Current and Pending Support (See GPG Section II.D.8 for guidance on information to include on this form.)

information may delay consideration of this proposal.	nvestigator and other senior personnel. Failure to provide this
Investigator: Marco Gruteser	Other agencies (including NSF) to which this proposal has been/will be submitted.
Support:	Submission Planned in Near Future
Project/Proposal Title: NeTS Medium: Visual MIMO N	Networks
Source of Support: NSF	Total Assard Davied Covered: 04/04/44 02/04/45
Total Award Amount: \$685,000 Location of Project: WINLAB, Rutgers University	Total Award Period Covered: 04/01/11-03/31/15
Person-Months Per Year Committed to the Project.	Cal: Acad: Sum: 1
Support:	Submission Planned in Near Future
Project/Proposal Title: Collaborative Research: SoCS Physical-World Tasks with My	S: Local Community Crowdsourcing of rmex
Source of Support: NSF Total Award Amount: \$530,134 Location of Project: WINLAB, Rutgers University	Total Award Period Covered: 09/01/12-08/31/15
Person-Months Per Year Committed to the Project.	Cal: Acad: Sum: 1
Support:	Submission Planned in Near Future
Source of Support: NSF Total Award Amount: \$318,636	Total Award Period Covered: 08/01/12-03/31/15
Location of Project: WINLAB, Rutgers University Person-Months Per Year Committed to the Project.	Cal: Acad: Sum: 0
	Submission Planned in Near Future
Project/Proposal Title: Development of the DSRC V2	V Scalability Simulator
Original Award = \$190,944 Suppl	ement 1 = \$190,944 Supplement 2 = \$55,000
Source of Support: Crash Avoidance Metrics Part Total Award Amount: \$436,888 Location of Project: WINLAB, Rutgers University	nership (CAMP) Total Award Period Covered: 01/14/13-01/31/2015
Person-Months Per Year Committed to the Project.	Cal: Acad: Sum: 0

Current and Pending Support (See GPG Section II.D.8 for guidance on information to include on this form.)

The following information should be provided for each invinformation may delay consideration of this proposal.	estigator and other senior personnel. Failure to provide this
Investigator: Marco Gruteser Oth	ner agencies (including NSF) to which this proposal has en/will be submitted.
Support:	omission Planned in Near Future
Project/Proposal Title: Exploring Smartphone-based Ve	hicle-Pedestrian Accident Risk Detection
Source of Support: Qualcomm Inc. Total Award Amount: \$50,000 Location of Project: WINLAB, Rutgers University	Total Award Period Covered: 04/01/13-03/31/15
Person-Months Per Year Committed to the Project.	Cal: Acad: Sum: 0
Support:	omission Planned in Near Future
Project/Proposal Title: CPS: Synergy: Collaborative Res	search: Harnessing the Automotive Infoverse
Source of Support: NSF Total Award Amount: \$455,575 Location of Project: WINLAB, Rutgers University	Total Award Period Covered: 10/01/13-09/30/17
Person-Months Per Year Committed to the Project.	Cal: Acad: Sum: 1
Support:	omission Planned in Near Future
Project/Proposal Title: Congestion Control Algorithms for	r Vehicular Networks
Original Award - \$25,000	Supplement - \$45,000
Source of Support: Toyota Info Technology	
Total Award Amount: \$70,000 Location of Project: WINLAB, Rutgers University	Total Award Period Covered: 03/01/14-10/01/16
Person-Months Per Year Committed to the Project.	Cal: Acad: Sum: 0
Support:	omission Planned in Near Future
	ardware Token-based Identification and Authentication d Devices with Capacitve Touch Communications (CTC)
Source of Support: Google Total Award Amount: \$14,887 Location of Project: WINLAB, Rutgers University	Total Award Period Covered: 02/25/14-02/28/16
Person-Months Per Year Committed to the Project.	Cal: Acad: Sum: 1

Current and Pending Support (See GPG Section II.D.8 for guidance on information to include on this form.)

The following information should be provided for eac information may delay consideration of this proposal.	h investigator and other senior personnel. Failure to provide this	
Investigator: Marco Gruteser	Other agencies (including NSF) to which this proposal has been/will be submitted.	
Support:	Submission Planned in Near Future	
Project/Proposal Title: CSR: Medium: Collaborative	Research: Guardian Angel—Enabling Mobile Safety Systems	
Source of Support: NSF Total Award Amount: \$350,000 Location of Project: WINLAB/Rutgers University	Total Award Period Covered: 10/01/14-09/30/17	
Person-Months Per Year Committed to the Project.	Cal: Acad: Sum: 1	
Support:	Submission Planned in Near Future	
Project/Proposal Title: Enhancements and Protoco	Revisions for the DSRC Simulator	
Source of Support: Crash Avoidance Metrics Pa Total Award Amount: \$261,157 Location of Project: WINLAB/Rutgers University	rtnership (CAMP) Total Award Period Covered: 02/01/15-01/31/16	
Person-Months Per Year Committed to the Project.	Cal: Acad: Sum: 1	
Support:	Submission Planned in Near Future	
Source of Support: NSF Total Award Amount: \$500,000 Location of Project: WINLAB, Rutgers University	Total Award Period Covered: 09/01/15-08/31/18	
Person-Months Per Year Committed to the Project.	Cal: Acad: Sum: 0.17	
Support:		
Source of Support: Total Award Amount:	Total Award Period Covered:	
Location of Project: Person-Months Per Year Committed to the Project.	Cal: Acad: Sum:	