

Chapter 3.

(2) Depth-Bounded Search Trees

Zoom out for a moment to think about the big picture

- Previously: kernelization shrink input to its core (kernel) in polynomial time
- But how do we solve the resulting smaller problem instance?
- We know that the problem is computationally hard (i.e. NP-hard) and, so, at some point we have to do an exhaustive search (unless P=NP)
- Can we come up with strategies to design an exhaustive search that is as `efficient' as possible?
- One such technique is depth-bounded search.

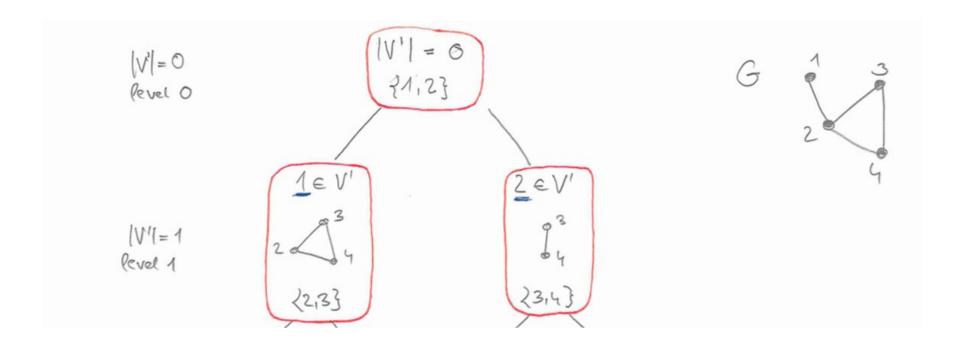
Idea of a bounded search

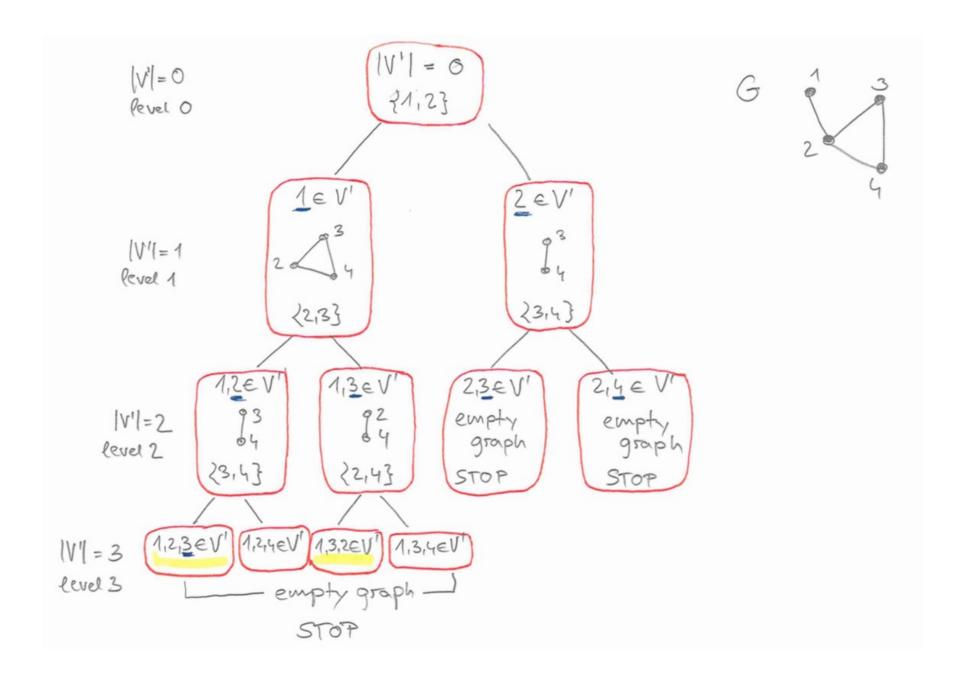
- Explores the search space to find an optimal solution. E.g. for VC, the search space consists of all $2^{|V(G)|}$ subsets of the vertices of a graph G. Each such subset may or may not be a feasible solution.
- How can we explore the huge search space systematically?
- Turns out that a search can be organized in a tree like fashion where each vertex in the tree corresponds to a possible solutions.
- We explore tricks to bound the size of this tree (e.g. bound the number of children each vertex of the tree can have).

Vertex Cover (VC)

Observations.

Let G=(V,E) be a graph, and let V' be a vertex cover of G. For each edge $\{u,v\}$ in E, either u or v (or both) is in V'.





Bounded-search tree for VC

- Tree lists all possible solutions. (*Is each possible solution considered exactly once?*)
- Level corresponds to the size of a (potential) vertex cover for G.
- If one is interested in deciding if (G=(V,E),k) is a yes-instance of VC, one can stop at level k.
- Level k of the search tree has 2^k vertices. Levels 0,1,...,k-1 have collectively 2^k-1 vertices.
- Size of the search tree is $O(2^k)$ (1).
- Hence, we can solve VC in time $O(2^k \mid E \mid)$ which is fpt! Time to remove edges from the graph at each step is $O(\mid E \mid)$.
- Ideally, combine kernelization and bounded-search tree: $O(2^k k^2 + |V|^2)$.
- (1) Has been improved to $O(1.28^k)$.

General idea of a bounded-search tree

Find, in polynomial time, a small constant-size subset *S* of the input such that at least one element in *S* is an element of an optimal solution.

What does this mean in the context of VC?

Let (G=(V,E),k) be an instance VC.

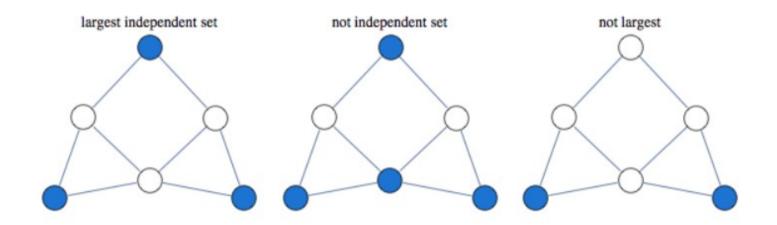
Let $S=\{u,v\}$ (i.e. a set of two vertices) such that $\{u,v\} \in E$. Then, by our earlier observation, we know that one of u and v is contained in **any** vertex cover of G.

Independent Set (IS) -- a maximization problem

Instance. A graph G=(V, E) and a non-negative integer k.

Question. Is there a subset I of V such that $|I| \ge k$ and no two vertices in I are adjacent to each other?

In other words, no two vertices in I are connected by an edge in E.



Independent Set (IS) vs. Vertex Cover (VC)

VC Instance. A graph G=(V, E) and a non-negative integer k.

VC Question. Is there a subset V' of V such that $|V'| \le k$ and for each edge $\{u,v\}$ in E, at least one of u and v is in V'?

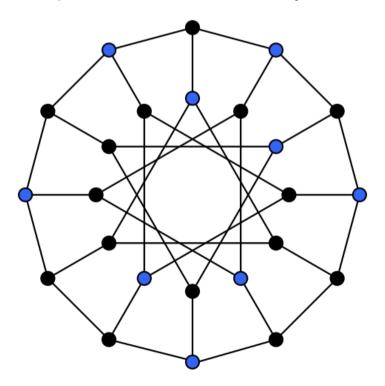
IS Instance. A graph G=(V, E) and a non-negative integer k.

IS Question. Is there a subset I of V such that $|I| \ge k$ and no two vertices in I are adjacent to each other?

A set I is an independent set of G if and only if $V \setminus I$ is a vertex cover of G.

Independent Set (IS) for general graphs

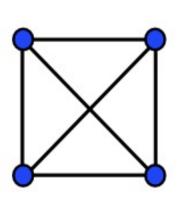
- NP-complete
- intractable from a parameterized point of view (W[1]-complete) with regards to parameter k (i.e. size of an independent set)

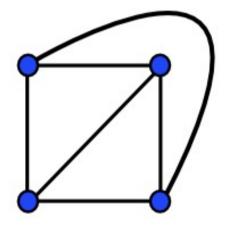


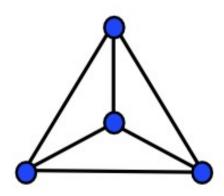
Independent Set (IS) for planar graphs

- NP-complete
- fixed-parameter tractable in *k*

Planar graphs can be drawn in the plane without crossing edges. It can be tested in O(n) if a graph G=(V,E) is planar, where n=|V|.







Results on planar graphs

Euler's formula. Let G=(V,E) be a planar graph. Then $|E| \le 3|V|-6$.

Consequence of Euler's formula. Every planar graph has a vertex of degree at most 5.

Proof. Let G=(V,E) be a planar graph and suppose that every vertex has degree at least 6 (proof by contradiction). Then, by the Handshaking Lemma (sum over all vertex degrees is equal to twice the number of edges) $2|E| \ge 6|V|$. Hence $|E| \ge 3|V|$. This gives a contradiction to Euler's formula.

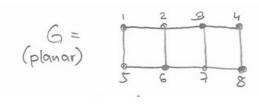
Bounded search for IS on planar graphs

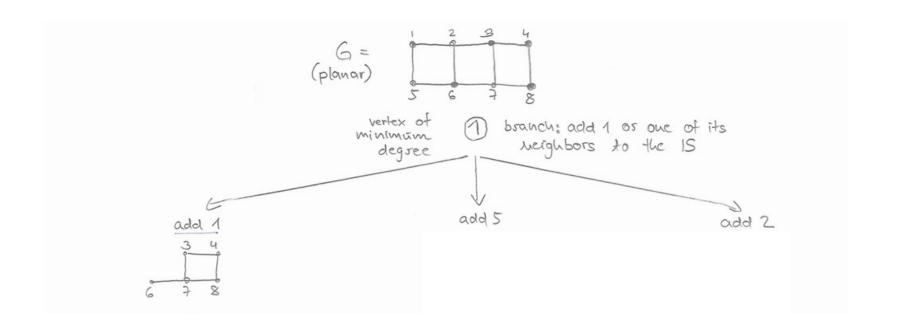
Idea.

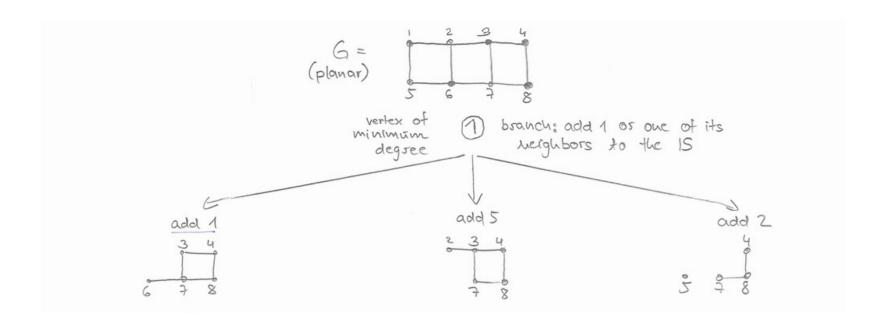
Consider an instance (G=(V,E),k) of IS, where G is planar.

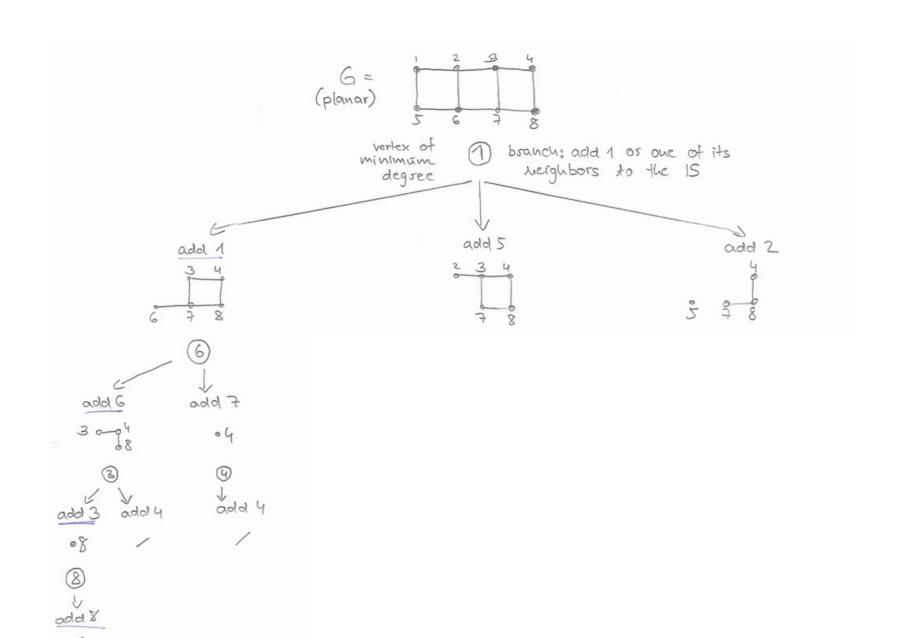
Select a vertex v in G of minimum degree. We know that v has degree at most 5. A **maximum independent set** for G contains either v or one of its 5 neighbors.

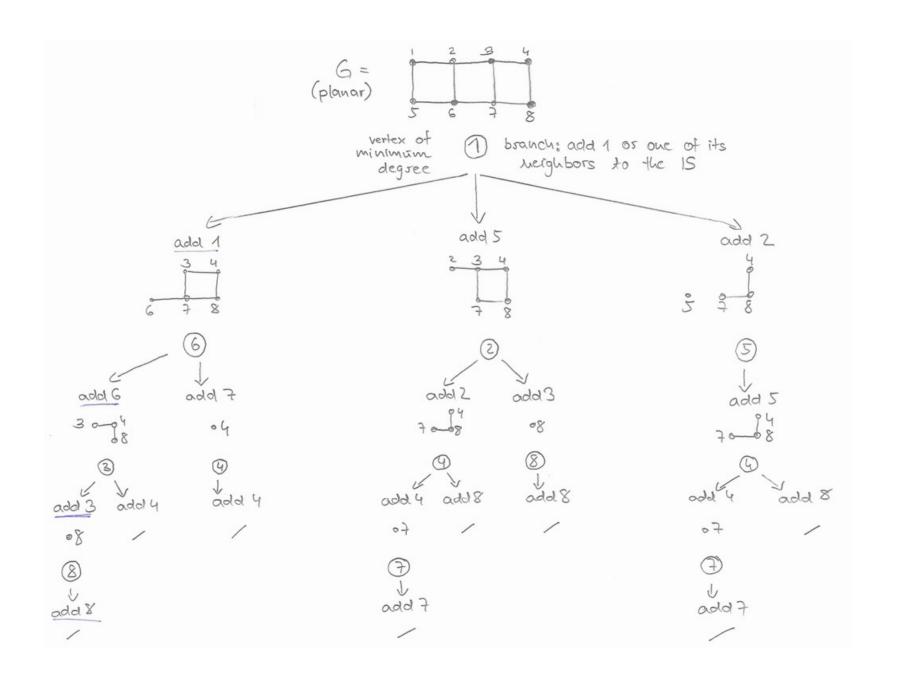
We branch into at most 5+1=6 cases. For each case, delete the corresponding vertex with all its adjacent vertices and edges to obtain a smaller graph G'. Recursively solve IS for (G',k-1).











Bounded search for IS on planar graphs

Theorem 7.

IS on planar graphs has a search tree of size at most $O(6^k)$. Moreover, for a planar graph G=(V,E), a maximum IS can be computed in time $O(6^k n)$, where n=|V|.

Correct as from $\{v\} \cup N(v)$ at least one vertex must be in a maximum independent set of G.

Instance. A set $\{s_1, s_2, ..., s_k\}$ of k strings each of length L and over an alphabet Σ ; and a non-negative integer d.

Question. Is there a closest string s such that $d_H(s,s_i) \le d$ for all $i \in \{1,2,...,k\}$?

What is $d_H(s,s_i)$?

Hamming distance between the two strings s and s_i .

Has applications in computational biology (e.g. comparison of DNA and protein sequences).

What is $d_H(s,s_i)$?

Hamming distance between the two strings s and s_i .

 $d_H(s,s_i)$ is equal to the number of positions 1,2,...,L that differ in s and s_i

s = 10010110

A = logarithm

s'= 11011011

B = algorithm

$$d_H(s,s')=4$$

$$d_H(A,B)=3$$

Example 6.

Consider the following four strings:

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s_1 = MAUS
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 $s_2 = HAUT$

 $s_3 = RAUS$

 $s_4 = HANS$

Does there exist a string s such that $d_H(s,s_i) \le 1$ for each $i \in \{1,2,3,4\}$?

Example 6.

Consider the following four strings:

 $s_1 = MAUS$

 $s_2 = HAUT$

 $s_3 = RAUS$

 $s_4 = HANS$

Does there exist a string s such that $d_H(s,s_i) \le 1$ for each $i \in \{1,2,3,4\}$?

s = HAUS

In what follows, we think of the strings $s_1, s_2, ..., s_k$ of length L as a character matrix with k rows and L columns.



Here, *k*=5 and *L*=12.

A column is called dirty if it has at least 2 different symbols from $\Sigma = \{A, C, G, T\}$.

Here, 5 dirty columns.

Lemma 8.

If a matrix has more than *kd* dirty column, then there is no solution to the associated instance of CS.

Proof. [Notation $i \in \{1, 2, ..., k\}$ and $j \in \{1, 2, ..., L\}$]

Fix a closest string s. For every dirty column j there exists a string s_i such that $s_i[j] \neq s[j]$. Since every string s_i differs from s on at most d positions (if it is a yes-instance), we can have at most kd dirty columns.

What if a matrix has at most kd dirty columns?

Consider an instance of $I=(\{s_1, s_2, ..., s_k\}, d)$ of CS.

Lemma 8 gives a simple reduction to a problem kernel: delete all non-dirty column. If there are more than *kd* columns left, then *I* is a no-instance. Otherwise, solve CS for the resulting matrix of size at most O(kd).

Kernelization depends on *d* and *k*.

No kernelization that only depends on *d* is known.

Next. Bounded-search tree whose size only depends on d.

Lemma 9.

If there exist $i,i' \in \{1,2,...,k\}$ such that $d_H(s_i,s_{i'}) > 2d$, then there is no solution to the associated instance of CS.

Proof.

The Hamming distance is a metric and satisfies the triangle inequality

$$d_H(x,y) \le d_H(x,z) + d_H(z,y)$$

for arbitrary strings x, y, and z. If $d_H(s_i, s_{i'}) > 2d$, then

$$d_{H}(s_{i},s)+d_{H}(s,s_{i'}) \geq d_{H}(s_{i},s_{i'}) > 2d$$

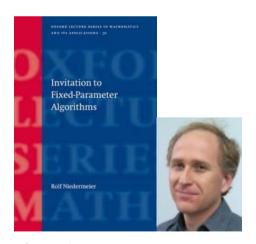
for a string s. It follows that $d_H(s_i,s) > d$ or $d_H(s_i,s) > d$.

Idea of algorithm. Suppose $I=(\{s_1, s_2, ..., s_k\}, d)$ of CS is a yes-instance.

Let \hat{s} be a **closest string** (i.e. a solution to a given instance of CS). Select one of the input strings, say s_1 , as **candidate string**. As long as there is a string s_i with i $\in \{2,3,...,k\}$ such that $d_H(s_1,s_i) \ge d+1$, then for at least one position p in which s_1 and s_i differ, we have $\hat{s}[p]=s_i[p]$. We can recursively try d+1 ways to move the candidate string closer to the closest string by setting $s_1[p]=s_i[p]$.

<u>CS-D.</u> Kernelize Check Lemma 8 Call *CSd(s₁,d)*

A recursive call decreases Δd by one



(Niedermeier, 2006, page 105)

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Recursive procedure CSd(s, \Delta d):
Global variables: Set of strings S = \{s_1, s_2, \dots, s_k\}, nonnegative integer d.
Input: Candidate string s and integer \Delta d.
Output: A string \hat{s} with \max_{i=1,...,k} d_H(\hat{s},s_i) \leq d and d_H(\hat{s},s) \leq \Delta d,
         if it exists, and "not found," otherwise.
Method:
(D0) if \Delta d < 0 then return "not found";
(D1) if d_H(s, s_i) > d + \Delta d for some i \in \{1, ..., k\} then return "not found";
(D2) if d_H(s, s_i) \leq d for all i = 1, ..., k then return s;
(D3) choose any i \in \{1, ..., k\} such that d_H(s, s_i) > d:
         P := \{ p \mid s[p] \neq s_i[p] \};
         choose any P' \subseteq P with |P'| = d + 1;
         for all p \in P' do
              s' := s;
              s'[p] := s_i[p];
              s_{ret} := CSd(s', \Delta d - 1);
              if s_{ret} \neq "not found" then return s_{ret};
(D4) return "not found"
Fig. 8.4. Algorithm CS-D. Inputs are a Closest String instance consisting
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of a set of strings $S = \{s_1, s_2, \dots, s_k\}$ of length L each, and a nonnegative integer d. The recursion is invoked with $CSd(s_1, d)$. Instead of s_1 , we could

choose an arbitrary element from S here.

Search tree size.

Consider the recursive part of the algorithm. Each call decreases Δd by one. The algorithm stops when $\Delta d < 0$. Hence, the height of the search tree is at most d.

In each recursive call, the algorithm explores d+1 subcases (branchings) for positions at which s and s_i disagree.

An upper bound on the size of the search tree is $O((d+1)^d)=O(d^d)$.

Correctness.

To establish correctness of CS-D, we need to show that the algorithm always finds a string \hat{s} such that $\max_{i=1,2,...,k} d_H(\hat{s},s_i) \le d$ if one exists.

We show correctness of the first recursive call (that is $CSd(s_1, d)$). Correctness for CS-D then follows by induction.

Correctness (cont.).

If $\max_{i=1,2,...,k} d_H(s_1,s_i) \le d$, then we already have a solution, namely s_1 . If s_1 is not a solution but there exists a closest string with distance at most d to all input strings, then there is a string s_i with $i \in \{2,3,...,k\}$ such that $d_H(s_1,s_i) > d$. [See 1st line of (D3)]

Now consider all positions 1,2,...,L where s_1 and s_i differ, i.e.

$$P = \{p \mid s_1[p] \neq s_i[p]\}.$$

By Lemma 9, we may assume that $d+1 \le |P| \le 2d$. [See 2nd line of (D3)]

Correctness (cont.).

The algorithm successfully creates d+1 branchings (choose d+1 elements in P). Each branching creates a new candidate string s' that can be obtained from s_1 by replacing $s_1[p]$ with $s_i[p]$. [See 6^{th} line of (D3)]

Question coming up: Why is this bringing us any closer to a solution?

Correctness (cont.).

Suppose that \hat{s} is a closest string. Hence $\max_{i=1,2,...,k} d_H(\hat{s},s_i) \leq d$. A change as described on the previous slide is correct if we choose a position p from $P \supset P_1 = \{p \mid s_1[p] \neq s_i[p] \text{ and } s_i[p] = \hat{s}[p]\}$. [Good guys!]

We next show that at least one of the d+1 branchings is correct.

Observe that $P=P_1 \cup P_2$, where $P_2=\{p \mid s_1[p] \neq s_i[p] \text{ and } s_i[p] \neq \hat{s}[p]\}$. [Bad guys!]

Since $d_H(\hat{s}, s_i) \le d$, we can conclude that $|P_2| \le d$. Hence, at least one of the d+1 branchings tries a position that is in P_1 .

Thus, d+1 branchings are sufficient to change s_1 into a new string s' that is "closer to \hat{s} ".

We now combine everything to get the following result.

Theorem 10.

CS can be solved in $O(kL d^d)$. Hence, CS is fixed-parameter tractable with parameter d.

kL size of matrix (without kernelization)

d^d size of bounded search tree

It is an open problem whether or not CS is fixed-parameter tractable when parameterized by k using a bounded-search tree approach.

Closest String (CS) – additional slide

Theorem.

There exists a closest string for $\{s_1, s_2, ..., s_k\}$ with distance at most d to each input string if and only if the algorithm returns string \hat{s} .

Proof.

Suppose \hat{s} exists. Then the previous correctness proof shows that the algorithm finds \hat{s} because at least one of the d+1 branchings brings us closer to \hat{s} in each iteration.

Suppose \hat{s} does not exist. Pick any string s. Then there exists a string s_i such that $d_H(s,s_i)>d$. But the algorithm stops after d iterations and correctly returns "not found".