

Assignment 1

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Download all the codes from

https://github.com/sudeepv/EE3025_IDP/Assignment1/codes

and latex-tikz codes from

https://github.com/sudeepv/EE3025_IDP/Assignment1

```
#filter the input signal with butterworth filter
output_signal = signal.filtfilt(b, a,
                                input_signal)
#output_signal = signal.lfilter(b, a,
                                input_signal)

#write the output signal into .wav file
sf.write('Sound_With_ReducedNoise.wav',
        output_signal, fs)
```

1 DIGITAL FILTER

1.1 Download the sound file from

```
wget https://raw.githubusercontent.com/
gadepall/EE1310/master/filter/codes/
Sound_Noise.wav
```

1.2 Write the python code for removal of out of band noise and execute the code.

Solution:

```
import soundfile as sf
from scipy import signal

#read .wav file
input_signal,fs = sf.read('Sound_Noise.wav
    ')

#sampling frequency of Input signal
sampl_freq=fs

#order of the filter
order=4

#cutoff frquency 4kHz
cutoff_freq=4000.0

#digital frequency
Wn=2*cutoff_freq/sampl_freq

# b and a are numerator and denominator
  polynomials respectively
b, a = signal.butter(order,Wn, 'low')
print(b)
print(a)
```

2 DIFFERENCE EQUATION

2.1 Write the difference equation of the above Digital filter obtained in problem 1.2.

Solution: From 1.2, we get,

$$a[n] = \left\{ \underset{\uparrow}{0.003}, 0.014, 0.021, 0.0138, 0.003 \right\} \quad (2.0.1)$$

$$b[n] = \left\{ \underset{\uparrow}{1}, -2.519, 2.561, -1.206, 0.220 \right\} \quad (2.0.2)$$

From

$$\sum_{m=0}^M a(m) y(n-m) = \sum_{k=0}^N b(k) x(n-k) \quad (2.0.3)$$

The resultant difference equation is given by (2.0.4)

$$y(n) - 2.52y(n-1) + 2.56y(n-2) - 1.206y(n-3) + 0.22013y(n-4) = 0.00345x(n) + 0.0138x(n-1) + 0.020725x(n-2) + 0.0138x(n-3) + 0.00345x(n-4) \quad (2.0.4)$$

2.2 Sketch $x(n]$ and $y(n]$.

Solution: The following code writes the .wav file into a .dat file.

```
codes/generate_x.c
```

The following C code computes $x(n]$ and $y(n]$ from the difference equation

```
codes/plot_xnyn.c
```

The following code plots Fig. 2.2

```
codes/plot_xnyn.py
```

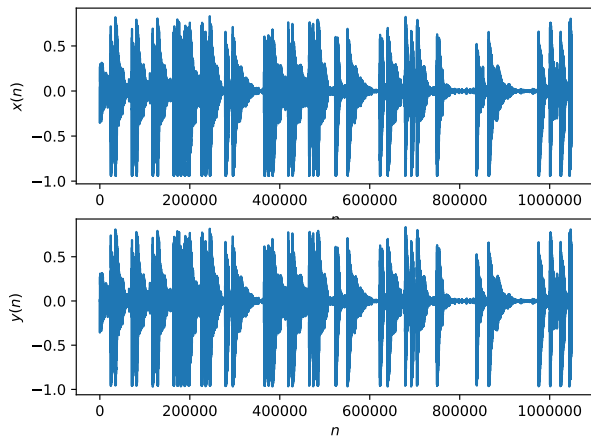


Fig. 2.2: $x(n)$ and $y(n)$ obtained from difference equations

3 Z-TRANSFORM

3.1 The Z-transform of $x(n)$ is defined as

$$X(z) = \mathcal{Z}\{x(n)\} = \sum_{n=-\infty}^{\infty} x(n)z^{-n} \quad (3.0.1)$$

Show that

$$\mathcal{Z}\{x(n-1)\} = z^{-1}X(z) \quad (3.0.2)$$

and find

$$\mathcal{Z}\{x(n-k)\} \quad (3.0.3)$$

Solution: From (3.0.1),

$$\mathcal{Z}\{x(n-1)\} = \sum_{n=-\infty}^{\infty} x(n-1)z^{-n} \quad (3.0.4)$$

$$= \sum_{n=-\infty}^{\infty} x(n)z^{-n-1} = z^{-1} \sum_{n=-\infty}^{\infty} x(n)z^{-n} \quad (3.0.5)$$

resulting in (3.0.2). Similarly, it can be shown that

$$\mathcal{Z}\{x(n-k)\} = z^{-k}X(z) \quad (3.0.6)$$

3.2 Find

$$H(z) = \frac{Y(z)}{X(z)} \quad (3.0.7)$$

from (2.0.4) assuming that the Z-transform is a linear operation.

Solution: From (3.0.6) and (2.0.4) we get,

$$\begin{aligned} H(z) &= \frac{Y(z)}{X(z)} \\ &= \frac{b[0] + b[1]z^{-1} + b[2]z^{-2} + b[3]z^{-3} + b[4]z^{-4}}{a[0] + a[1]z^{-1} + a[2]z^{-2} + a[3]z^{-3} + a[4]z^{-4}} \end{aligned} \quad (3.0.8)$$

where a and b are given by (2.0.1) and (2.0.2)

3.3 Let

$$H(e^{j\omega}) = H(z = e^{j\omega}). \quad (3.0.9)$$

Plot $|H(e^{j\omega})|$.

Solution: The following code plots Fig. 3.3.

```
codes/plot_H_jw.py
```

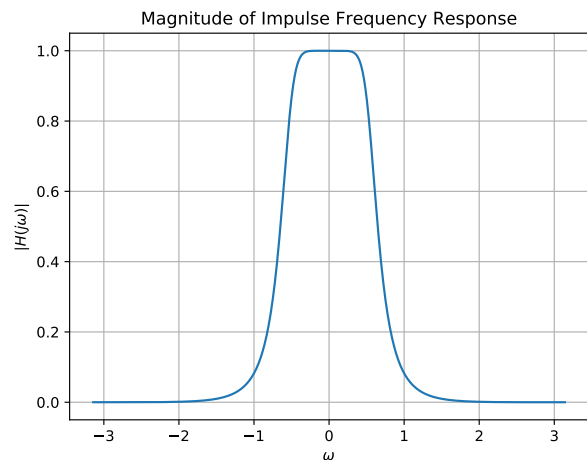


Fig. 3.3: $|H(e^{j\omega})|$

4 IMPULSE RESPONSE

4.1 Sketch $h(n)$.

Solution: $h(n)$ (impulse response) is the output of the system if the unit impulse $\delta(n)$ is given as the input. Substituting $x(n) = \delta(n)$ in Eq. (2.0.4), we get $h(n)$ of the system.

The following C code computes $h(n)$ from the difference equation (2.0.4)

```
codes/hn_compute.c
```

The following code plots Fig. 4.1

```
codes/hn_plot.py
```

4.2 Check whether $h(n)$ obtained is stable.

Solution: From BIBO stability criterion - for a

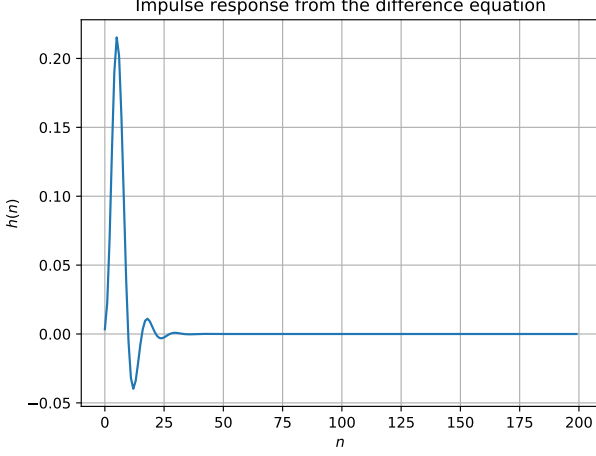


Fig. 4.1: Impulse Response ($h(n)$)

system to be stable, output should be bounded for any bounded input. Since the input $x(n)$ is bounded, if B_x is some finite value

$$|y(n)| \leq B_x \sum_{-\infty}^{\infty} |x(n-k)| \quad (4.0.1)$$

As $y(n)$ is the convolved output of $x(n)$ and $h(n)$

$$y(n) = h(n) * x(n) = x(n) * h(n) \quad (4.0.2)$$

Equation (4.0.1) implies,

$$|y(n)| = \left| \sum_{-\infty}^{\infty} h(k)x(n-k) \right| \quad (4.0.3)$$

$$|y(n)| \leq \sum_{-\infty}^{\infty} |h(k)| |x(n-k)| \quad (4.0.4)$$

Let B_x be the maximum value $x(n-k)$ can take, then

$$|y(n)| \leq B_x \sum_{-\infty}^{\infty} |h(k)| \quad (4.0.5)$$

If

$$\sum_{-\infty}^{\infty} |h(k)| < \infty \quad (4.0.6)$$

Then

$$|y(n)| \leq B_y < \infty \quad (4.0.7)$$

Therefore we can say that $y(n)$ is bounded if $x(n)$ and $h(n)$ are bounded. Since the audio input is bounded, the system is said to be stable

if $h(n)$ is also bounded

$$\sum_{n=-\infty}^{n=\infty} |h(n)| < \infty \quad (4.0.8)$$

The above equation can be re written as,

$$\sum_{n=-\infty}^{n=\infty} |h(n)z^{-n}|_{|z|=1} < \infty \quad (4.0.9)$$

$$\sum_{n=-\infty}^{n=\infty} |h(n)| |z^{-n}|_{|z|=1} < \infty \quad (4.0.10)$$

From Triangle inequality,

$$\left| \sum_{n=-\infty}^{n=\infty} h(n)z^{-n} \right|_{|z|=1} < \infty \quad (4.0.11)$$

$$\Rightarrow |H(z)|_{|z|=1} < \infty \quad (4.0.12)$$

For the system to be stable, the Region of Convergence (ROC) should include the unit circle. Since, $h(n)$ is right sided the ROC is outside the outer most pole. The following code computes the poles of the transfer function given by (3.0.8)

codes/compute_poles.py

Poles of the given transfer equation are:

$$z(\text{approx}) = 0.69786079 \pm 0.41316978j, \\ 0.56187146 \pm 0.13779107j \quad (4.0.13)$$

From the above poles, we can see that the ROC of the system is

$$|z| > \max(\sqrt{0.69^2 + 0.41^2}, \sqrt{0.56^2 + 0.13^2}) \quad (4.0.14)$$

$$|z| > \max(0.811, 0.578) \quad (4.0.15)$$

$$|z| > 0.811 \quad (4.0.16)$$

From (4.0.16), ROC of the system includes unit circle $|z| = 1$. Therefore, the given IIR filter is stable, since $h(n)$ is absolutely summable.

Verification:- Given bounded input $x(n)$ (audio sample) and system difference equation (2.0.4) From Fig. 2.2 we can see that the maximum value of $x(n)$ is 0.8311 and minimum value is around -0.9417. Similarly from Fig. 2.2 we can also observe that the maximum value of

$y(n)$ is 0.8362 and minimum value is -0.97 and it tends to zero after the length of signal. We can conclude that for the bounded input $x(n)$, the output $y(n)$ is bounded. Therefore, the system is BIBO stable.

4.3 Compute filtered output using convolution formula with $h(n)$ obtained in 4.1

$$y(n) = x(n) * h(n) = \sum_{n=-\infty}^{\infty} x(k)h(n-k) \quad (4.0.17)$$

Solution: The following code plots Fig. 4.3 where $y(n)$ is computed using convolution.

```
codes/conv_plot.py
```

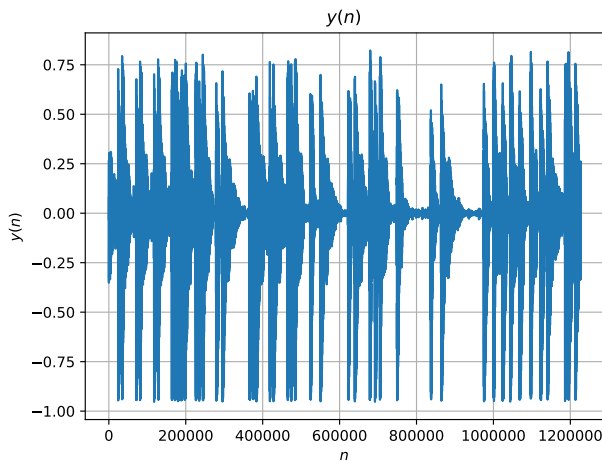


Fig. 4.3: $y(n)$ through convolution

We can observe that the output obtained in the Fig. 4.3 is same as $y(n)$ obtained in Fig. 2.2.

5 FFT AND IFFT

5.1 Compute

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (5.0.1)$$

and $H(k)$ using $h(n)$.

Solution: The audio sample $x(n)$ has been obtained in 2.2 and the impulse response $h(n)$

has been obtained in 4.1 DFT of the Input Signal $x(n)$ is

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (5.0.2)$$

DFT of the Impulse Response $h(n)$ is

$$H(k) \triangleq \sum_{n=0}^{N-1} h(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (5.0.3)$$

The following C code computes DFT of $x(n)$ and $h(n)$ efficiently using fft algorithm. It also computes IFFT of $Y(k)$ and creates a .dat file.

```
codes/fft.c
```

The following code plots FFTs of $x(n)$ and $h(n)$.

```
codes/fft_plot.py
```

Magnitude plots of $|X(k)|$ and $|H(k)|$

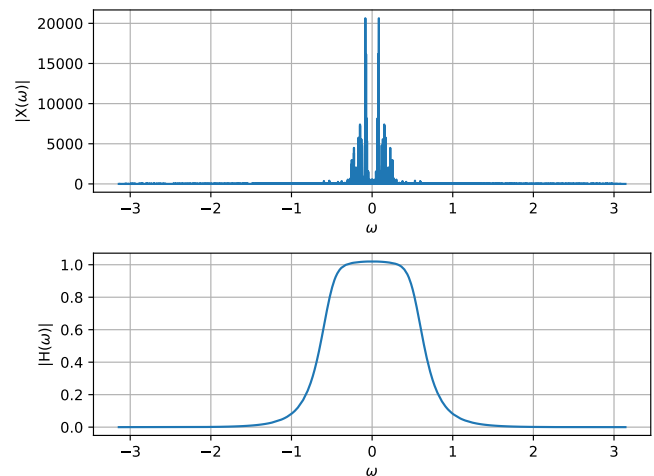


Fig. 5.1: $X(k)$ and $H(k)$

5.2 From

$$Y(k) = X(k)H(k) \quad (5.0.4)$$

Compute

$$y(n) \triangleq \sum_{k=0}^{N-1} Y(k)e^{j2\pi kn/N}, \quad n = 0, 1, \dots, N-1 \quad (5.0.5)$$

Solution: The following code computes the DFT of $y(n)$ by multiplying $X(\omega)$ and $H(\omega)$ and

subsequently computes inverse DFT of $Y(\omega)$ to get $y(n)$.

```
codes/iff.py
```

The following code plots $y(n)$.

```
codes/iff_plot.py
```

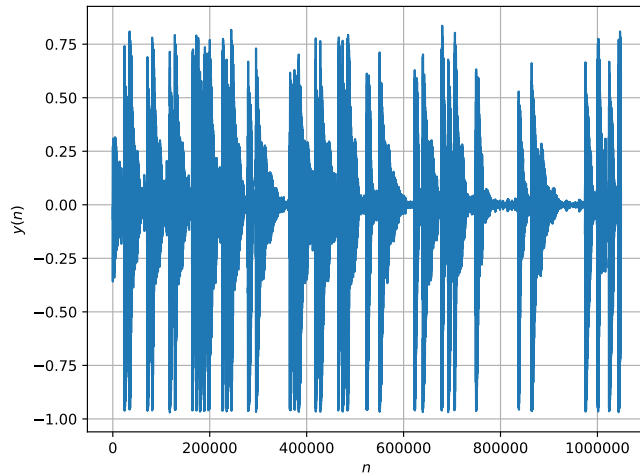


Fig. 5.2: $y(n)$ through ifft

We can observe from the Fig. 5.2 that it is same as the $y(n)$ observed in Fig.2.2