

Some Equations for Econometrics I

Contents

| | | |
|-----------|--|-----------|
| 1 | The Linear Regression Model | 1 |
| 1.1 | Simple Regression Model | 1 |
| 1.2 | Multiple Regression | 1 |
| 2 | Statistical Inferences of Linear Regression Model | 2 |
| 2.1 | Under the Normality Assumption | 2 |
| 2.2 | Classical Asymptotic Theory | 2 |
| 3 | Maximum Likelihood Estimation | 3 |
| 3.1 | MLE Basics | 3 |
| 3.2 | MLE of Linear Regression Model | 3 |
| 3.3 | Asymptotic Tests | 3 |
| 3.4 | Newton-Raphson Method | 4 |
| 4 | Discrete Choice Models | 4 |
| 4.1 | Introduction | 4 |
| 4.2 | Probit and Logit Models | 4 |
| 5 | Truncation, Censoring and Sample Selection | 5 |
| 5.1 | Truncation | 5 |
| 5.2 | Censoring | 5 |
| 5.3 | Truncated Data and Censored Data: Tobit Models | 5 |
| 5.4 | Sample Selection: Type II Tobit Model | 6 |
| 6 | Generalized Linear Regression Model | 6 |
| 6.1 | Generalized Least Squares | 6 |
| 6.2 | WLS | 6 |
| 6.3 | Autocorrelated Disturbance | 6 |
| 6.4 | Set of Regression Equations | 7 |
| 7 | Simultaneous-Equations Models and IV Estimation | 7 |
| 7.1 | IV Estimation | 7 |
| 7.2 | Hausman's Specification Test | 8 |
| 8 | Generalized Method of Moments | 8 |
| 9 | Panel Data Models | 9 |
| 9.1 | Fixed Effects Model | 9 |
| 9.2 | Random Effects Model (Error Component Model) (or Variance Component Model) | 9 |
| 9.3 | Dynamic Panel Data | 9 |
| 10 | Spatial Econometrics | 10 |

1 The Linear Regression Model

1.1 Simple Regression Model

$y_i = \beta_1 + \beta_2 x_i + \epsilon_i$, $i = 1, 2, \dots, n$.

Or, $y = \beta_1 + \beta_2 x + \epsilon$ where y , x and ϵ are $n \times 1$ vector.

- The method of least squares: $\min_{\beta_1, \beta_2} \sum_{i=1}^n (y_i - \beta_1 - \beta_2 x_i)^2$.
- The normal equations (FOC):

$$\begin{aligned}\sum_{i=1}^n y_i &= n\beta_1 + \beta_2 \sum_{i=1}^n x_i, \\ \sum_{i=1}^n x_i y_i &= \beta_1 \sum_{i=1}^n x_i + \beta_2 \sum_{i=1}^n x_i^2.\end{aligned}$$

- R^2 -measure of fit: (Coefficient of determination)

$$\begin{aligned}R^2 &= \frac{\sum_{i=1}^n (\hat{y}_i - \bar{y})^2}{\sum_{i=1}^n (y_i - \bar{y})^2} = 1 - \frac{\sum_{i=1}^n e_i^2}{\sum_{i=1}^n (y_i - \bar{y})^2} \\ (\text{Optional}) &= \hat{\beta}_2^2 \sum_{i=1}^n (x_i - \bar{x})^2 / \sum_{i=1}^n (y_i - \bar{y})^2 = r_{xy}^2\end{aligned}$$

- Testing $\beta_1 = 0$.

$$t_{\beta_1} = \frac{\hat{\beta}_1 - 0}{se_{\beta_1}} \sim t_{n-2}$$

1.2 Multiple Regression

- Least Squares

$$\min_{\beta} S(\beta) \equiv (y - X\beta)'(y - X\beta).$$

- Normal equations: $\frac{\partial S}{\partial \beta} = -2X'y + 2X'X\beta = 0$

$$\bar{R}^2 = 1 - \frac{n-1}{n-K}(1 - R^2)$$

We can write $(X'X)\hat{\beta} = X'y$ as

$$\begin{aligned}X'_1 X_1 \hat{\beta}_1 + X'_1 X_2 \hat{\beta}_2 &= X'_1 y \\ X'_2 X_1 \hat{\beta}_1 + X'_2 X_2 \hat{\beta}_2 &= X'_2 y.\end{aligned}$$

$$\begin{aligned}\hat{\beta}_1 &= (X'_1 M_2 X_1)^{-1} X'_1 M_2 y \\ \hat{\beta}_2 &= (X'_2 M_1 X_2)^{-1} X'_2 M_1 y.\end{aligned}$$

Thus, $\hat{\beta}_1 = (X_1^{*'} X_1^*)^{-1} X_1^{*'} y^*$ where $X_1^* = M_2 X_1$ and $y^* = M_2 y$.

2 Statistical Inferences of Linear Regression Model

2.1 Under the Normality Assumption

$$\frac{\hat{\beta}_k - \beta_k}{\hat{\sigma}([(X'X)^{-1}]_{kk})^{1/2}} = \frac{\frac{\hat{\beta}_k - \beta_k}{\sigma([[(X'X)^{-1}]_{kk})^{1/2}}}{\sqrt{\frac{(n-K)\frac{\hat{\sigma}^2}{\sigma^2}}{n-K}}} \sim t_{n-k}.$$

$$F = \frac{Wald}{J} \frac{\sigma^2}{\hat{\sigma}^2} = \frac{(R\hat{\beta} - q)'[\sigma^2 R(X'X)^{-1}R']^{-1}(R\hat{\beta} - q)/J}{[(n-K)\hat{\sigma}^2/\sigma^2]/(n-K)}.$$

2.2 Classical Asymptotic Theory

Some basic asymptotic concepts and useful results:

Definition: *Convergence in probability* $X_n \xrightarrow{p} X$ or $\text{plim} X_n = X$.

A sequence of random variables $\{X_n\}$ is said to converge to a random variable X *in probability* if

$$\lim_{n \rightarrow \infty} P(|X_n - X| > \epsilon) = 0, \text{ for all } \epsilon > 0.$$

Definition: *Convergence in distribution* $X_n \xrightarrow{d} X$.

A sequence $\{X_n\}$ is said to converge to X *in distribution* if the distribution function F_n of X_n converges to the distribution function F of X at every continuity point of F . (F is called the limiting distribution of $\{X_n\}$).

Let $\{X_n, Y_n\}$, $n = 1, 2, \dots$ be a sequence of pairs of random variables. Then

a).

$$X_n \xrightarrow{d} X, Y_n \xrightarrow{p} 0 \implies X_n Y_n \xrightarrow{p} 0.$$

b).

$$X_n \xrightarrow{d} X, Y_n \xrightarrow{p} c \implies X_n + Y_n \xrightarrow{d} X + c, X_n Y_n \xrightarrow{d} cX, X_n/Y_n \xrightarrow{d} X/c, \text{ if } c \neq 0.$$

Law of Large Numbers

Proposition: (Chebyshev's theorem W.L.L.N) Let $E(X_i) = \mu_i$, $V(X_i) = \sigma_i^2$, $\text{Cov}(X_i, X_j) = 0$, $i \neq j$. Then,

$$\lim_{n \rightarrow \infty} \frac{1}{n^2} \sum_{i=1}^n \sigma_i^2 = 0 \implies \bar{X}_n - \bar{\mu}_n \xrightarrow{p} 0.$$

where $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$ and $\bar{\mu}_n = \frac{1}{n} \sum_{i=1}^n \mu_i$.

Central Limit Theorems

Theorem: (Lindberg-Feller Theorem C.L.T) Let $\{X_n\}$ be a sequence of independent random variables. Let $E(X_i) = \mu_i$, $E(X_i - \mu_i)^2 = \sigma_i^2 \neq 0$ exist. Denote $C_n = (\sum_{i=1}^n \sigma_i^2)^{1/2}$. If no single dominates the variance average such that $\lim_{n \rightarrow \infty} \frac{\max(\sigma_i)}{\sum_{i=1}^n \sigma_i} = 0$, and $\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n \sigma_i$ exists. then $\frac{\sum_{i=1}^n (X_i - \mu_i)}{C_n} \xrightarrow{d} N(0, 1)$.

3 Maximum Likelihood Estimation

3.1 MLE Basics

$$f(y_1, \dots, y_n | \theta) = \prod_{i=1}^n f(y_i | \theta) = L(\theta | \mathbf{y}),$$

$$\ln L(\theta | y) = \sum_{i=1}^n \ln f(y_i, \theta),$$

Information Identity

$$E \left[\frac{\partial \ln L(\theta | y)}{\partial \theta} \frac{\partial \ln L(\theta | y)}{\partial \theta'} \right] + E \left[\frac{\partial^2 \ln L(\theta | y)}{\partial \theta \partial \theta'} \right] = 0.$$

- Information matrix is $I(\theta)$ where

$$I(\theta) = E \left[\frac{\partial \ln L(\theta | y)}{\partial \theta} \frac{\partial \ln L(\theta | y)}{\partial \theta'} \right].$$

3.2 MLE of Linear Regression Model

$$\ln L = -\frac{n}{2} \ln 2\pi - \frac{n}{2} \ln \sigma^2 - \frac{1}{2\sigma^2} (y - X\beta)'(y - X\beta).$$

$$\frac{\partial \ln L}{\partial \beta} = \frac{1}{\sigma^2} X'(y - X\beta) = 0,$$

$$\frac{\partial \ln L}{\partial \sigma^2} = \frac{-n}{2\sigma^2} + \frac{1}{2\sigma^4} (y - X\beta)'(y - X\beta) = 0.$$

MLE: $\hat{\beta}_{ML} = (X'X)^{-1}X'y$; $\hat{\sigma}_{ML}^2 = e'e/n$.

- The information matrix of the linear regression model:

$$I(\beta, \sigma^2) = \left(-\frac{1}{n} E \frac{\partial^2 \ln L(\theta)}{\partial \theta \partial \theta'} \right)^{-1} = \begin{pmatrix} \sigma^2 (\frac{1}{n} X'X)^{-1} & 0 \\ 0 & 2\sigma^4 \end{pmatrix}.$$

3.3 Asymptotic Tests

- Likelihood ratio test statistic:

$$-2 \ln \left[\frac{\max_{h(\theta)=0} L(\theta | y)}{\max_{\theta} L(\theta | y)} \right] = 2[\ln L(\hat{\theta} | y) - \ln L(\bar{\theta} | y)].$$

- Wald test statistics:

$$h'(\hat{\theta}) \left[\frac{\partial h(\hat{\theta})}{\partial \theta'} \left(-\frac{\partial^2 \ln L(\hat{\theta})}{\partial \theta \partial \theta'} \right)^{-1} \frac{\partial h(\hat{\theta})}{\partial \theta} \right]^{-1} h(\hat{\theta}).$$

- (Efficient) Score statistics:

$$\frac{\partial \ln L(\bar{\theta})}{\partial \theta'} \left(-\frac{\partial^2 \ln L(\bar{\theta})}{\partial \theta \partial \theta'} \right)^{-1} \frac{\partial \ln L(\bar{\theta})}{\partial \theta}.$$

3.4 Newton-Raphson Method

This method is applicable for either maximization or minimization problems. Let $Q_n(\theta)$ be the object function for optimization. Let θ_1 be an initial estimate of θ . By a quadratic approximation, define

$$Q_n(\theta) \equiv Q_n(\hat{\theta}_1) + \frac{\partial Q_n(\hat{\theta}_1)}{\partial \theta'}(\theta - \hat{\theta}_1) + \frac{1}{2}(\theta - \hat{\theta}_1)' \frac{\partial^2 Q_n(\hat{\theta}_1)}{\partial \theta \partial \theta'}(\theta - \hat{\theta}_1).$$

Maximizing (or minimizing) the right-hand side approximation provides a second-round estimator $\hat{\theta}_2$,

$$\hat{\theta}_2 = \hat{\theta}_1 - \left[\frac{\partial^2 Q_n(\hat{\theta}_1)}{\partial \theta \partial \theta'} \right]^{-1} \frac{\partial Q_n(\hat{\theta}_1)}{\partial \theta'}.$$

The iteration is to be repeated until the sequence $\{\hat{\theta}_j\}$ converges. The step sizes in the iteration can also be modified as

$$\hat{\theta}_2 = \hat{\theta}_1 - \lambda \left[\frac{\partial^2 Q_n(\hat{\theta}_1)}{\partial \theta \partial \theta'} \right]^{-1} \frac{\partial Q_n(\hat{\theta}_1)}{\partial \theta'},$$

4 Discrete Choice Models

4.1 Introduction

- Pbit and Logit

$$F(u) = \int_{-\infty}^u \phi(w) dw,$$

where ϕ is the standard normal density $\phi(w) = \frac{1}{\sqrt{2\pi}} e^{-\frac{w^2}{2}}$, then this model is called *probit* model.

$$F(u) = \frac{e^u}{1 + e^u}$$

where $f(u) = \frac{\exp(u)}{(1 + \exp(u))^2}$, it is known as the *logit* model.

4.2 Probit and Logit Models

$$\begin{aligned} \ln L(\beta) &= \text{sum of } \begin{cases} \ln[1 - F(x_i\beta)] & \text{if } y_i = 0 \\ \ln F(x_i\beta) & \text{if } y_i = 1 \end{cases} \\ &= \sum_{i=1}^n [y_i \ln F(x_i\beta) + (1 - y_i) \ln(1 - F(x_i\beta))]. \end{aligned}$$

$$\begin{aligned} \frac{\partial \ln L}{\partial \beta} &= \sum_{i=1}^n y_i \frac{f(x_i\beta)x'_i}{F(x_i\beta)} + \sum_{i=1}^n (1 - y_i) \frac{-f(x_i\beta)x'_i}{1 - F(x_i\beta)} \\ &= \sum_{i=1}^n \frac{y_i [1 - F(x_i\beta)] - (1 - y_i) F(x_i\beta)}{F(x_i\beta) [1 - F(x_i\beta)]} f(x_i\beta)x'_i \\ &= \sum_{i=1}^n \frac{y_i - F(x_i\beta)}{F(x_i\beta)(1 - F(x_i\beta))} f(x_i\beta)x'_i, \end{aligned}$$

$$\frac{\partial^2 \ln L}{\partial \beta \partial \beta'} = \left\{ - \sum_{i=1}^n \left[\frac{y_i}{F^2(x_i\beta)} + \frac{1 - y_i}{[1 - F(x_i\beta)]^2} \right] f^2(x_i\beta) + \sum_{i=1}^n \frac{y - F(x_i\beta)}{F(x_i\beta) [1 - F(x_i\beta)]} f' \right\} x_i x'_i.$$

5 Truncation, Censoring and Sample Selection

5.1 Truncation

$$y_i = x'_i \beta + \epsilon_i, \quad \epsilon_i | x \sim N(0, \sigma^2)$$

$$f(y|x_i, c_i) = \frac{\phi(y|x'_i \beta, \sigma^2)}{\Phi(c_i|x'_i \beta, \sigma^2)} = \frac{\frac{1}{\sigma} \phi\left(\frac{y - x'_i \beta}{\sigma}\right)}{\Phi\left(\frac{c_i - x'_i \beta}{\sigma}\right)}, \quad y \leq c_i, \quad (5.1)$$

5.2 Censoring

$$y_i = \begin{cases} y_i^* & \text{if } y_i^* > 0 \\ 0 & \text{if } y_i^* \leq 0 \end{cases} \quad (5.2)$$

$$P(y_i = 0|x_i) = P(y_i^* < 0|x_i) = P(x'_i \beta + \epsilon_i < 0|x_i) = P\left(\frac{\epsilon_i}{\sigma} < -\frac{x'_i \beta}{\sigma} | x_i\right) = \Phi\left(-\frac{x'_i \beta}{\sigma}\right).$$

$$f(y|x_i) = \Phi\left(-\frac{x'_i \beta}{\sigma}\right)^{1(y=0)} \cdot \left(\frac{1}{\sigma} \phi\left(\frac{y_i - x'_i \beta}{\sigma}\right)\right)^{1(y=1)}$$

$$\begin{aligned} \log L(\beta, \sigma) &= \sum_{i=1}^n \log f(y_i|x_i) \\ &= \sum_{y_i=0} \log \Phi\left(-\frac{x'_i \beta}{\sigma}\right) + \sum_{y_i=1} \log \left(\frac{1}{\sigma} \phi\left(\frac{y_i - x'_i \beta}{\sigma}\right)\right). \end{aligned}$$

5.3 Truncated Data and Censored Data: Tobit Models

$$y_i^* = x'_i \beta + \epsilon_i, \quad \epsilon_i \text{ is i.i.d.}$$

$$y_i = \begin{cases} y_i^* & \text{if } y_i^* > 0 \\ 0 & \text{if } y_i^* \leq 0 \end{cases}, \quad (5.3)$$

$$E(y|y > 0) = E(y^*|y^* > 0) = x\beta + E(\epsilon|\epsilon > -x\beta) = x\beta + \sigma_\epsilon \cdot \frac{\phi\left(\frac{x\beta}{\sigma_\epsilon}\right)}{\Phi\left(\frac{x\beta}{\sigma_\epsilon}\right)}. \quad (5.4)$$

$$\begin{aligned} E(y|x) &= \Pr(y = 0) \cdot 0 + \Pr(y > 0|x) \cdot E(y|y > 0, x) \\ &= \Pr(\epsilon \leq -x\beta) \cdot 0 + \Pr(\epsilon > -x\beta) E(y^*|x; \epsilon > -x\beta) \\ &= \Pr(\epsilon > -x\beta) [x\beta + E(\epsilon|\epsilon > -x\beta)]. \end{aligned} \quad (5.5)$$

The likelihood function of the truncated data is equal to

$$L_1 = \prod_1 [\Pr(y_i > 0|x_i)]^{-1} f(y_i),$$

The likelihood function for the censored data is equal to

$$\begin{aligned} L_2 &= \prod_0 \Pr(y_i = 0|x_i) \prod_1 f(y_i) \\ &= \{\prod_0 \Pr(y_i = 0|x_i) \prod_1 \Pr(y_i > 0|x_i)\} \\ &\quad \times \{\prod_1 [\Pr(y_i > 0|x_i)]^{-1} f(y_i)\}, \end{aligned} \quad (5.6)$$

$$\begin{aligned}
y_i &= E(y_i|x_i; y_i > 0) + \eta_i \\
&= x_i\beta + \sigma_\epsilon \frac{\phi(x\delta)}{\Phi(x\delta)} + \eta_i \text{ for those } i \text{ such that } y_i > 0,
\end{aligned}$$

where $E(\eta_i|x_i) = 0$, $var(\eta_i|x_i) = \sigma_\epsilon^2[1 - (x_i\delta)\lambda_i - \lambda_i^2]$, and $\lambda_i = \frac{\phi(x\delta)}{\Phi(x\delta)}$.

5.4 Sample Selection: Type II Tobit Model

$$\begin{aligned}
y_i^* &= x_i'\beta + \epsilon_{1i} \\
d_i &= 1(z_i'\gamma + \epsilon_{0i} > 0)
\end{aligned}$$

$$E(y_i|d_i = 1) = x_i\beta + E(\epsilon_{1i}|\epsilon_{0i} > -z_i'\gamma).$$

$$\begin{aligned}
E(\epsilon_{1i}|d_i = 1, z_i) &= E(\epsilon_{1i}|\{\epsilon_{0i} > -z_i'\gamma\}, z_i) \\
&= \rho E(\epsilon_{0i}|\{\epsilon_{0i} > -z_i'\gamma\}, z_i) + E(v_i|\{\epsilon_{0i} > -z_i'\gamma\}, z_i) \\
&= \rho\lambda(z_i'\gamma)
\end{aligned}$$

$$y_i = x_i'\beta + \rho\lambda(z_i'\gamma) + u_i$$

is a valid regression equation for the observations for which $T_i = 1$.

6 Generalized Linear Regression Model

6.1 Generalized Least Squares

$$\hat{\beta}_G = (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}y.$$

- If $\Omega X = X\Gamma$ where Γ is a nonsingular matrix, then $\hat{\beta}_G = \hat{\beta}_{LS}$, i.e., GLS=OLS. (e.g., the SUR)

Proof: The equality $\Omega X = X\Gamma$ implies that $X\Gamma^{-1} = \Omega^{-1}X$ and hence $X'\Omega^{-1} = \Gamma'^{-1}X'$. Therefore,

$$(X'\Omega^{-1}X)^{-1}X'\Omega^{-1} = (\Gamma'^{-1}X'X)^{-1}\Gamma'^{-1}X' = (X'X)^{-1}\Gamma'\Gamma'^{-1}X' = (X'X)^{-1}X'.$$

6.2 WLS

$$\hat{\beta}_G = [\sum_{i=1}^n \omega_i^{-1} x_i x_i']^{-1} \sum_{i=1}^n \omega_i^{-1} x_i y_i.$$

6.3 Autocorrelated Disturbance

$$\sigma_u^2 \Omega = \frac{\sigma_u^2}{(1 - \rho^2)} \begin{pmatrix} 1 & \rho & \rho^2 & \cdots & \rho^{T-1} \\ \rho & 1 & \rho & \cdots & \rho^{T-2} \\ \rho^2 & \rho & 1 & \cdots & \rho^{T-3} \\ \cdots & \cdots & \cdots & \ddots & \vdots \\ \rho^{T-1} & \rho^{T-2} & \rho^{T-3} & \cdots & 1 \end{pmatrix}.$$

$$P = \begin{pmatrix} \sqrt{(1-\rho^2)} & 0 & 0 & \cdots & 0 & 0 \\ -\rho & 1 & 0 & \cdots & 0 & 0 \\ 0 & -\rho & 1 & \cdots & 0 & 0 \\ 0 & 0 & 0 & \cdots & -\rho & 1 \end{pmatrix}.$$

$$d = \frac{\sum_{t=2}^T (e_t - e_{t-1})^2}{\sum_{t=2}^T e_t^2}.$$

6.4 Set of Regression Equations

$$\begin{aligned} Y_1 &= X_1\beta_1 + U_1 \\ &\vdots \\ Y_m &= X_m\beta_m + U_m \end{aligned}$$

$$\begin{pmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_m \end{pmatrix} = \begin{pmatrix} X_1 & 0 & \cdots & 0 \\ 0 & X_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & X_m \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_m \end{pmatrix} + U,$$

or $Y = X\beta + U$, where

$$U = \begin{pmatrix} U_1 \\ U_2 \\ \vdots \\ U_m \end{pmatrix}.$$

- The GLS estimator is

$$\hat{\beta}_G = (X'V^{-1}X)^{-1}X'V^{-1}Y$$

$$\begin{pmatrix} \sigma^{11}X_1'X_1 & \sigma^{12}X_1'X_2 & \cdots & \sigma^{1m}X_1'X_m \\ \vdots & \vdots & \ddots & \vdots \\ \sigma^{m1}X_m'X_1 & \sigma^{m2}X_m'X_2 & \cdots & \sigma^{mm}X_m'X_m \end{pmatrix}^{-1} \begin{pmatrix} \sum_{j=1}^m \sigma^{1j}X_1'Y_j \\ \vdots \\ \sum_{j=1}^m \sigma^{mj}X_m'Y_j \end{pmatrix}.$$

7 Simultaneous-Equations Models and IV Estimation

7.1 IV Estimation

$$y_j = Y_j\gamma_j + X_j\beta_j + \epsilon_j = Z_j\delta_j + \epsilon_j,$$

$$\hat{\delta}_{j,IV} = [W_j'Z_j]^{-1}W_j'y_j.$$

$$Asy.Var[\hat{\delta}_{j,IV}] = \frac{\sigma_{jj}}{T} \text{plim} \left[\frac{W_j'Z_j}{T} \right]^{-1} \left[\frac{W_j'W_j}{T} \right] \left[\frac{Z_j'W_j}{T} \right]^{-1}.$$

$$\begin{aligned}\hat{\delta}_{j,2SLS} &= [\hat{Z}_j' \hat{Z}_j]^{-1} \hat{Z}_j' y_j \\ &= [Z_j' X (X' X)^{-1} X' Z_j]^{-1} Z_j' X (X' X)^{-1} X' y_j.\end{aligned}$$

$$\begin{pmatrix} y_1 \\ \vdots \\ y_m \end{pmatrix} = \begin{pmatrix} Z_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & Z_m \end{pmatrix} \begin{pmatrix} \delta_1 \\ \vdots \\ \delta_m \end{pmatrix} + \begin{pmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_m \end{pmatrix},$$

3SLS:

Step 1: regress Z_j on X and get \hat{Z}_j ;

Step 2: get 2SLS, $\hat{\delta}_{j,2sls} = [\hat{Z}_j' \hat{Z}_j]^{-1} \times [\hat{Z}_j' y_j]$, get $\hat{\varepsilon}_j$, estimate $\hat{\sigma}_{ij} = \frac{1}{T} \hat{\varepsilon}_i' \hat{\varepsilon}_j$,

hence an estimate of $\Sigma = \begin{pmatrix} \sigma_{11} & \cdots & \sigma_{1m} \\ \vdots & \ddots & \vdots \\ \sigma_{m1} & \cdots & \sigma_{mm} \end{pmatrix}$;

Step 3, feasible GLS, $\delta_{3sls} = [\hat{\mathbf{Z}}(\hat{\Sigma}^{-1} \otimes I_T) \mathbf{Z}]^{-1} \times [\hat{\mathbf{Z}}(\hat{\Sigma}^{-1} \otimes I_T) \mathbf{y}]$.

7.2 Hausman's Specification Test

1. $\hat{\theta}$ is asymptotically efficient under H_0 but is inconsistent under H_1 ,
2. $\bar{\theta}$ is asymptotically inefficient under H_0 but is consistent under both H_0 and H_1 .

$$(\hat{\theta} - \bar{\theta})' \hat{V}^{-1} (\hat{\theta} - \bar{\theta}) \xrightarrow{d} \chi^2(k).$$

$$\mathcal{HS} = \frac{1}{\hat{\sigma}^2} \{ (\hat{\beta}_{2SLS} - \hat{\beta}_{OLS})' [(X' Z_1 (Z_1' Z_1)^{-1} Z_1' X)^{-1} - (X' X)^{-1}] (\hat{\beta}_{2SLS} - \hat{\beta}_{OLS}) \}$$

8 Generalized Method of Moments

- *Orthogonality condition*

$$Ef(x, \beta_0) = 0$$

$$g_T(x, \beta) = \frac{1}{T} \sum_{t=1}^T f(x_t, \beta)$$

$$\hat{\beta} = \arg \min_{\beta} g_T'(x, \beta) a_T' a_T g_T(x, \beta).$$

$$\frac{\partial g_T'(\hat{\beta}_T)}{\partial \beta} a_T' a_T g_T(\hat{\beta}_T) = 0.$$

Let a_T^* denote $\frac{\partial g_T'(\omega)}{\partial \beta} a_T' a_T$.

$$0 = a_T^* g_T(\hat{\beta}_T) = a_T^* g_T(\beta_0) + a_T^* \frac{\partial g_T(\bar{\beta})}{\partial \beta} (\hat{\beta}_T - \beta_0),$$

which implies that

$$\begin{aligned}\sqrt{T}(\hat{\beta}_T - \beta_0) &= - \left(a_T^* \frac{\partial g_T(\bar{\beta})}{\partial \beta} \right)^{-1} \sqrt{T} a_T^* g_T(\beta_0) \\ &= - \left(a_T^* \frac{\partial g_T(\bar{\beta})}{\partial \beta} \right)^{-1} a_T^* \frac{1}{\sqrt{T}} \sum_{t=1}^T f(x_t, \beta_0).\end{aligned}$$

It follows that $\sqrt{T}(\hat{\beta}_T - \beta_0)$ converges in distribution to a normally distributed random vector with mean zero and covariance matrix

$$(d'_0 a'_0 a_0 d_0)^{-1} d'_0 a'_0 a_0 S_w a'_0 a_0 d_0 (d'_0 a'_0 a_0 d_0)^{-1},$$

where $S_w \equiv \lim_{T \rightarrow \infty} \text{var} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T f(x_t, \beta_0) \right) = \sum_{t=-\infty}^{\infty} E[(f(x_t, \beta_0) f(x_t, \beta_0))]$, $a_0 = p \lim a_T$ and $d_0 = p \lim \frac{\partial g_T(\beta_0)}{\partial \beta}$.

Optimal a_0 , the GMM method corresponds to

$$\min_{\beta} g'_T(\beta) \hat{S}_w^{-1} g_T(\beta),$$

9 Panel Data Models

9.1 Fixed Effects Model

$$y_{it} = \alpha_i + x_{it}\beta + \epsilon_{it}, \quad i = 1, \dots, n; t = 1, \dots, T,$$

$$\min_{\alpha_i, \beta} Q(\alpha_1, \dots, \alpha_n, \beta) = \sum_{i=1}^n \sum_{t=1}^T (y_{it} - \alpha_i - x_{it}\beta)^2$$

$$\sum_{t=1}^T (y_{it} - \hat{\alpha}_i - x_{it}\hat{\beta}) = 0, \quad i = 1, \dots, n;$$

$$\sum_{i=1}^n \sum_{t=1}^T (y_{it} - \hat{\alpha}_i - x_{it}\hat{\beta}) x'_{it} = 0,$$

$$\hat{\alpha}_i = \bar{y}_i - \bar{x}_i \hat{\beta}, \text{ and } \hat{\beta} = \left[\sum_{i=1}^n \sum_{t=1}^T (x_{it} - \bar{x}_i)' (x_{it} - \bar{x}_i) \right]^{-1} \sum_{i=1}^n \sum_{t=1}^T (x_{it} - \bar{x}_i)' (y_{it} - \bar{y}_i). \quad (9.1)$$

9.2 Random Effects Model (Error Component Model) (or Variance Component Model)

$$y_{it} = x_{it}\beta + u_{it}, \quad u_{it} = \alpha_i + \epsilon_{it}$$

$$E(u_i u'_i) = E((\alpha_i l_T + \epsilon_i)(\alpha_i l_T + \epsilon_i)') = \sigma_\alpha^2 l_T l'_T + \sigma_\epsilon^2 I_T = \sigma_u^2 A,$$

where $\sigma_u^2 = \sigma_\alpha^2 + \sigma_\epsilon^2$, and

$$A = \begin{pmatrix} 1 & \rho & \cdots & \rho \\ \rho & 1 & \cdots & \rho \\ \vdots & \vdots & \ddots & \vdots \\ \rho & \rho & \cdots & 1 \end{pmatrix} = (1 - \rho)I_T + \rho l_T l'_T$$

with $\rho = \sigma_\alpha^2 / (\sigma_\alpha^2 + \sigma_\epsilon^2)$.

9.3 Dynamic Panel Data

$$y_{it} = \gamma y_{i,t-1} + \alpha_i + v_{it}, \quad t = 1, \dots, T.$$

$$\hat{\gamma} = \left[\sum_{i=1}^n \sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})' (y_{i,t-1} - \bar{y}_{i,-1}) \right]^{-1} \sum_{i=1}^n \sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})' (y_{it} - \bar{y}_i) \quad (9.2)$$

$$= \gamma + \left[\sum_{i=1}^n \sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})' (y_{i,t-1} - \bar{y}_{i,-1}) \right]^{-1} \sum_{i=1}^n \sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})' (v_{it} - \bar{v}_i) \quad (9.3)$$

As $y_{i,t-1} - \bar{y}_{i,-1}$ and $v_{it} - \bar{v}_i$ are correlated (because $\bar{y}_{i,-1}$ and \bar{v}_i are correlated), $\hat{\gamma}$ is biased. Unless T is large, $\hat{\gamma}$ is inconsistent.

$$\sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})' (v_{it} - \bar{v}_i) = \sum_{t=1}^T y_{i,t-1} v_{it} - T \cdot \bar{y}_{i,-1} \bar{v}_i$$

- We make the first difference such that

$$\Delta y_{it} = \gamma \Delta y_{i,t-1} + \Delta v_{it}, \quad t = 2, \dots, T.$$

We can use the lagged value of y_{is} where $s \leq t-2$ as the IVs.

$$E(y_{i,t-s} \Delta v_{it}) = 0, \quad \text{for } t = 2, \dots, T \text{ and } s \geq 2.$$

Denote $(T-1) \times m$ matrix $Z_i = \begin{bmatrix} y_0 & 0 & 0 & \cdots & 0 & \cdots & 0 \\ 0 & y_0 & y_1 & \cdots & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \cdots & \vdots & \cdots & \vdots \\ 0 & 0 & 0 & \cdots & y_0 & \cdots & y_{T-2} \end{bmatrix}$ and $T-1$ vector $\Delta u_i = (\Delta v_{i2}, \Delta v_{i3}, \dots, \Delta v_{iT})'$.

$$g_i = Z_i' \Delta u_i, \text{ so that } g = Z' u$$

we have GMM estimator γ as

$$\hat{\gamma}_{dif} = (y_{-1}' Z A_n Z' y_{-1})^{-1} (y_{-1}' Z A_n Z' y)$$

$$A_n = \left(\frac{1}{n} \sum_{i=1}^n Z_i' \hat{u}_i \hat{u}_i' Z_i \right)^{-1}$$

10 Spatial Econometrics

$$Y_n = \lambda W_n Y_n + X_n \beta + \epsilon_n$$

1): **MLE**

$$\ln L_n(\lambda, \beta, \sigma^2) = -\frac{n}{2} \ln(2\pi) - \frac{n}{2} \ln \sigma^2 + \ln |S_n(\lambda)| - \frac{1}{2\sigma^2} (S_n(\lambda) Y_n - X_n \beta)' (S_n(\lambda) Y_n - X_n \beta),$$

2): **Method of Moments (MOM)** for SAR process:

$$\min_{\theta} g_n'(\theta) g_n(\theta).$$

The moment equations are based on three moments:

$$E(\epsilon_n' \epsilon_n) = n\sigma^2, \quad E(\epsilon_n' W_n' W_n \epsilon_n) = \sigma^2 \text{tr}(W_n' W_n), \quad E(\epsilon_n' W_n \epsilon_n) = 0.$$

These correspond to

$$g_n(\theta) = (Y_n' S_n'(\lambda) S_n(\lambda) Y_n - n\sigma^2, Y_n' S_n'(\lambda) W_n' W_n S_n(\lambda) Y_n - \sigma^2 \text{tr}(W_n' W_n), Y_n' S_n'(\lambda) W_n S_n(\lambda) Y_n)'.$$

3): **2SLS Estimation** for the MRSAR model

Denote $Z_n = (W_n Y_n, X_n)$ and $\delta = (\lambda, \beta')'$.

$$\hat{\delta}_{n,2sls} = \{Z_n' H_n (H_n' H_n)^{-1} H_n' Z_n\}^{-1} \times Z_n' H_n (H_n' H_n)^{-1} H_n' Y_n.$$

4) **Moments for GMM estimation**

Now consider constant $n \times n$ matrix P_{1n}, \dots, P_{mn} each with a zero diagonal. The moment functions $(P_{jn} \epsilon_n(\theta))' \epsilon_n(\theta)$ can be used in addition to $Q_n' \epsilon_n(\theta)$. These moment functions form a vector

$$g_n(\theta) = (P_{1n} \epsilon_n(\theta), \dots, P_{mn} \epsilon_n(\theta), Q_n)' \epsilon_n(\theta) = \begin{pmatrix} \epsilon_n'(\theta) P_{1n} \epsilon_n(\theta) \\ \vdots \\ \epsilon_n'(\theta) P_{mn} \epsilon_n(\theta) \\ Q_n' \epsilon_n(\theta) \end{pmatrix}$$