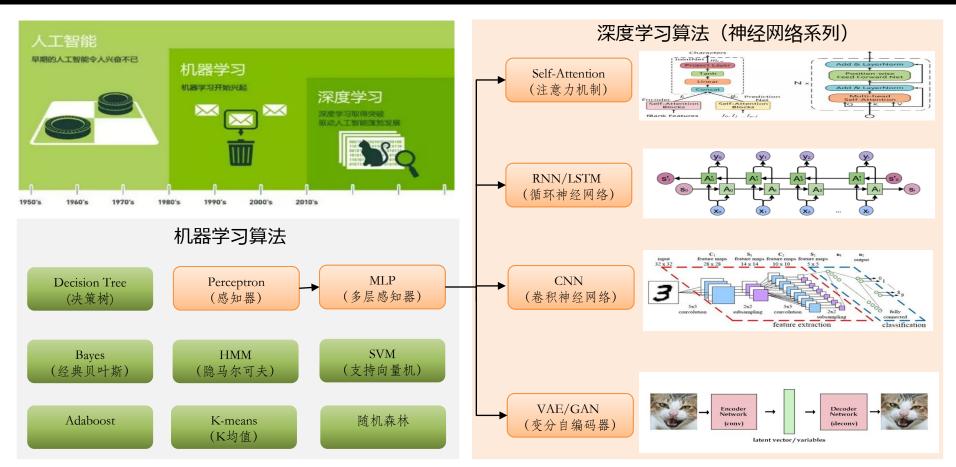


Deep Learning Introduction

CSC Wuxi SDD2-2 Andy Zhou, Cao Fei 2021/08/31







1957年美国神经学家Frank根据大脑神经元的工作原理提出了感知器模型,最简单的前馈式神经网络诞生

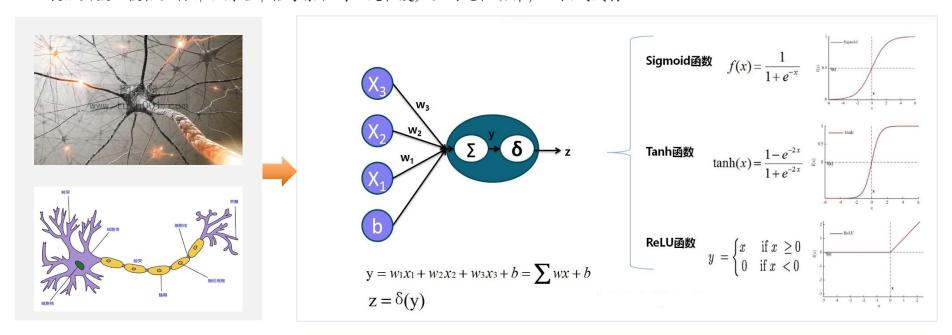
#1 X 输入: 模拟来神经网络中来自其他神经元的输入

#2 W权重:模拟每个神经元接收突触强度的不同,所以对于外界输入剩以一定的权重

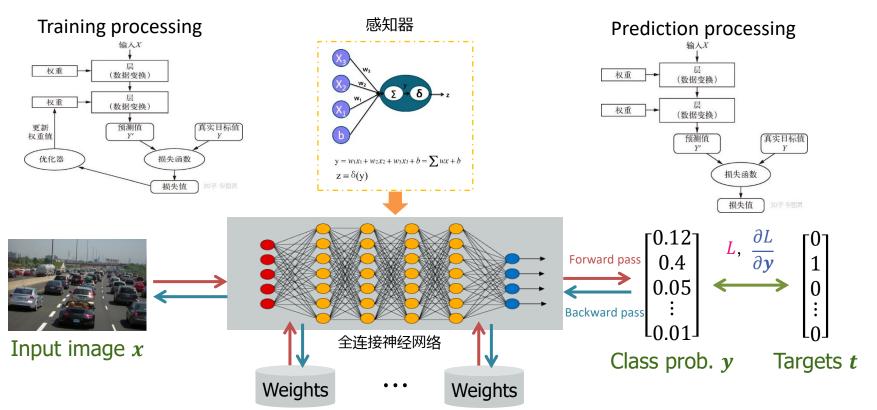
#3 b偏置:模拟每个神经元的一般敏感性,每个神经元的敏感性不同,需要一定的偏差来调整

#4 求和: 模拟生物神经网络对外界接收信号的汇总

#5 激活函数:模拟生物神经网络中信号累积到一定程度产生的电位动作,加强或减弱

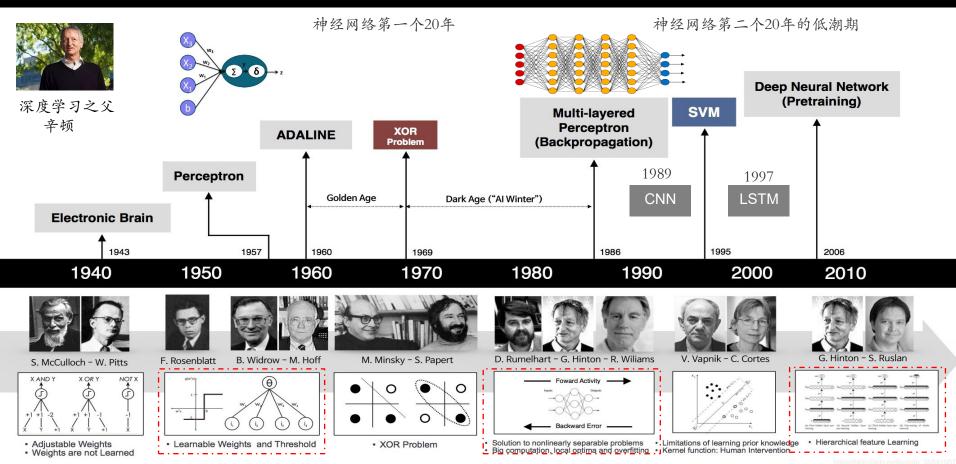


1986年,辛顿等提出了多层感知器模型,以及反馈网络的训练方法,也称BP神经网络,神经网络训练算法开始诞生并采用了sigmoid函数作为激活函数



深度学习发展的关键事件





Software Design Division

运算能力



运算能力的大幅度 提升 GPU/TPU





互联网大数据



互联网时代 创造大数据

#1 Imagenet 140万的图像标注数据集, 1000个类别

#2 维基百科是训练自然语言处理的数据宝库

#3 YouTube 视频也是一座宝库

训练算法改进



新的训练方法解决深度网络训练不成功的问题

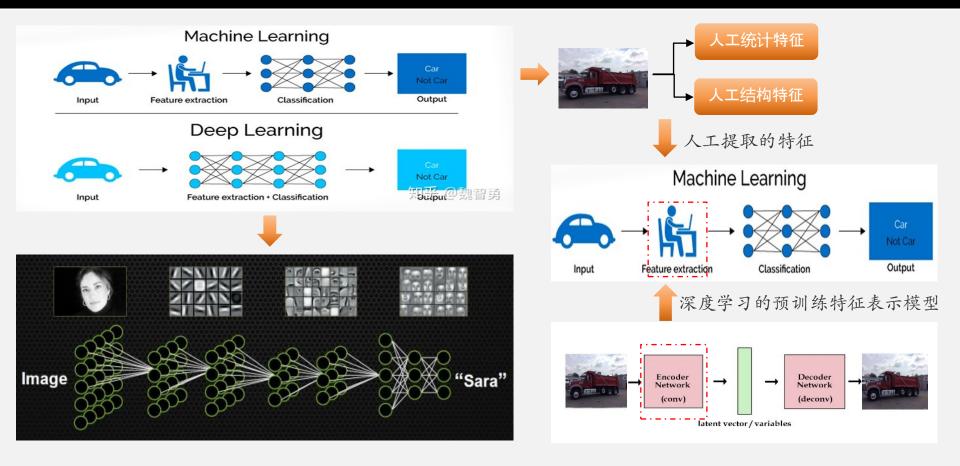
#1 2006年,辛顿提出权重初始化方案解决深度 网络梯度消失问题(无监督初始化权重)

#2 2011年,辛顿首次使用ReLU激活函数, 有效的抑制梯度消失问题

#3 2012年, 微软首次应用DL进行语音识别, 获得重大突破

#4 2016年的阿尔法go,深度学习进入大众视野





#监督学习: 大多数的机器学习算法 + 几乎所有的深度学习算法

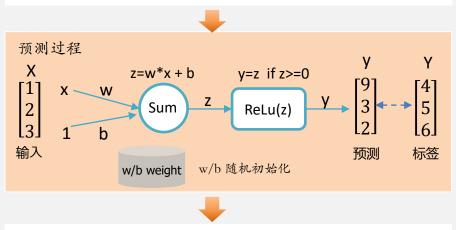
#无监督学习: K-means



#目前,比较成熟的应用主要集中在3大领域,计算机视觉、语音工程和NLP



给定一些X=[1,2,3] Y=[4,5,6] 训练一个线性传感器神经网络



如何训练网络更新权重,使得预测值y与目标标签的误差减少?



训练过程:采用梯度下降法来训练和更新参数,先构建代价或损失函数,代价函数有很多中,但必须是凸函数

$$LossFun = (y - Y)^2/2$$

问题转化为求LossFun的极小点问题,所以沿着导数反方向更新权重则可以逼近极值点

深度学习的本质就是通过损失函数的误差反向传播来更新网络的权重参数,采用梯度下降法来实现此过程



$$z = w * x + b$$

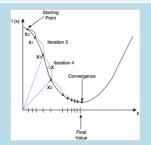
$$\frac{\partial L}{\partial w} = \frac{\partial L}{\partial y} * \frac{\partial y}{\partial z} * \frac{\partial z}{\partial w} = (y - Y) * x$$

$$y = z$$

$$LossFun = \frac{1}{2}(y - Y)^{2}$$

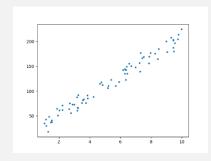
$$\frac{\partial L}{\partial b} = \frac{\partial L}{\partial y} * \frac{\partial y}{\partial z} * \frac{\partial z}{\partial b} = (y - Y)$$

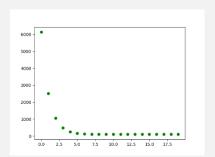
$$w=w-\alpha*(y-Y)*x$$
$$b=b-\alpha*(y-Y)$$



α是学习率,属于超参数,优化 训练效果,防止进入局部最优

```
def init (self, learning rate=0.01, max iter=100, seed=None):
   np.random.seed(seed)
   self.lr = learning rate
   self.max iter = max iter
   self.w = np.random.normal(1, 0.1)
   self.b = np.random.normal(1, 0.1)
   self.loss arr = []
def fit(self, x, v):
    self.x = x
    self.v = v
    print(40*'=')
    print('max iter=',self.max iter)
    for i in range(self.max iter):
        self. train step(i)
        self.loss arr.append(self.loss())
def loss(self, y true=None, y pred=None):
   if y true is None or y pred is None:
       y true = self.y
       y pred = self.predict(self.x)
   return np.mean((y true - y pred) **2)
def f(self, x, w, b):
    return x * w + b
def predict(self, x=None):
    if x is None:
        x = self.x
    y pred = self. f(x, self.w, self.b)
    return y pred
```





```
z = w * x + b
y = z
LossFun = \frac{1}{2}(y - Y)^{2}
\frac{\partial L}{\partial b} = \frac{\partial L}{\partial y} * \frac{\partial y}{\partial z} * \frac{\partial z}{\partial w} = (y - Y) * x
\frac{\partial L}{\partial b} = \frac{\partial L}{\partial y} * \frac{\partial y}{\partial z} * \frac{\partial z}{\partial b} = (y - Y)
w \leftarrow w - \alpha \frac{\partial L}{\partial w}
b \leftarrow b - \alpha \frac{\partial L}{\partial w}
b = b - \alpha * (y - Y)
b = b - \alpha * (y - Y)
```

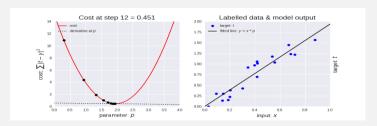
```
def _train_step(self,index):
    d_w, d_b = self._calc_gradient()
    self.w = self.w - self.lr * d_w
    self.b = self.b - self.lr * d_b
    return self.w, self.b
```

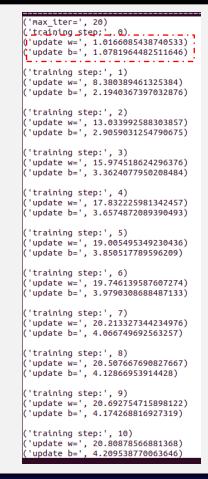
def _calc_gradient(self):
 d_w = np.mean((self.x * self.w + self.b - self.y) * self.x)
 d_b = np.mean(self.x * self.w + self.b - self.y)
 return d_w, d_b

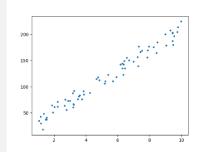
深度学习-线性回归的python代码实现过程打印

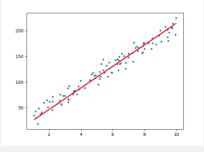
```
Firefox 网络浏览器 V([8.44340561, 7.87504622, 6.16401141, 3.22948482, 9.74028186, 1.93090899, 7.94965088, 1.53388415, 6.3675922 ,
      3.7540866 , 9.78171215, 2.88741486, 1.17483877, 7.85282943,
      1.53388668, 6.40979505, 7.53056809, 3.54680345, 5.91926314,
      2.65275974, 9.55238812, 3.85023415, 3.18006603, 9.43819064,
      3.87154281, 1.35479553, 3.21811252, 5.39565557, 2.69809158,
      2.77558845, 8.26495323, 3.25266916, 6.29276673, 3.48792901,
      3.61807215, 9.9880322, 4.66348509, 5.21980683, 7.27448618,
      9.48460207, 1.04624586, 4.24228745, 4.7533448 , 8.98995125,
      2.21697786. 7.24899019. 6.56105895. 8.48405352. 7.41953419.
      2.02123466. 4.84655189. 6.34184487. 5.70244546. 1.28426277.
      5.18814828. 2.22014269. 6.99344605. 6.29956213. 6.44082128.
      6.71627606, 9.44108164, 3.00154469, 9.29960965, 9.43826648,
      3.19788601, 1.46440793, 1.86626583, 1.15467664, 9.04862078]))
('v train=', arrav([164.73407324, 169.51999592, 142.12652646, 65.51657475,
      204.14393052, 176.67516972, 51.01576161, 176.53183029,
       40.9823875 , 142.17970458, 76.03776255, 213.79969288,
       72.82853888, 30.27234335, 155.85468932, 37.60390904,
      148.9399438 , 168.56871208, 81.87202055, 118.63195312,
       63.97333433, 196.45047117, 91.5249247, 87.69429952,
      203.25074828, 85.45662878, 48.29643605, 66.90170955,
      122.76863036, 75.63252695, 55.59511534, 175.47187277,
      91.79586416, 134.85666162, 75.94348705, 83.35553782,
      224.46660574, 114.52708478, 110.39994274, 139.11808577,
      180.12131644, 34.6720626 , 88.2381613 , 118.06845207,
      199.92900887, 62.13748758, 156.37119427, 155.48197233,
      185.09056976, 166.20522842, 61.24036406, 112.18434645,
      122.56688228, 110.59635443, 18.11278399, 106.48057764,
      71.21639458, 148.04676026, 144.19303394, 134.99218941,
      150.29405312, 187.44241492, 73.21964224, 207.56966906,
      202.10856943, 60.92396975, 37.15381523, 64.25305999,
       42.99987739, 178.741762381))
```

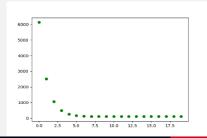
cost: 1.04e+02 w: 21.0 b: 4.41

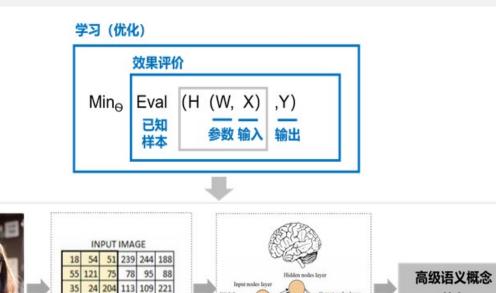












3 154 104 235 25 130 15 253 225 159 78 233

68 85 180 214 245



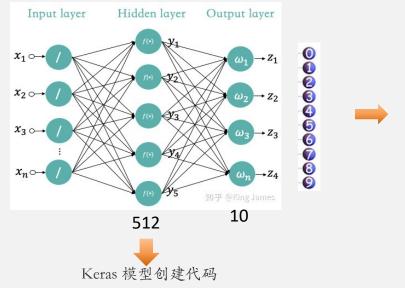
任何深度神经网络模型,都可以用一个f(x) 去表示,都是一个链式嵌套函数,区别在于 每一层嵌套函数的复杂程度和嵌套函数的 公式不同

所以,无论模型如何变化,训练过程,都是链式求导,迭代更新网络参数的过程,直至训练结束

深度学习的本质就是通过损失函数的误差反向传播来更新网络参数过程,这种学习是对参数的改变来使得预测值进一步的接近目标值的过程。

美女

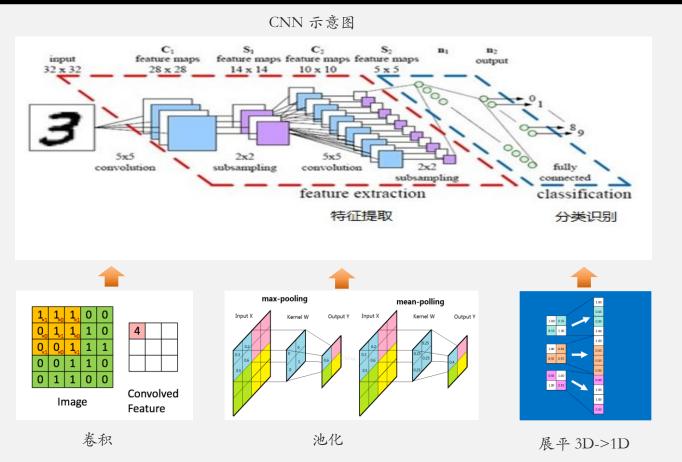
MLP 模型示意图

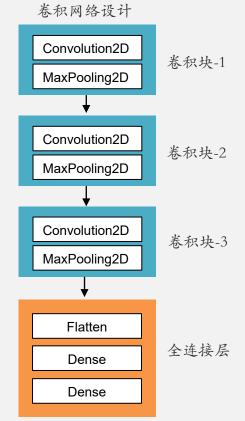


```
def create_model():
    model=models.Sequential()
    model.add(layers.Dense(512,activation='relu',input_shape=(28*28,)))
    model.add(layers.Dense(10,activation='softmax'))
    model.summary()
    model.save('mlp.h5')
    return model
```

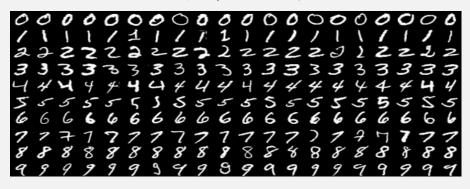
网络参数和训练过程

```
Layer (type)
        Output Shape
               Param #
dense (Dense)
        (None, 512)
               401920
dense 1 (Dense)
        (None, 10)
               5130
Total params: 407,050
Trainable params: 407,050
Non-trainable params: 0
(60000, 784)
(60000, 10)
Epoch 1/10
Epoch 8/10
469/469 [============ ] - 1s 2ms/step - loss: 0.0130 - accuracy: 0.9963
Epoch 10/10
loss= 0.0703979954123497
acc= 0.9810000061988831
(10.)
1.0
```





手写数字训练数据库



CNN模型创建代码

```
def create_model():
    model=models.Sequential()
    model.add(layers.Conv2D(32,(3,3),activation='relu',input_shape=(28,28,1)))
    model.add(layers.MaxPooling2D((2,2)))
    model.add(layers.Conv2D(64,(3,3),activation='relu'))
    model.add(layers.MaxPooling2D((2,2)))
    model.add(layers.Conv2D(64,(3,3),activation='relu'))
    model.add(layers.Flaten()) #3D->1D
    model.add(layers.Dense(64,activation='relu'))
    model.add(layers.Dense(64,activation='relu'))
    model.add(layers.Dense(10,activation='softmax'))
    model.summary()
    model.save('cnn.h5')
    return model
```

模型参数和训练过程

```
Laver (type)
                                Param #
                 Output Shape
conv2d (Conv2D)
                 (None, 26, 26, 32)
                                320
max pooling2d (MaxPooling2D) (None, 13, 13, 32)
conv2d 1 (Conv2D)
                 (None, 11, 11, 64)
                                18496
max pooling2d 1 (MaxPooling2 (None, 5, 5, 64)
                                0
conv2d 2 (Conv2D)
                 (None, 3, 3, 64)
                                36928
flatten (Flatten)
                 (None, 576)
dense (Dense)
                 (None, 64)
                                36928
dense 1 (Dense)
                 (None, 10)
 _________
Total params: 93.322
Trainable params: 93.322
Non-trainable params: 0
(60000, 28, 28, 1)
(60000, 10)
Epoch 1/10
938/938 [================== ] - 8s 8ms/step - loss: 0.1781 - accuracy: 0.9445
938/938 [============= ] - 8s 9ms/step - loss: 0.0201 - accuracy: 0.9939
Epoch 6/10
938/938 [=============== ] - 8s 9ms/step - loss: 0.0128 - accuracy: 0.9961
938/938 [=============== ] - 8s 9ms/step - loss: 0.0113 - accuracy: 0.9966
Epoch 9/10
938/938 [=============== ] - 8s 9ms/step - loss: 0.0085 - accuracy: 0.9975
loss= 0.036258965730667114
acc= 0.9922000169754028
(10,)
```



SONY

Thank You



