Details unavailable since this is an API Only simulation.

Iterations   0   1

1

Status: Success

Start time: 5/10/2022, 11:57:40 AM

Real time
duration: 00 : 00 : 19.000

Simulation
time
duration: 00 : 00 : 4.270

Bridge type: CyberRT

Connection: N/A

| Analysis | Visualization |

Sensors

CAN Bus   **[Simulator.Sensors.CanBusSensor]**

GearUsed: 1

MaxSpeed: 12.819 m/s

MaxThrottl   0 (user input)
e:

MaxBrake: 0 (user input)

MaxSteerin
g:
                 0 °

GPS   [Simulator.Sensors.GpsSensor]

Start
Latitude: 37.414 °

Start
Longitude: -122.017 °

Start
Altitude: -7.121 m

Start
Northing: 4,141,235.349 m East

Start
Easting: 586,980.997 m North

Start Map
Url: **open Google Maps**

Latitude: 37.414 °

Longitude: -122.017 °

Altitude: -7.196 m

Northing: 4,141,228.335 m East

Easting: 587,007.003 m North

Map Url: **open Google Maps**

GPS Odometry   [Simulator.Sensors.GpsOdometrySe…

Start
Latitude: 37.414 °

Start
Longitude: -122.017 °

Start
Altitude: -7.121 m

Start

Northing:	4,141,235.349 m East
Start Easting:	586,980.997 m North
Start Map Url:	**open Google Maps**
Latitude:	37.414 °
Longitude:	-122.017 °
Altitude:	-7.196 m
Northing:	4,141,228.335 m East
Easting:	587,007.003 m North
Map Url:	**open Google Maps**

GPS INS Status   [Simulator.Sensors.GpsInsSensor]

Status:	3 misc
Position Type:	56 misc

IMU   [Simulator.Sensors.ImuSensor]

minX:	-89.003 km
maxX:	0 km
minGyroX:	0 °
maxGyroX:	0.021 °
minY:	-348.665 km
maxY:	0 km
minGyroY:	-0.002 °
maxGyroY:	0.003 °
minZ:	-7.196 km
maxZ:	0 km
minGyroZ:	-0.131 °
maxGyroZ:	0 °

3D Ground Truth   [Simulator.Sensors.PerceptionSen…

MaxTracked: 0 counts

Signal Sensor   [Simulator.Sensors.SignalSensor]

SignalsDetected: 0 counts

DetectedStates: misc

Keyboard Car Control   [Simulator.Sensors.Keyboard…

MaxSteer: 0 (user input)

MaxAccel: 0 (user input)

MaxBrake: 0 (user input)

Wheel Car Control   [Simulator.Sensors.WheelContr…

MaxSteer: 0 (user input)

MaxAccel: 0 (user input)

MaxBrake: 0 (user input)

Apollo Car Control   [Simulator.Sensors.ApolloContr…

MaxSteer: 0.004 (user input)

MaxAccel: 0.339 (user input)

MaxBrake: 0 (user input)

IsControlReceived: true misc

Clock Sensor	[Simulator.Sensors.ClockSensor]

Simulation Duration:	4.27 seconds
RealtimeDuration:	4.329 seconds

Callbacks

Clock Sensor	[Simulator.Sensors.ClockSensor]