$$O_2^{\dagger} = \begin{bmatrix} \cos O_2 & O & \sin O_2 \\ O & I & O \\ -\sin O_2 & O & \cos O_2 \end{bmatrix}$$

$$O_{1}^{T}a = \begin{bmatrix} coso_{1} & sino_{1} & 0 \\ -sino_{1} & coso_{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}$$

$$n = \sqrt{1+2^2} = \sqrt{5}$$

$$SinO, +2COO, = 1$$

$$SinO, = 2$$

$$SinO, = 2$$

$$O_{2}^{T}O_{1}^{T}a = \begin{bmatrix} Goso_{2} & O & Sino_{2} \\ O & I & O \\ -Sino_{2} & O & Goso_{2} \end{bmatrix} \begin{bmatrix} Gs \\ O \end{bmatrix} = \begin{bmatrix} Gs \\ O \end{bmatrix}$$

$$y = \sqrt{5+4} = 3$$

$$\begin{array}{rcl}
\sin \alpha_2 &=& \frac{2}{3} \\
\cos \alpha_2 &=& \sqrt{5} \\
\hline
3
\end{array}$$

$$Sino_2 = \frac{2}{3}$$
 $Coro_2 = \frac{7}{3}$
 $O_1^T = \begin{bmatrix} -15 & 255 & 0 \\ -255 & 0 \\ 0 & 0 \end{bmatrix}$

$$O_{1}^{T} = \begin{bmatrix} \sqrt{5} & 0 & \frac{2}{3} \\ 0 & 1 & 0 \\ -\frac{2}{3} & 0 & \sqrt{5} \end{bmatrix}$$

$$O_{2}^{T}O_{1}^{T}a = \begin{bmatrix} 3\\ 0\\ 0 \end{bmatrix}$$

$$0 = 0_{2}^{T} 0_{1}^{T} = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{2}{3} \end{bmatrix}$$

$$\frac{2}{3}$$



$$L = L_{31} L_{21} = \begin{cases} R_{2} - 2R_{1} \\ R_{3} - 2R_{1} \end{cases}$$

$$a = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$$

$$a = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$$
 $l_{2i} = l_{3i} = 2 = \frac{a_2}{a_1} = \frac{a_3}{a_1}$

$$L_{21} = \{R_2 - 2R_1\}$$

$$\begin{bmatrix}
1 & 0 & 0 \\
-2 & 1 & 0 \\
0 & 0 & 1
\end{bmatrix}$$

$$L_{21} = \left\{ R_3 - 2R_1 \right\}$$

$$L = L_{31}L_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix}$$