

Gram Schmidt Orthogonalization Procedure:-

Consider a set of M energy signals $x_1(t)$, $x_2(t)$, $x_3(t)$, ..., $x_M(t)$.

ex:- DPSK modulation $M=2$

for bit 1 $\rightarrow x_1(t)$ is transmitted

bit 0 $\rightarrow x_2(t)$ is transmitted

In general we will have M array modulation scheme.

To find no. of basis function required to represent all M signals. \therefore We use Gram Schmidt Orthogonalization Scheme to find out no. of orthonormal basis functions

^{first}
The ^{1st} basis function is found as follows:-

First find energy of 1st signal as

$$E_1 = \int_0^T x_1^2(t) dt \quad \begin{array}{l} T - \text{symbol duration} \\ x_1(t) - \text{real valued signal} \end{array}$$

1st orthonormal basis function is given as

$$\phi_1(t) = \frac{x_1(t)}{\sqrt{E_1}}$$

orthonormal means -
to have unit energy.

In order to have unit energy
we normalise $x_1(t)$ by \div by $\sqrt{E_1}$

To find other orthonormal basis functions, we go for intermediate signal $g_i(t)$.

$$g_i(t) = x_i(t) - \sum_{j=1}^{i-1} x_{ij} \phi_j(t) \quad \begin{array}{l} i \rightarrow \text{index of possible} \\ \text{transmitted waveform} \\ i = 1, 2, \dots, M \end{array}$$

always $N \leq M$.

where,

$$x_{ij} = \int_0^T x_i(t) \phi_j(t) dt \quad j = 1, 2, \dots, i-1$$

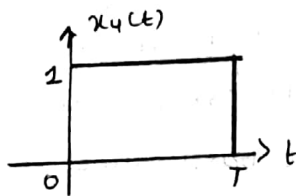
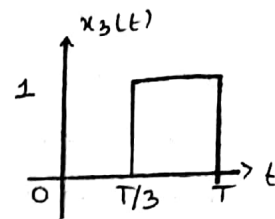
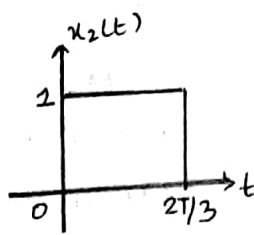
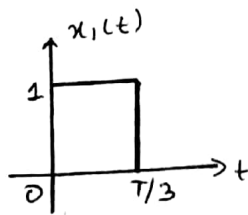
$j \rightarrow$ index of basis function
 $j = 1, 2, \dots, \textcircled{N}$ no. of basis functions

\hookrightarrow projection of $x_i(t)$ on $\phi_j(t)$

From given $g_i(t)$ {intermediate signal}, a new set of basis functions are defined as

$$\phi_i(t) = \frac{g_i(t)}{\sqrt{\int_0^T g_i^2(t) dt}} \quad i = 2, 3, \dots, N$$

Example:- Using Gram-Schmidt Orthogonalisation Procedure, find orthonormal basis functions for set of given signals

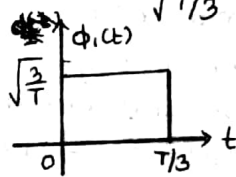


Given:- $M=4$, $N=?$ $\phi_1(t)=?$ $\phi_2=?$...

Max value of $N=M$

$$\phi_1(t) = \frac{x_1(t)}{\sqrt{E_1}}, \quad E_1 = \int_0^{T/3} 1^2 \cdot dt = T/3$$

$$\phi_1(t) = \frac{x_1(t)}{\sqrt{T/3}} = \sqrt{\frac{3}{T}} x_1(t) \quad 0 \leq t \leq T/3$$



Intermediate signal:-

$$g_i(t) = x_i(t) - \sum_{j=1}^{i-1} x_{ij} \phi_j(t)$$

Sub. $i=2$

$$g_2(t) = x_2(t) - \sum_{j=1}^1 x_{2j} \phi_j(t)$$

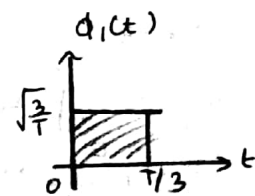
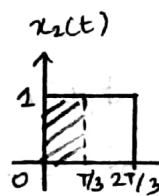
Substitute $j=1$

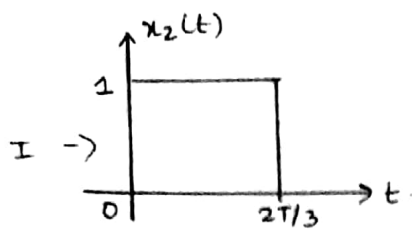
$$g_2(t) = x_2(t) - x_{21} \phi_1(t)$$

$$x_{21} = \int_0^T x_2(t) \phi_1(t) \cdot dt$$

$$\Rightarrow \int_0^{T/3} (1) \left(\sqrt{\frac{3}{T}} \right) \cdot dt$$

$$\Rightarrow \sqrt{\frac{3}{T}} \cdot \frac{T}{3} \Rightarrow \sqrt{\frac{T}{3}}$$

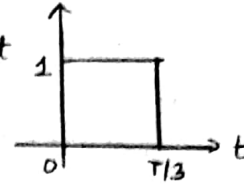




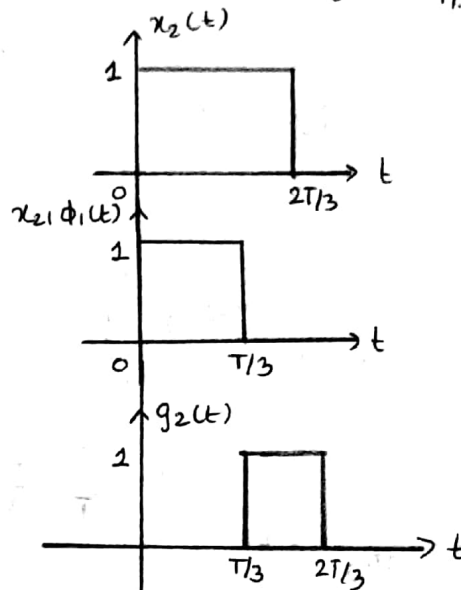
$$g_2(t) = x_2(t) - x_{21}\phi_1(t)$$

$$x_{21} = \sqrt{\frac{T}{3}}$$

$$x_{21}\phi_1(t) = \sqrt{\frac{T}{3}} \times \sqrt{\frac{3}{T}} = 1 \Rightarrow \text{resultant II} \rightarrow$$



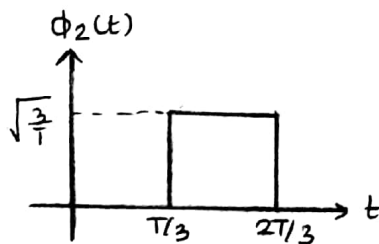
Subtract I & II



Energy of $g_2(t)$

$$= \int_0^T g_2^2(t) \cdot dt = \int_{T/3}^{2T/3} 1^2 \cdot dt = \frac{T}{3}$$

$$\phi_2(t) = \frac{g_2(t)}{\sqrt{T/3}} = \sqrt{\frac{3}{T}} g_2(t), \quad T/3 \leq t \leq 2T/3$$



$$\int \phi_2^2(t) \cdot dt = \frac{3}{T} \cdot \frac{T}{3} = 1$$

\hookrightarrow orthogonal.

$$\int_0^T \phi_1(t) \phi_2(t) \cdot dt = 0$$

To find 3rd basis function:-

$$g_i(t) = x_i(t) - \sum_{j=1}^{i-1} x_{ij} \phi_j(t)$$

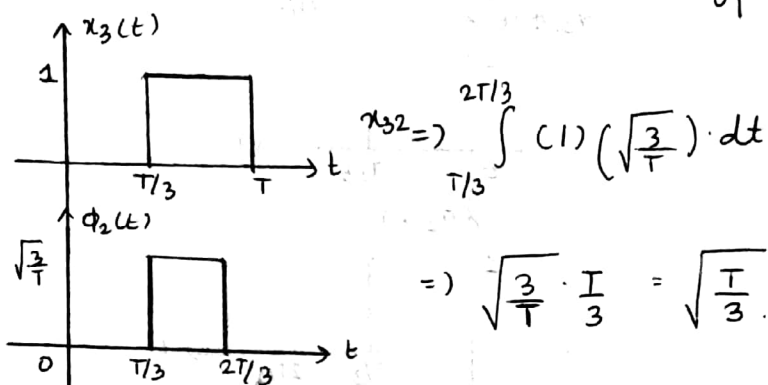
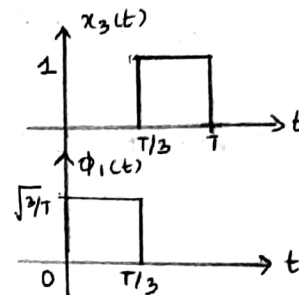
Sub $i=3$.

$$g_3(t) = x_3(t) - \sum_{j=1}^2 x_{3j} \phi_j(t)$$

$$g_3(t) = x_3(t) - x_{31} \phi_1(t) - x_{32} \phi_2(t)$$

$$x_{31} = \int_0^T x_3(t) \phi_1(t) \cdot dt = 0$$

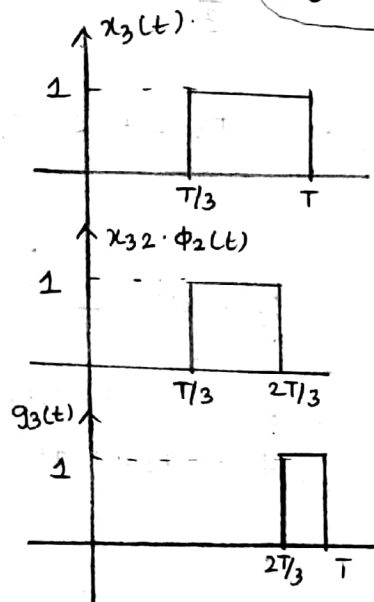
$$x_{32} = \int_0^T x_3(t) \phi_2(t) \cdot dt$$



$$x_{32} = \int_{T/3}^{2T/3} (1) \left(\sqrt{\frac{3}{T}} \right) \cdot dt$$

$$= \Rightarrow \sqrt{\frac{3}{T}} \cdot \frac{T}{3} = \sqrt{\frac{T}{3}}$$

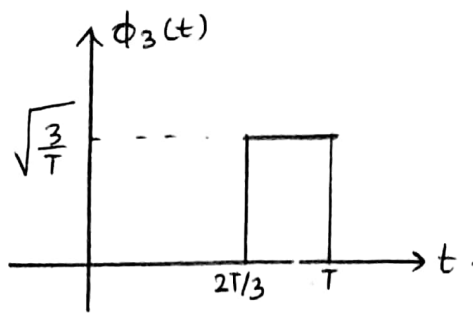
$$g_3(t) = x_3(t) - \left(\sqrt{\frac{T}{3}} \phi_2(t) \right) \rightarrow \sqrt{\frac{T}{3}} \cdot \sqrt{\frac{3}{T}} = 1 \times \phi_2(t)$$



$$\text{Energy of } g_3(t) = \int_{2T/3}^T g_3^2(t) dt = \int_{2T/3}^T 1 \cdot dt$$

$$= \Rightarrow T - \frac{2T}{3} = \frac{T}{3}$$

$$\phi_3(t) = \frac{g_3(t)}{\sqrt{T/3}} \Rightarrow \sqrt{\frac{3}{T}} g_3(t) \quad \frac{2T}{3} \leq t \leq T$$



$$g_i(t) = x_i(t) - \sum_{j=1}^{i-1} x_{ij}(t) \phi_j(t)$$

Sub $i=4$.

$$g_4(t) = x_4(t) - \sum_{j=1}^4 x_{4j}(t) \phi_j(t)$$

$$\Rightarrow x_4(t) - x_{41} \phi_1(t) - x_{42} \phi_2(t) - x_{43} \phi_3(t).$$

$$x_{41} = \int_0^T x_4(t) \phi_1(t) \cdot dt$$

$$\Rightarrow \int_0^{T/3} (1) \left(\sqrt{\frac{3}{T}} \right) \cdot dt$$

$$x_{41} \Rightarrow \sqrt{\frac{3}{T}} \cdot \frac{T}{3} = \sqrt{\frac{T}{3}}$$

$$x_{42} = \int_0^T x_4(t) \phi_2(t) \cdot dt$$

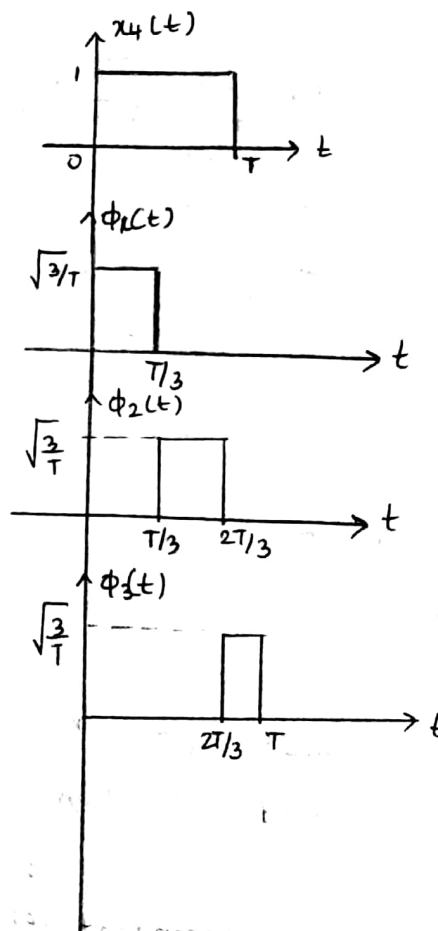
$$\Rightarrow \int_{T/3}^{2T/3} (1) \sqrt{\frac{3}{T}} \cdot dt$$

$$= \sqrt{\frac{3}{T}} \left(\frac{2T}{3} - \frac{T}{3} \right)$$

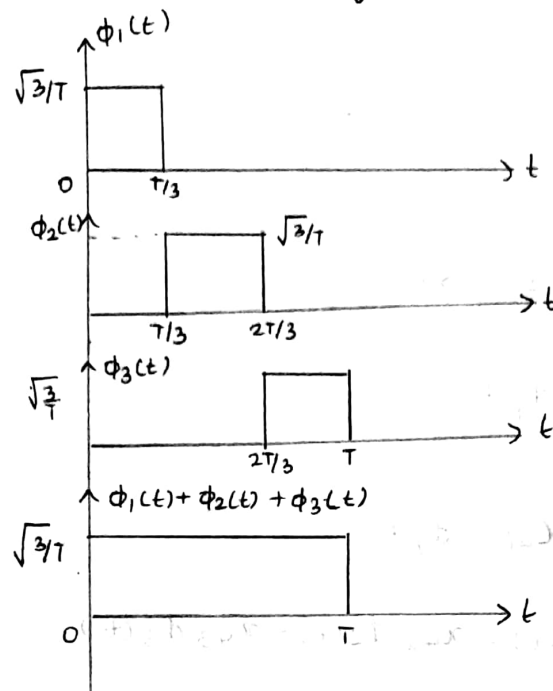
$$x_{42} \Rightarrow \sqrt{\frac{T}{3}}$$

$$x_{43} = \int_0^T x_4(t) \phi_3(t) \cdot dt$$

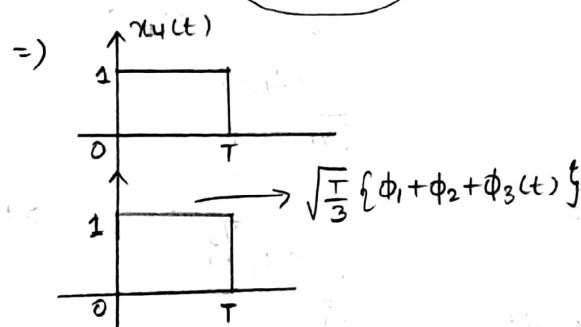
$$\Rightarrow \int_{2T/3}^T (1) \sqrt{\frac{3}{T}} \cdot dt = \sqrt{\frac{3}{T}} \left(\frac{2T}{3} - \frac{T}{3} \right) = \sqrt{\frac{T}{3}}$$



$$g_4(t) = x_4(t) - \sqrt{\frac{T}{3}} \left\{ \phi_1(t) + \phi_2(t) + \phi_3(t) \right\}$$



$$\Rightarrow x_4(t) - \left(\sqrt{\frac{T}{3}} \times \sqrt{\frac{3}{T}} \right) \Rightarrow 1$$



$$g_4(t) = 0.$$

$$\phi_4(t) = 0.$$

NOTE :-

- * If signals $x_1(t), x_2(t), \dots, x_M(t)$ form linearly independent set, then $N = M$.
- * If signals $x_1(t), x_2(t), \dots, x_M(t)$ are not linearly independent set then $N < M$.

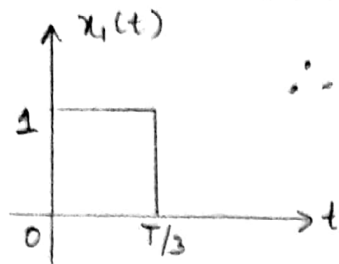
Here in the example, $x_1(t) + x_3(t) = x_4(t)$

\therefore No of orthonormal func = 3 (No of independent signals).

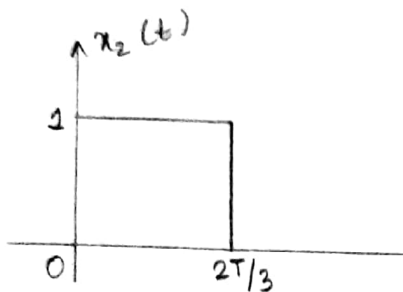
3 \rightarrow linearly independent signals

4th signal is linearly dependent (i.e $x_4(t) = x_1(t) + x_3(t)$)

To represent $x_1(t), x_2(t), x_3(t), x_4(t)$ in terms of orthonormal func
w.k.t $\phi_1(t) = x_1(t)/\sqrt{T/3}$



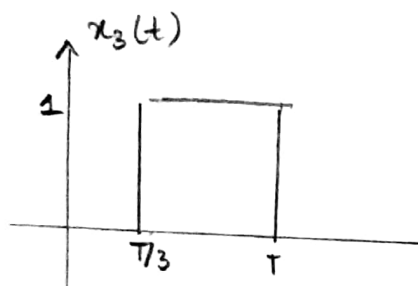
$$\therefore x_1(t) = \sqrt{\frac{T}{3}} \cdot \phi_1(t)$$



$$x_2(t) = \sqrt{\frac{T}{3}} \phi_1(t) + \sqrt{\frac{T}{3}} \phi_2(t)$$

$\phi_1(t)$ varies from $0 \leq t \leq T/3$

$\phi_2(t)$ varies from $T/3 \leq t \leq \frac{2T}{3}$

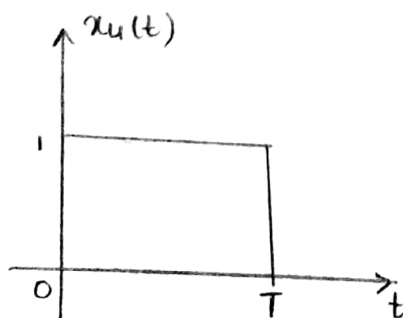


$$x_3(t) = \sqrt{\frac{T}{3}} \phi_2(t) + \sqrt{\frac{T}{3}} \phi_3(t)$$

\hookrightarrow scaling factor

$\phi_2(t)$ varies from $T/3 \leq t \leq 2T/3$

$\phi_3(t)$ varies from $\frac{2T}{3} \leq t \leq T$



$$x_4(t) = x_1(t) + x_3(t)$$

$$= \sqrt{\frac{T}{3}} \{ \phi_1(t) + \phi_2(t) + \phi_3(t) \}$$