




Please read the Sunset Plan for SVL Simulator.



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Simulation Details

▲

Details unavailable since this is an API Only simulation.

Iterations

10

1

Status:

Failed

Cause:

EgoCollision

Start time:

5/10/2022, 11:54:11 AM

Real time duration:

00 : 00 : 34.000

Simulation time duration:

00 : 00 : 34.560

Bridge type:

CyberRT

Connection:

N/A

Analysis

Visualization

Sensors

CAN Bus

[Simulator.Sensors.CanBusSensor]

GearUsed:

1

MaxSpeed:

13.05 m/s

MaxThrottle:

0 (user input)

MaxBrake:

0 (user input)

MaxSteering:

0 °

GPS

[Simulator.Sensors.GpsSensor]

Start Latitude:

37.417 °

Start Longitude:

-122.016 °

Start Altitude:

-0.684 m

Start Northing:

4,141,628.644 m East

Start Easting:

587,061.315 m North

Start Map Url:

open Google Maps

Latitude:

37.417 °

Longitude:

-122.016 °

Altitude:

-2.064 m

Northing:

4,141,561.761 m East

Easting:

587,042.67 m North

Map Url:

open Google Maps

GPS Odometry

[`Simulator.Sensors.GpsOdometrySensor`]

Start Latitude:

37.417 °

Start Longitude:

-122.016 °

Start Altitude:

-0.684 m

Start Northing:

4,141,628.644 m East

Start Easting:

587,061.315 m North

Start Map Url:

open Google Maps

Latitude:

37.417 °

Longitude:

-122.016 °

Altitude:

-2.064 m

Northing:

4,141,561.761 m East

Easting:

587,042.67 m North

Map Url:

[open Google Maps](#)

GPS INS Status

[`Simulator.Sensors.GpsInsSensor`]

Status:

3 misc

Position Type:

56 misc

IMU

[`Simulator.Sensors.ImuSensor`]

minX:

-27.33 km

maxX:

0 km

minGyroX:

-0.027 °

maxGyroX:

0.016 °

minY:

-15.275 km

maxY:

51.644 km

minGyroY:

-0.022 °

maxGyroY:

0.007 °

minZ:

-2.12 km

maxZ:

0 km

minGyroZ:

-0.798 °

maxGyroZ:

0 °

3D Ground Truth

[Simulator.Sensors.PerceptionSensor3D]

MaxTracked:

1 counts

Signal Sensor

[Simulator.Sensors.SignalSensor]

SignalsDetected:

0 counts

DetectedStates:

red,green misc

Keyboard Car Control

[Simulator.Sensors.KeyboardControlSensor]

MaxSteer:

0 (user input)

MaxAccel:

0 (user input)

0 (user input)

MaxBrake:

0 (user input)

Wheel Car Control

[Simulator.Sensors.WheelControlSensor]

MaxSteer:

0 (user input)

MaxAccel:

0 (user input)

MaxBrake:

0 (user input)

Apollo Car Control

[Simulator.Sensors.ApolloControlSensor]

MaxSteer:

0.291 (user input)

MaxAccel:

0.991 (user input)

MaxBrake:

0 (user input)

IsControlReceived:

true misc

Clock Sensor

[Simulator.Sensors.ClockSensor]

SimulationDuration:

34.56 seconds

RealtimeDuration:

34.622 seconds

Callbacks