

Details unavailable since this is an API Only simulation.

Iterations

01

1

Status:

Success

Start time:

5/10/2022, 11:56:54 AM

Real time
duration:

00 : 00 : 18.000

Simulation
time
duration:

00 : 00 : 18.460

Bridge type:

CyberRT

Connection:

N/A

AnalysisVisualization

Sensors

CAN Bus

[Simulator.Sensors.CanBusSensor]

GearUsed:

1

MaxSpeed:

11.38 m/s

MaxThrottl

0 (user input)

e:

MaxBrake: 0 (user input)

MaxSteering: 0 °

GPS

[Simulator.Sensors.GpsSensor]

Start Latitude: 37.417 °

Start Longitude: -122.016 °

Start Altitude: -0.684 m

Start Northing: 4,141,589.975 m East

Start Easting: 587,051.081 m North

Start Map Url: **open Google Maps**

Latitude: 37.416 °

Longitude: -122.017 °

Altitude: -3.254 m

Northing: 4,141,489.374 m East

Easting: 587,027.491 m North

Map Url: **open Google Maps**

GPS Odometry

[Simulator.Sensors.GpsOdometrySe...

Start Latitude: 37.417 °

Start Longitude: -122.016 °

Start Altitude: -0.684 m

Altitude:

Start

Northing:

4,141,589.975 m East

Start

Easting:

587,051.081 m North

Start Map

Url:

open Google Maps

Latitude:

37.416 °

Longitude:

-122.017 °

Altitude:

-3.254 m

Northing:

4,141,489.374 m East

Easting:

587,027.491 m North

Map Url:

open Google Maps

GPS INS Status

[[Simulator.Sensors.GpsInsSensor](#)]

Status:

3 misc

Position

Type:

56 misc

IMU

[[Simulator.Sensors.ImuSensor](#)]

minX:

-42.492 km

maxX:

0 km

minGyroX:

-0 °

maxGyroX:

0.017 °

minY:

-87.564 km

maxY:

12.977 km

minGyroY:

-0.008 °

maxGyroY:

0.009 °

minZ:

-3.253 km

maxZ:

0 km

minGyroZ:

-0.799 °

maxGyroZ: 0 °

3D Ground Truth [Simulator.Sensors.PerceptionSen...

MaxTracke
d: 14 counts

Signal Sensor [Simulator.Sensors.SignalSensor]

SignalsDete
cted: 0 counts

DetectedSta
tes: misc

Keyboard Car Control [Simulator.Sensors.Keyboard...

MaxSteer: 0 (user input)
MaxAccel: 0 (user input)
MaxBrake: 0 (user input)

Wheel Car Control [Simulator.Sensors.WheelContr...

MaxSteer: 0 (user input)
MaxAccel: 0 (user input)
MaxBrake: 0 (user input)

Apollo Car Control [Simulator.Sensors.ApolloContr...

MaxSteer: 0.157 (user input)
MaxAccel: 0.983 (user input)
MaxBrake: 0 (user input)
IsControlR
eceived: true misc

Clock Sensor

[Simulator.Sensors.ClockSensor]

Simulation

Duration: 18.46 seconds

RealtimeDu

ration: 18.538 seconds

Callbacks