ACM 100b

Application of the Laplace transform to ODEs

Dan Meiron

Caltech

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Examples of the application to ODE's

- We give two examples of the application of Laplace transforms below
- The first is just the solution of a homogeneous constant coefficient ODE
- We can of course do that many ways
- The second has an inhomogeneous term
- Typically Laplace transforms are most useful for constant coefficient IVP's
- Because they handle the initial conditions and any inhomogeneous terms they are very useful



Homogeneous example

Consider the initial value problem

$$y'' - y' - 2y = 0$$
 $y(0) = 1$, $y'(0) = 0$.

Now apply the Laplace transform to both sides of this equation:

$$\mathcal{L}[y'' - y' - 2y] = \mathcal{L}[0].$$

- Call the transform of y(t) Y(s).
- We then have

$$\mathcal{L}[y''] - \mathcal{L}[y'] - 2\mathcal{L}[y] = 0,$$



Homogeneous example

Now recall

$$\mathfrak{L}[f^{n}(t)] = s^{n} \mathfrak{L}[f(t)] - s^{n-1} f(0) - s^{n-2} f'(0) - \dots - s f^{(n-2)}(0) - f^{(n-1)}(0).$$

Using the properties of derivatives of Laplace transforms we have

$$(s^2-s-2)Y(s)+(1-s)y(0)-y'(0)=0.$$

Plug in the known initial values to get

$$Y(s)=\frac{s-1}{(s-2)(s+1)}.$$

- Note we have factored the denominator which shows two poles at s = 2 and s = -1.
- These are just the roots of the polynomial in α we solve when we substitute $\exp(\alpha x)$ into a constant coefficient ODE.

Homogeneous example

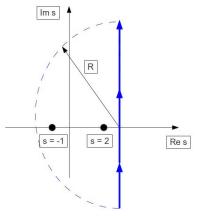
- Now comes the problem of inverting the Laplace transform.
- The Inverse Laplace transform is given by

$$f(t) = \frac{1}{2\pi i} \int_{C-i\infty}^{C+i\infty} \frac{s-1}{(s-2)(s+1)} \exp(st) dt,$$

- Again the real number C is to be chosen so the vertical contour lies to the right of all singularities of the transform.
- In this case the singularities are at s = -1 and s = 2 so if we set say C > 2 that will work.

The Bromwich contour

- To finish the inversion we use the techniques of contour integrals learned in ACM 95/100a
- The Bromwich contour looks like this



Doing the integral

- We close the vertical contour in the left half plane.
- It has to be closed there if we want to compute the solution for t > 0
- In that case the real part of the complex variable s will become negative and in that case we can show that the completion of the contour vanishes
- Using the residue theorem we get

$$y(t) = \frac{1}{3} \exp(2t) + \frac{2}{3} \exp(-t).$$

Note the result automatically satisfies the IVP.



Closing the contour the other way

- Note you can close the contour for t < 0 in the right half plane.
- In that case we get nothing.
- This is because the integrand is analytic
- And so by Cauchy's theorem the integral is zero.
- This reflects the fact that there is a built-in definition in the Laplace transform that our function f(t) vanishes for t < 0.
- The initial value problem is defined only for t > 0
- And so as a result we get no information about t < 0.
- Finally note the fact that our solution satisfies the initial conditions.
- This is an immediate benefit of the Laplace transform. In the next section we explore the benefits for inhomogeneous problems.



- In the previous lecture we showed how the Laplace transform can be used for homogeneous ODE's
- Next we'll do an inhomogeneous example
- Consider the IVP

$$y'' + 4y = h(t)$$
 $y(0) = 1$, $y'(0) = 0$,

where

$$h(t) = \begin{cases} 0 & 0 \le t < \pi \\ 1 & \pi \le t < 2\pi \\ 0 & t \ge 2\pi. \end{cases}$$

We recall that

$$h(t) = u_{\pi}(t) - u_{2\pi}(t).$$

in terms of the unit step function.



We transform both sides of the ODE to get

$$(s^2 + 4)Y(s) - sy(0) - y'(0) = \mathcal{L}[u_{\pi}(t)] - \mathcal{L}[u_{2\pi}(t)],$$

This then gives us the transform of the solution

$$Y(s) = \frac{s}{s^2 + 4} + \frac{\exp(-\pi s)}{s(s^2 + 4)} - \frac{\exp(-2\pi s)}{s(s^2 + 4)}.$$

We now want to invert the transform to compute

$$y(t) = \frac{1}{2\pi i} \int_{C-i\infty}^{C+i\infty} \exp(st) \left[\frac{s}{s^2+4} + \frac{\exp(-\pi s)}{s(s^2+4)} - \frac{\exp(-2\pi s)}{s(s^2+4)} \right] ds.$$



• The best way to do this integral is to break it up into three terms:

$$y(t) = y_1(t) + y_2(t) + y_3(t).$$

- The first term is just an example of the kind of contour integral we did before.
- Close in the left half plane to get via the residue theorem that

$$y_1(t) = \frac{1}{2\pi i} \int_{C-i\infty}^{C+i\infty} \exp(st) \frac{s}{s^2 + 4} ds$$

$$= \frac{1}{2\pi i} \left[2\pi i \left(\exp(2it) \left(\frac{2i}{4i} \right) + \exp(-2it) \left(\frac{-2i}{-4i} \right) \right) \right]$$

$$= \cos(2t).$$

• The second integral is a little more involved but not much harder:

$$y_2(t) = rac{1}{2\pi i} \int_{C-i\infty}^{C+i\infty} \exp(st) rac{\exp(-\pi s)}{s(s^2+4)} ds.$$

- If $0 < t < \pi$ we have to close the contour in the right half plane or the integral won't exist due to the argument of the exponential.
- If $t > \pi$ we close in the left half plane.
- The result is

$$y_2(t) = \begin{cases} 0 & 0 < t < \pi \\ \frac{1}{2\pi i} \left[2\pi i \left(\frac{\exp(2i(t-\pi))}{(2i)(4i)} + \frac{1}{4} + \frac{\exp(-2i(t-\pi))}{(-2i)(-4i)} \right) \right] & t > \pi, \end{cases}$$

or

$$y_2(t) = \begin{cases} 0 & 0 < t < \pi \\ 1/4 - \cos(2(t-\pi))/4 & t > \pi. \end{cases}$$



• A similar procedure will give you the third integral:

$$y_3(t) = \begin{cases} 0 & 0 < t < 2\pi \\ -1/4 + \cos(2(t-2\pi))/4 & t > 2\pi. \end{cases}$$

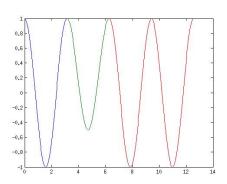
Expanding out the cosines and putting everything together we get

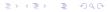
$$y(t) = \begin{cases} \cos(2t) & 0 < t < \pi \\ 3/4\cos(2t) + 1/4 & \pi \le t \le 2\pi \\ \cos(2t) & t > 2\pi. \end{cases}$$

A few notes on the solution

$$y(t) = egin{cases} \cos(2t) & 0 < t < \pi \ 3/4\cos(2t) + 1/4 & \pi \le t \le 2\pi \ \cos(2t) & t > 2\pi. \end{cases}$$

A plot of the solution can be seen below





- Look at the values of the solution at $t = \pi$ and $t = 2\pi$ which are the locations of the discontinuities in the right hand side.
- You will see that they are continuous there.
- Their derivatives are also continuous.
- We certainly expect this from the solution because we have solved a second order ODE with a right hand side that is only piece-wise discontinuous.
- The smoothness of the solution is controlled by the highest order derivative.
- Since that is a second order derivative then we expect the solution to be continuous as well as to have continuous first derivatives.
- The Laplace transform is convenient in this regard since all initial values as well as the continuity of the solution are built into the inverse transform we computed.