⚠ **Please read the Sunset Plan for SVL Simulator.**

☰   ⬢   S   sudha ▾

⌁ Sharing   🗑 Delete   ▾

Simulation Details   ▾

Iterations   0   2

| 1 | | 2 |

Status:

Success

Start time:

5/10/2022, 11:50:01 AM

Real time duration:

00 : 01 : 17.000

Simulation time duration:

00 : 00 : 41.000

Bridge type:

CyberRT

Connection:

| Analysis | Visualization |

N/A

Sensors

CAN Bus   [Simulator.Sensors.CanBusSensor]

GearUsed:

  1

MaxSpeed:

  1.042 m/s

MaxThrottle:

  0 (user input)

MaxBrake:

  0 (user input)

MaxSteering:

  0 °

GPS   [Simulator.Sensors.GpsSensor]

Start Latitude:

  37.417 °

Start Longitude:

  -122.016 °

Start Altitude:

  -0.684 m

Start Northing:

  4,141,628.644 m East

Start Easting:

  587,061.315 m North

Start Map Url:

  open Google Maps

Latitude:

37.417 °

Longitude:

-122.016 °

Altitude:

-0.74 m

Northing:

4,141,628.642 m East

Easting:

587,061.314 m North

Map Url:

open Google Maps

GPS Odometry   [Simulator.Sensors.GpsOdometrySensor]

Start Latitude:

37.417 °

Start Longitude:

-122.016 °

Start Altitude:

-0.684 m

Start Northing:

4,141,628.644 m East

Start Easting:

587,061.315 m North

Start Map Url:

open Google Maps

Latitude:

37.417 °

Longitude:

-122.016 °

Altitude:

-0.74 m

Northing:

4,141,628.642 m East

Easting:

587,061.314 m North

Map Url:

open Google Maps

GPS INS Status   [Simulator.Sensors.GpsInsSensor]

Status:

3 misc

Position Type:

56 misc

IMU   [Simulator.Sensors.ImuSensor]

minX:

-8.689 km

maxX:

0 km

minGyroX:

-0 °

maxGyroX:

0.015 °

minY:

0 km

maxY:

51.644 km

minGyroY:

-0 °

maxGyroY:

  0.005 °

minZ:

  -0.75 km

maxZ:

  0 km

minGyroZ:

  -0.792 °

maxGyroZ:

  0 °

3D Ground Truth   [Simulator.Sensors.PerceptionSensor3D]

MaxTracked:

  0 counts

Signal Sensor   [Simulator.Sensors.SignalSensor]

SignalsDetected:

  0 counts

DetectedStates:

  red,green,yellow misc

Keyboard Car Control   [Simulator.Sensors.KeyboardControlSensor]

MaxSteer:

  0 (user input)

MaxAccel:

  0 (user input)

MaxBrake:

  0 (user input)

Wheel Car Control   [Simulator.Sensors.WheelControlSensor]

MaxSteer:

   0 (user input)

MaxAccel:

   0 (user input)

MaxBrake:

   0 (user input)

Apollo Car Control   [Simulator.Sensors.ApolloControlSensor]

MaxSteer:

   0 (user input)

MaxAccel:

   0.5 (user input)

MaxBrake:

   0 (user input)

IsControlReceived:

   true misc

Clock Sensor   [Simulator.Sensors.ClockSensor]

SimulationDuration:

   41 seconds

RealtimeDuration:

   41.06 seconds

Callbacks