Image Segmentation via Thresholding

```
import numpy as np
import math
import cv2
import matplotlib.pyplot as plt
```

Algorithm Basic Global Thresholding

```
In [4]:
    from IPython.display import Image
    Image("midean.png")
```

Out[4]:

1. Input:

- Grayscale image (a 2D array of pixel intensities).
- Initial guess for the threshold value, T₀.
- · Tolerance value to determine convergence.

2. Initialization:

Set T to the initial guess value T₀.

3. Iterative Thresholding:

· Repeat until convergence:

a. Partition the Image:

- Divide the image into two sets based on the current threshold T:
 - Foreground (F): Pixels with intensities greater than T.
 - Background (B): Pixels with intensities less than or equal to T.

b. Calculate Mean Intensities:

- · Compute the mean intensities of pixels in F and B:
 - Calculate the average intensity of pixels in F (denoted as μ_F).
 - Calculate the average intensity of pixels in B (denoted as μ_B).

c. Update Threshold:

• Compute a new threshold value $T_{
m new}$ using:

$$T_{\text{new}} = \frac{\mu_F + \mu_B}{2}$$

d. Check Convergence:

- Calculate the absolute difference between T_{new} and T:
 - ullet If the absolute difference $|T_{
 m new}-T|$ is less than the tolerance value, stop iterating.

e. Update Threshold:

Update T to T_{new}.

4. Output:

- ullet Use the final threshold T to binarize the image:
 - Set pixel intensity to 0 (representing background) if the pixel intensity is less than or equal to T.
 - Set pixel intensity to 255 (representing foreground) if the pixel intensity is greater than
 T.

Apply Basic Global Thresholding

```
In [2]:
         def basic_global_thresholding(img,deltheshold):
             initial_mean = np.mean(img)
             while(True):
                  pre mean = initial mean
                  background = []
                  foreground = []
                  for i in range(img.shape[0]):
                      for j in range(img.shape[1]):
                          if(img[i][j] > initial_mean):
                              foreground.append(img[i][j])
                          else:
                              background.append(img[i][j])
                  mean_back = np.mean(background)
                  mean_fore = np.mean(foreground)
                  initial_mean = (mean_back + mean_fore)/2
                  if(abs(initial_mean - pre_mean) <= deltheshold):</pre>
             return math.ceil(initial_mean)
```

Algorithm Otsu Thresholding

```
In [6]:
    from IPython.display import Image
    Image("otsu.png")
```

Out[6]:

1. Compute Histogram:

 Calculate the histogram of the input grayscale image. The histogram represents the frequency of each pixel intensity level.

2. Normalize Histogram:

 Normalize the histogram so that each bin value represents the probability density function of the pixel intensities.

3. Compute Cumulative Sum:

Compute the cumulative sum cumsum(i) of the normalized histogram up to intensity level
 i.

4. Compute Cumulative Mean:

 Compute the cumulative mean cum_mean(i) of the pixel intensities up to intensity level i: cum_mean(i) = ∑_{k=0}ⁱ k × hist(k)

5. Global Mean:

Calculate the global mean intensity μ of the entire image:

$$\mu = \sum_{i=0}^{L-1} i \times hist(i)$$

where L is the number of intensity levels (typically 256 for an 8-bit grayscale image).

6. Compute Between-Class Variance:

• For each possible threshold t (from 0 to L=1):

a. Compute the weight $w_0(t)$ of the background (pixels with intensity $\leq t$):

$$w_0(t) = \operatorname{cumsum}(t)$$

b. Compute the weight $w_1(t)$ of the foreground (pixels with intensity $\geq t$):

$$w_1(t) = 1 - w_0(t)$$

c. Compute the mean intensity $\mu_0(t)$ of the background:

$$\mu_0(t) = \frac{\operatorname{cum_mean}(t)}{w_0(t)}$$

d. Compute the mean intensity $\mu_1(t)$ of the foreground:

$$\mu_1(t) = \frac{\mu - \operatorname{cum_mean}(t)}{\operatorname{mod}(t)}$$

e. Compute the between-class variance $\sigma_h^2(t)$:

$$\sigma_b^2(t) = w_0(t) \times w_1(t) \times (\mu_0(t) - \mu_1(t))^2$$

7. Find Optimal Threshold:

• The optimal threshold T is the one that maximizes the between-class variance $\sigma_{\rm b}^2(t)$: $T=\arg\max_t \sigma_{\rm b}^2(t)$

8. Threshold the Image:

- Use the optimal threshold T to binarize the image:
 - Set pixel intensity to 0 (background) if intensity < T.
 - Set pixel intensity to 255 (foreground) if intensity ≥ T.

Apply Otsu Thresholding

```
In [3]:
    def otsu_thresholding(image):
        histogram, _ = np.histogram(image, bins=256, range=(0, 256))

# Normalize histogram
    histogram = histogram / float(image.size)

max_variance = 0
    threshold = 0

for i in range(1, 256):
        w0 = np.sum(histogram[:i])
        w1 = np.sum(histogram[i:])

        if w0 == 0:
            mu0 = 0
        else:
            mu0 = np.sum(np.arange(i) * histogram[:i]) / w0

if w1 == 0:
```

```
mu1 = 0
else:
    mu1 = np.sum(np.arange(i, 256) * histogram[i:]) / w1

variance = w0 * w1 * (mu0 - mu1) ** 2

if variance > max_variance:
    max_variance = variance
    threshold = i
return threshold
```

```
def segmented_image(img,threshold):
    bin_image = np.zeros_like(img)
    for i in range(img.shape[0]):
        for j in range(img.shape[1]):
            if(threshold<img[i][j]):
                 bin_image[i][j] = 1

    return bin_image</pre>
```

```
img = cv2.imread('CoverImages/lena.tiff',0)
plt.imshow(img, cmap='gray')
plt.title("Real Image")
plt.xticks([])
plt.yticks([])
plt.show()
```

Real Image



```
In [6]:
    threshold_value = otsu_thresholding(img)
    threshold_value
```

Out[6]: 118

```
In [7]: seg = segmented_image(img,threshold_value)

In [8]: plt.imshow(seg, cmap='gray')
   plt.title("Apply Otsu Thresholding")
   plt.xticks([])
   plt.yticks([])
   plt.show()
```

Apply Otsu Thresholding



```
In [9]: threshold_value = basic_global_thresholding(img,0.01)
    seg1 = segmented_image(img,threshold_value)

In [10]: threshold_value

Out[10]: 118

In [11]: plt.imshow(seg1, cmap='gray')
    plt.title("Apply Basic Global Thresholding")
    plt.xticks([])
    plt.yticks([])
    plt.show()
```

Apply Basic Global Thresholding



In []:			