5/16/22, 7:40 PM

Iterations 0 1

1

Status: Success

Start time: 5/10/2022, 11:58:39 AM

Real time duration:

00:01:31.000

Simulation

time 00:01:30.870

duration:

Bridge type: CyberRT

Connection: N/A

Analysis

Visualization

Sensors

CAN Bus [Simulator.Sensors.CanBusSensor]

GearUsed: 1

13.697 m/s

MaxThrottl

MaxSpeed:

0 (user input)

e:

MaxBrake: 0 (user input)

MaxSteerin 0°

https://wise.svlsimulator.com/test-results/a1a7edfa-9e98-4d3c-8c4b-8c3c6156ed42

g:

GPS [Simulator.Sensors.GpsSensor]

Start

37.417°

Latitude:

Start

-122.016°

Longitude:

Start

-0.684 m

Start

4,141,628.644 m East

Northing:

Altitude:

Start

587,061.315 m North

Easting:

Start Map

open Google Maps

Url:

37.413°

Longitude:

Latitude:

-122.015 °

Altitude:

-7.639 m

Northing:

4,141,189.369 m East

Easting:

587,154.747 m North

Map Url:

open Google Maps

GPS Odometry [Simulator.Sensors.GpsOdometrySe...

Start

37.417°

Latitude:

Start

-122.016°

Longitude:

Start

-0.684 m

Altitude:

Start

4,141,628.644 m East

Northing:

Start

597 061 215 m North

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Easting:

Start Map

open Google Maps

Url:

Latitude: 37.413 °

Longitude: -122.015°

Altitude: -7.639 m

Northing: 4,141,189.369 m East

Easting: 587,154.747 m North

Map Url: open Google Maps

GPS INS Status [Simulator.Sensors.GpsInsSensor]

Status: 3 misc

Position

56 misc

Type:

IMU [Simulator.Sensors.ImuSensor]

minX: -104.677 km

maxX: 84.747 km

minGyroX: -0.018 °

maxGyroX: 0.03 °

minY: -387.631 km

maxY: 51.644 km

minGyroY: -0.009°

maxGyroY: 0.014 °

minZ: -7.667 km

maxZ: 0 km

minGyroZ: -0.798 °

maxGyroZ: 0°

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MaxTracke

0 counts

d:

Signal Sensor [Simulator.Sensors.SignalSensor]

SignalsDete

0 counts

cted:

DetectedSta

red, green misc

tes:

Keyboard Car Control [Simulator.Sensors.Keyboard...

MaxSteer: 0 (user input)

MaxAccel: 0 (user input)

MaxBrake: 0 (user input)

Wheel Car Control Simulator. Sensors. Wheel Contr...

MaxSteer: 0 (user input)

MaxAccel: 0 (user input)

MaxBrake: 0 (user input)

Apollo Car Control [Simulator.Sensors.ApolloContr...

MaxSteer: 0.3 (user input)

MaxAccel: 0.986 (user input)

MaxBrake: 0 (user input)

IsControlR

true misc

eceived:

Clock Sensor [Simulator.Sensors.ClockSensor]

Simulation

90.87 seconds

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RealtimeDu

90.939 seconds

ration:

Callbacks