

Physics 106a — Classical Mechanics

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Lecture 18: Normal Modes

- General setup
- Linear algebra theory of normal modes
- Examples
 - Two coupled pendulums
 - Linear triatomic molecule CO_2
 - Triangular molecule O_3

Equations of motion and eigenvalue problem

- Lagrangian

$$L = \frac{1}{2} \tilde{\mathbf{q}} \cdot \mathbf{T} \cdot \dot{\mathbf{q}} - \frac{1}{2} \tilde{\mathbf{q}} \cdot \mathbf{V} \cdot \mathbf{q}$$

- Euler-Lagrange equations

$$\mathbf{T} \cdot \ddot{\mathbf{q}} + \mathbf{V} \cdot \mathbf{q} = 0$$

- Look for sinusoidal solution

$$\mathbf{q}(t) = \Phi e^{i\omega t}$$

- Generalized eigenvalue problem \Rightarrow characteristic equation

$$\mathbf{V} \cdot \Phi - \omega^2 \mathbf{T} \cdot \Phi = 0 \quad \Rightarrow \quad \det(\mathbf{V} - \omega^2 \mathbf{T}) = 0$$

- Solution

- N solutions for ω_α^2 (the eigenvalues): ω_α are the *normal mode frequencies*.
- Corresponding eigenvectors $\Phi^{(\alpha)}$ are the *normal modes*
- Components $\Phi_i^{(\alpha)}$ give the relative sizes of q_i if the α th mode is excited

Theorems

The following results can be proved (e.g. Hand and Finch §9.6):

- the eigenvalues ω_α^2 are real
- the eigenvectors $\Phi^{(\alpha)}$ may be chosen real
- assuming T is positive definite, then if V is positive definite, corresponding to a stable equilibrium, $\omega_\alpha^2 > 0$ and the mode frequencies ω_α are real
- a symmetry may lead to no change in potential energy for some displacement: this will give a zero eigenvalue and a *zero frequency mode*
- different eigenvectors can be chosen orthonormal (orthogonal and normalized to 1) in the sense

$$\tilde{\Phi}^{(\alpha)} \cdot T \cdot \Phi^{(\beta)} = \delta_{\alpha\beta}$$

- the eigenvectors form a basis (complete orthonormal set)

General solution

Equations of motion $\mathbf{T} \cdot \ddot{\mathbf{q}} + \mathbf{V} \cdot \mathbf{q} = 0$

A general set of displacements can be expanded in the normal mode basis

$$\mathbf{q}(t) = \sum_{\alpha} \rho_{\alpha}(t) \Phi^{(\alpha)} \quad \Rightarrow \quad q_i(t) = \sum_{\alpha} \rho_{\alpha}(t) \Phi_i^{(\alpha)}$$

The $\rho_{\alpha}(t)$ are called *normal mode coordinates*. Substituting into the EOM

$$0 = \sum_{\alpha} (\ddot{\rho}_{\alpha} \mathbf{T} \cdot \Phi^{(\alpha)} + \rho_{\alpha} \mathbf{V} \cdot \Phi^{(\alpha)}) = \sum_{\alpha} (\ddot{\rho}_{\alpha} + \omega_{\alpha}^2 \rho_{\alpha}) \mathbf{T} \cdot \Phi^{(\alpha)}$$

so that they satisfy *independent* SHO equations

$$\ddot{\rho}_{\beta} + \omega_{\beta}^2 \rho_{\beta} = 0$$

Using the orthogonality of the $\Phi^{(\alpha)}$ we can calculate the inverse relation

$$\rho_{\beta}(t) = \tilde{\Phi}^{(\beta)} \cdot \mathbf{T} \cdot \mathbf{q}(t)$$

Driven motion

Equations of motion: $\mathbf{T} \cdot \ddot{\mathbf{q}} + \mathbf{V} \cdot \mathbf{q} = \mathbf{F}(t)$

Expand the solution in the normal modes

$$\mathbf{q}(t) = \sum_{\alpha} \rho_{\alpha}(t) \Phi^{(\alpha)}$$

Substituting into the EOM

$$\sum_{\alpha} (\ddot{\rho}_{\alpha} + \omega_{\alpha}^2 \rho_{\alpha}) \mathbf{T} \cdot \Phi^{(\alpha)} = \mathbf{F}$$

so that the normal mode coordinates satisfy the equations

$$\ddot{\rho}_{\beta} + \omega_{\beta}^2 \rho_{\beta} = \mathcal{F}_{\beta} \quad \text{with} \quad \mathcal{F}_{\beta} = \tilde{\Phi}^{(\beta)} \cdot \mathbf{F}$$

Initial conditions

Often convenient to use complex notation for the normal mode oscillations

$$\rho_\alpha(t) = \text{Re}[A_\alpha e^{i\omega_\alpha t}]$$

The general solution can now be written

$$\mathbf{q}(t) = \sum_{\alpha} \text{Re}[A_\alpha e^{i\omega_\alpha t}] \mathbf{\Phi}^{(\alpha)}$$

and then

$$\dot{\mathbf{q}}(t) = \sum_{\alpha} \text{Re}[i\omega_\alpha A_\alpha e^{i\omega_\alpha t}] \mathbf{\Phi}^{(\alpha)}$$

Suppose initial conditions for $\mathbf{q}(0)$ and velocities $\dot{\mathbf{q}}(0)$. Use the orthogonality relation to give

$$\text{Re } A_\beta = \tilde{\mathbf{\Phi}}^{(\beta)} \cdot \mathbf{T} \cdot \mathbf{q}(0)$$

$$\omega_\beta \text{Im } A_\beta = -\tilde{\mathbf{\Phi}}^{(\beta)} \cdot \mathbf{T} \cdot \dot{\mathbf{q}}(0)$$

Transformation matrix

Define the matrix \mathbf{R} as the matrix with *columns* given by the normal mode vectors

$$R_{i\alpha} = \Phi_i^{(\alpha)}$$

Then

$$\mathbf{q}(t) = \mathbf{R} \cdot \boldsymbol{\rho}(t)$$

The orthogonality of the normal mode vectors can be expressed as

$$\tilde{\mathbf{R}} \cdot \mathbf{T} \cdot \mathbf{R} = \mathbf{I}$$

with \mathbf{I} the unit $N \times N$ matrix.

The inverse relation is

$$\boldsymbol{\rho}(t) = \tilde{\mathbf{R}} \cdot \mathbf{T} \cdot \mathbf{q}(t)$$

Diagonalization

The orthogonality of the normal mode vectors gave

$$\tilde{\mathbf{R}} \cdot \mathbf{T} \cdot \mathbf{R} = \mathbf{I}$$

Also

$$(\tilde{\mathbf{R}} \cdot \mathbf{V} \cdot \mathbf{R})_{\alpha\beta} = \tilde{\Phi}^{(\alpha)} \cdot \mathbf{V} \cdot \Phi^{(\beta)} = \omega_\beta^2 \tilde{\Phi}^{(\alpha)} \cdot \mathbf{T} \cdot \Phi^{(\beta)} = \omega_\beta^2 \delta_{\alpha\beta}$$

so that \mathbf{R} also diagonalizes \mathbf{V}

$$\tilde{\mathbf{R}} \cdot \mathbf{V} \cdot \mathbf{R} = \mathbf{\Omega}$$

where $\mathbf{\Omega}$ is the diagonal matrix with entries ω_α^2 .

The *congruence transformation* $\tilde{\mathbf{R}} \cdot \mathbf{?} \cdot \mathbf{R}$ diagonalizes both \mathbf{T} and \mathbf{V} .

Lagrangian and Hamiltonian

It is straightforward to show using $\mathbf{q} = \mathbf{R} \cdot \boldsymbol{\rho}$

$$T = \frac{1}{2} \tilde{\mathbf{q}} \cdot \mathbf{T} \cdot \dot{\mathbf{q}} = \frac{1}{2} \tilde{\boldsymbol{\rho}} \cdot \dot{\boldsymbol{\rho}}$$

$$V = \frac{1}{2} \tilde{\mathbf{q}} \cdot \mathbf{V} \cdot \mathbf{q} = \frac{1}{2} \tilde{\boldsymbol{\rho}} \cdot \boldsymbol{\Omega} \cdot \boldsymbol{\rho}$$

so that the Lagrangian is

$$L = \frac{1}{2} \sum_{\alpha} (\dot{\rho}_{\alpha}^2 - \omega_{\alpha}^2 \rho_{\alpha}^2)$$

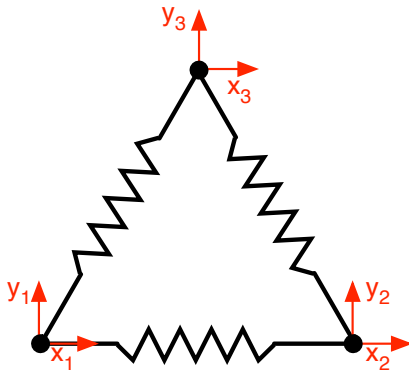
Defining the momentum conjugate to the normal mode coordinate

$$p_{\rho, \alpha} = \frac{\partial L}{\partial \dot{\rho}_{\alpha}} = \dot{\rho}_{\alpha}$$

gives the Hamiltonian

$$H = \frac{1}{2} \sum_{\alpha} (p_{\rho, \alpha}^2 + \omega_{\alpha}^2 \rho_{\alpha}^2)$$

Vibrations of Ozone



$$V = \frac{1}{2}k \left\{ \left[\frac{1}{2}(x_2 - x_3) + \frac{\sqrt{3}}{2}(y_3 - y_2) \right]^2 + \left[\frac{1}{2}(x_3 - x_1) + \frac{\sqrt{3}}{2}(y_3 - y_1) \right]^2 + (x_2 - x_1)^2 \right\}$$

(Only need projection of displacements *along* spring)

Vibrations of Ozone

$$V = \frac{1}{2}k \left\{ \left[\frac{1}{2}(x_2 - x_3) + \frac{\sqrt{3}}{2}(y_3 - y_2) \right]^2 + \left[\frac{1}{2}(x_3 - x_1) + \frac{\sqrt{3}}{2}(y_3 - y_1) \right]^2 + (x_2 - x_1)^2 \right\}$$

$$\mathbf{q} = (x_1, y_1, x_2, y_2, x_3, y_3), \quad V_{14} = \frac{\partial^2 V}{\partial x_1 \partial y_2} \quad \text{etc.}$$

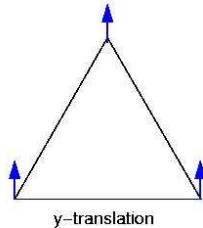
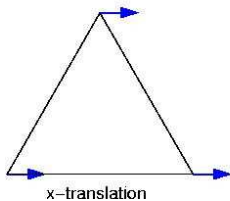
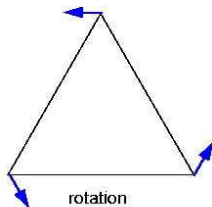
$$\mathbf{V} = k \begin{pmatrix} 5/4 & \sqrt{3}/4 & -1 & 0 & -1/4 & -\sqrt{3}/4 \\ \sqrt{3}/4 & 3/4 & 0 & 0 & -\sqrt{3}/4 & -3/4 \\ -1 & 0 & 5/4 & -\sqrt{3}/4 & -1/4 & \sqrt{3}/4 \\ 0 & 0 & -\sqrt{3}/4 & 3/4 & \sqrt{3}/4 & -3/4 \\ -1/4 & -\sqrt{3}/4 & -1/4 & \sqrt{3}/4 & 1/2 & 0 \\ -\sqrt{3}/4 & -3/4 & \sqrt{3}/4 & -3/4 & 0 & 3/2 \end{pmatrix}$$

$$\mathbf{T} = m\mathbf{I}$$

$$\text{Eigenvalues}[\mathbf{V}/m] : \quad \left\{ 0, 0, 0, \frac{3k}{2m}, \frac{3k}{2m}, \frac{3k}{m} \right\}$$

Vibrations of Ozone

Zero modes



Vibrations of Ozone

Other modes

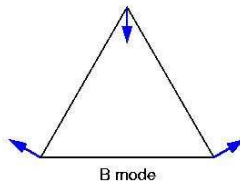
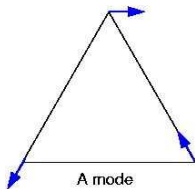
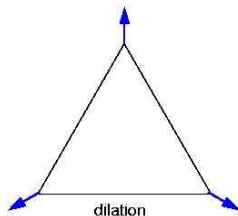
$$\text{Eigenvectors}[V][[6]]: \left\{ -\frac{\sqrt{3}}{2}, -\frac{1}{2}, \frac{\sqrt{3}}{2}, -\frac{1}{2}, 0, 1 \right\}$$

$$\text{Eigenvectors}[V][[5]]: \left\{ -\frac{1}{2}, -\frac{\sqrt{3}}{2}, -\frac{1}{2}, \frac{\sqrt{3}}{2}, 1, 0 \right\}$$

$$\text{Eigenvectors}[V][[4]]: \left\{ \frac{-\sqrt{3}}{2}, \frac{1}{2}, \frac{\sqrt{3}}{2}, \frac{1}{2}, 0, -1 \right\}$$

Vibrations of Ozone

Other modes



A and B modes are *degenerate* — group theory for $\bar{6}m2$ point group