## **KUMAR P**

Ideal Solution / Nyquist Solution for Zero ISI

In baseband transmission of digital data, ISI is the major problem ISI can be minimized by controlling pulse spectrum P(t) / P(f) of the overall system Lincluding transmit filter, channel & receive filter).

P(t) - time domain, P(f) - frequency domain

In order to meet zero ISI, Nyquist criterion for distortion less baseband transmission must be fulfilled.

P(t) = sinc(2Bot) -> function which fulfills requirement of zero ISI

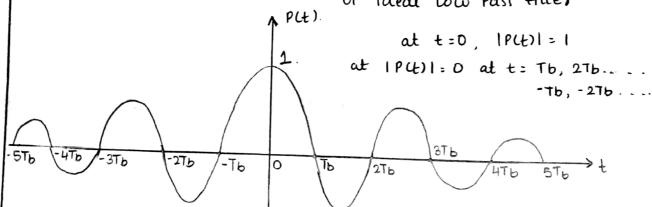
Through this func P(t), we get ideal solution.

P(t) = sinc (2Bot) Bo = 1 (Nyquist bandwidth)
2Tb.

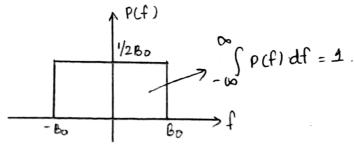
Bo-, min. B.W for zero ISI

 $P(t) = \operatorname{Sinc}\left(\frac{t}{Tb}\right)$  Tb -> bit duration.

PCt) is shown in fig (1). which characterise impulse response of ideal low Pass filter



Using Fourier Transform, P(t) (F.T) PCf) as shown in fig.
rect pulse of magnitude 1/280 & width 280. Area under curve is unity



PCF) mathematically given as PCf) = of 1/280, If 1 < Bo -) frequency response of ideal o, If 1 > Bo low pass filter. Ideal Solution: we take P(t)= Sinc (2Bot)  $Bo = \frac{1}{2Tb}$ as shown in figc1). IP(t) 1 = 0 at Tb, 2Tb... g int multiple -Tb, -2Tb... of Tb. : P(t) can be written as. PCt-KTb) = Sinc [2Bo(t-KTb)] K-integral multiple -ve sign -> delay in time. In baseband transmission of binary data, modified PAM signal = y(t) given as y(t) = u = ak p(t-k7b) In order to get zero ISI, olf y(t) is sampled at t=0, ± Tb, 1276 . a o ... To get ideal solution, put p(t) = Sinc(2Bot) in below ytt) = u \( \tilde{\Sigma} \) akp(t-KTb) p(t) = sinc (2Bot) y(t) = u ∑ ak sin c (2Bo(t-KTb) g w.k.t  $B_0 = \frac{1}{2Th}$  or  $2B_0Tb = 1$ y(t) = u \( \sum\_{k=-\infty} \) ak sinc [280t - 280Tb.k] modified of is ylt) = U \( \sinc \) ak sinc [2Bot-k]

In ISI, there is inaccurate synchronication of the clock in the receiver sampling circuit Here, we consider timing error(At) in place of Lt).

olp becomes

Y (At) = M I ak sinc [2BO At-k]

Using normalise sinc formula i.e sincx = sintx we write

y(Δt) = μ Σ ακ sin [280πΔt-πκ]
π[280Δt-κ]

We consider numerator in above expression, sin(A-B).

we get

y(Δt) = μ \( \sum\_{K=-\infty} \frac{\alpha \kappa \sum\_{L=0} \frac{\alpha \kappa \left}{\pi \left[ 280 \Delta t - \kappa \right]} \( \sin \frac{\alpha \kappa \cos (\pi \kappa \kappa \tappa \cos (\pi \kappa \kappa \tappa \kappa \kappa \tappa \kappa \kapp

SinTK = 0. -) I term in num = 0.

replace cosTK = (-1) K in I term.

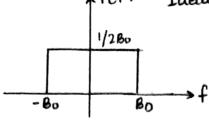
 $y(\Delta t) = \mu \sum_{K=-\infty}^{\infty} \frac{a_K}{\pi [2B_0\Delta t - K]} (-1)^K \sin(2B_0\pi \Delta t)$ 

Separate summation for K=0 & K+0 we get.

I term is desired symbol & can be written as Mao sinc (2Bo ΔE)

I term -> IsI caused by timing error Dt. This term delay slowly at rate i due to discontinuity of P(f) at +Bo

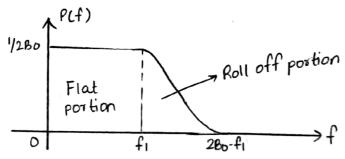
Physical Realizability of Nyquist Channel: - Ctype of Low Pass channel) having ideal amplitude response APCF) Ideal Amplitude Response



In freq response P(f), there is discontinuity at ± Bo, so frequency response decreases towards zero abruptly, which is physically unrealisable.

To make it realisable with many desirable features, we make some modifications. The modified PG) is called

Raised Cosine - roll off Nyquist filter, which has roll off portion in addition to flat portion. PCf) = flat portion + Roll-off portion as shown in fig.

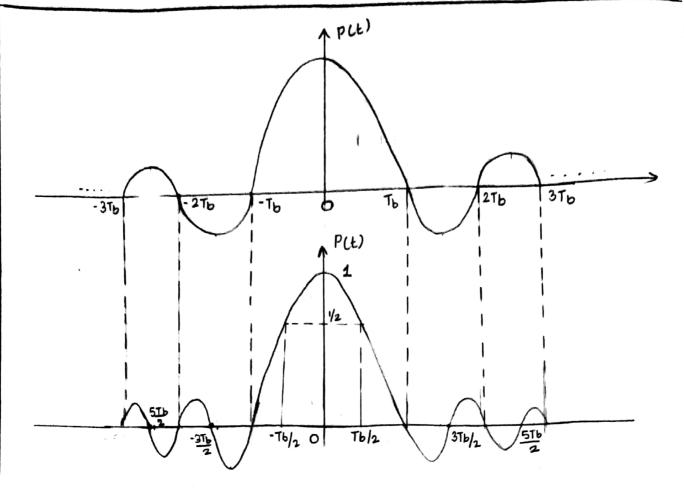


Here the abrupt discontinuity is converted into roll-off portion from frequency fi to 280-fi. Flat portion has magnitude 1/2Bo from freq (0 to fi). This characteristic is called raised cosine roll off filter. The roll-off portion introduce parameter & called roll-off factor

Roll off factor,  $\alpha = 1 - \frac{f_1}{BO}$  -> Relation blue freq fi

Mathematically raised cosine roll-off filter PCf) is  $P(f) = \int \frac{1}{280} \frac{1}{280} \sin \frac{f(x)}{280 - 2f_1} = \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ 1 + \cos \left( \frac{\pi C (f) - f_1}{280 - 2f_1} \right) \right] - \int \frac{1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int \frac{\pi C (f) - f_1}{480} \left[ \frac{\pi C (f) - f_1}{280 - 2f_1} \right] - \int$ given by. 1f1 >, 2Bo-f1 shows ff 0 portion In roll-off portion when IfI = f1, PCf): 1/280 If 1 = 2Bo-f, P(f) = 0. This characteristic is called raised cosine function, which is physically realisable having transmission B.W ZBO-fi Significance of roll-off factor  $d = 1 - \frac{f_1}{a_n}$ , when d = 0. fi = 60 -) represents ideal low pass amplitude response with BT = Bo (minimum) Nyquist B.W. when d=1, f1=0=) we get full cosine roll-off characteristic with BI = 2Bo (Twice of ideal). Time Domain Analysis Taking IFT of Pcf) = pct) = sinc(2Bot) cos(2T1xBot)

1-16x2Bo2t2 x-roll-off factor Bo - Nyquist B.W. Time domain func consists of product of 2 terms 1) -> sinc(2Bot) - associated with ideal solution which shows Zero crossing of p(t) at t= ± Tb, ± 2Tb. - ... (a=0). at t= = 1.5Tb, = 2.5Tb .... for d=1 It is shown in fig. i.e Time Response of raised cosine roll-off Nyquist filter.



at t=0, p(t) has zero crossing at  $t=\pm 7b$ ,  $\pm 27b$ ...

at t=0, p(t)=1

at  $\alpha = 1$ ,  $t = \frac{13Tb}{2}$ ,  $\frac{1}{2}$  including  $t = \frac{1}{2}$  to  $\frac{1}{2}$  etc.  $\frac{1}{2}$  etc.  $\frac{1}{2}$ 

\* at t= ! The or ! 1 , P(t) = 0.5.

On comparison, for  $\alpha=1$ , side lobe height is decreased as compared to  $\alpha=0$ , which makes physical realisability of Nyquist channel for zero ISI

2) 'It2-) factor reduces for large value at 't.';
This factor reduce tail of sinc function (side lobe func)
compared to ideal soln which reduces sampling errors.

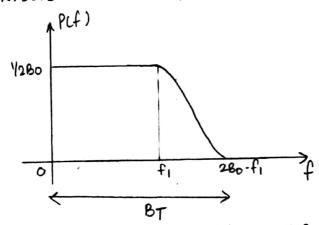
When d=1 ie  $l=1-\frac{f_1}{BD}$  or  $f_1=0$ . q PCf) given as

Pcf): 
$$\int \frac{1}{4B_0} \left[ 1 + \cos \left( \frac{\pi 1 f_1}{2B_0} \right) \right], \quad 0 < |f| < 2B_0$$

$$0 \qquad , \qquad |f| > 2B_0$$

After taking IFT of PLF) we get p(t) pct) = sinc (4Bot) -> which is called raised cosine roll off filter.

Transmission B.W Requirement for Raised Cosine Filler.



Here transmission B.W Bt = 2B0-fi

Bo = 1 2Tb -- Nyquist B.W.

Roll of postion from freq (fi to 2Bo-fi) depend on roll-off factor (x)

we can write

put fi in BT eq.

BT = Bo (1+d) -) in terms of Nyquist B.W & roll off factor

when d=0, BT = Bo (Nyquist B.W)

X=1, Br = 2Bo LTwice of ideal soln)

We consider BT = Bo (1+2)

BT = Bot a Bo

Bo -> Nyquist B.W

&Bo → \* Excess BW that the transmission BW requirement of raised cosine spectrum

On basis of physical realisability, there is need of excess by which make raised cosine spectrum.

Ratio of excess BW = &Bo = & CROLL off factor) Nyquist BW

d-) also called excess BW factor

Summary: IDEAL CASE

When Roll-off factor d=0

Excess BW ExBO) = D

 $B_T = B_0 = \frac{1}{2T_b}$ 

-minimum possible value

PRACTICAL CASE

when d=1

& Bo: Bo Cexcess BW)

BT = 2B0 = 1 (double the ideal).

Note: d=1 provides basis for synchronizing the receiver & transmitter