

posterior

$$\pi_1(\theta|x_1)$$

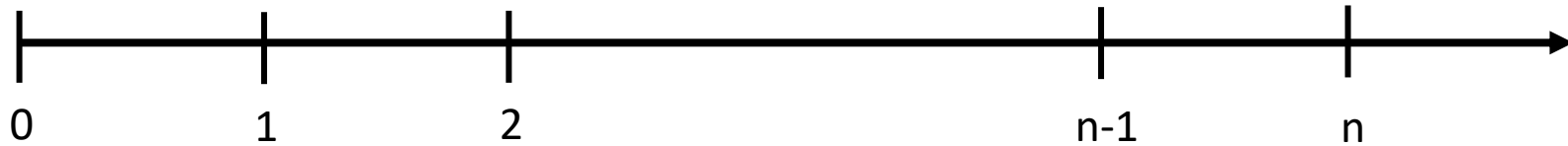
prior

$$\pi_0(\theta)$$

data

$$x_1$$

timeline



posterior

$$\pi_1(\theta|x_1)$$

$$\pi_2(\theta|x_{1:2})$$

prior

$$\pi_0(\theta)$$

$$\pi_1(\theta|x_1)$$

data

$x_1$

$x_2$

timeline

