# **Muhammad Sohaib Ashraf**

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Portfolio <u>suhaibashraf.github.io/Portfolio</u>

### **EXPERIENCE**

### Software Engineer – Oneberry

12/19 - 05/20

Developed industrial level autonomous mobile robots and worked on Albased features using SLAM and images from the camera while working with robotics R&D team.

### Web Developer - Epullon

02/17 - 10/17

Worked as a back-end web developer and completed multiple web applications that went into production. Led a team of software developers.

### **PROJECTS**

KenOB 03/20 – 05/20

Upgraded a robot of Oneberry Technologies. Converted it from 2d Sick Lidar to depth camera. It improved the performance of the robots while reduced the production cost significantly.

#### Sidewalk Robot

01/20 - 02/20

While working at Oneberry Technologies, I have developed an autonomous robot that can move on the sidewalk by applying Semantic Segmentation on an image from the camera.

#### Evolutionary Flocking Shooter

03/19 - 04/19

Developed a robotics simulation with Genetic algorithm in my Master's project. Which enabled bots to learn how to locate the target, avoid danger zone and it after finding its origin. I used Unity3d Engine and Genetic Algorithm. I got 92% marks in this module.

**Demo Link:** www.youtube.com/watch?v=A9k6WBoY548

# **EDUCATION**

# MSc Artificial Intelligence & Robotics 01/18 – 05/19

University of Hertfordshire (Distinction – 81%)

#### Modules:

- Theory and Practice of Artificial Intelligence and Robotics
- Artificial Life with Robotics
- Machine Learning and Neural Networks
- Investigative Methods in Computer Science

### **BS Software Engineering**

02/13 - 05/17

University of Management and Technology

#### Modules:

- Information Retrieval
- Object Oriented Programming
- Assembly Language
- Digital logic design
- Computer Vision
- Computer Graphics

# **PROFILE**

Autonomous robotics developer, worked as a Software engineer (Robotics) at Oneberry Technologies, Singapore. Graduated in MSc Artificial Intelligence and Robotics with a degree in Software Engineering. Ambitious to seek a career robotics software development. Experienced in developing scripts using ROS, Isaac SDK, Python, C++, Image SLAM, segmentation, Artificial Intelligence, Neural network and Machine learning algorithm.

## **SKILLS**

### Coding

- Robotics
- ROS/IsaacPython

• TenserRT

• Unity3d

PCI

- Machine Learning
- Genetic Algorithm C++
- Artificial Intelligence C#
- Computer Vision
- Computer vision
- Neural Network
- Game Development
- Image Segmentation PHP

#### Other

- Teamwork
- Problem-solving
- Meeting deadlines
- Creative thinking

# **INTERESTS**

- Badminton, Cricket and video games
- Travelling and learning new languages
- Learning about the latest research and technologies