Syllabus

Cambridge International A & AS Level Mathematics Syllabus code 9709

For examination in June and November 2011

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Note for Exams Officers: Before making Final Entries, please check availability of the codes for the components and options in the E3 booklet (titled "Procedures for the Submission of Entries") relevant to the exam session. Please note that component and option codes are subject to change.



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1. Introduction

1.1 Why choose Cambridge?

University of Cambridge International Examinations (CIE) is the world's largest provider of international qualifications. Around 1.5 million students from 150 countries enter Cambridge examinations every year. What makes educators around the world choose Cambridge?

Recognition

A Cambridge International A or AS Level is recognised around the world by schools, universities and employers. The qualifications are accepted as proof of academic ability for entry to universities worldwide. Cambridge International A Levels typically take two years to complete and offer a flexible course of study that gives students the freedom to select subjects that are right for them. Cambridge International AS Levels often represent the first half of an A Level course but may also be taken as a freestanding qualification. They are accepted in all UK universities and carry half the weighting of an A Level. University course credit and advanced standing is often available for Cambridge International A/AS Levels in countries such as the USA and Canada. Learn more at **www.cie.org.uk/recognition**.

Support

CIE provides a world-class support service for teachers and exams officers. We offer a wide range of teacher materials to Centres, plus teacher training (online and face-to-face) and student support materials. Exams officers can trust in reliable, efficient administration of exams entry and excellent, personal support from CIE Customer Services. Learn more at **www.cie.org.uk/teachers**.

Excellence in education

Cambridge qualifications develop successful students. They not only build understanding and knowledge required for progression, but also learning and thinking skills that help students become independent learners and equip them for life.

Not-for-profit, part of the University of Cambridge

CIE is part of Cambridge Assessment, a not-for profit-organisation and part of the University of Cambridge. The needs of teachers and learners are at the core of what we do. CIE invests constantly in improving its qualifications and services. We draw upon education research in developing our qualifications.



1.2 Why choose Cambridge International A & AS Level Mathematics?

Cambridge International A & AS Level Mathematics is accepted by universities and employers as proof of mathematical knowledge and understanding. Successful candidates gain lifelong skills, including:

- a deeper understanding of mathematical principles;
- the further development of mathematical skills including the use of applications of mathematics in the context of everyday situations and in other subjects that they may be studying;
- the ability to analyse problems logically, recognising when and how a situation may be represented mathematically;
- the use of mathematics as a means of communication;
- a solid foundation for further study.

The syllabus allows Centres flexibility to choose from three different routes to AS Level Mathematics – Pure Mathematics only **or** Pure Mathematics and Mechanics **or** Pure Mathematics and Probability and Statistics. Centres can choose from three different routes to A Level Mathematics depending on the choice of Mechanics, or Probability and Statistics, or both, in the broad area of 'applications'.

1.3 How can I find out more?

If you are already a Cambridge Centre

You can make entries for this qualification through your usual channels, e.g. CIE Direct. If you have any queries, please contact us at **international@cie.org.uk**.

If you are not a Cambridge Centre

You can find out how your organisation can become a Cambridge Centre. Email us at **international@cie.org.uk**. Learn more about the benefits of becoming a Cambridge Centre at **www.cie.org.uk**.

2. Assessment at a glance

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Scheme of Assessment

The 7 units in the scheme cover the following subject areas:

- Pure Mathematics (units P1, P2 and P3);
- Mechanics (units M1 and M2);
- Probability and Statistics (units S1 and S2).

Centres and candidates may:

- take all four Advanced (A) Level components in the same examination session for the full A Level.
- follow a staged assessment route to the A Level by taking two Advanced Subsidiary (AS) papers (P1 & M1 or P1 & S1) in an earlier examination session;
- take the Advanced Subsidiary (AS) qualification only.

AS Level candidates take:

Paper 1: Pure Mathematics 1 (P1)

1¾ hours

About 10 shorter and longer questions 75 marks weighted at 60% of total

plus one of the following papers:

Paper 2: Pure Mathematics 2 (P2)	Paper 4: Mechanics 1 (M1)	Paper 6: Probability and Statistics (S1)
1¼ hours About 7 shorter and longer questions 50 marks weighted at 40% of total	1¼ hours About 7 shorter and longer questions 50 marks weighted at 40% of total	1¼ hours About 7 shorter and longer questions 50 marks weighted at 40% of total

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A Level candidates take:

Paper 1: Pure Mathematics 1 (P1)	Paper 3 Pure Mathematics 3 (P3)
1% hours About 10 shorter and longer questions 75 marks weighted at 30% of total	1% hours About 10 shorter and longer questions 75 marks weighted at 30% of total

plus one of the following combinations of two papers:

Paper 4: Mechanics 1 (M1)	Paper 6: Probability and Statistics 1 (S1)
1¼ hours	1¼ hours
About 7 shorter and longer questions	About 7 shorter and longer questions
50 marks weighted at 20% of total	50 marks weighted at 20% of total

or

Paper 4: Mechanics 1 (M1)	Paper 5: Mechanics 2 (M2)
1¼ hours About 7 shorter and longer questions 50 marks weighted at 20% of total	1% hours About 7 shorter and longer questions 50 marks weighted at 20% of total

or

Paper 6: Probability and Statistics 1 (S1)	Paper 7: Probability and Statistics 2 (S2)
1¼ hours About 7 shorter and longer questions 50 marks weighted at 20% of total	1¼ hours About 7 shorter and longer questions 50 marks weighted at 20% of total

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2. Assessment at a glance

Question papers

There is no choice of questions in any of the question papers and questions will be arranged approximately in order of increasing mark allocations.

It is expected that candidates will have a calculator with standard 'scientific' functions available for use for all papers in the examination. Computers, and calculators capable of algebraic manipulation, are not permitted.

A list of formulae and tables of the normal distribution (MF9) is supplied for the use of candidates in the examination. Details of the items in this list are given for reference in Section 6.

Relationships between units

Units P2, M2, S2 are sequential to units P1, M1, S1 respectively, and the later unit in each subject area may not be used for certification unless the corresponding earlier unit is being (or has already been) used.

Unit P3 is also sequential to unit P1, and may not be used for certification unless P1 is being (or has already been) used. The subject content of unit P2 is a subset of the subject content of unit P3; otherwise, the subject content for different units does not overlap, although later units in each subject area assume knowledge of the earlier units.



3. Syllabus aims and assessment

3.1 Aims

The aims of the syllabus are the same for all students. These are set out below and describe the educational purposes of any course based on the Mathematics units for the AS and A Level examinations. The aims are not listed in order of priority.

The aims are to enable candidates to:

- develop their mathematical knowledge and skills in a way which encourages confidence and provides satisfaction and enjoyment;
- develop an understanding of mathematical principles and an appreciation of mathematics as a logical and coherent subject;
- acquire a range of mathematical skills, particularly those which will enable them to use applications of mathematics in the context of everyday situations and of other subjects they may be studying;
- develop the ability to analyse problems logically, recognise when and how a situation may be
 represented mathematically, identify and interpret relevant factors and, where necessary, select an
 appropriate mathematical method to solve the problem;
- use mathematics as a means of communication with emphasis on the use of clear expression;
- acquire the mathematical background necessary for further study in this or related subjects.

3.2 Assessment objectives

The abilities assessed in the examinations cover a single area: **technique with application**.

The examination will test the ability of candidates to:

- understand relevant mathematical concepts, terminology and notation;
- recall accurately and use successfully appropriate manipulative techniques;
- recognise the appropriate mathematical procedure for a given situation;
- apply combinations of mathematical skills and techniques in solving problems;
- present mathematical work, and communicate conclusions, in a clear and logical way.

The mathematical content for each unit in the scheme is detailed below. The order in which topics are listed is not intended to imply anything about the order in which they might be taught.

As well as demonstrating skill in the appropriate techniques, candidates will be expected to apply their knowledge in the solution of problems. Individual questions set may involve ideas and methods from more than one section of the relevant content list.

For all units, knowledge of the content of O Level/IGCSE Mathematics is assumed. Candidates will be expected to be familiar with scientific notation for the expression of compound units, e.g. 5 m s⁻¹ for 5 metres per second.

Unit P1: Pure Mathematics 1 (Paper 1)		
	Candidates should be able to:	
1. Quadratics	 carry out the process of completing the square for a quadratic polynomial ax² + bx + c, and use this form, e.g. to locate the vertex of the graph of y = ax² + bx + c or to sketch the graph; find the discriminant of a quadratic polynomial ax² + bx + c and use the discriminant, e.g. to determine the number of real roots of the equation ax² + bx + c = 0; solve quadratic equations, and linear and quadratic inequalities, in one unknown; solve by substitution a pair of simultaneous equations of which one is linear and one is quadratic; recognise and solve equations in x which are quadratic in some function of x, e.g. x⁴ - 5x² + 4 = 0. 	
2. Functions	 understand the terms function, domain, range, one-one function, inverse function and composition of functions; identify the range of a given function in simple cases, and find the composition of two given functions; determine whether or not a given function is one-one, and find the inverse of a one-one function in simple cases; illustrate in graphical terms the relation between a one-one function and its inverse. 	

3. Coordinate geometry	 find the length, gradient and mid-point of a line segment, given the coordinates of the end-points; find the equation of a straight line given sufficient information (e.g. the coordinates of two points on it, or one point on it and its gradient); understand and use the relationships between the gradients of parallel and perpendicular lines; interpret and use linear equations, particularly the forms y = mx + c and y - y₁ = m(x - x₁); understand the relationship between a graph and its associated algebraic equation, and use the relationship between points of intersection of graphs and solutions of equations (including, in simple cases, the correspondence between a line being tangent to a curve and a repeated root of an equation).
4. Circular measure	 understand the definition of a radian, and use the relationship between radians and degrees; use the formulae s = rθ and A = ½ r²θ in solving problems concerning the arc length and sector area of a circle.
5. Trigonometry	 sketch and use graphs of the sine, cosine and tangent functions (for angles of any size, and using either degrees or radians); use the exact values of the sine, cosine and tangent of 30°, 45°, 60°, and related angles, e.g. cos 150° = -½√3; use the notations sin⁻¹x, cos⁻¹x, tan⁻¹x to denote the principal values of the inverse trigonometric relations; use the identities sinθ/cosθ = tanθ and sin²θ + cos²θ = 1; find all the solutions of simple trigonometrical equations lying in a specified interval (general forms of solution are not included).

6. Vectors	 use standard notations for vectors, i.e. (x y), xi + yj, (x y z), xi + yj + zk, AB, a; carry out addition and subtraction of vectors and multiplication of a vector by a scalar, and interpret these operations in geometrical terms; use unit vectors, displacement vectors and position vectors; calculate the magnitude of a vector and the scalar product of two vectors; use the scalar product to determine the angle between two directions and to solve problems concerning perpendicularity of vectors.
7. Series	 use the expansion of (a + b)ⁿ, where n is a positive integer (knowledge of the greatest term and properties of the coefficients are not required, but the notations (n) and n! should be known); recognise arithmetic and geometric progressions; use the formulae for the nth term and for the sum of the first n terms to solve problems involving arithmetic or geometric progressions; use the condition for the convergence of a geometric progression, and the formula for the sum to infinity of a convergent geometric progression.
8. Differentiation	 understand the idea of the gradient of a curve, and use the notations f'(x), f"(x), dy/dx and d²y/dx² (the technique of differentiation from first principles is not required); use the derivative of xⁿ (for any rational n), together with constant multiples, sums, differences of functions, and of composite functions using the chain rule; apply differentiation to gradients, tangents and normals, increasing and decreasing functions and rates of change (including connected rates of change); locate stationary points, and use information about stationary points in sketching graphs (the ability to distinguish between maximum points and minimum points is required, but identification of points of inflexion is not included).

9. Integration

- understand integration as the reverse process of differentiation, and integrate $(ax + b)^n$ (for any rational n except -1), together with constant multiples, sums and differences;
- solve problems involving the evaluation of a constant of integration, e.g. to find the equation of the curve through (1, -2) for which $\frac{dy}{dx} = 2x + 1;$
- evaluate definite integrals (including simple cases of 'improper' integrals, such as $\int_0^1 x^{-\frac{1}{2}} dx$ and $\int_1^\infty x^{-2} dx$);
- use definite integration to find

the area of a region bounded by a curve and lines parallel to the axes, or between two curves,

a volume of revolution about one of the axes.

Unit P2: Pure Mathematics 2 (Paper 2)

Knowledge of the content of unit P1 is assumed, and candidates may be required to demonstrate such knowledge in answering questions.

	Candidates should be able to:	
1. Algebra	 understand the meaning of x , and use relations such as a = b ⇔ a² = b² and x-a < b ⇔ a-b < x < a + b in the course of solving equations and inequalities; divide a polynomial, of degree not exceeding 4, by a linear or quadratic polynomial, and identify the quotient and remainder (which may be zero); use the factor theorem and the remainder theorem, e.g. to find factors, solve polynomial equations or evaluate unknown coefficients. 	
2. Logarithmic and exponential functions	 understand the relationship between logarithms and indices, and use the laws of logarithms (excluding change of base); understand the definition and properties of e^x and In x, including their relationship as inverse functions and their graphs; use logarithms to solve equations of the form a^x = b, and similar inequalities; use logarithms to transform a given relationship to linear form, and hence determine unknown constants by considering the gradient and/ or intercept. 	
3. Trigonometry	 understand the relationship of the secant, cosecant and cotangent functions to cosine, sine and tangent, and use properties and graphs of all six trigonometric functions for angles of any magnitude; use trigonometrical identities for the simplification and exact evaluation of expressions and in the course of solving equations, and select an identity or identities appropriate to the context, showing familiarity in particular with the use of sec² θ ≡ 1 + tan² θ and cosec² θ ≡ 1 + cot² θ, the expansions of sin(A ± B), cos(A ± B) and tan(A ± B), the formulae for sin 2A, cos 2A and tan 2A, the expressions of a sin θ + b cos θ in the forms R sin(θ ± α) and R cos(θ ± α) 	

4. Differentiation	 use the derivatives of e^x, ln x, sin x, cos x, tan x, together with constant multiples, sums, differences and composites; differentiate products and quotients; find and use the first derivative of a function which is defined parametrically or implicitly.
5. Integration	 extend the idea of 'reverse differentiation' to include the integration of e^{ax+b}, 1/(ax+b), sin(ax+b), cos(ax+b) and sec² (ax+b) (knowledge of the general method of integration by substitution is not required); use trigonometrical relationships (such as double-angle formulae) to facilitate the integration of functions such as cos² x; use the trapezium rule to estimate the value of a definite integral, and use sketch graphs in simple cases to determine whether the trapezium rule gives an over-estimate or an under-estimate.
6. Numerical solution of equations	 locate approximately a root of an equation, by means of graphical considerations and/or searching for a sign change; understand the idea of, and use the notation for, a sequence of approximations which converges to a root of an equation; understand how a given simple iterative formula of the form X_{n+1} = F(X_n) relates to the equation being solved, and use a given iteration, or an iteration based on a given rearrangement of an equation, to determine a root to a prescribed degree of accuracy (knowledge of the condition for convergence is not included, but candidates should understand that an iteration may fail to converge).

Unit P3: Pure Mathematics 3 (Paper 3)

Knowledge of the content of unit P1 is assumed, and candidates may be required to demonstrate such knowledge in answering questions.

demonstrate such knowledge in answering questions.	
	Candidates should be able to:
1. Algebra	 understand the meaning of x , and use relations such as a = b ⇔ a² = b² and x-a < b ⇔ a-b < x < a + b in the course of solving equations and inequalities; divide a polynomial, of degree not exceeding 4, by a linear or quadratic polynomial, and identify the quotient and remainder (which may be zero); use the factor theorem and the remainder theorem, e.g. to find factors, solve polynomial equations or evaluate unknown coefficients; recall an appropriate form for expressing rational functions in partial fractions, and carry out the decomposition, in cases where the denominator is no more complicated than (ax + b)(cx + d)(ex + f), (ax + b)(cx + d)², (ax + b)(x² + c²), and where the degree of the numerator does not exceed that of the denominator; use the expansion of (1 + x)ⁿ, where n is a rational number and x <1 (finding a general term is not included, but adapting the standard series to expand e.g. (2 - ½ x)⁻¹ is included).
2. Logarithmic and exponential functions	 understand the relationship between logarithms and indices, and use the laws of logarithms (excluding change of base); understand the definition and properties of e^x and ln x, including their relationship as inverse functions and their graphs; use logarithms to solve equations of the form a^x = b, and similar inequalities; use logarithms to transform a given relationship to linear form, and hence determine unknown constants by considering the gradient and/ or intercept.

3. Trigonometry	 understand the relationship of the secant, cosecant and cotangent functions to cosine, sine and tangent, and use properties and graphs of all six trigonometric functions for angles of any magnitude; use trigonometrical identities for the simplification and exact evaluation of expressions and in the course of solving equations, and select an identity or identities appropriate to the context, showing familiarity in particular with the use of sec² θ = 1 + tan² θ and cosec² θ = 1 + cot² θ, the expansions of sin(A ± B), cos(A ± B) and tan(A ± B), the formulae for sin 2A, cos 2A and tan 2A, the expressions of a sin θ + b cos θ in the forms R sin(θ ± α) and R cos(θ ± α).
4. Differentiation	 use the derivatives of e^x, ln x, sin x, cos x, tan x, together with constant multiples, sums, differences and composites; differentiate products and quotients; find and use the first derivative of a function which is defined parametrically or implicitly.
5. Integration	 extend the idea of 'reverse differentiation' to include the integration of e^{ax+b}, 1/(ax+b), sin(ax+b), cos(ax+b) and sec²(ax+b); use trigonometrical relationships (such as double-angle formulae) to facilitate the integration of functions such as cos² x; integrate rational functions by means of decomposition into partial fractions (restricted to the types of partial fractions specified in paragraph 1 above); recognise an integrand of the form kf'(x)/f(x), and integrate, for example, x or tan x; recognise when an integrand can usefully be regarded as a product, and use integration by parts to integrate, for example, x sin 2x, x² ex or ln x; use a given substitution to simplify and evaluate either a definite or an indefinite integral; use the trapezium rule to estimate the value of a definite integral, and use sketch graphs in simple cases to determine whether the trapezium rule gives an over-estimate or an under-estimate.

6. Numerical solution of equations	 locate approximately a root of an equation, by means of graphical considerations and/or searching for a sign change; understand the idea of, and use the notation for, a sequence of approximations which converges to a root of an equation; understand how a given simple iterative formula of the form X_{n+1} = F(X_n) relates to the equation being solved, and use a given iteration, or an iteration based on a given rearrangement of an equation, to determine a root to a prescribed degree of accuracy (knowledge of the condition for convergence is not included, but candidates should understand that an iteration may fail to converge).
7. Vectors	 understand the significance of all the symbols used when the equation of a straight line is expressed in the form r = a + tb; determine whether two lines are parallel, intersect or are skew; find the angle between two lines, and the point of intersection of two lines when it exists; understand the significance of all the symbols used when the equation of a plane is expressed in either of the forms ax + by + cz = d or (r - a).n = 0; use equations of lines and planes to solve problems concerning
	distances, angles and intersections, and in particular find the equation of a line or a plane, given sufficient information, determine whether a line lies in a plane, is parallel to a plane, or intersects a plane, and find the point of intersection of a line and a plane when it exists, find the line of intersection of two non-parallel planes, find the perpendicular distance from a point to a plane, and from a point to a line, find the angle between two planes, and the angle between a line and a plane.

8. Differential equations	 formulate a simple statement involving a rate of change as a differential equation, including the introduction if necessary of a constant of proportionality; find by integration a general form of solution for a first order differential equation in which the variables are separable; use an initial condition to find a particular solution; interpret the solution of a differential equation in the context of a problem being modelled by the equation.
9. Complex numbers	 understand the idea of a complex number, recall the meaning of the terms real part, imaginary part, modulus, argument, conjugate, and use the fact that two complex numbers are equal if and only if both real and imaginary parts are equal; carry out operations of addition, subtraction, multiplication and division of two complex numbers expressed in cartesian form x + iy; use the result that, for a polynomial equation with real coefficients, any non-real roots occur in conjugate pairs; represent complex numbers geometrically by means of an Argand diagram; carry out operations of multiplication and division of two complex numbers expressed in polar form r(cos θ + i sin θ) = r e^{i θ}; find the two square roots of a complex number; understand in simple terms the geometrical effects of conjugating a complex number and of adding, subtracting, multiplying and dividing two complex numbers; illustrate simple equations and inequalities involving complex numbers by means of loci in an Argand diagram, e.g. z - a < k, z - a = z - b , arg(z - a) = α.

Unit M1: Mechanics 1 (Paper 4)

Questions set will be mainly numerical, and will aim to test mechanical principles without involving difficult algebra or trigonometry. However, candidates should be familiar in particular with the following

trigonometrical results: $\sin(90^\circ - \theta) \equiv \cos\theta$, $\cos(90^\circ - \theta) \equiv \sin\theta$, $\tan\theta \equiv \frac{\sin\theta}{\cos\theta}$, $\sin^2\theta + \cos^2\theta \equiv 1$.

Vector notation will not be used in the question papers, but candidates may use vector methods in their solutions if they wish.

In the following content list, reference to the equilibrium or motion of a 'particle' is not intended to exclude questions that involve extended bodies in a 'realistic' context; however, it is to be understood that any such bodies are to be treated as particles for the purposes of the question.

Unit M1: Mechanics 1 (Paper 4)			
	Candidates should be able to:		
1. Forces and equilibrium	 identify the forces acting in a given situation; understand the vector nature of force, and find and use components and resultants; use the principle that, when a particle is in equilibrium, the vector sum of the forces acting is zero, or equivalently, that the sum of the components in any direction is zero; 		
	 understand that a contact force between two surfaces can be represented by two components, the normal component and the frictional component; 		
	 use the model of a 'smooth' contact, and understand the limitations of this model; understand the concepts of limiting friction and limiting equilibrium; recall the definition of coefficient of friction, and use the relationship F = μR or F ≤ μR, as appropriate; use Newton's third law. 		

2. Kinematics of motion in a straight line	 understand the concepts of distance and speed as scalar quantities, and of displacement, velocity and acceleration as vector quantities (in one dimension only); sketch and interpret displacement-time graphs and velocity-time graphs, and in particular appreciate that the area under a velocity-time graph represents displacement, the gradient of a displacement-time graph represents velocity, the gradient of a velocity-time graph represents acceleration; use differentiation and integration with respect to time to solve simple problems concerning displacement, velocity and acceleration (restricted to calculus within the scope of unit P1); use appropriate formulae for motion with constant acceleration in a straight line.
3. Newton's laws of motion	 apply Newton's laws of motion to the linear motion of a particle of constant mass moving under the action of constant forces, which may include friction; use the relationship between mass and weight; solve simple problems which may be modelled as the motion of a particle moving vertically or on an inclined plane with constant acceleration; solve simple problems which may be modelled as the motion of two particles, connected by a light inextensible string which may pass over a fixed smooth peg or light pulley.
4. Energy, work and power	 understand the concept of the work done by a force, and calculate the work done by a constant force when its point of application undergoes a displacement not necessarily parallel to the force (use of the scalar product is not required); understand the concepts of gravitational potential energy and kinetic energy, and use appropriate formulae; understand and use the relationship between the change in energy of a system and the work done by the external forces, and use in appropriate cases the principle of conservation of energy; use the definition of power as the rate at which a force does work, and use the relationship between power, force and velocity for a force acting in the direction of motion; solve problems involving, for example, the instantaneous acceleration of a car moving on a hill with resistance.

Unit M2: Mechanics 2 (Paper 5) Knowledge of the content of unit M1 is assumed, and candidates may be required to demonstrate such knowledge in answering questions.			
	Candidates should be able to:		
1. Motion of a projectile	 model the motion of a projectile as a particle moving with constant acceleration and understand any limitations of the model; use horizontal and vertical equations of motion to solve problems on the motion of projectiles, including finding the magnitude and direction of the velocity at a given time of position, the range on a horizontal plane and the greatest height reached; derive and use the cartesian equations of the trajectory of a projectile, including problems in which the initial speed and/or angle of projection may be unknown. 		
2. Equilibrium of a rigid body	 calculate the moment of a force about a point, in two dimensional situations only (understanding of the vector nature of moments is not required); use the result that the effect of gravity on a rigid body is equivalent to a single force acting at the centre of mass of the body, and identify the position of the centre of mass of a uniform body using considerations of symmetry; use given information about the position of the centre of mass of a triangular lamina and other simple shapes; determine the position of the centre of mass of a composite body by considering an equivalent system of particles (in simple cases only, e.g. a uniform L-shaped lamina); use the principle that if a rigid body is in equilibrium under the action of coplanar forces then the vector sum of the forces is zero and the sum of the moments of the forces about any point is zero, and the converse of this; solve problems involving the equilibrium of a single rigid body under the action of coplanar forces, including those involving toppling or sliding (problems set will not involve complicated trigonometry). 		

3. Uniform motion in a circle	 understand the concept of angular speed for a particle moving in a circle, and use the relation v = rω; understand that the acceleration of a particle moving in a circle with constant speed is directed towards the centre of the circle, and use the formulae rω² and v²/r; solve problems which can be modelled by the motion of a particle moving in a horizontal circle with constant speed.
4. Hooke's law	 use Hooke's law as a model relating the force in an elastic string or spring to the extension or compression, and understand the term modulus of elasticity; use the formula for the elastic potential energy stored in a string or spring; solve problems involving forces due to elastic strings or springs, including those where considerations of work and energy are needed.
5. Linear motion under a variable force	 use dx/dt for velocity, and dv/dt or v dv/dx for acceleration, as appropriate; solve problems which can be modelled as the linear motion of a particle under the action of a variable force, by setting up and solving an appropriate differential equation (restricted to equations in which the variables are separable).

Unit S1: Probability & Statistics 1 (Paper 6)		
	Candidates should be able to:	
1. Representation of data	 select a suitable way of presenting raw statistical data, and discuss advantages and/or disadvantages that particular representations may have; construct and interpret stem-and-leaf diagrams, box-and-whisker plots, histograms and cumulative frequency graphs; understand and use different measures of central tendency (mean, median, mode) and variation (range, interquartile range, standard deviation), e.g. in comparing and contrasting sets of data; use a cumulative frequency graph to estimate the median value, the quartiles and the interquartile range of a set of data; calculate the mean and standard deviation of a set of data (including grouped data) either from the data itself or from given totals such as Σx and Σx and Σx², or Σ(x – a) and Σ(x – a)². 	
2. Permutations and combinations	 understand the terms permutation and combination, and solve simple problems involving selections; solve problems about arrangements of objects in a line, including those involving: repetition (e.g. the number of ways of arranging the letters of the word 'NEEDLESS'), restriction (e.g. the number of ways several people can stand in a line if 2 particular people must — or must not — stand next to each other). 	
3. Probability	 evaluate probabilities in simple cases by means of enumeration of equiprobable elementary events (e.g. for the total score when two fair dice are thrown), or by calculation using permutations or combinations; use addition and multiplication of probabilities, as appropriate, in simple cases; understand the meaning of exclusive and independent events, and calculate and use conditional probabilities in simple cases, e.g. situations that can be represented by means of a tree diagram. 	

4. Discrete random variables	 construct a probability distribution table relating to a given situation involving a discrete random variable variable X, and calculate E(X) and Var(X); use formulae for probabilities for the binomial distribution, and recognise practical situations where the binomial distribution is a suitable model (the notation B(n, p) is included); use formulae for the expectation and variance of the binomial distribution.
5. The normal distribution	 understand the use of a normal distribution to model a continuous random variable, and use normal distribution tables; solve problems concerning a variable X, where X ~ N(μ, σ²), including finding the value of P(X > x₁), or a related probability, given the values of x₁, μ, σ , finding a relationship between x₁, μ and σ given the value of P(X > x₁) or a related probability; recall conditions under which the normal distribution can be used as an approximation to the binomial distribution (n large enough to ensure that np > 5 and nq > 5), and use this approximation, with a continuity correction, in solving problems.

Unit S2: Probability & Statistics 2 (Paper 7) Knowledge of the content of unit S1 is assumed, and candidates may be required to demonstrate such knowledge in answering questions.

demonstrate such knowledge in answering questions.			
	Candidates should be able to:		
1. The Poisson distribution	 calculate probabilities for the distribution Po(μ); use the fact that if X ~ Po(μ) then the mean and variance of X are each equal to μ; understand the relevance of the Poisson distribution to the distribution of random events, and use the Poisson distribution as a model; use the Poisson distribution as an approximation to the binomial distribution where appropriate (n > 50 and np < 5, approximately); use the normal distribution, with continuity correction, as an approximation to the Poisson distribution where appropriate (μ > 15, approximately). 		
2. Linear combinations of random variables	 use, in the course of solving problems, the results that E(aX + b) = aE(X) + b and Var(aX + b) = a²Var(X), E(aX + bY) = aE(X) + bE(Y), Var(aX + bY) = a²Var(X) + b²Var(Y) for independent X and Y, if X has a normal distribution then so does aX + b, if X and Y have independent normal distributions then aX + bY has a normal distribution, if X and Y have independent Poisson distributions then X + Y has a Poisson distribution. 		
3. Continuous random variables	 understand the concept of a continuous random variable, and recall and use properties of a probability density function (restricted to functions defined over a single interval); use a probability density function to solve problems involving probabilities, and to calculate the mean and variance of a distribution (explicit knowledge of the cumulative distribution function is not included, but location of the median, for example, in simple cases by direct consideration of an area may be required). 		

4. Sampling and estimation

- understand the distinction between a sample and a population, and appreciate the necessity for randomness in choosing samples;
- explain in simple terms why a given sampling method may be unsatisfactory (knowledge of particular sampling methods, such as quota or stratified sampling, is not required, but candidates should have an elementary understanding of the use of random numbers in producing random samples);
- recognise that a sample mean can be regarded as a random variable, and use the facts that $E(\overline{X}) = \mu$ and that $Var \overline{X} = \frac{\sigma^2}{R}$;
- use the fact that \overline{X} has a normal distribution if X has a normal distribution;
- use the Central Limit theorem where appropriate;
- calculate unbiased estimates of the population mean and variance from a sample, using either raw or summarised data (only a simple understanding of the term 'unbiased' is required);
- determine a confidence interval for a population mean in cases where the population is normally distributed with known variance or where a large sample is used;
- determine, from a large sample, an approximate confidence interval for a population proportion.

5. Hypothesis tests

- understand the nature of a hypothesis test, the difference between one-tail and two-tail tests, and the terms null hypothesis, alternative hypothesis, significance level, rejection region (or critical region), acceptance region and test statistic;
- formulate hypotheses and carry out a hypothesis test in the context
 of a single observation from a population which has a binomial or
 Poisson distribution, using either direct evaluation of probabilities or a
 normal approximation, as appropriate;
- formulate hypotheses and carry out a hypothesis test concerning the population mean in cases where the population is normally distributed with known variance or where a large sample is used;
- understand the terms Type I error and Type II error in relation to hypothesis tests;
- calculate the probabilities of making Type I and Type II errors in specific situations involving tests based on a normal distribution or direct evaluation of binomial or Poisson probabilities.

5. Resource list

These titles represent some of the texts available in the UK at the time of printing this booklet. Teachers are encouraged to choose texts for class use which they feel will be of interest to their students. The inclusion of a text does not imply that it is either recommended or approved by CIE. Wherever possible, the International Standard Book Number (ISBN) is given.

Endorsed Textbooks

The following textbooks are endorsed by CIE for use with the syllabuses in this booklet – please contact Cambridge University Press for further information.

Author	Title	Publisher	ISBN
Neill & Quadling	Pure Mathematics 1	Cambridge University Press	0 521 53011 3
Neill & Quadling	Pure Mathematics 2 & 3	Cambridge University Press	0 521 53012 1
Quadling	Mechanics 1	Cambridge University Press	0 521 53015 6
Quadling	Mechanics 2	Cambridge University Press	0 521 53016 4
Dobbs & Miller	Statistics 1	Cambridge University Press	0 521 53013 X
Dobbs & Miller	Statistics 2	Cambridge University Press	0 521 53014 8

Suggested Books

Pure Mathematics

Author	Title	Publisher	ISBN
Backhouse, Houldsworth & Horrill	Pure Mathematics 1	Longman, 1985	0 582 35386 6
Backhouse, Houldsworth & Horrill	Pure Mathematics 2	Longman, 1985	0 582 35387 4
Backhouse, Houldsworth, Horrill & Wood	Essential Pure Mathematics	Longman, 1991	0582 066581
Bostock & Chandler	Core Maths for Advanced Level	Nelson Thornes, 2000	0 7487 5509 8
Butcher & Megeny	Access to Advanced Level Maths (short introductory course)	Nelson Thornes, 1997	0 7487 2999 2
Emanuel, Wood & Crawshaw	Pure Mathematics 1	Longman, 2001	0 582 40550 5

5. Resource list

Emanuel, Wood & Crawshaw	Pure Mathematics 2	Longman, 2001	0 582 40549 1				
Hunt	Graded Exercises in Pure Mathematics (Practice questions)	Cambridge University Press, 2001	0 521 63753 8				
Martin, Brown, Rigby & Riley	Complete Advanced Level Mathematics: Pure Mathematics: Core Text	Nelson Thornes, 2000 0 7487 35					
Morley	Practice for Advanced Mathematics – Pure Mathematics (Practice questions)	Hodder & Stoughton Educational, 1999	0 340 701676				
Sadler & Thorning	Understanding Pure Mathematics	Oxford University Press, 1987 019 914243					
Smedley & Wiseman	Introducing Pure Mathematics	Oxford University Press, 2001	0 19 914803 1				
SMP	Mathematics for AS and A Level – Pure Mathematics	Cambridge University Press, 1997	0 521 56617 7				
Solomon	Advanced Level Mathematics: Pure Mathematics	John Murray, 1995	0 7195 5344 X				

Integrated Courses

Author	Title	Publisher	ISBN
Berry, Fentern, Francis & Graham	Discovering Advanced Mathematics – AS Mathematics	Collins Educational, 2000	0 00 322502 X
Berry, Fentern, Francis & Graham	Discovering Advanced Mathematics – A2 Mathematics	Collins Educational, 2001	0 00 322503 8

Mechanics

Author	Title	Publisher	ISBN			
Adams, Haighton, Trim	Complete Advanced Level Mathematics: Mechanics: Core Text	Nelson Thornes, 2000	0 7487 3559 3			
Bostock & Chandler	Mechanics for A Level	Nelson Thornes, 1996	07487 2596 2			
Jefferson & Beadsworth	Introducing Mechanics	Oxford University Press, 2000	0 19 914710 8			
Kitchen & Wake	Graded Exercises in Mechanics (Practice questions)	Cambridge University Press, 2001	0 521 64686 3			
Nunn & Simmons	Practice for Advanced Mathematics (Practice questions)	Hodder & Stoughton Educational, 1998	0 340 70166 8			
Sadler & Thorning	Understanding Mechanics	Oxford University Press, 1996	019 914675 6			
SMP	Mathematics for A and AS Level – Mechanics	Cambridge University Press, 1997	0 521 56615 0			
Solomon	Advanced Level Mathematics: Mechanics	John Murray, 1995 07195 7				
Young	Maths in Perspective 2: Mechanics	Hodder & Stoughton 07131 782 Educational, 1989				

Statistics

Author	Title	Publisher	ISBN				
Clarke & Cooke	A Basic Course in Statistics	Hodder & Stoughton 0 340 7199 Educational, 1998					
Crawshaw & Chambers	A Concise Course in Advanced Level Statistics	Nelson Thornes, 2001	0 7487 5475X				
Crawshaw & Chambers	A-Level Statistics Study Guide	Nelson Thornes, 1997	0 7487 2997 6				
McGill, McLennan, Migliorini	Complete Advanced Level Mathematics: Statistics: Core Text	Nelson Thornes, 2000	07487 3560 7				



5. Resource list

Norris	Graded Exercises in Statistics (Practice questions)	Cambridge University Press, 2000	0 521 65399 1
Rees	Foundations of Statistics	Chapman & Hall, 1987	0 412 28560 6
Smith	Practice for Advanced Mathematics: Statistics (Practice questions)	Hodder & Stoughton Educational, 1998	0 340 70165X
SMP	Mathematics for AS and A Level – Statistics	Cambridge University Press, 1997	0 521 56616 9
Solomon	Advanced Level Mathematics: Statistics	John Murray, 1996	0 7195 7088 3
Upton & Cook	Introducing Statistics	Oxford University Press, 2001	0 19 914801 5
Upton & Cook	Understanding Statistics	Oxford University Press, 1997	0 19 914391 9

PURE MATHEMATICS

Algebra

For the quadratic equation $ax^2 + bx + c = 0$:

$$x = \frac{-b \pm \sqrt{(b^2 - 4ac)}}{2a}$$

For an arithmetic series:

$$u_n = a + (n-1)d,$$

$$S_n = \frac{1}{2}n(a+l) = \frac{1}{2}n\{2a+(n-1)d\}$$

For a geometric series:

$$u_n = ar^{n-1},$$

$$S_n = \frac{a(1-r^n)}{1-r} \quad (r \neq 1), \qquad S_\infty = \frac{a}{1-r} \quad (|r| < 1)$$

$$S_{\infty} = \frac{a}{1 - r} \quad (|r| < 1)$$

Binomial expansion:

$$(a+b)^n = a^n + \binom{n}{1}a^{n-1}b + \binom{n}{2}a^{n-2}b^2 + \binom{n}{3}a^{n-3}b^3 + \dots + b^n, \text{ where } n \text{ is a positive integer}$$
and
$$\binom{n}{r} = \frac{n!}{r!(n-r)!}$$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2!}x^2 + \frac{n(n-1)(n-2)}{3!}x^3 \cdots$$
, where *n* is rational and $|x| < 1$

Trigonometry

Arc length of circle =
$$r\theta$$
 (θ in radians)

Area of sector of circle = $\frac{1}{2}r^2\theta$ (θ in radians)

$$\tan\theta \equiv \frac{\sin\theta}{\cos\theta}$$

$$\cos^2\theta + \sin^2\theta \equiv 1.$$

$$1 + \tan^2 \theta \equiv \sec^2 \theta$$
, $\cot^2 \theta + 1 \equiv \csc^2 \theta$

$$\sin(A \pm B) \equiv \sin A \cos B \pm \cos A \sin B$$

$$cos(A \pm B) \equiv cos A cos B \mp sin A sin B$$

$$\tan(A \pm B) \equiv \frac{\tan A \pm \tan B}{1 \mp \tan A \tan B}$$

$$\sin 2A \equiv 2\sin A\cos A$$

$$\cos 2A \equiv \cos^2 A - \sin^2 A \equiv 2\cos^2 A - 1 \equiv 1 - 2\sin^2 A$$

$$\tan 2A = \frac{2\tan A}{1 - \tan^2 A}$$

Principal values:

$$-\frac{1}{2}\pi \le \sin^{-1} x \le \frac{1}{2}\pi$$

$$0 \le \cos^{-1} x \le \pi$$

$$-\frac{1}{2}\pi < \tan^{-1}x < \frac{1}{2}\pi$$

Differentiation

$$f(x) f'(x) x^n nx^{n-1}$$

$$\ln x \frac{1}{x} e^x e^x e^x sin x cos x -sin x$$

$$\tan x sec^2 x uv u \frac{dv}{dx} + v \frac{du}{dx}$$

$$\frac{u}{v} \frac{v \frac{du}{dx} - u \frac{dv}{dx}}{v^2}$$

If
$$x = f(t)$$
 and $y = g(t)$ then $\frac{dy}{dx} = \frac{dy}{dt} \div \frac{dx}{dt}$

Integration

$$f(x) \qquad \qquad \int f(x) \, dx$$

$$x^n \qquad \qquad \frac{x^{n+1}}{n+1} + c \quad (n \neq -1)$$

$$\frac{1}{x} \qquad \qquad \ln|x| + c$$

$$e^x \qquad \qquad e^x + c$$

$$\sin x \qquad \qquad -\cos x + c$$

$$\cos x \qquad \qquad \sin x + c$$

$$\sec^2 x \qquad \qquad \tan x + c$$

$$\int u \frac{dv}{dx} \, dx = uv - \int v \frac{du}{dx} \, dx$$

$$\int \frac{f'(x)}{f(x)} \, dx = \ln|f(x)| + c$$

Vectors

If
$$\mathbf{a} = a_1 \mathbf{i} + a_2 \mathbf{j} + a_3 \mathbf{k}$$
 and $\mathbf{b} = b_1 \mathbf{i} + b_2 \mathbf{j} + b_3 \mathbf{k}$ then
$$\mathbf{a} \cdot \mathbf{b} = a_1 b_1 + a_2 b_2 + a_3 b_3 = |\mathbf{a}| |\mathbf{b}| \cos \theta$$

Numerical integration

Trapezium rule:

$$\int_{a}^{b} f(x) dx \approx \frac{1}{2} h \{ y_0 + 2(y_1 + y_2 + \dots + y_{n-1}) + y_n \}, \text{ where } h = \frac{b - a}{n}$$

MECHANICS

Uniformly accelerated motion

$$v = u + at$$
, $s = \frac{1}{2}(u + v)t$, $s = ut + \frac{1}{2}at^2$, $v^2 = u^2 + 2as$

Motion of a projectile

Equation of trajectory is:

$$y = x \tan \theta - \frac{gx^2}{2V^2 \cos^2 \theta}$$

Elastic strings and springs

$$T = \frac{\lambda x}{l} \,, \qquad E = \frac{\lambda x^2}{2l}$$

Motion in a circle

For uniform circular motion, the acceleration is directed towards the centre and has magnitude

$$\omega^2 r$$
 or $\frac{v^2}{r}$

Centres of mass of uniform bodies

Triangular lamina: $\frac{2}{3}$ along median from vertex

Solid hemisphere or radius r: $\frac{3}{8}r$ from centre

Hemispherical shell of radius r: $\frac{1}{2}r$ from centre

Circular arc of radius r and angle 2α : $\frac{r \sin \alpha}{\alpha}$ from centre

Circular sector of radius r and angle 2α : $\frac{2r\sin\alpha}{3\alpha}$ from centre

Solid cone or pyramid of height h: $\frac{3}{4}h$ from vertex

PROBABILITY AND STATISTICS

Summary statistics

For ungrouped data:

$$\overline{x} = \frac{\sum x}{n}$$
, standard deviation $= \sqrt{\frac{\sum (x - \overline{x})^2}{n}} = \sqrt{\frac{\sum x^2}{n} - \overline{x}^2}$

For grouped data:

$$\overline{x} = \frac{\sum xf}{\sum f}$$
, standard deviation $= \sqrt{\frac{\sum (x - \overline{x})^2 f}{\sum f}} = \sqrt{\frac{\sum x^2 f}{\sum f} - \overline{x}^2}$

Discrete random variables

$$E(X) = \sum xp$$
$$Var(X) = \sum x^2 p - \{E(X)\}^2$$

For the binomial distribution B(n, p):

$$p_r = \binom{n}{r} p^r (1-p)^{n-r}, \qquad \mu = np, \qquad \sigma^2 = np(1-p)$$

For the Poisson distribution Po(a):

$$p_r = e^{-a} \frac{a^r}{r!}, \qquad \qquad \mu = a, \qquad \qquad \sigma^2 = a$$

Continuous random variables

$$E(X) = \int x f(x) dx$$

$$Var(X) = \int x^2 f(x) dx - \{E(X)\}^2$$

Sampling and testing

Unbiased estimators:

$$\overline{x} = \frac{\sum x}{n}$$
,

$$s^2 = \frac{1}{n-1} \left(\sum x^2 - \frac{(\sum x)^2}{n} \right)$$

Central Limit Theorem:

$$\overline{X} \sim N\left(\mu, \frac{\sigma^2}{n}\right)$$

Approximate distribution of sample proportion:

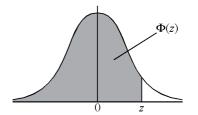
$$N\left(p, \frac{p(1-p)}{n}\right)$$

THE NORMAL DISTRIBUTION FUNCTION

If Z has a normal distribution with mean 0 and variance 1 then, for each value of z, the table gives the value of $\Phi(z)$, where

$$\Phi(z) = P(Z \le z) .$$

For negative values of z use $\Phi(-z) = 1 - \Phi(z)$.



	0	1		2	4		-	7	0	9	1	2	3	4	5	6	7	8	9
Z	0	1	2	3	4	5	6	7	8	9				A	ADI)			
0.0	0.5000	0.5040	0.5080	0.5120	0.5160	0.5199	0.5239	0.5279	0.5319	0.5359	4	8	12	16	20	24	28	32	36
0.1	0.5398	0.5438	0.5478	0.5517	0.5557	0.5596	0.5636	0.5675	0.5714	0.5753	4	8	12	16	20	24	28	32	36
0.2	0.5793	0.5832	0.5871	0.5910	0.5948	0.5987	0.6026	0.6064	0.6103	0.6141	4	8	12	15	19	23	27	31	35
0.3	0.6179	0.6217	0.6255	0.6293	0.6331	0.6368	0.6406	0.6443	0.6480	0.6517	4	7	11	15	19	22	26	30	34
0.4	0.6554	0.6591	0.6628	0.6664	0.6700	0.6736	0.6772	0.6808	0.6844	0.6879	4	7	11	14	18	22	25	29	32
0.5	0.6915	0.6950	0.6985	0.7019	0.7054	0.7088	0.7123	0.7157	0.7190	0.7224	3	7	10	14	17	20	24	27	31
0.6	0.7257	0.7291	0.7324	0.7357	0.7389	0.7422	0.7454	0.7486	0.7517	0.7549	3	7	10	13	16	19	23	26	29
0.7	0.7580	0.7611	0.7642	0.7673	0.7704	0.7734	0.7764	0.7794	0.7823	0.7852	3	6	9	12	15	18	21	24	27
0.8	0.7881	0.7910	0.7939	0.7967	0.7995	0.8023	0.8051	0.8078	0.8106	0.8133	3	5	8	11	14	16	19	22	25
0.9	0.8159	0.8186	0.8212	0.8238	0.8264	0.8289	0.8315	0.8340	0.8365	0.8389	3	5	8	10	13	15	18	20	23
1.0	0.8413	0.8438	0.8461	0.8485	0.8508	0.8531	0.8554	0.8577	0.8599	0.8621	2	5	7	9	12	14	16	19	21
1.1	0.8643	0.8665	0.8686	0.8708	0.8729	0.8749	0.8770	0.8790	0.8810	0.8830	2	4	6	8	10	12	14	16	18
1.2	0.8849	0.8869	0.8888	0.8907	0.8925	0.8944	0.8962	0.8980	0.8997	0.9015	2	4	6	7	9	11	13	15	17
1.3	0.9032	0.9049	0.9066	0.9082	0.9099	0.9115	0.9131	0.9147	0.9162	0.9177	2	3	5	6	8	10	11	13	14
1.4	0.9192	0.9207	0.9222	0.9236	0.9251	0.9265	0.9279	0.9292	0.9306	0.9319	1	3	4	6	7	8	10	11	13
1.5	0.9332	0.9345	0.9357	0.9370	0.9382	0.9394	0.9406	0.9418	0.9429	0.9441	1	2	4	5	6	7	8	10	11
1.6	0.9452	0.9463	0.9474	0.9484	0.9495	0.9505	0.9515	0.9525	0.9535	0.9545	1	2	3	4	5	6	7	8	9
1.7	0.9554	0.9564	0.9573	0.9582	0.9591	0.9599	0.9608	0.9616	0.9625	0.9633	1	2	3	4	4	5	6	7	8
1.8	0.9641	0.9649	0.9656	0.9664	0.9671	0.9678	0.9686	0.9693	0.9699	0.9706	1	1	2	3	4	4	5	6	6
1.9	0.9713	0.9719	0.9726	0.9732	0.9738	0.9744	0.9750	0.9756	0.9761	0.9767	1	1	2	2	3	4	4	5	5
2.0	0.9772	0.9778	0.9783	0.9788	0.9793	0.9798	0.9803	0.9808	0.9812	0.9817	0	1	1	2	2	3	3	4	4
2.1	0.9821	0.9826	0.9830	0.9834	0.9838	0.9842	0.9846	0.9850	0.9854	0.9857	0	1	1	2	2	2	3	3	4
2.2	0.9861	0.9864	0.9868	0.9871	0.9875	0.9878	0.9881	0.9884	0.9887	0.9890	0	1	1	1	2	2	2		
2.3	0.9893	0.9896	0.9898	0.9901	0.9904	0.9906	0.9909	0.9911	0.9913	0.9916	0	1	1	1	1	2	2	2	2
2.4	0.9918	0.9920	0.9922	0.9925	0.9927	0.9929	0.9931	0.9932	0.9934	0.9936	0	0	1	1	1	1	1	2	2
2.5	0.9938	0.9940	0.9941	0.9943	0.9945	0.9946	0.9948	0.9949	0.9951	0.9952	0	0	0	1	1	1	1	1	1
2.6	0.9953	0.9955	0.9956	0.9957	0.9959	0.9960	0.9961	0.9962	0.9963	0.9964	0	0	0	0	1	1	1	1	1
2.7	0.9965	0.9966	0.9967	0.9968	0.9969	0.9970	0.9971	0.9972	0.9973	0.9974	0	0	0	0	0	1	1	1	1
2.8	0.9974	0.9975	0.9976	0.9977	0.9977	0.9978	0.9979	0.9979	0.9980	0.9981	0	0	0	0	0	0	0	1	1
2.9	0.9981	0.9982	0.9982	0.9983	0.9984	0.9984	0.9985	0.9985	0.9986	0.9986	0	0	0	0	0	0	0	0	0

Critical values for the normal distribution

If Z has a normal distribution with mean 0 and variance 1 then, for each value of p, the table gives the value of z such that

$$P(Z \le z) = p$$
.

p	0.75	0.90	0.95	0.975	0.99	0.995	0.9975	0.999	0.9995
Z	0.674	1.282	1.645	1.960	2.326	2.576	2.807	3.090	3.291

Examinations for the syllabus in this booklet may use relevant notation from the following list.

1 Set Notation

```
is an element of
                                is not an element of
\{x_1, x_2, ...\}
                                the set with elements x_1, x_2...
\{x:\ldots\}
                                the set of all x such that ...
n(A)
                                the number of elements in set A
Ø
                                the empty set
E
                                the universal set
 A'
                                the complement of the set A
N
                                the set of natural numbers, \{1, 2, 3, ...\}
7
                                the set of integers, \{0, \pm 1, \pm 2, \pm 3, \ldots\}
\mathbb{Z}^+
                                the set of positive integers, \{1, 2, 3, ...\}
\mathbb{Z}_n
                                the set of integers modulo n, \{0, 1, 2, ..., n-1\}
                                the set of rational numbers, \left\{\frac{p}{q}: p \in \mathbb{Z}, q \in \mathbb{Z}^+\right\}
\mathbb{Q}
\mathbb{O}^+
                                the set of positive rational numbers, \{x \in \mathbb{Q} : x > 0\}
\mathbb{Q}_0^+
                                set of positive rational numbers and zero, \{x \in \mathbb{Q} : x \ge 0\}
\mathbb{R}
                                the set of real numbers
\mathbb{R}^{+}
                                the set of positive real numbers, \{x \in \mathbb{R} : x > 0\}
                                the set of positive real numbers and zero, \{x \in \mathbb{R} : x \ge 0\}
\mathbb{R}_{0}^{+}
\mathbb{C}
                                the set of complex numbers
(x, y)
                                the ordered pair x, y
A \times B
                                the cartesian product of sets A, and B, i.e. A \times B = \{(a, b) : a \in A, b \in B\}
                                is a subset of
\subseteq
                                is a proper subset of
\subset
                                union
\cup
                                intersection
                                the closed interval \{x \in \mathbb{R} : a \le x \le b\}
[a, b]
                                the interval \{x \in \mathbb{R} : a \le x < b\}
[a,b)
                                the interval \{x \in \mathbb{R} : a < x \le b\}
(a, b]
(a, b)
                                the open interval \{x \in \mathbb{R} : a < x < b\}
y R x
                                y is related to x by the relation R
y \sim x
                                y is equivalent to x, in the context of some equivalence relation
```

2 Miscellaneous Symbols

```
is equal to
                             is not equal to
≠
                             is identical to or is congruent to
                             is approximately equal to
                             is isomorphic to
                             is proportional to
\infty
                             is less than
                             is less than or equal to, is not greater than
\leq
                             is greater than
                             is greater than or equal to, is not less than
                             infinity
                             p and q
p \wedge q
                             p or q (or both)
p \vee q
                             not p
~p
                             p implies q (if p then q)
p \Rightarrow q
                             p is implied by q (if q then p)
p \Leftarrow q
                             p implies and is implied by q (p is equivalent to q)
p \Leftrightarrow q
\exists
                             there exists
                             for all
```

3 Operations

$$\begin{array}{lll} a+b & a \text{ plus } b \\ a-b & a \text{ minus } b \\ a\times b, ab, a.b & a \text{ multiplied by } b \\ a \div b, \frac{a}{b}, a/b & a \text{ divided by } b \\ & \sum_{i=1}^n a_i & a_1 + a_2 + \ldots + a_n \\ & \prod_{i=1}^n a_i & a_1 \times a_2 \times \ldots \times a_n \\ & \sqrt{a} & \text{the positive square root of } a. \\ |a| & \text{the modulus of } a. \\ n! & n \text{ factorial} \\ \begin{pmatrix} n \\ r \end{pmatrix} & \text{the binomial coefficient } \frac{n!}{r!(n-r)!} \text{ for } n \in \mathbb{Z}^+ \\ & \text{or } \frac{n(n-1)\ldots(n-r+1)}{r!} \text{ for } n \in \mathbb{Q} \\ & \end{array}$$

4 Functions

f(x)the value of the function f at x $f: A \rightarrow B$ f is a function under which each element of set A has an image in set B $f: x \mapsto y$ the function f maps the element x to the element y f^{-1} the inverse function of the function f gf the composite function of f and g which is defined by gf(x) = g(f(x)) $\lim_{x \to a} \mathbf{f}(x)$ the limit of f(x) as x tends to a Δx , δx an increment of x dvthe derivative of *y* with respect to *x* dx $d^n y$ the n th derivative of y with respect to x $\mathrm{d}x^n$ $f'(x), f''(x), \dots, f^{(n)}(x)$ the first, second, ..., n th derivatives of f(x) with respect to x $\int y \, dx$ the indefinite integral of y with respect to x $\int_{a}^{b} y \, dx$ the definite integral of y with respect to x between the limits x = a and x = bthe partial derivative of V with respect to x $\frac{\partial}{\partial x}$ \dot{x}, \ddot{x}, \dots the first, second, ... derivatives of x with respect to t

5 Exponential and Logarithmic Functions

e base of natural logarithms e^x , $\exp x$ exponential function of x $\log_a x$ logarithm to the base a of x $\ln x$, $\log_e x$ natural logarithm of x logarithm of x to base 10

6 Circular and Hyperbolic Functions

 $\begin{array}{ll} sin,\; cos,\; tan,\; \\ cosec,\; sec,\; cot \end{array} \hspace{1cm} \text{the circular functions} \\ sin^{-1},\; cos^{-1},\; tan^{-1},\; \\ cosec^{-1},\; sec^{-1},\; cot^{-1} \end{array} \hspace{1cm} \text{the inverse circular functions} \\ sinh,\; cosh,\; tanh,\; \\ cosech,\; sech,\; coth \end{array} \hspace{1cm} \text{the hyperbolic functions} \\ sinh^{-1},\; cosh^{-1},\; tanh^{-1},\; \\ cosech^{-1},\; sech^{-1},\; coth^{-1} \end{array} \hspace{1cm} \text{the inverse hyperbolic functions} \\ \end{array}$

Complex Numbers

square root of -1

a complex number, $z = x + iy = r(\cos \theta + i \sin \theta)$ Z

Re z the real part of z, Re z = xIm zthe imaginary part of z, Im z = ythe modulus of z, $|z| = \sqrt{x^2 + y^2}$ |z|

the argument of z, arg $z = \theta$, $-\pi < \theta \le \pi$ arg z

 z^* the complex conjugate of z, x - i y

Matrices

 \mathbf{M} a matrix M

 \mathbf{M}^{-1} the inverse of the matrix M \mathbf{M}^{T} the transpose of the matrix M

det M or |M|the determinant of the square matrix M

Vectors

the vector a

the vector represented in magnitude and direction by the directed line segment \overrightarrow{AB}

â a unit vector in the direction of a

unit vectors in the directions of the cartesian coordinate axes i, j, k

the magnitude of a |a|, a the magnitude of AB

the scalar product of a and b a.b

 $\mathbf{a} \times \mathbf{b}$ the vector product of a and b

10 Probability and Statistics

A, B, C, etc. events

 $A \cup B$ union of the events A and B $A \cap B$ intersection of the events A and B

P(A) probability of the event A complement of the event A

 $P(A \mid B)$ probability of the event A conditional on the event B

X, Y, R, etc. random variables

x, y, r, etc. values of the random variables X, Y, R etc

 x_1, x_2, \dots observations

 f_1, f_2, \dots frequencies with which the observations x_1, x_2 occur

p(x) probability function P(X = x) of the discrete random variable X p_1, p_2, \dots probabilities of the values x_1, x_2 of the discrete random variable X

f(x), g(x),... the value of the probability density function of a continuous random variable X F(x), G(x),... the value of the (cumulative) distribution function $P(X \le x)$ of a continuous

the value of the (cumulative) distribution function $\Gamma(A \le \lambda)$ of a consequence variable V

random variable X

E(X) expectation of the random variable X

E(g(X)) expectation of g(X)

Var(X) variance of the random variable X

G(t) probability generating function for a random variable which takes the values 0,

1, 2 ...

B(n, p) binomial distribution with parameters n and p

 $Po(\mu)$ Poisson distribution, mean μ

 $N(\mu, \sigma^2)$ normal distribution with mean μ and variance σ^2

 μ population mean σ^2 population variance

 σ population standard deviation

 \bar{x} , m sample mean

 s^2 , $\hat{\sigma}^2$ unbiased estimate of population variance from a sample, $s^2 = \frac{1}{n-1} \sum_{i=1}^{n} (x_i - \bar{x}_i)^2$

 ϕ probability density function of the standardised normal variable with distribution

N(0, 1)

Φ corresponding cumulative distribution function

ho product moment correlation coefficient for a population r product moment correlation coefficient for a sample

Cov(X, Y) covariance of X and Y

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