

A nondestructive method for estimating the total green leaf area of individual rice plants using multi-angle color images

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Total green leaf area (GLA) is an important trait for agronomic studies. However, existing methods for estimating the GLA of individual rice plants are destructive and labor-intensive. A nondestructive method for estimating the total GLA of individual rice plants based on multi-angle color images is presented. Using projected areas of the plant in images, linear, quadratic, exponential and power regression models for estimating total GLA were evaluated. Tests demonstrated that the side-view projected area had a stronger relationship with the actual total leaf area than the top-projected area. And power models fit better than other models. In addition, the use of multiple side-view images was an efficient method for reducing the estimation error. The inclusion of the top-view projected area as a second predictor provided only a slight improvement of the total leaf area estimation. When the projected areas from multi-angle images

were used, the estimated leaf area (ELA) using the power model and the actual leaf area had a high correlation coefficient ($R^2 > 0.98$), and the mean absolute percentage error (MAPE) was about 6%. The method was capable of estimating the total leaf area in a nondestructive, accurate and efficient manner, and it may be used for monitoring rice plant growth.

Keywords: Agri-photonics; image processing; plant phenotyping; regression model; visible light imaging.

1. Introduction

Rice is a staple food for approximately half the world's population and is one of the most widely grown crops.¹ Since rice yield is important to crop production, exploring for methods to increase the rice yield has always been a hot topic in research.^{2–4} Green leaf area (GLA) is closely related to plant growth, light interception, photosynthetic efficiency, evapotranspiration and response to fertilizers and irrigation,⁵ which basically determines the rice yield and quality.^{6,7} Therefore, it is a key parameter that needs to be accurately measured.

GLA can be obtained via the gravimetric technique after harvesting the leaves. The gravimetric technique is based on the leaf mass per area (LMA) determined from a sub sample, and the total leaf area is calculated based on the sub sample LMA and the dry weight of all leaves.⁸ Commercialized scanning planimeters, such as LI-3100 (LI-COR Biosciences, NE, USA), can make rapid GLA measurements for individual plants in an automatic but destructive manner. These destructive methods are accurate but labor-intensive. For nondestructive GLA estimation, special instruments have been developed. Plant canopy analyzers, such as LAI-2000 (LI-COR, Inc., Nebraska, USA) and the Delta-T Devices SunScan (Delta-T Devices, Cambridge, UK), are used for estimating leaf area index of field-grown rice plants. However, these instruments are not suitable for GLA estimation of individual plants. Portable scanning planimeters that support *in vivo* GLA assessment of individual plants, such as CI-202 (CID Inc., NW Camas, WA, USA), could be labor-intensive and time-consuming when measuring large quantities of leaves. Therefore, a non-destructive and high-throughput method for GLA estimation of rice is needed.

Optical and photonics technologies have been important tools in agriculture area,⁹ and have been widely used for inspection and grading of agricultural and food products,¹⁰ quality evaluation of fruit¹¹ and plant growth measurement.^{12–15} The

visible light imaging technique has been widely used as a nondestructive method for GLA estimation. Baker *et al.*¹⁶ showed that the total leaf area of a whole tree plant can be calculated from image-based areas. Leroy *et al.*¹⁷ obtained single leaf measurements from digital pictures and reported relationships between various leaf measurements relative to the actual leaf area. Rajendran *et al.*¹⁸ found a strong linear relationship between the total leaf area of individual wheat plants and the sum of the projected area in three orthogonal images. Marcon *et al.*¹⁹ proposed two models for total leaf area estimations of coffee plants using the width and the height of tree canopies obtained from images as well as the total leaf area visible on the images. Nagel *et al.*²⁰ also found a strong linear relationship between the total leaf area and the sum of two side-views at a 90° horizontal rotation for maize and barley plants. Pereyra-Irujo *et al.*²¹ used a power function to describe the relationship between the total leaf area of individual soybean plants and the projected shoot area, which was calculated by summing one top-view projected leaf area and one side-view projected area from the images of the plants. However, nondestructive approaches are yet to be employed in estimating the GLA for individual rice plant.

Previously, our group developed an automated high-throughput system for measuring rice tillers (H-SMART²²). In this study, the visible light imaging system was incorporated into the H-SMART for rice image acquisition. In this paper, we present and validate a nondestructive method for estimating the total GLA of individual rice plants using multi-angle color images. The visible light imaging system was incorporated into the H-SMART for rice image acquisition. And the GLA was estimated through a modeling approach using projected areas of the plant in images. The objectives of this paper were: (i) to adapt the image-based method for estimating the GLA of individual rice plants; (ii) to propose a model using projected area for calculating

the GLA; and (iii) to evaluate the accuracy improvement of GLA estimation by using multi-angle color images.

2. Materials and Methods

2.1. Sample preparation and the destructive method

A total of 235 rice plants were used to develop and validate the models. The species of plants were Liangyoupeiyou and Peiliangyou 3076. All of the samples were imaged before the leaves were harvested. In this study, a commercial scanner (BenQ 8800, BenQ Corporation, China) was used to obtain the actual leaf area measurement. The destructive method was similar to that of Caldas *et al.*²³ Leaves were clipped and pasted flat on white sheets of paper, after which the papers were placed in the scanner. The scan was performed with 300 dpi, and the images were saved as 8-bit grayscale images. Using a fixed grayscale threshold, leaves in the saved images were discriminated from the background. Based on the foreground pixel counts of all leaves that belonged to the same plant, the total leaf area for individual rice plant was obtained. The experiment was performed during the tillering stage. The minimum and maximum leaf area measurements were 30.34 and 1741.51 cm², respectively.

2.2. Digital image acquisition

When incorporated with visible light imaging system, the H-SMART was able to effectively acquire rice images. Figure 1 shows a schematic of the imaging system, which consisted of a side-view color camera (Stingray F-504C, Allied Vision

Technologies, Germany), a top-view color camera (DH-SV1410, Daheng Group Inc., China), a rotating platform, a servo motor controller (MBDDT-2210, Panasonic Corporation, China), a computer workstation (HP xw6400, Hewlett-Packard Development Company, USA) and light sources. Both cameras were equipped with an 8 mm focal length (f) lens (F1.8 EX DG Aspherical Macro, SIGMA, Japan), and the axes of the two cameras were oriented orthogonal to each other. The side-view camera was mounted rigidly with the viewing plane perpendicular to the ground plane at a distance of 1700 mm from the plant, and the top-view camera was mounted on a top plane at a distance of 1700 mm above the plant. To improve the image quality, a dark blue backdrop was used to provide a consistent background behind the plant. In addition, to prevent strong shadows, two light sources were fixed to the left and right of the plant respectively, and two light sources were fixed on the top plane. The cell size of the top-view camera was $6.45 \mu\text{m} \times 6.45 \mu\text{m}$, and the picture size was 1392×1040 pixels. The cell size of the side-view camera was $3.5 \mu\text{m} \times 3.5 \mu\text{m}$, and the picture size was 2452×2056 pixels. Therefore, the field of view for the top-view camera was approximately $1908 \text{ mm} \times 1425 \text{ mm}$ (length \times width), and the field of view for the side-view camera was approximately $1824 \text{ mm} \times 1529 \text{ mm}$ (height \times width). A total of 12 side-view images (angle-interval of 30°) were acquired as the potted rice plant was continuously rotated, and one top-view image was taken.

2.3. Image processing

The image processing procedure is illustrated in Fig. 2. Figure 2(a) presents a color plant image from the side view. To enhance the plant region extraction, the image was transformed to an excessive green ($E \times G$) image [Fig. 2(b)] and an excessive red ($E \times R$) image [Fig. 2(c)] using²⁴:

$$E \times G = 2g - r - b, \quad (1)$$

$$E \times R = 1.4r - b. \quad (2)$$

The variables r , g and b are the normalized color features calculated according to:

$$r = R/(R + G + B), \quad (3)$$

$$g = G/(R + G + B), \quad (4)$$

$$b = B/(R + G + B), \quad (5)$$

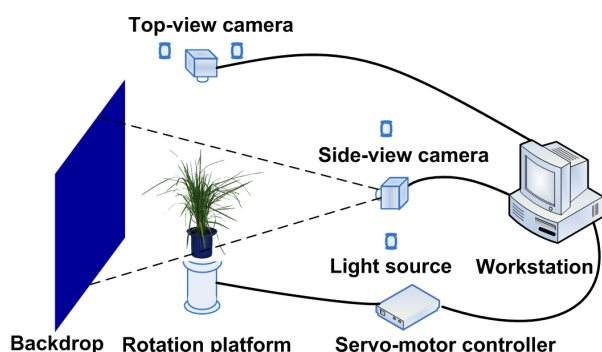


Fig. 1. Schematic drawing of the imaging system.

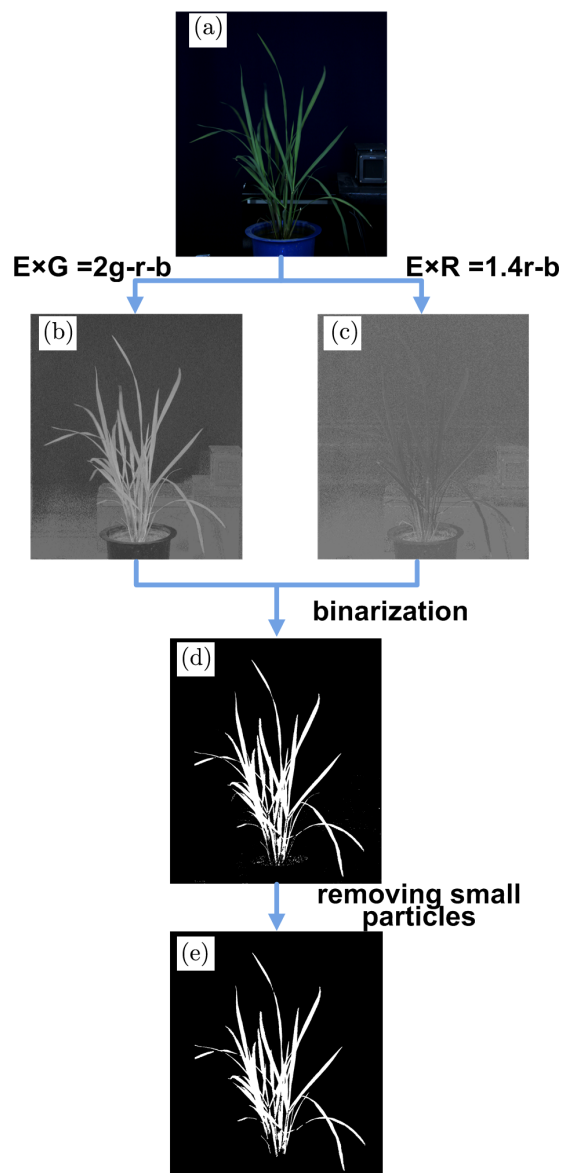


Fig. 2. Outline of the side-view image processing procedure. (a) The original image; (b) the $E \times G$ image; (c) the $E \times R$ image; (d) the binary image; and (e) the result of removing small particles.

where R , G and B are the grayscale values for each RGB channel.

A fixed threshold was applied to the $E \times G$ image to identify bright objects, and a fixed threshold was applied to the $E \times R$ image to identify dark objects. By applying an AND operation to the two binary image, the plant region was extracted, and the soil in the pot was not discriminated as plant [Fig. 2(d)]. Due to the presence of undesirable spots in the binary image, a processing step was employed to remove small areas, and

regions with areas smaller than a predefined threshold were eliminated [Fig. 2(e)].

All of the 12 side-view images and one top-view image were processed in the same way. The projected areas of the plant in multiple views were calculated by counting the number of pixels that belonged to the plant region in each image.

2.4. Model development and validation

A total of 135 pots of the samples were randomly selected for model development, and the remaining 100 samples were used as test samples for model validation. Using projected areas of the plant in images, linear, quadratic, exponential and power regression models for estimating total GLA were developed based on regression analyses. For each model, the following statistics for assessing the goodness of fit were calculated:

- (1) Coefficient of determination value (R^2): a measure of how well the model represented the data.
- (2) t -test value and its significance: tests of individual independent variables indicated the statistical significance of respective independent variable.
- (3) Mean absolute percentage error (MAPE): a measure of accuracy, which was given as follows:

$$\text{MAPE} = \frac{1}{n} \sum_{i=1}^n \frac{|\text{ELA}_i - \text{GLA}_i|}{\text{GLA}_i} * 100\%, \quad (6)$$

where ELA_i is the estimated leaf area using a model for the i th sample, and n is the number of plant samples.

- (4) Root mean square error (RMSE): a measure of error variance, which was given as follows:

$$\text{RMSE} = \sqrt{\frac{1}{n} \sum_{i=1}^n (\text{ELA}_i - \text{GLA}_i)^2}. \quad (7)$$

To assess the predictive performance of the models and test their ability to generalize, the test samples were used for model validation. The ELAs, which were determined using the models, were compared with the actual leaf area, and leave-one-out cross validation using the 235 samples was applied. The R^2 , MAPE and RMSE values of calibration, prediction and cross validation (R_c^2 , R_p^2 , R_{cv}^2 , MAPEC, MAPEP, MAPECV, RMSEC,

RMSEP and RMSECV), were calculated. Based on these analysis results, the best model was selected.

3. Results

3.1. Performance of linear and nonlinear models

A total of 135 pots of rice plants were randomly selected as calibration samples for model development. To determine the best predictor of GLA, the relationship between the GLA and the top-projected area (TA) was compared with the relationship between the GLA and the average projected area of 12 side-view images (SA_{ave}). The scatter plots of TA vs GLA and SA_{ave} vs GLA are shown in Figs. 3(a) and 3(b), respectively. It can be observed that both TA and SA_{ave} have a close relationship with GLA. The two plots are similar, although the plot of TA vs GLA shows a greater dispersion of the data. Therefore, SA_{ave} is the better predictor of GLA.

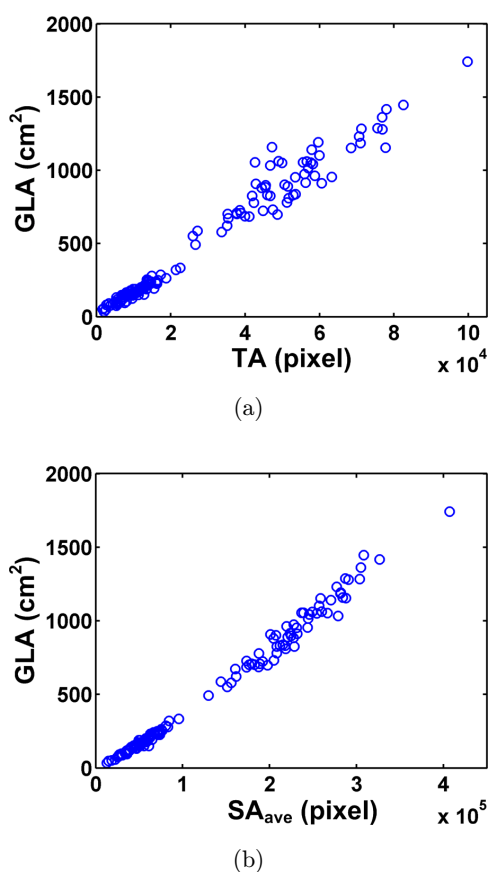


Fig. 3. Scatter plots of projected areas vs the actual total GLA. (a) top-view projected area (TA) vs GLA; (b) average side-view projected area (SA_{ave}) vs GLA.

Using SA_{ave} and GLA as independent and dependent variables, respectively, linear, quadratic, exponential and power models were developed. The models are:

$$\text{Linear: } GLA = a_0 + a_1 \times SA_{ave}, \quad (\text{Model 1})$$

$$\text{Quadratic: } GLA = a_0 + a_1 \times SA_{ave} + a_2 \times SA_{ave}^2, \quad (\text{Model 2})$$

$$\text{Exponential: } GLA = a_0 \times e^{a_1 \times SA_{ave}}, \quad (\text{Model 3})$$

$$\text{Power: } \ln(GLA) = a_0 + a_1 \times \ln(SA_{ave}), \quad (\text{Model 4})$$

where a_0 , a_1 and a_2 are the coefficients.

To compare with the four models fitted to SA_{ave} vs GLA, the image-based leaf sum (IBLS) model of Rajendran *et al.*¹⁸ was also developed using the calibration samples.

$$\text{IBLS: } GLA = a_0 + a_1 \times A_{sum}, \quad (\text{Model 5})$$

where A_{sum} is the sum of the projected area from the top-view image and two orthogonal side-view images.

Table 1 presents the regression coefficients and statistical parameters for the five models described above. Figure 4 shows the relationship between the ELA using regression models and SA_{ave} or A_{sum} , as well as the dispersion pattern of the residuals for the respective models. As can be seen from Table 1, all of the models showed high R_c^2 values, and the coefficients were significant. For all of the models, the correlation R_p^2 exceeded 0.87, and the accuracy on the test samples was slightly less than that on the calibration samples, and the estimation error predicted by the cross validation gave similar results to the error on the calibration samples. The results showed that the five models did not overfit the calibration samples and had good ability to generalize.

In the five developed models, the exponential model had the worst precision. The scatter plot of the residual of the exponential model had a heteroscedastic behavior, and the estimation error was large when the plants were large [Fig. 4(h)]. The MAPEC values of Model 1, Model 2 and Model 5 were less than 10%, although their bias led to an underestimation for small samples [Figs. 4(f), 4(g) and 4(j)]. Compared with other models, the power

Table 1. Statistical summary of the five developed models for total GLA estimation.

Model	Coefficients	Std. Error	t	Sig.	R^2_c	MAPEC	RMSEC (cm ²)	R^2_p	MAPEP	RMSEP (cm ²)	R^2_{cv}	MAPECV	RMSECV (cm ²)
Model 1: Linear	$a_0 = -58.517$ $a_1 = 0.004$	6.003 0.000	-9.748 118.168	0.000 0.000	0.991	9.52%	41.086	0.986	12.43%	48.524	0.988	10.66%	45.063
Model 2: Quadratic	$a_0 = -27.454$ $a_1 = 0.004$ $a_2 = 2.10E-9$	8.683 0.000 0.000	-3.162 25.442 4.671	0.002 0.000 0.000	0.992	6.28%	38.062	0.988	7.72%	47.144	0.989	6.83%	42.997
Model 3: Exponential	$a_0 = 96.607$ $a_1 = 9.60E-6$	3.846 0.000	25.121 39.117	0.000 0.000	0.920	22.33%	301.261	0.871	27.07%	197.856	0.793	24.66%	300.706
Model 4: Power	$a_0 = -7.277$ $a_1 = 1.143$	0.084 0.007	-86.654 156.427	0.000 0.000	0.995	5.36%	37.934	0.988	5.81%	48.532	0.990	5.59%	41.974
Model 5: IBLS	$a_0 = -54.223$ $a_1 = 0.002$	6.234 0.000	-8.697 113.216	0.000 0.000	0.990	9.55%	42.865	0.985	11.91%	51.827	0.987	10.44%	47.090

model gave the best performance and had the highest R^2 value, and highest accuracy (Table 1); in addition, the residuals were close to a normal distribution. Model 1 and Model 5, where the relationship between the variables was linear, behaved similarly for GLA estimation. The non-linear models, with the exception of the exponential model, fit the GLA better than the linear models.

3.2. Performance of the models using various numbers of side-view images

A greater number of side views would obviously have more information about the plant architecture. For example, additional hidden leaves can be observed when using multiple views. The projected areas of 10 randomly selected samples in each

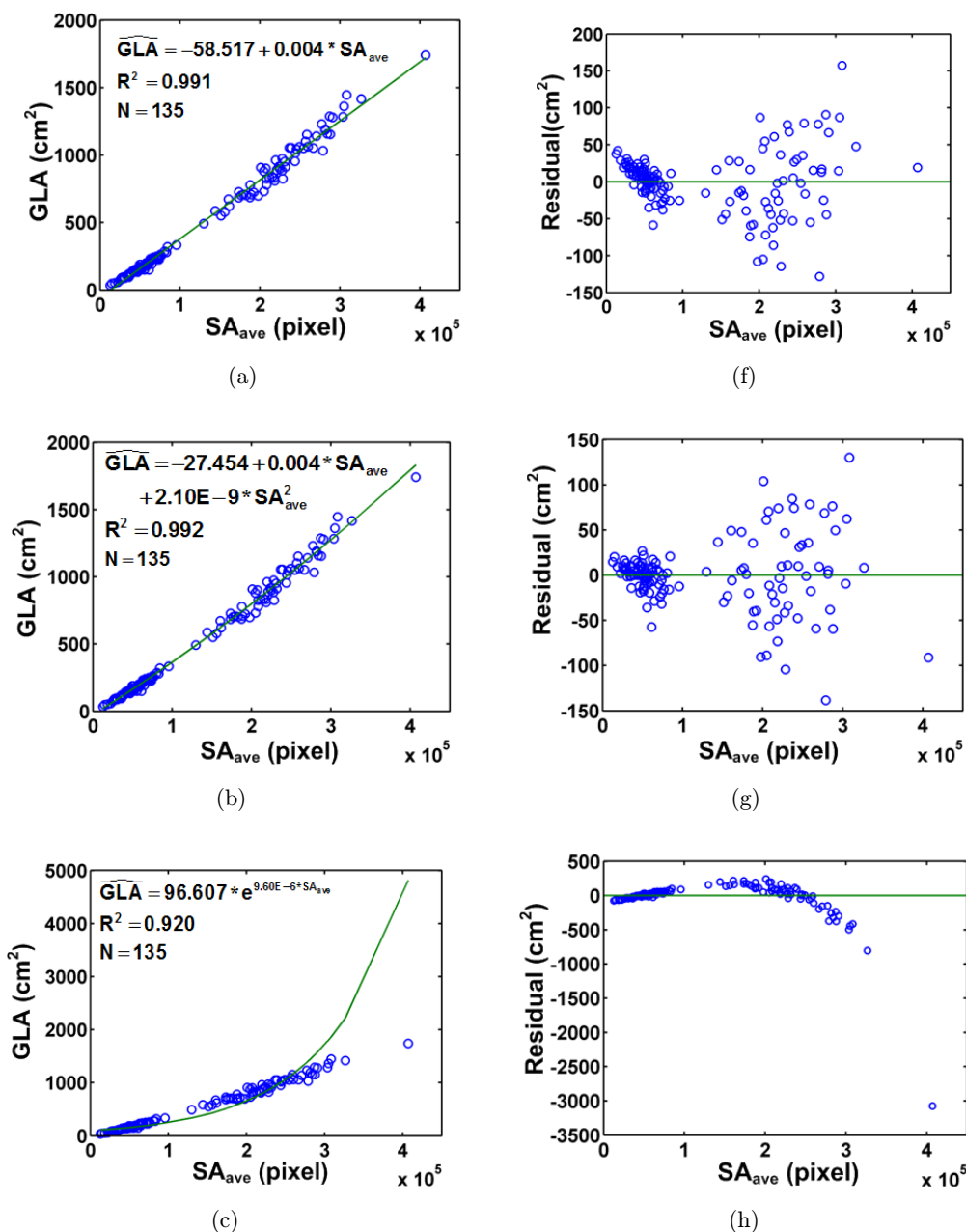


Fig. 4. Performance of the linear and nonlinear models. The relationships between the ELA and the average side-view projected area for modeling samples using the (a) linear model, (b) quadratic model, (c) exponential model, (d) power model and (e) IBL model are shown in the left panel. The dispersion pattern of the residual for the respective (f) linear model, (g) quadratic model, (h) exponential model, (i) power model and (j) IBL model are shown in the right panel.

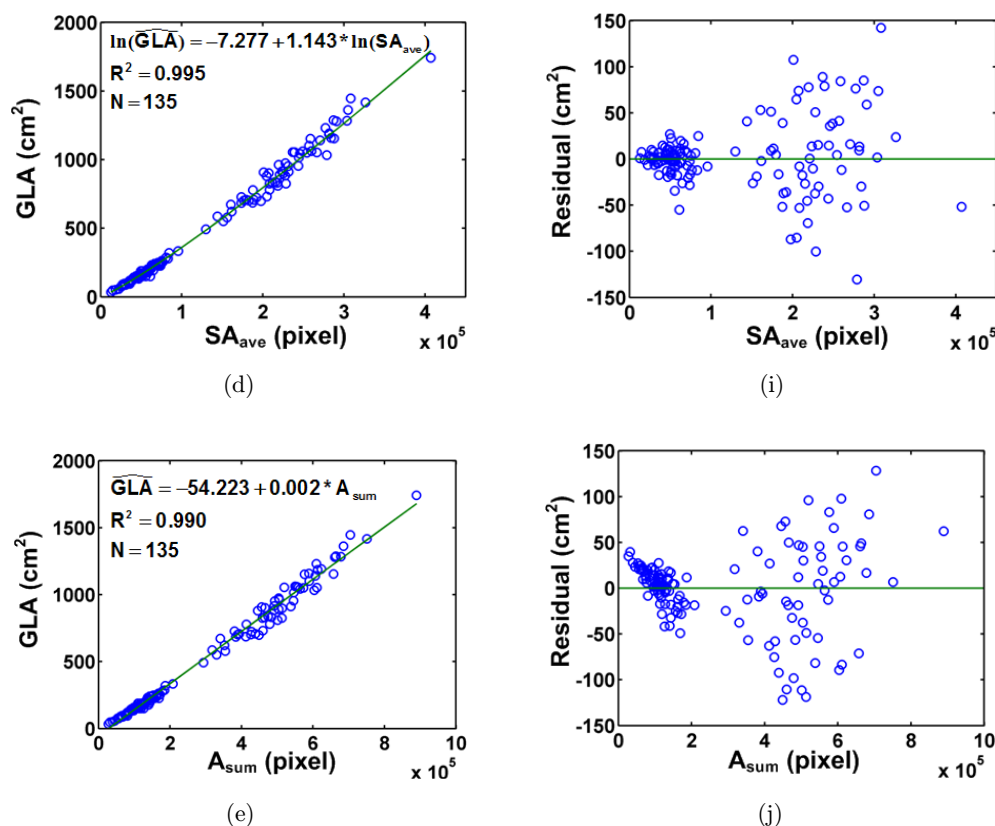


Fig. 4. (Continued)

side-view image are shown in Fig. 5, where the curves of the projected area fluctuate, and the scale of this fluctuation varies among different plants. Since different overlapping leaves were discerned in multi-side-view images, the projected area varied in different side views. To determine the appropriate number of side views, power models that use the

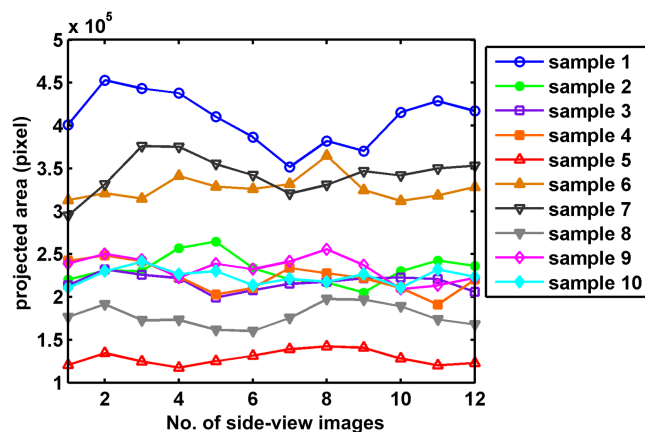


Fig. 5. The curves of the projected areas in each side-view image for 10 randomly selected samples.

average projected area from different numbers of side-view images for the same 135 samples were developed and evaluated:

$$\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_1), \quad (\text{Model 6})$$

$$\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_2), \quad (\text{Model 7})$$

$$\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_4), \quad (\text{Model 8})$$

$$\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_6), \quad (\text{Model 9})$$

where SA_1 is the projected area from a single image with an angle of 0; SA_2 is the average projected area from two images with angles of 0 and 90; SA_4 is the average projected area from four images with angles of 0, 90, 180 and 270; and SA_6 is the average projected area from six images with angles of 0, 60, 120, 180, 240 and 300.

Table 2 shows the results for the four power models. For all of the models, the ELA had a strong relationship with the actual leaf area. Comparing the predicted accuracy of the models, Model 6, which used a single side-view image, had the highest MAPEP value with 10.23%. In comparison, for Model 7, the MAPEP decreased by 4.12% points to

Table 2. Statistical summary of the models using various numbers of side-view images.

Model	Coefficients	Std. Error	t	Sig.	R^2_c	MAPEC (cm ²)	RMSEC (cm ²)	R^2_p	MAPEP (cm ²)	RMSEP (cm ²)	R^2_{cv}	MAPECV (%)	RMSECV (cm ²)
Model 6: $\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_1)$	$a_0 = -7.094$ $a_1 = 1.128$	0.135 0.012	-52.409 95.699	0.000 0.000	0.986	9.06%	59.066	0.977	10.23%	68.818	0.977	9.65%	63.027
Model 7: $\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_2)$	$a_0 = -7.282$ $a_1 = 1.144$	0.091 0.008	-80.201 144.730	0.000 0.000	0.994	6.13%	42.731	0.986	6.11%	51.251	0.987	6.16%	46.611
Model 8: $\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_4)$	$a_0 = -7.292$ $a_1 = 1.145$	0.086 0.007	-85.124 153.517	0.000 0.000	0.994	5.73%	39.897	0.986	5.99%	49.962	0.989	5.90%	44.620
Model 9: $\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_6)$	$a_0 = -7.265$ $a_1 = 1.142$	0.084 0.007	-86.186 155.692	0.000 0.000	0.995	5.48%	38.310	0.988	5.87%	46.839	0.990	5.72%	42.167

Table 3. Statistical summary of the models with the top-view projected area.

Model	Coefficients	Std. Error	t	Sig.	R^2_c	MAPEC (cm ²)	RMSEC (cm ²)	R^2_p	MAPEP (cm ²)	RMSEP (cm ²)	R^2_{cv}	MAPECV (%)	RMSECV (cm ²)
Model 10: $\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_1 + \text{TA})$	$a_0 = -7.084$ $a_1 = 1.109$	0.119 0.010	-59.380 108.494	0.000 0.000	0.989	7.93%	52.602	0.981	8.82%	62.348	0.982	8.41%	56.603
Model 11: $\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_1) + a_2 \times \ln(\text{TA})$	$a_0 = -6.176$ $a_1 = 0.780$ $a_2 = 0.310$	0.180 0.053 0.046	-34.255 14.770 6.707	0.000 0.000 0.000	0.989	7.65%	51.720	0.983	8.38%	63.879	0.983	8.00%	55.019
Model 12: $\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_2) + a_2 \times \ln(\text{TA})$	$a_0 = -6.783$ $a_1 = 0.963$ $a_2 = 0.160$	0.140 0.041 0.036	-48.476 23.467 4.483	0.000 0.000 0.000	0.995	5.53%	39.699	0.987	5.84%	49.054	0.989	5.74%	44.348
Model 13: $\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_4) + a_2 \times \ln(\text{TA})$	$a_0 = -6.815$ $a_1 = 0.972$ $a_2 = 0.152$	0.131 0.038 0.033	-51.899 25.294 4.576	0.000 0.000 0.000	0.995	5.24%	37.114	0.988	5.64%	50.072	0.990	5.51%	42.662
Model 14: $\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_6) + a_2 \times \ln(\text{TA})$	$a_0 = -6.837$ $a_1 = 0.988$ $a_2 = 0.135$	0.131 0.039 0.034	-52.357 25.596 4.028	0.000 0.000 0.000	0.995	5.10%	36.178	0.989	5.55%	49.069	0.991	5.37%	40.656
Model 15: $\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_{\text{ave}}) + a_2 \times \ln(\text{TA})$	$a_0 = -6.873$ $a_1 = 0.997$ $a_2 = 0.129$	0.134 0.040 0.034	-51.297 25.170 3.760	0.000 0.000 0.000	0.995	5.02%	35.944	0.989	5.49%	47.111	0.991	5.27%	40.660

6.11%. In addition, the use of Model 8 or Model 9 further reduced the MAPEP to 5.99% and 5.87%, respectively. The same trend was observed in the RMSE values. Model 6 had the highest RMSE value, and the RMSE value dropped as the number of side-view images increased. These results showed that the use of multi-angle images was efficient in reducing the estimation error, which was expected because the rice plants were not radially symmetrical with a straight axis of symmetry, resulting that a small number of views did not adequately represent the overall architecture of a plant. By comparison, Model 4 showed only a slight reduction in the MAPE and RMSE values relative to Model 8 and Model 9. Therefore, using more than four side-view images would give only marginal improvement.

3.3. Performance of the models with and without the top-view projected area

The use of a top-view image allowed for the correction of the leaf area estimation for the overlapping leaves in side-view images.¹⁵ Therefore, the value of the top-view image for leaf area estimation was tested in the models. The models were extended as follows:

$$\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_1 + \text{TA}), \quad (\text{Model 10})$$

$$\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_1) + a_2 \times \ln(\text{TA}), \quad (\text{Model 11})$$

$$\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_2) + a_2 \times \ln(\text{TA}), \quad (\text{Model 12})$$

$$\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_4) + a_2 \times \ln(\text{TA}), \quad (\text{Model 13})$$

$$\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_6) + a_2 \times \ln(\text{TA}), \quad (\text{Model 14})$$

$$\ln(\text{GLA}) = a_0 + a_1 \times \ln(\text{SA}_{\text{ave}}) + a_2 \times \ln(\text{TA}). \quad (\text{Model 15})$$

The parameters of the models and the error measures are listed in Table 3. The addition of the top-view image yielded better results than the use of the corresponding side-view images alone, which indicated that the top-view images was useful for correcting the estimates. In addition, Model 11

performed better than Model 10, which showed that adding TA as a separate predictor achieved greater improvement than incorporating it into the term (SA + TA). The MAPEP value decreased by 1.85% points, to 8.38%, when using Model 11 instead of Model 6, whereas the MAPEP value decreased only 0.32% points when using Model 15 instead of Model 4. These results indicated that the improvement diminished as the number of side-view images increased, and the comparison of RMSE values for these models also indicated that adding the top-view image did not significantly improve the performance of models, when using multi-side-view images.

4. Discussion

A nondestructive method for estimating the total GLA of individual rice plants was presented. Images of rice plants can be effectively acquired using the visible light imaging system, which was incorporated into the H-SMART system. For many plant species, total leaf area or biomass can be estimated simply based on the projected area in the image.^{14,15,18–21} In this paper, it is demonstrated that the GLA of individual rice plants also had a strong relationship with the plant area in the image, and the side-view projected area had a stronger relationship with the actual total leaf area than the TA.

Among the models mentioned above, the power models performed better than linear models, such as Model 1 and the IBL model (Model 5). Model 6, which used only one side-view image, had accuracy similar to that obtained by the IBL model, and the estimation error for Model 12, which also used three orthogonal images, was much less than that for the IBL model. As shown in Tables 1 and 2, the coefficients a_1 and a_2 in the quadratic model were positive, and the coefficient a_1 in each power model was greater than 1. It can be inferred that GLA might have been allometrically scaled in terms of the projected area in the image. This scaling occurs because, the leaf overlapping becomes more extensive as the plant grew larger, resulting in an increase in the proportion of occluded leaves in the side-view images.

For each rice plant, 12 side-view images and one top-view image were taken. By comparing the performance of the models using various numbers of side-view images, it was found that the accuracy of

the GLA estimation was increased as the number of side-view images increased. The reason was that rice plants lacked inherent asymmetry, resulting in varied projected area in different view angles. To get the overall representation of plant area, it was necessary to use many different view images. On the other hand, top-view image was useful for correcting the leaf occlusion. By comparing the performance of the models with and without the top-view projected area, it was found that estimation error decreased when TA was added. In addition, the improvement in accuracy was greater when adding TA as a separate independent variable instead of using the sum of SA and TA as the independent variables. This might be caused by the high correlation between TA and SA. However, the improvement provided by adding TA diminished as the number of side-view images increased. The reason was that the rice plants considered in the studies were erect growth forms and the leaves were tilted, thus multi-side-view images of the plant could correct the hidden leaf area and represent the total leaf area. In addition, the overhead camera distance should be long enough to avoid a difference in the pixel resolution between the top leaves and the bottom leaves; i.e., when the plants were excessively tall, it was difficult to configure the image acquisition system. Therefore, when attempting to estimate leaf area, the need to use a top-view image should be taken into consideration. And considering that the image acquisition and processing time increased according to the number of the images, the use of four or six side-view images should be sufficient to estimate the leaf area with high accuracy.

The power models proposed were able to estimate the GLA of individual rice plants with high R^2 and high precision. When using multi-angle color images, the R_p^2 exceeded 0.98, and the MAPEP value was about 6%. The sources of error were mainly attributed to extensive leaf overlapping, nonuniform leaf orientation and nonuniform leaf density. In addition, the inevitable leaf sway during the rotation of the plant may have resulted in undesired discrimination of leaves, which also introduced error into the leaf area estimation.

5. Conclusion

In summary, we presented a nondestructive method for estimating the total GLA of individual rice

plants. Models for estimating the total leaf area of rice plants were developed. Based on the projected area derived from multiple images, the power models were capable of estimating the total GLA in a nondestructive, accurate and efficient manner. This method allowed time-lapse measurements during the plant growth period and, thus, the growth curve of plants could be attained. Using this method, researchers are able to monitor plant growth and control growth conditions in a timely fashion. The models in this study were designed for two similar rice varieties. In the future, certain key parameters characterizing different rice phenotypes will be derived and incorporated in the model, and a model for various rice cultivars (e.g., rice germplasm resources) will be developed.

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