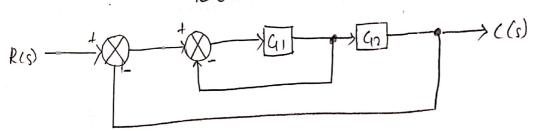
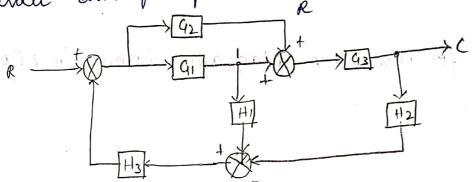
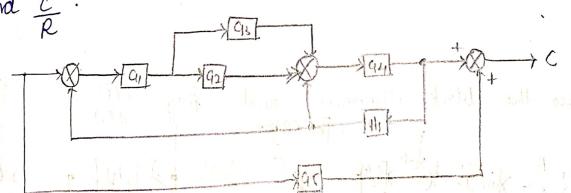
O leger the vlock diagram shown in Fig. Using block idiagram vuduction techniques, $\exists lnd$ the overall teamsfer function $\frac{4 co}{R(s)}$.



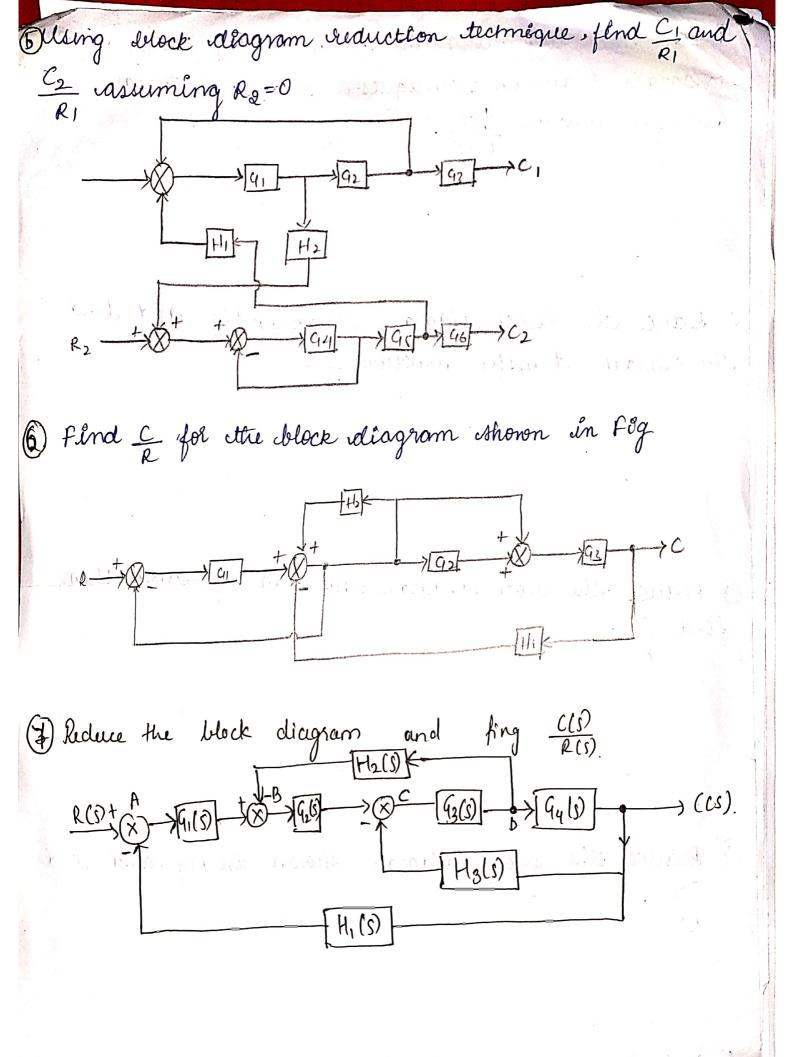
Deduce the Block diagram shown in Fig and find the order transfer function \subseteq .



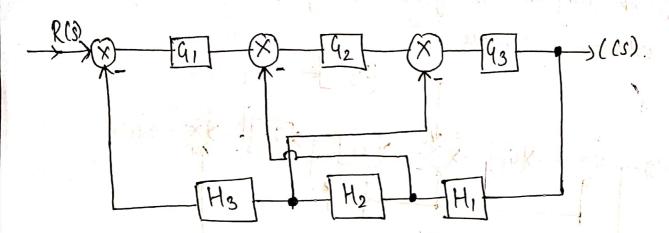
③ Reduce the block diagram shown in Fig. and then find $\frac{C}{0}$.



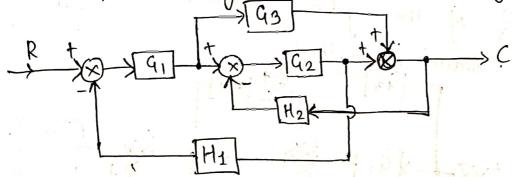
Res) Reduce the block diagram shown in Fig and find



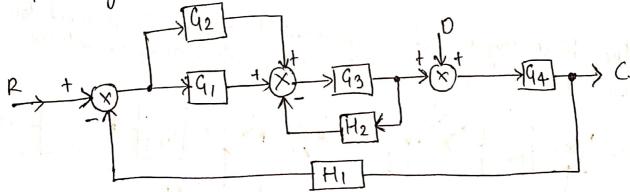
(8) Obtain C(5)/R(s) using block diagram reduction rules.



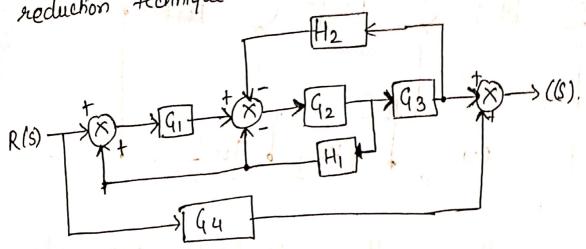
and R for the system whose block diagram is shown:



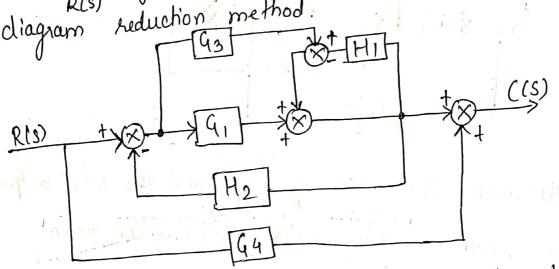
(i) Determine the ratio $\frac{C}{R}$, $\frac{C}{D}$ and the total output for the system whose block diagram is shown.



Deturnine the tecansfer functions of a system whose block diagram is given using the block diagram reduction technique.

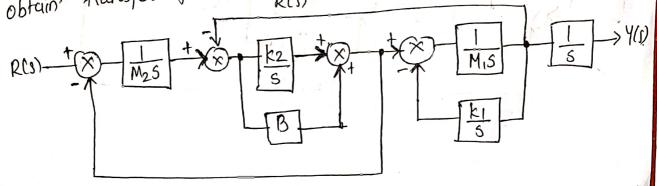


(12) Obtain <u>CCS</u>) of the system shown below using block diagram reduction method.



(3) The block diagram of a mechanical system is shown below.

Obtain transfer function 4(s) using block diagram reduction rules



Using block diagram reduction, find the transfer function from each ilp to olp (R / X / Y)

X

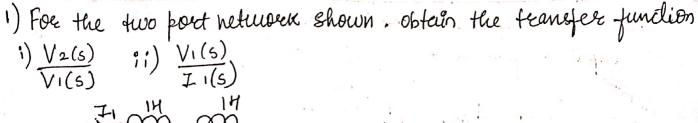
GA

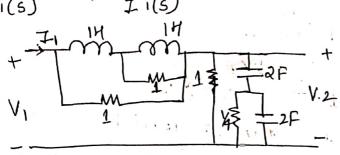
H2

H2

H2

H3





- 2) For a single loop unity feed back system the unit step response is given by $C(t) = 1-3e^{2t} + 2e^{3t}$ Evaluate
 - i) closed loop Transfer function
 - ii) open loop Tranger function
- 3) A certain System is described by a differential equation $\frac{d^2y(t)}{dt^2} + 3\frac{dy(t)}{dt} + 11 y(t) = 5 n(t) \text{ where } y(t) \text{ is the output and } the n(t) \text{ is obtain, obtain the teamsfer function of the System}$
- 4) A certain system how its transfer as $\frac{C(s)}{R(s)} = \frac{2s+1}{s^2+s+1}$ obtain its differential equation
- 5) If a System equation is given as $3 \pm ((t) + 2((t) = 8(t-T))$ where ((t)) is output & 8(t) is input shifted by T seconds. Obtain its teamsfer function
- 6) Defermine the transfer function if the Dc gain is equal to 10 for the System whose pole-zero plot is shown below $*-19^{i}$ maginary

Real

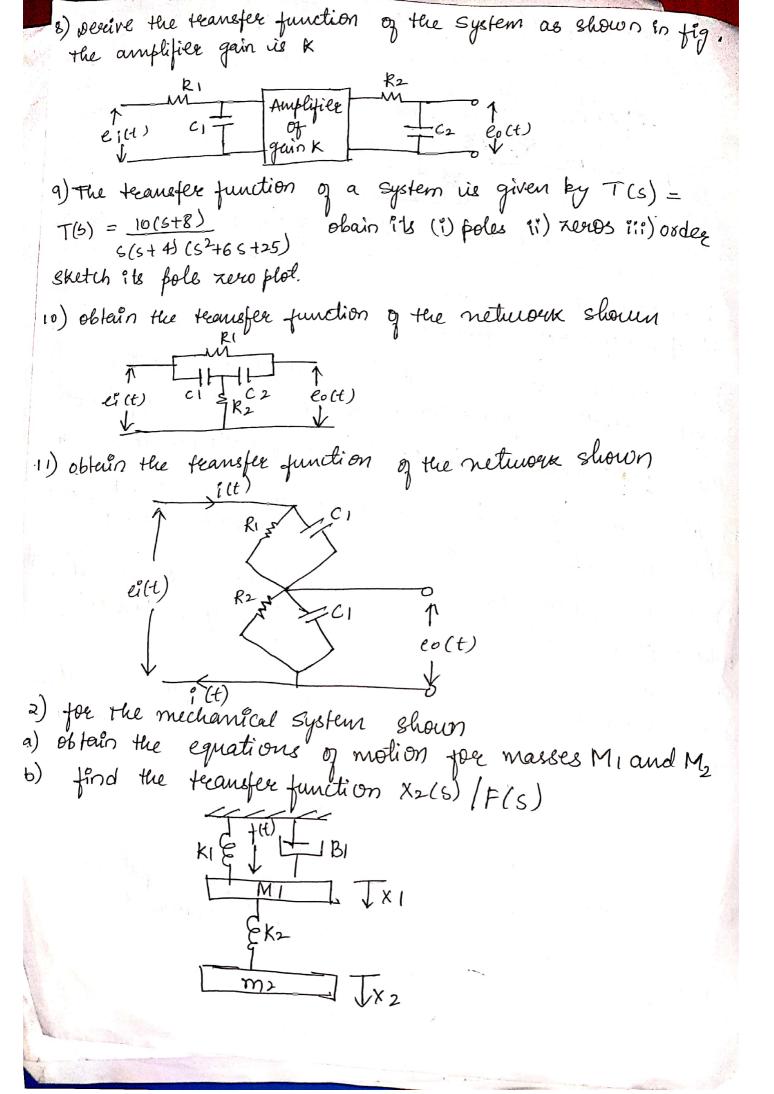
-3-21-10

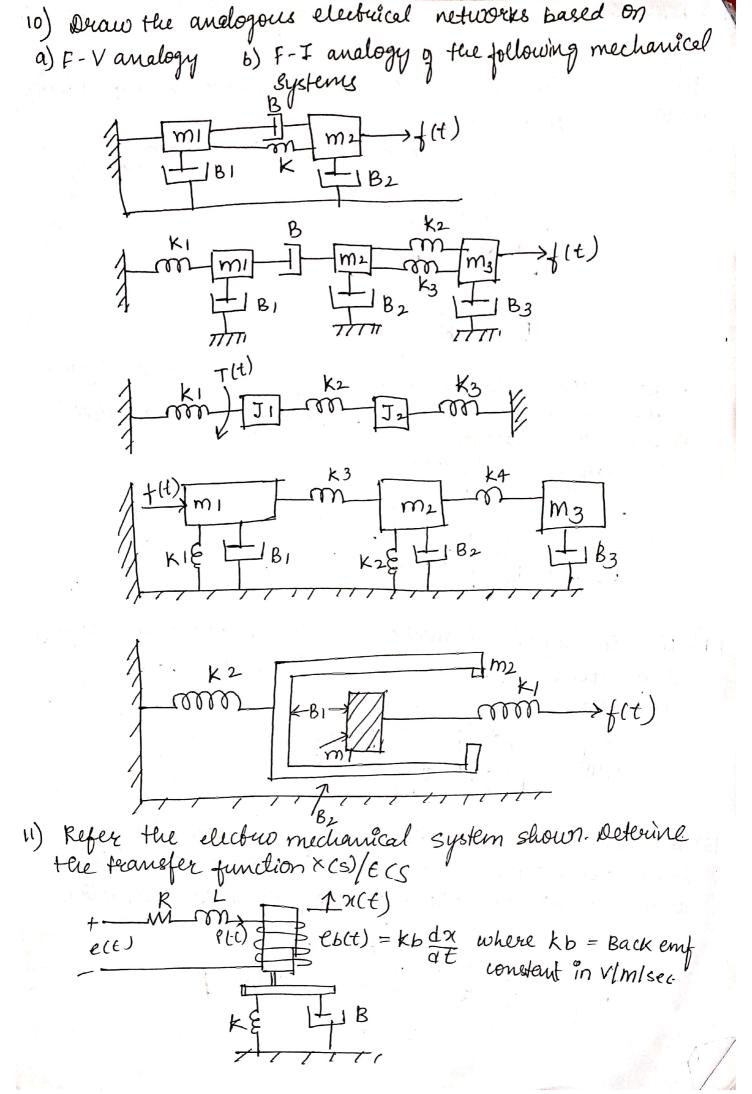
X----
Real

Real

A System when enrifed by unit

7) A system when encited by unit step type of input gives following response $C(t) = 1 - 2e^t + 4e^{3t}$ obtain its teausfer function C(s)/R(s)

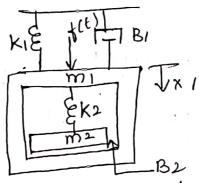




(2) Refer the mechanical system shows in fig a) Decaw the mechanical network

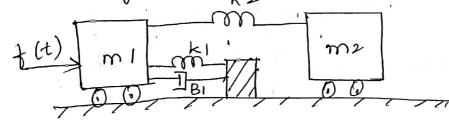
b) from the mechanical network drawn, write the differential equations of performance

c) Deaw the electrical network based on F-Vanalogy

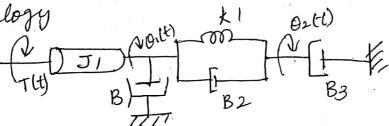


13) a) oraw the mechanical network for the mechanical system shows below

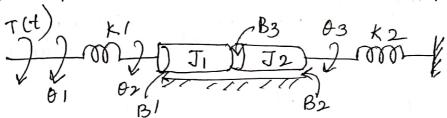
6) Dean the analogous electric circuit in which force is analogous to coverent

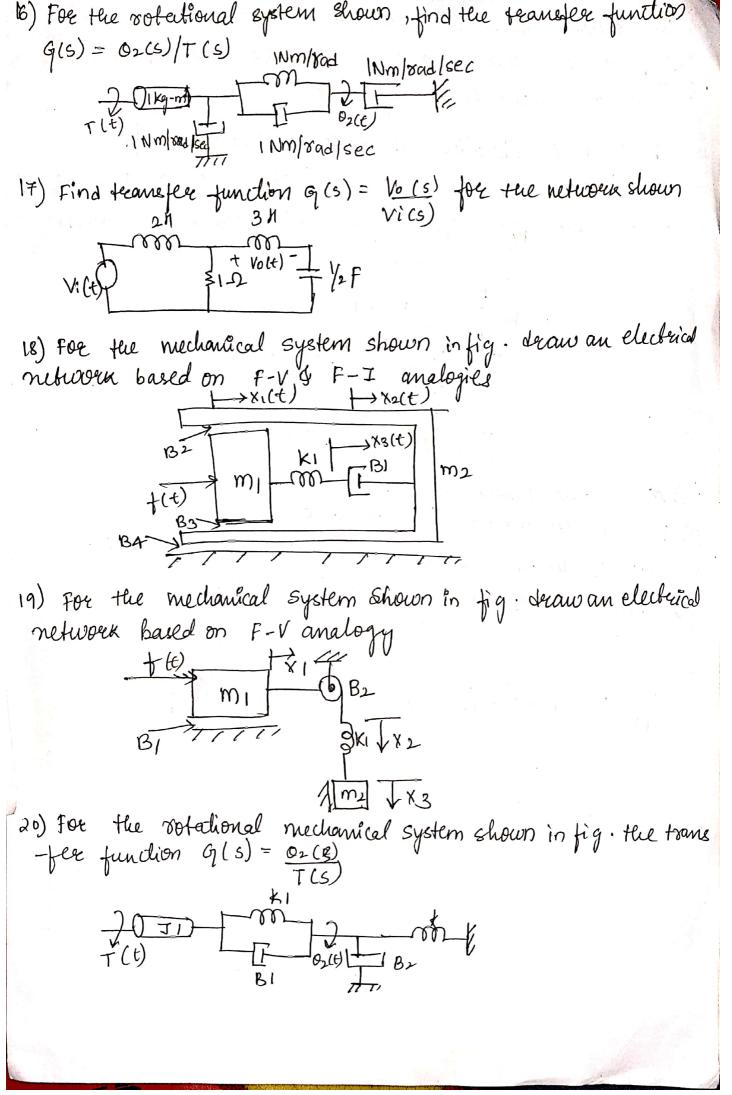


14) for the rotational mechanical system shown in figure. draw an electrical network based on torque-Voltage analogy &1 Arti)

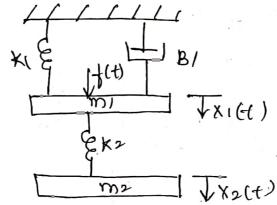


15) For the rotational mechanical system shows in fig. draw an electrical network based on torque - current analogy. Give all the neccessary cause effect equality





- 21) An automobile driver uses a control system to maintering the speed of a car at a prescribed level. Sketch the block diagram to illustrate this feedback system
- 22) A dynamic Vibration absorber is shown in fig
- a) sketch the analogous electrical cht based on F-I analogy
- b) obtain the differential equations rescribing the system



- a) Draw the shown figure
- 6) write the differential equations of performance
- c) Draw the analogous electric coruit,

