Project plan

Participants

Students

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Supervisors

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Goal

Construct a rasterization-based image generator for industrial surfaces and explore benefits and shortcomings of such an approach.

Tasks:

- Load 3D models in a PBR rasterization engine (e.g. Blender, Godot, **UE4/5**)
- Compose rasterization materials from existing procedural path tracing materials
- Compare and incrementally improve the result quality through comparison to the ground-truth results from path tracing
- Explore usage of anisotropic material shaders for more consistent results
- Explore usage of pre-computable light simulation techniques for more realistic results
- (reflection captures, GI probes, RTRT)
- Encapsulate the pipeline into a configurable image generator

Timeline

21.11.2022. - 31.3.2023. ~ 19 weeks

- 1. Get acquainted with basics of UE (2 weeks: 21.11. 2.12.)
 - a. Scene hierarchy and management
 - b. Object loading
 - c. Light setup and building lightmaps
 - d. Material definition and usage
 - e. Blueprint for object and scene programming
 - f. Finding resources to help with solving specific problems
- 2. Prepare the inspection scene (3 weeks: 2.12. 23.12.)
 - a. Load and set material for inspection light source
 - b. Setup a simple light source
 - i. Spot light with doughnut material function and large source radius
 - ii. Area light with material function is probably better
 - c. Load the target mesh and place it into the scene
 - d. Write a simple target materials using existing OSL shader as a reference
- 3. Setup the appropriate anti-aliasing settings for raytracing (3 weeks: 26.12. 13.1.)
 - a. Investigate anti-aliasing techniques used in UE's new hybrid pipeline
 - b. Experiment with techniques and parameters (MSAA/spp) to remove aliasing as much as possible
 - c. Try finding good parameters to reduce the cost of rendering while keeping it close to real-time
- 4. Program the image acquisition blueprint (3 weeks: 26.12. 13.1. 16.1. 3.2.)
 - a. Define several camera poses as array for testing purposes
 - b. Program a method for traversing camera poses
 - c. Export each image into a structured directory (ExportRenderTarget)
- 5. Parse viewpoints from a file (3 weeks: 16.1. 3.2.)
 - a. Setup C++ environment for UE
 - b. Define viewpoint struct and proper trans, matrix calculation
 - c. Write file loader and parser
 - d. Expose modules to blueprints
 - e. Update image acquisition to use the new modules
 - f. Generate images
- 6. Translate more materials into UE (1 week: 6.2. 10.2.)
- 7. Compare images to path traced targets (1.5 weeks: 13.2. 22.2.)
 - a. Write a small script in Python to load pairs of images and compares them
 - b. Describe where are the differences most prominent
- 8. Increase image quality (4.5 weeks: 23.2. 24.3.)
 - a. Reflection capsules
 - b. GI nodes
 - c. Material anisotropy
 - d. RTRT
 - e. ...

9. Collect results and write the final project report (1 week: 27.3. - 31.3.)