.,

$$\mathbb{E} \left\{ [T(\mathbf{X}) - g(\theta)]^2 \right\} \geq \frac{[\psi'(\theta)]^2}{I_{\mathbf{X}}(\theta)}$$

Equality in information inequality

- Corollary: equality in the information equality holds if and only if

$$V(\mathbf{X}, \theta) = k(\theta) [T(\mathbf{X}) - g(\theta)], \quad \forall \theta \in \Theta$$

- Note: $k(\theta)$ is a constant with respect to \mathbf{x} , but can be a function of θ

Information inequality for unbiased estimator

- Corollary: If $T(\mathbf{X})$ is unbiased estimator of $g(\theta)$, then

$$\mathbb{V}\{T(\mathbf{X})\} \geq \frac{[g'(\theta)]^2}{I_{\mathbf{X}}(\theta)}$$

- Proof: The result follows directly from information inequality

- Corollary: If $T(\mathbf{X})$ is unbiased estimator of θ , then

$$\mathbb{V}\{T(\mathbf{X})\} \geq \frac{1}{I_{\mathbf{X}}(\theta)}$$

- Proof: The result follows directly from information inequality

Independent samples

- Corollary: For n stationary independent samples, the lower bound goes to zero as $1/n$
- Proof: Stationary X_i are identically distributed. Recall that for X_1, X_2, \dots, X_n that are i.i.d.,

$$I_{\mathbf{X}}(\theta) = nI_X(\theta)$$

Therefore,

$$\mathbb{E} [T(\mathbf{X}) - g(\theta)]^2 \geq \frac{1}{n} \frac{[\psi'(\theta)]^2}{I_X(\theta)}$$

Other forms for Fisher information

- Fisher information can be expressed as

$$\begin{aligned} I_{\mathbf{X}}(\theta) &= \mathbb{E} \{ V^2(\mathbf{X}, \theta) \} \\ &= \mathbb{V} \{ V(\mathbf{X}, \theta) \} \\ &= -\mathbb{E} \left\{ \frac{\partial^2}{\partial \theta^2} \ln f(\mathbf{X}|\theta) \right\} \end{aligned}$$

- Proof: First

$$\begin{aligned} \underbrace{\mathbb{E} \{ V(X, \theta) \}}_{=0} &= \mathbb{E} \left\{ \frac{\partial}{\partial \theta} \ln f(\mathbf{x}|\theta) \right\} \\ &= \int \cdots \int \frac{\partial}{\partial \theta} \ln f(\mathbf{x}|\theta) f(\mathbf{x}|\theta) d\mathbf{x} \end{aligned}$$

Other forms for Fisher information

- Take $\frac{\partial}{\partial\theta}$ for both sides, we have

$$\begin{aligned} 0 &= \int \cdots \int \frac{\partial^2}{\partial\theta^2} \ln f(\mathbf{x}|\theta) f(\mathbf{x}|\theta) d\mathbf{x} + \int \cdots \int \frac{\partial}{\partial\theta} \ln f(\mathbf{x}|\theta) \frac{\partial}{\partial\theta} f(\mathbf{x}|\theta) d\mathbf{x} \\ &= \mathbb{E} \left\{ \frac{\partial^2}{\partial\theta^2} \ln f(\mathbf{x}|\theta) \right\} + \underbrace{\mathbb{E} \left\{ V^2(\mathbf{X}, \theta) \right\}}_{=I_{\mathbf{X}}(\theta)} \end{aligned}$$

Therefore,

$$I_{\mathbf{X}}(\theta) = -\mathbb{E} \left\{ \frac{\partial^2}{\partial\theta^2} \ln f(\mathbf{x}|\theta) \right\}$$

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EXAMPLES ON INFORMATION INEQUALITY

Example 1

- The iid Gaussian case: Let X_1, X_2, \dots, X_n be iid $N(0, \sigma^2)$
Recall that MLE of σ^2 is given by $T_{\text{ML}}(\mathbf{X}) = \frac{1}{n} \sum_{i=1}^n X_i^2$

$$\mathbb{E}\{T_{\text{ML}}(\mathbf{X})\} = \frac{1}{n} \sum_{i=1}^n \mathbb{E}\{X_i^2\} = \sigma^2$$

and

$$\begin{aligned}\mathbb{V}\{T_{\text{ML}}(\mathbf{X})\} &= \frac{1}{n^2} \sum_{i=1}^n \mathbb{V}\{X_i^2\} \\ &= \frac{1}{n^2} \sum_{i=1}^n \sigma^4 \mathbb{V}\{Y_i\} \\ &= \frac{2\sigma^4}{n}\end{aligned}$$

where $Y_i = X_i^2 / \sigma^2$ has gamma distribution with one degree of freedom

Example 1

- Let's look at the information inequality. We saw that

$$I_X(\sigma^2) = \frac{1}{4\sigma^4}(\alpha^4 - 1) = \frac{1}{2\sigma^4}$$

where

$$\alpha^4 = \frac{1}{\sigma^4} \underbrace{\mathbb{E}\{(x - \mu)^4\}}_{=3\sigma^4} = 3$$

- For any unbiased estimator $T(\mathbf{X})$ for σ^2 , we know from CRLB:

$$\begin{aligned}\mathbb{E}\{T(\mathbf{X}) - \sigma^2\} &\geq \frac{1}{I_X(\sigma^2)} \\ &= \frac{1}{nI_X(\theta)} \\ &= \frac{2\sigma^4}{n}\end{aligned}$$

Therefore, MLE achieves the lower bound in this case

Example 1

- Conversely: Let $T(\mathbf{X})$ be any estimator that achieves information inequality
- Let's analyze the equality condition

$$k(\sigma^2) [T(\mathbf{x}) - \sigma^2] = V(\mathbf{x}, \theta)$$

$$V(\mathbf{x}, \sigma^2) = \frac{\partial}{\partial \sigma^2} \ln f(\mathbf{x} | \sigma^2) = \frac{1}{2\sigma^4} \sum_{i=1}^n x_i - \frac{n}{2\sigma^2}$$

Therefore,

$$k(\sigma^2) [T(\mathbf{x}) - \sigma^2] = \frac{n}{2\sigma^4} \left[\frac{1}{n} \sum_{i=1}^n x_i^2 - \sigma^2 \right]$$

Thus, $T(\mathbf{X}) = \frac{1}{n} \sum_{i=1}^n X_i^2$ and $k(\sigma^2) = \frac{n}{2\sigma^4}$

- Therefore, $T(\mathbf{X})$ that satisfies the equality condition is MLE of σ^2

Example 2

- The iid exponential case: Let X_1, X_2, \dots, X_n be iid random variables with

$$f(x|\lambda) = \begin{cases} \frac{1}{\lambda} e^{-\frac{x}{\lambda}} & x \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

We also have $\mathbb{E}\{X\} = \lambda$ and $\mathbb{V}\{X\} = \lambda^2$

- Recall that MLE of λ is given by $T_{\text{ML}}(\mathbf{X}) = \frac{1}{n} \sum_{i=1}^n X_i$
 $\mathbb{E}\{T_{\text{ML}}(\mathbf{X})\} = \lambda$ and $\mathbb{V}\{T_{\text{ML}}(\mathbf{X})\} = \frac{\lambda^2}{n}$

Example 2

- Let's look at the information inequality. The score function is

$$\begin{aligned}V(x, \theta) &= \frac{\partial}{\partial \theta} \ln f(x|\lambda) \\&= \frac{\partial}{\partial \lambda} \left(-\ln \lambda - \frac{x}{\lambda} \right) \\&= -\frac{1}{\lambda} + \frac{x}{\lambda^2} \\&= \frac{1}{\lambda^2}(x - \lambda)\end{aligned}$$

and the Fisher information is

$$I_X(\theta) = \frac{1}{\lambda^4} \mathbb{E} \{(x - \lambda)^2\} = \frac{1}{\lambda^2}$$

Therefore, information inequality is $\mathbb{V}\{T(\mathbf{X})\} \geq \frac{\lambda^2}{n}$

We see that MLE achieves the lower bound in this example

Example 2

- Conversely, let $T(\mathbf{X})$ be any estimator that achieves information inequality. What can we say about $T(\mathbf{X})$?
- The equality condition is

$$k(\lambda) [T(\mathbf{x}) - \lambda] = V(\mathbf{x}, \theta)$$

where $V(\mathbf{x}, \theta) = \frac{1}{\lambda^2} [\sum_{i=1}^n x_i - n\lambda]$.
Therefore,

$$k(\lambda) [T(\mathbf{x}) - \lambda] = \frac{n}{\lambda^2} \left[\frac{1}{n} \sum_{i=1}^n x_i - \lambda \right]$$

Thus $T(\mathbf{X}) = \frac{1}{n} \sum_{i=1}^n X_i$ and $k(\lambda) = \frac{n}{\lambda^2}$

- Therefore, $T(\mathbf{X})$ that satisfies equality condition is MLE of λ

MLE and information inequality

- Corollary: If an estimator $T(\mathbf{X})$ for θ satisfies the condition for equality in the information inequality, then $T(\mathbf{X})$ is a MLE of θ i.e., $\hat{\theta}_{\text{ML}} = T(\mathbf{X})$
- Proof: For the maximum likelihood estimate $\hat{\theta}_{\text{ML}}$, we have

$$V(\mathbf{x}, \theta)|_{\theta=\hat{\theta}_{\text{ML}}} = \frac{\partial}{\partial \theta} \ln f(\mathbf{x}|\theta) \Big|_{\theta=\hat{\theta}_{\text{ML}}} = 0$$

Since $T(\mathbf{X})$ achieves equality,

$$k(\theta) [T(\mathbf{X}) - \theta]|_{\theta=\hat{\theta}_{\text{ML}}} = V(\mathbf{X}, \theta)|_{\theta=\hat{\theta}_{\text{ML}}} = 0$$

Therefore, $\hat{\theta}_{\text{ML}} = T(\mathbf{X})$

Example 4

- The iid uniform case: Let X_1, X_2, \dots, X_n be iid random variables with pdf

$$f(x|\theta) = \begin{cases} \frac{1}{\theta}, & 0 \leq x \leq \theta \\ 0, & \text{otherwise} \end{cases}$$

Recall that $Y_n = \max \{X_1, \dots, X_n\}$ is a MLE of θ , and

$$\mathbb{E}\{Y_n\} = \frac{n}{n+1}\theta$$

i.e., Y_n is biased. An unbiased estimator for θ is given by

$$T_1(\mathbf{X}) = \frac{n+1}{n} \max \{X_1, \dots, X_n\}$$

Another unbiased estimator for θ is

$$T_2(\mathbf{X}) = \frac{2}{n} \sum_{i=1}^n X_i$$

Example 4

- One can verify that

$$\mathbb{V}\{T_1(\mathbf{X})\} = \frac{1}{n(n+2)}\theta^2$$

$$\begin{aligned}\mathbb{V}\{T_2(\mathbf{X})\} &= \frac{4}{n}\mathbb{V}\{X_i\} \\ &= \frac{4}{n} \frac{\theta^2}{12} \\ &= \frac{\theta^2}{3n}\end{aligned}$$

Example 4

- The score function is

$$\begin{aligned} V(x, \theta) &= \frac{\partial}{\partial \theta} \ln f(x|\theta) \\ &= \frac{\partial}{\partial \theta} (-\ln \theta) \\ &= \frac{1}{\theta} \end{aligned}$$

and Fisher information is

$$I_X(\theta) = \mathbb{V} \left\{ \left(\frac{1}{\theta} \right)^2 \right\} = \frac{1}{\theta^2}$$

We find that $T_1(\mathbf{X})$ and $T_2(\mathbf{X})$ both beats “CRLB”. The reason is regularity conditions are not satisfied, i.e., the support of $f(x|\theta)$ depends on θ