

# Sudharshan Kannan

403-872-1735 | [sudharkannan04@gmail.com](mailto:sudharkannan04@gmail.com) | <https://sudharkannan.github.io>

## EDUCATION

### University of British Columbia

*Bachelor of Applied Science in Engineering Physics*

| Sep. 2021 – Apr. 2026 (Expected)

*Vancouver, BC*

## EXPERIENCE

### Electrical Division Member

| Sept 2023 – August 2024

*UBC Supermileage*

*Vancouver, BC*

- Designed and specced Safety PCB on a Hydrogen Fuel Cell powered vehicle.
- PCB responsible for ensuring safety of the driver by cutting off the power supply from the fuel cell if any spikes in power are detected, or if it receives a signal from a separate control board.
- Gained familiarity with KiCAD.
- Version control and file sharing performed through Git.

### Manufacturing and Production Co-op

| Jan 2023 – May 2023

*Moment Energy*

*Coquitlam, BC*

- Efficiently and accurately produced electrical assemblies for second-life energy storage systems.
- Performed hands-on work soldering and harnessing electrical systems, with all finished harnesses passing QA.
- Built and debugged various PCBs that were incorporated into test benches and final products.
- Supported development of test benches and helped perform quality control on manufactured parts.

## PROJECTS

### Simulated Driving Detective | *AI, Machine Learning, Computer Vision, Python, ROS, Gazebo, CNNs*

| 2024

- Programmed a simulated car driving on a competition course in Gazebo, with the car placing in the top 3 vehicles in competition.
- Created a Convolutional Neural Network (CNN) using TensorFlow in order to recognize letters on signposts throughout the track, which worked with 100% accuracy during the competition.
- Used Image processing and computer vision techniques from OpenCV to process camera input in order to stay on the track, read signs, and avoid obstacles.

### Mario Kart Robot | *Circuit Design, Microcontrollers, CAD, Soldering*

| 2023

- In a group, built an autonomous robot that would follow electrical tape to compete in a head to head race.
- Designed, implemented, and debugged all circuits and harnesses in the robot, including H-bridges, power distribution, and signal sensing and processing circuits.
- Controlled circuits and sensors through use of a STM-32 microcontroller.

### Servo Control Loop Circuit | *Circuit Analysis, Circuit Design, Lab Equipment*

| 2022

- Designed, implemented, and debugged a servo control loop circuit that used feedback to precisely control the speed of a servo motor.
- Circuit featured various components such as Schmitt-Trigger Inverters, D-Latches, Op-Amps, counter chips, and various types of transistors.
- Performed debugging and analysis through the use of oscilloscopes, function generators, and multimeters.

### Cardboard Claw | *Arduino, CAD, Sonar, Servos*

| 2022

- Played an integral part of a team in order to design and build an automated mechatronic claw capable of lifting various small objects using cardboard, arduino boards, sensors, and servo motors.
- Claw was able to lift items with diverse shapes, from a golf ball to a piece of paper.
- Used servos to control the opening and closing mechanisms in the claw.
- Used an Arduino for automation, with the sonar sensor detecting when the claw has grasped the object.

## TECHNICAL SKILLS

**Languages:** Python, C++, Javascript, Java, HTML, CSS, Git

**Software:** Scripting, Machine Learning, Testing, Computer Vision

**Electrical:** KiCad, LTSpice, Circuit Design, Soldering, Harnessing

**Mechanical:** CAD, Machine Design