

# ARIMA model

## I. AR model description

Model  $AR(p)$  is given by a following expression

$$y_t = c + \varphi_1 y_{t-1} + \varphi_2 y_{t-2} + \dots + \varphi_p y_{t-p} + \varepsilon_t,$$

where:

- $y_t$  – value of TS @ time  $t$ ;
- $C$  – constant term to be determined;
- $\varphi_t$  – parameters of the model;
- $\varepsilon_t$  – model error term at time  $t$ , a.k.a. noise term.

Assumptions and limitations:

1.  $\mathbb{E}(y_t) = 0 \ \forall t$ ;
2.  $\text{Var}(y_t) = \text{const} = \sigma^2 \ \forall t$ ;
3.  $\text{Cov}(\varepsilon_t, \varepsilon_s) = 0 \ \forall t \neq s$ ;
4.  $\varepsilon_t \sim \mathcal{N}(0, \sigma^2)$

Key features:

1. Interpretability
2.  $AR(p)$  can be applied to stationary TS;
  - 2.1. Influence of previous values fades over time;
3. ACF: autocorrelation function decays over time;
4. PACF: partial autocorrelation function breaks off after lag  $p$ , hence it can be used to find optimal  $p$ .

## Training AR model

1. OLS

$$\sum_t \varepsilon_t^2 = \sum_t (y_t - c - \varphi_1 y_{t-1} - \dots - \varphi_p y_{t-p})^2 \rightarrow \min_{c, \varphi_i}$$

2. MLE

Given that  $Y = (y_1, \dots, y_n)$ :

$$L(\theta \mid y) \approx \prod_{t=p+1}^n f(y_t \mid y_{t-1}, \dots, y_{t-p}, \theta).$$

Considering that  $y_t \mid y_{t-1}, \dots, y_{t-p} \sim \mathcal{N}(c + \sum_{i=1}^p \varphi_i y_{t-i}, \sigma^2)$ ,

$$L(\theta \mid y) = \prod_{i=p+1}^n \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{1}{2}\left(y_t - c - \sum_{i=1}^p \varphi_i y_{t-i}\right)^2\right) \rightarrow \max_{\theta}.$$

## II. MA(q) model description

$$y_t = \mu + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_q$$

where:

- $\theta_i$  – model parameters;
- $\varepsilon_i$  – time series error terms at time  $i$ ;
- $\mu$  – configurable constant term;

Key features:

1. Interpretability;
2. Always stationary;
3. ACF: breaks off after lag  $q$ , hence used to determine the optimal  $q$  value;
4. PACF: decays gradually;

## Training MA model

Let us assume that  $\varepsilon_i = 0$ ,  $i = 0, \dots, q + 1$ . Then

1. Conditional LS. Denoting  $\theta = \{\theta_1, \dots, \theta_q\}$  we get the following:

$$\sum_{t=1}^n \varepsilon_t^2 = \sum_t \left( y_t - \mu - \sum_{i=1}^q \varepsilon_{t-i} \theta_i \right)^2 \rightarrow \min_{\mu, \theta}$$

2. MLE. Denoting  $Y = (y_1, \dots, y_n)$ , we get

$$L(\theta \mid y) \approx \prod_{t=p+1}^n f(y_t \mid \varepsilon_{t-1}, \dots, \varepsilon_{t-q}, \theta)$$

## ARMA(p, q) model description

$$y_t = c + \varphi_1 y_{t-1} + \dots + \varphi_p y_{t-p} + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q}$$

here  $p$  is defined as the first zero of PACF and  $q$  as the first zero of ACF

## ARIMA(p, q, d) model description

ARIMA is an ARMA model fit to  $\Delta^d y_t$ :

$$\begin{aligned}\Delta y_t &= y_t - y_{t-1} = (1 - L)y_t, \quad Ly_t = y_{t-1} \\ \Delta^2 y_t &= \Delta(y_t - y_{t-1}) = y_t - 2y_{t-1} + y_{t-2} = (1 - L)^2 y_t \\ \Delta^d y_t &= (1 - L)^d y_t.\end{aligned}$$

Thus:

$$\begin{aligned}y_t &= c + \varphi_1 y_{t-1} + \dots + \varphi_p y_{t-p} + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q} \\ (1 - \varphi_1 L - \dots - \varphi_p L^p) y_t &= \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q} \\ \left(1 - \sum_{i=1}^p \varphi_i L^i\right) \Delta^d y_t &= c + \varepsilon_t + \sum_{i=1}^q \theta_i \varepsilon_{t-i} \\ \left(1 - \sum_{i=1}^p \varphi_i L^i\right) (1 - L)^d y_t &= c + \varepsilon_t + \sum_{i=1}^q \theta_i \varepsilon_{t-i}\end{aligned}$$

## ARIMA model usage

Training:

1.  $Y = (y_1, \dots, y_n)$
2. Find  $z_j^{(m)}$  terms (todo: find out how they are called)

$$z_j^{(m)} = [y_{j-m+1}, \dots, y_{j-1}, y_j] \rightarrow Z^m = \begin{pmatrix} z_m^{(m)} \\ z_{m+1}^{(m)} \\ \vdots \\ z_n^{(m)} \end{pmatrix}, Z^m \in \mathbb{R}^{n-m+1 \times m}.$$

Inference:

$$3. \hat{z}_{n+1}^{(m)} = [y_{n-m+2}, \dots, y_n, \hat{y}_{n+1}]$$

$$\tilde{z}_{n+1}^{(m)} = z_{n+1}^{(m)}[:, -1] = [y_{n-m+2}, \dots, y_n]$$

4. Collect a set of possible predictions:

$$S_{n+1} = \left\{ z_i^{(m)}[m] \mid \|\tilde{z}_i^{(m)} - \tilde{z}_{n+1}\| < \varepsilon \right\}.$$

5. Choose single prediction:

- $\hat{y}_{n+1} = \text{mean}(S_{n+1})$
- $\hat{y}_{n+1} = \text{mode}(S_{n+1})$
- $\text{Cusler}(S_{n+1}) \xrightarrow{\text{cluster}} \{C_1, \dots, C_k\}$

$$\hat{y}_{n+1} = \text{mean}(C_i), \quad i = \text{argmax}_j |C_j|.$$

Multistep ahead prediction:  $\tilde{z}_{n+2}^{(m)} = [y_{n-m+3}, \dots, y_n, \hat{y}_{n+1}]$ .

2\*.  $Z^m \xrightarrow{\text{cluster}} C_1, \dots, C_k$  clusters of  $z^{(m)}$  vectors

$$X^m = \begin{pmatrix} \xi_1^{(m)} \\ \vdots \\ \xi_k^{(m)} \end{pmatrix}, \quad \xi_i = \text{"central element"}$$

$$3^*. \tilde{z}_{n+1}^{(m)} = [y_{n-m+2}, \dots, y_n]$$

$$4^*. S_n = \left\{ \xi_i^{(m)}[m] \mid \|\tilde{\xi}_i^{(m)} - \tilde{z}_{n+1}^{(m)}\| < \varepsilon \right\}$$

Let us modify the algorithm:

$$1. Y = (y_1, \dots, y_n)$$

2. Given  $K, L$  : generate patterns (rus. *шаблоны*). For example:

$$K = 10, L = 4 : A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 2 \\ \vdots & \vdots & \vdots & \vdots \\ 10 & 10 & 10 & 10 \end{pmatrix}$$

$$z_i^{(10,10,10,10)} = [y_{i-40}, \dots, y_{i-10}, y_i]$$

Note that in this example  $A$  can have only elements with values from 1 to 10.

3.  $\forall \alpha \in A : \alpha = (K_1, \dots, K_L), K_i \in \overline{1, \dots, K}$

$$z_i^* = [y_{i-K_L-K_{L-1}-\dots-K_1}, \dots, y_{i-K_L-K_{L-1}}, y_{i-K_L}, y_i]$$

$$\text{Generate } Z^\alpha = \begin{pmatrix} z_{K_m-K_L}^\alpha \\ z_{K_m-K_{L+1}}^\alpha \\ \vdots \\ z_n^\alpha \end{pmatrix} \forall \alpha \in A$$

4.  $\forall \alpha \in A :$

$$\tilde{z}_{n+1}^\alpha = [y_{n+1-K_L-K_{L-1}-\dots}, \dots, y_{n+1-K_L}]$$

5.  $\forall \alpha \in A$

$$S_{n+1}^\alpha = \{z_i^\alpha[i+1] \mid ||\tilde{z}_i^\alpha - \tilde{z}_{n+1}^\alpha||\}$$

$$S_{n+1} = \cup_\alpha S_{n+1}^\alpha$$

6. Classify point the point as predictable or not prediactable.

6.1 Cluster  $S_{n+1} \rightarrow C_1, \dots, C_l, C_0$ , where  $C_0$  is a noise cluster and  $C_i, i = \overline{1, \dots, l}$  are sorted by size from largest ( $C_1$ ) to smallest ( $C_l$ ).

$$\eta_1 = \frac{|C_1|}{|C_2|} \gg 1 \rightarrow \text{goto 6.2}$$

$$\eta_2 = \frac{|C_1|}{\sum_{i=1}^l |C_i|} > \varepsilon_1 \rightarrow \text{goto 6.2}$$

6.2 Estimate the variance of cluster  $C_1$ . If  $\text{Var}(C_1) < \varepsilon_1 \rightarrow \text{goto 7}$ , if  $\text{IQR}(C_1) < \varepsilon_2 \rightarrow \text{goto 7}$

6.3 Identify the point as non-predictable and move to the next point.

7. Obtain single prediction.

example on the photo (what do we do if a value is skipped)

## Self-healing algorithms

1. Forecast  $h$  steps ahead.
2. Run self-healing until convergence or max iteration is reached.
3. Move to step 1.