

Vectors

P1/6/1: Standard notations for vectors and basic concepts

P1/6/2: Unit vectors, displacement vectors and position vectors

P1/6/3: The scalar product

P1/6/4: The scalar product

P1/6/5: Revision

P1-6 VECTORS

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P1/6/1:

Standard notations for vectors and basic concepts

Learning Outcome

Students should be able to:

- know how to use the standard notations for vectors and carry out addition, subtraction and multiplication of a vector by a scalar.
- interpret these operations in geometrical terms.

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P1/6/2:

Unit vectors, displacement vectors and position vectors

Learning Outcome

Students should be able to:

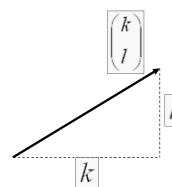
- Define unit vectors, displacement vectors and position vectors
- Use of standard symbols for the vectors
- Locate points or coordinates in a 2 or 3-D diagram on the Cartesian plane.

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Vector Algebra

A general translation of k units across and l units up the grid is called a vector and is written $\begin{pmatrix} k \\ l \end{pmatrix}$



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Vector Algebra

In handwriting vectors are indicated as follow:

Vector $\vec{p} = \begin{pmatrix} k \\ l \end{pmatrix}$ Components of \vec{p} in the x -direction
Components of \vec{p} in the y -direction

In print, bold type is used to distinguish vectors from numbers.

$$\mathbf{p} = \begin{pmatrix} k \\ l \end{pmatrix}$$

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Basic Unit Vectors

A unit vector is a vector of length one unit in a given direction.

$$\mathbf{p} = \begin{pmatrix} k \\ l \end{pmatrix} = k \begin{pmatrix} 1 \\ 0 \end{pmatrix} + l \begin{pmatrix} 0 \\ 1 \end{pmatrix} = k\mathbf{i} + l\mathbf{j}$$

Basic unit vectors in x - directionBasic unit vectors in y - direction

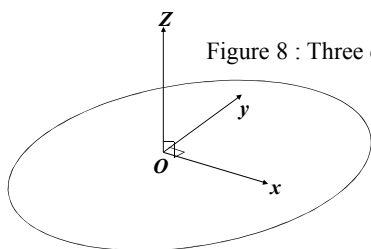
$$\mathbf{i} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \text{ and } \mathbf{j} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

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Vectors in three dimensions

Figure 8 : Three dimensions



The position of a point is given by its three coordinates (x, y, z) .

A vector \mathbf{p} in three dimensions is a translation of the whole of space relative to a fixed coordinate framework.

It is written as $\begin{pmatrix} l \\ m \\ n \end{pmatrix}$ Translation of l , m and n units in the x -, y - and z -directions.

$$\begin{pmatrix} l \\ m \\ n \end{pmatrix} = l\mathbf{i} + m\mathbf{j} + n\mathbf{k}$$

$$\text{where } \mathbf{i} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \mathbf{j} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \mathbf{k} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

are basic unit vectors in the x -, y - and z - directions.

Multiplication of a vector by a scalar

If s is a scalar and $\mathbf{p} = \begin{pmatrix} k \\ l \\ m \end{pmatrix}$, then $s\mathbf{p} = \begin{pmatrix} sk \\ sl \\ sm \end{pmatrix}$

If $s > 0$, the vector $s\mathbf{p}$ is a translation in the same direction as \mathbf{p} but s times as large.

If $s < 0$, it is in the opposite direction $|s|$ times as large.

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(2) Addition of vector

Vector are added by performing one translation after another.

If $\mathbf{p} = \begin{pmatrix} k \\ l \\ m \end{pmatrix}$ and $\mathbf{q} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$, then $\mathbf{p} + \mathbf{q} = \begin{pmatrix} k+x \\ l+y \\ m+z \end{pmatrix}$

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Position Vectors

The position vector of the point A with coordinates (u, v) is

$$\overrightarrow{OA} = \begin{pmatrix} u \\ v \\ w \end{pmatrix} = u\mathbf{i} + v\mathbf{j} + w\mathbf{k}$$

Parallelogram rule of addition for position vectors

The arrows from O to A and from O to B are not related in the way needed for addition.

It is therefore necessary to complete the parallelogram OACB.

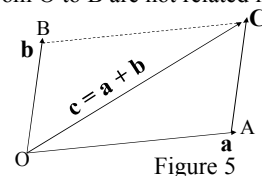
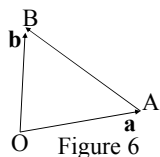


Figure 5

$$\begin{aligned} \overrightarrow{OC} &= \overrightarrow{OA} + \overrightarrow{AC} \\ &= \overrightarrow{OA} + \overrightarrow{OB} \\ &= \mathbf{a} + \mathbf{b} \end{aligned}$$

Subtraction for position vectors

To interpret $\overrightarrow{AB} = \mathbf{b} - \mathbf{a}$ as a position vector:

$$\begin{aligned}\overrightarrow{AB} &= \overrightarrow{AO} + \overrightarrow{OB} \\ &= \overrightarrow{OB} - \overrightarrow{OA} \\ &= \mathbf{b} - \mathbf{a}\end{aligned}$$

Example 1:

Two points A and B have position vectors $\begin{pmatrix} 4 \\ -1 \\ 2 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ 5 \\ 3 \end{pmatrix}$.

C is the point on the line segment AB such that $\frac{AC}{CB} = 2$.

Find

- The vector \overrightarrow{AB} ,
- The vector \overrightarrow{AC} ,
- The position vector of C .

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Parallel vectors

If \mathbf{a} and \mathbf{b} are two parallel vectors they can be represented by

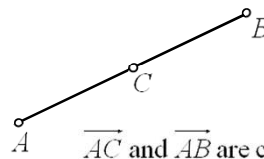
$$\mathbf{a} = k\mathbf{b}$$

where k is constant. k can also be negative.

Collinear vectors

In collinear vectors, all the vectors are on one straight line as shown in the below diagram. If point C lies on the line passing through A and B ,

$$\overrightarrow{AC} = k\overrightarrow{AB}$$



\overrightarrow{AC} and \overrightarrow{AB} are collinear vectors.

Example 2:

If C is the point AB such that $\vec{AC} = t \vec{AB}$,
 prove that $\mathbf{c} = t\mathbf{b} + (1-t)\mathbf{a}$.



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Example 3:

Four points A, B, C and D have coordinates $(0,1,-2)$,
 $(1,3,2)$, $(4,3,4)$, and $(5,-1,-2)$ respectively. Find the
 position vectors of

- (a) The mid-point E of AC ,
 (b) The point F on BD such that $\frac{BF}{FD} = \frac{1}{3}$.



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Example 4:

ABC is a triangle. D is the mid-point of BC , E is the mid-
 point of AD and F is the point of trisection of AC closer to
 A . G is the point on FB such that $\vec{FG} = \frac{1}{4} \vec{FB}$.

Express $\mathbf{d}, \mathbf{e}, \mathbf{f}$ and \mathbf{g} in terms of \mathbf{a}, \mathbf{b} and \mathbf{c} , and deduce that
 G is the same point as E . Draw a figure to illustrate this
 result.



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Practice Exercise

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Exercise 13B (Page 197)

Q2, Q4

Exercise 13C (Page 200)

Q2, Q3, Q5



P1/6/3 P1/6/4:
The scalar product

Learning Outcome

Students should be able to:

- understand and the use of scalar product
- Calculate the magnitude of a vector and the scalar product of two vectors
- Determine the angle between two directions
- Solving problems concerning perpendicularity of vectors.

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The Magnitude of a vector

The **magnitude** of a vector $\mathbf{p} = \begin{pmatrix} l \\ m \\ n \end{pmatrix}$ is $|\mathbf{p}|$.

$$|\mathbf{p}| = \sqrt{l^2 + m^2 + n^2}$$

The Magnitude of a vector

A vector of magnitude 1 is called a **unit vector**.

The **unit vector** in the same direction of $\mathbf{p} = \begin{pmatrix} l \\ m \\ n \end{pmatrix}$:

$$\text{Unit Vector} = \frac{1}{|\mathbf{p}|} \begin{pmatrix} l \\ m \\ n \end{pmatrix}$$

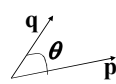
Example 5:

(a) Find the unit vector in the same direction as $\mathbf{p} = \begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix}$.

(b) Hence, find the vector which is in the same direction as \mathbf{p} and has magnitude 30.

Angle between two directions

The **scalar product**, or **dot product**, of vectors **p** and **q**

$$\mathbf{p} \cdot \mathbf{q} = |\mathbf{p}| |\mathbf{q}| \cos \theta,$$


$$\Rightarrow \theta = \cos^{-1} \left(\frac{\mathbf{p} \cdot \mathbf{q}}{|\mathbf{p}| |\mathbf{q}|} \right)$$

The angle θ may be acute or obtuse, and it is the angle between **p** and **q**.

Properties of the scalar products

\Rightarrow if **p** and **q** are parallel,

$$\mathbf{p} \cdot \mathbf{q} = |\mathbf{p}| |\mathbf{q}| \cos 0^\circ \Rightarrow \mathbf{p} \cdot \mathbf{q} = |\mathbf{p}| |\mathbf{q}|$$

\Rightarrow If **p** and **q** are in perpendicular direction.

$$\mathbf{p} \cdot \mathbf{q} = |\mathbf{p}| |\mathbf{q}| \cos 90^\circ \Rightarrow \mathbf{p} \cdot \mathbf{q} = 0$$

Scalar products in component form

In component form, the scalar product is

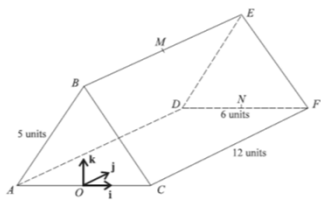
$$\begin{pmatrix} l \\ m \\ n \end{pmatrix} \cdot \begin{pmatrix} u \\ v \\ w \end{pmatrix} = (l\mathbf{i} + m\mathbf{j} + n\mathbf{k}) \cdot (u\mathbf{i} + v\mathbf{j} + w\mathbf{k})$$

$$= lu + mv + nw$$

Example 6:

Find the angle between the line joining (1,2) and (3,-5) and the line joining (2,-3) to (1,4).

Example 7:

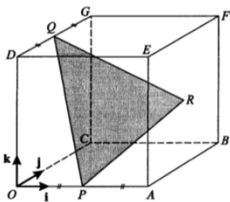


The diagram shows a triangular prism with a horizontal rectangular base $ADFC$, where $CF = 12$ units and $DF = 6$ units. The vertical ends ABC and DEF are isosceles triangles with $AB = BC = 5$ units. The mid-points of BE and DF are M and N respectively. The origin O is at the mid-point of AC .

Unit vectors i, j and k are parallel to OC, ON and OB respectively.

- (i) Find the length of OB . [1]
- (ii) Express each of the vectors \overrightarrow{MC} and \overrightarrow{MN} in terms of i, j and k . [3]
- (iii) Evaluate $\overrightarrow{MC} \cdot \overrightarrow{MN}$ and hence find angle CMN , giving your answer correct to the nearest degree. [4]

Example 8:



The diagram shows a cube $OABCDEFG$ in which the length of each side is 4 units. The unit vectors i, j and k are parallel to $\overrightarrow{OA}, \overrightarrow{OC}$ and \overrightarrow{OD} respectively. The mid-points of OA and DG are P and Q respectively and R is the centre of the square face $ABFE$.

- (i) Express each of the vectors \overrightarrow{PR} and \overrightarrow{PQ} in terms of i, j and k . [3]
- (ii) Use a scalar product to find angle QPR . [4]
- (iii) Find the perimeter of triangle PQR , giving your answer correct to 1 decimal place. [3]

Example 9:

Find the angle between the diagonals of a cube.



Practice Exercise

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Exercise 13D (Page 206)

Q7, Q12, Q15

