

PoPL-08

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Imperative Languages

Language + Assignment

Programs Are Functions

Interactive

Dynamically Typed

Recursive

Language with Contexts

Block Structured
Language
Applicative Language

Summary

CS40032: Principles of Programming Languages Module 08: Denotational Semantics of Imperative Languages

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Source: Denotational Semantics by David A. Schmidt, 1997

March 15, 17, 22, & 24: 2021



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 Most sequential programming languages use a Data Structure that exists independently of any program in the language

- The data structure is not explicitly mentioned in the language's syntax, but it is possible to build phrases that access it and update it
- This data structure is called the *Store*, and languages that utilize stores are called *Imperative*
- Fundamental Store's are:
 - Primary memory
 - File stores, and
 - Databases

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Imperative Languages: Stores

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• The Store and a Program share an intimate relationship:

- The store is critical to the evaluation of a *Phrase* in a program
- A phrase is understood in terms of
 - how it handles the store, and
 - the absence of a proper store makes the phrase non-executable
- The store serves as a means of communication between the different phrases in the program
 - Values computed by one phrase are deposited in the store so that another phrase may use them
 - The language's sequencing mechanism establishes the order of communication
- The store is an inherently large argument
- Only one copy of store exists at any point during the evaluation
- We use lifted domains to model the Store



Example Language with Assignment: Command

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Language with Contexts Block Structured Language Applicative Languag A declaration-free Pascal subset

A program in the language is a sequence of commands

• Stores belong to the domain *Store* and serve as arguments to the valuation function:

 $C: Command \rightarrow Store_{\perp} \rightarrow Store_{\perp}$

 The purpose of a command is to produce a new store from its store argument

 A command might not terminate its actions upon the store – it can loop

• The looping of a command [[C]] with store s has semantics $C[[C]]s = \bot$

Store is lifted to Store⊥

Command Composition is:

$$C[[C_1; C_2]] = C[[C_2]] \circ C[[C_1]]$$
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Example Language with Assignment: Abstract Syntax

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Abstract Syntax:

Consider the entities as:

 $P \in Program$

 $C \in Command$

 $E \in Expression$

 $B \in Boolean_expr$

 $I \in Identifier$

 $N \in Numeral$

P ::= C.

 $C ::= C_1$; $C_2 \mid \text{if } B \text{ then } C \mid \text{if } B \text{ then } C_1 \text{ else } C_2 \mid$

 $I := E \mid \text{diverge}$

 $E ::= E_1 + E_2 | I | N$

 $B ::= E_1 = E_2 \mid \neg B$

diverge is a non-terminating command

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Example Language with Assignment: Semantic Algebras

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Semantic Algebras:

Truth values

Domain: $t \in Tr = B$

Operations:

true, false: Tr

 $not: Tr \rightarrow Tr$

Identifiers

Domain: $i \in Id = Identifier$

Natural Numbers

Domain: $n \in Nat = \mathcal{N}$

Operations:

zero, one, ... : Nat

 $\textit{plus}: \textit{Nat} \times \textit{Nat} \rightarrow \textit{Nat}$

equals : $Nat \times Nat \rightarrow Tr$



Example Language with Assignment: Semantic Algebras

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Store

Domain: $s \in Store = Id \rightarrow Nat$

Operations:

newstore : Store

 $newstore = \lambda i.zero$

 $access: Id \rightarrow Store \rightarrow Nat$

 $access = \lambda i.\lambda s.s(i)$

update : $Id \rightarrow Nat \rightarrow Store \rightarrow Store$

 $update = \lambda i.\lambda n.\lambda s.[i \mapsto n]s$



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Valuation Functions:

P: Program → Nat → Nat_⊥
 P[[P]] = P[[C.]] =?
 where the input number n is associated with identifier
 [[A]] in a new store. As the program body is evaluated, and the answer is extracted from the store at [[Z]]

• C: $Command \rightarrow Store_{\perp} \rightarrow Store_{\perp}$ $C[[C_1; C_2]] = ?$ $C[[if \ B \ then \ C]] = ?$ $C[[if \ B \ then \ C_1 \ else \ C_2]] = ?$ C[[I := E]] = ?C[[diverge]] = ?



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- The clauses of the C function are all strict in their use of the store
- Command composition works as discussed earlier
- The conditional commands are choice functions
- The expression $(e_1 \rightarrow e_2 \ [] \ e_3)$ is non-strict in arguments e_2 and e_3 the value of C[[if B then C]]s is s when B[[B]]s is false, even if C[[C]] $s = \bot$
- The assignment statement performs the expected *update*
- The [[diverge]] command causes non-termination



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• E : Expression \rightarrow Store \rightarrow Nat $E[[E_1 + E_2]] = ?$ E[[/]] = ?E[[N]] = ?

• B : Boolean_expr \rightarrow Store \rightarrow Tr $B[[E_1 = E_2]] = ?$ $B[[\neg B]] = ?$

• N : Numeral \rightarrow Nat (maps numeral $\mathcal N$ to corresponding $n \in Nat$



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- The E function also needs a store argument, but the store is used in a read only mode
- E's functionality shows that an expression produces a number, not a new version of store; the store is not updated by an expression
- The equation for addition is stated so that the order of evaluation of $[[E_1]]$ and $[[E_2]]$ is not important to the final answer. Indeed, the two expressions might even be evaluated in parallel
- A strictness check of the store is not needed, because C has already verified that the store is proper prior to passing it to E



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Valuation Functions:

• P: $Program \rightarrow Nat \rightarrow Nat_{\perp}$ $P[[C.]] = \lambda n.let \ s = (update \ [[A]] \ n \ newstore) \ in$ $let \ s' = C[[C]]s \ in \ (access \ [[Z]] \ s')$ where the input number n is associated with identifier [[A]] in a new store. As the program body is evaluated, and the answer is extracted from the store at [[Z]]

```
• C: Command \rightarrow Store_{\perp} \rightarrow Store_{\perp}

C[[C_1; C_2]] = \underline{\lambda}s.C[[C_2]](C[[C_1]]s)

C[[if \ B \ then \ C]] = \underline{\lambda}s.B[[B]]s \rightarrow C[[C]]s \ [] \ s

C[[if \ B \ then \ C_1 \ else \ C_2]] =

\underline{\lambda}s.B[[B]]s \rightarrow C[[C_1]]s \ [] \ C[[C_2]]s

C[[I := E]] = \underline{\lambda}s.update[[I]] \ (E[[E]]s) \ s

C[[diverge]] = \lambda s.\bot
```



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• E : Expression \rightarrow Store \rightarrow Nat E[[E₁ + E₂]] = λ s.E[[E₁]]s plus E[[E₂]]s E[[I]] = λ s.access [[I]] s E[[N]] = λ s.N[[N]]

• B : $Boolean_expr \rightarrow Store \rightarrow Tr$ $B[[E_1 = E_2]] = \lambda s. E[[E_1]] s equals E[[E_2]] s$ $B[[\neg B]] = \lambda s. not(B[[B]]s)$

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• N : Numeral \rightarrow Nat (omitted)



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Summary

• P[[Z := 1; if A = 0 then diverge; Z := 3.]](two)



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```
• P[[Z:=1; if A=0 \text{ then diverge}; Z:=3.]](two)
= let s = (update [[A]] two newstore) in
let s' = C[[Z:=1; if A=0 \text{ then diverge}; Z:=3]]s
in (access [[Z]] s')
```

```
let s' = C[[Z := 1; if A = 0 \text{ then diverge}; Z := 3]]([ [[A]] \mapsto two] \text{ newstore}) in access [[Z]] s'
```



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```
• P[[Z := 1; if A = 0 \text{ then diverge}; Z := 3.]](two)
= let s = (update [[A]] two newstore) in
let s' = C[[Z := 1; if A = 0 \text{ then diverge}; Z := 3]]s
in (access [[Z]] s')
```

let $s' = C[[Z:=1; \text{if } A=0 \text{ then diverge; } Z:=3]]([\ [[A]] \mapsto two] \ newstore)$ in access [[Z]] s'

• C[[Z := 1; if A = 0 then diverge; Z := 3]] s_1 , $s_1 = [$ [[A]] \mapsto two] newstore $= (\underline{\lambda}s.C[[$ if A = 0 then diverge; Z := 3]](C[[Z := 1]]s)) s_1 C[[if A = 0 then diverge; Z := 3]]($C[[Z := 1]]s_1$)

```
\begin{split} & \text{C}[[Z:=1]] s_1 \\ &= (\underline{\lambda} s. update \ [[Z]] \ (E[[1]] s) \ s) s_1 \\ &= update \ [[Z]] \ (E[[1]] s_1) s_1 \\ &= update \ [[Z]] \ (N[[1]]) s_1 \\ &= update \ [[Z]] \ one \ s_1 \\ &= [\ [[Z]] \mapsto one][\ [[A]] \mapsto two] \ newstore = s_2 \end{split}
```

C[[if A=0 then diverge; Z:=3]] s_2 = $(\underline{\lambda}s.C[[Z:=3]]((\underline{\lambda}s.B[[A=0]]s \rightarrow C[[diverge]]s [] s)s))s_2$ = $C[[Z:=3]]((\underline{\lambda}s.B[[A=0]]s \rightarrow C[[diverge]]s [] s)s_2$ = $C[[Z:=3]](B[[A=0]]s_2 \rightarrow C[[diverge]]s_2 [] s_2)$



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```
• B[[A = 0]]s_2

= (\lambda s. E[[A]]s equals E[[0]]s)s_2

= E[[A]]s_2 equals E[[0]]s_2

= (access [[A]] s_2) equals zero

access [[A]] s_2

= s_2[[A]]

= ([[Z]] \mapsto one][[A]] \mapsto two] newstore)[[A]]

= ([[A]] \mapsto two] newstore)[[A]] (why?)

= two
```



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```
• B[[A = 0]]s_2
    = (\lambda s. \mathsf{E}[[A]]s \text{ equals } \mathsf{E}[[0]]s)s_2
    = E[[A]]s_2 equals E[[0]]s_2
```

= (access [[A]] s_2) equals zero

```
access [[A]] s<sub>2</sub>
= s_2[[A]]
= ([[Z]] \mapsto one][[A]] \mapsto two] newstore)[[A]]
= ([[A]] \mapsto two] newstore)[[A]] (why?)
= two
```

• Thus, $B[[A = 0]]s_2 = false$, implying that $C[[if A = 0 \text{ then diverge}]]s_2 = s_2$. Now.

```
C[[Z := 3]]s_2
= [[Z]] \mapsto three]s_2
```

$$\textit{let } s' = [\; [[Z]] \mapsto \textit{three}] s_2 \textit{ in access } [[Z]] s'$$

$$= \textit{access} \ [[Z]][\ [[Z]] \mapsto \textit{three}] s_2$$

$$= ([[Z]] \mapsto three]s_2)[[Z]]$$



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Language + Assignment

• P[[Z := 1; if A = 0 then diverge; Z := 3.]](zero)= let s' = C[[Z := 1]] if A = 0 then diverge; $Z := 3][s_3]$ in access [[Z]] s'where $s_3 = [[A]] \mapsto zero]$ newstore

• $C[[Z := 1; \text{ if } A = 0 \text{ then diverge}; Z := 3]]s_3$ $= C[[if A = 0 then diverge; Z := 3]]s_4$ where $s_4 = [[Z]] \mapsto one]s_3$

 $= true \rightarrow C[[diverge]]s_4 [] s_4$ $= C[[diverge]]s_4$ $=(\lambda s.\bot)s_4$ = 1

• P = let $s' = \bot$ in access [[Z]] s'= 1



Example Language with Assignment: Equivalence of Stores

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Summary

Prove that:

$$C[[X := 0; Y := X + 1]]s = C[[Y := 1; X := 0]]s$$

That is, these programs are equivalent.



Example Language with Assignment

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Prove that:

$$C[[X := 0; Y := X + 1]]s = C[[Y := 1; X := 0]]s$$

That is, these programs are equivalent.

•
$$C[[X := 0; Y := X + 1]]s$$

= $C[[Y := X + 1]](C[[X := 0]]s)$
= $C[[Y := X + 1]]([[X]] \mapsto zero]s)$
= $update[[Y]]$ ($E[[X + 1]]$ ([$[[X]] \mapsto zero]s$))([$[[X]] \mapsto zero]s$)
= $update[[Y]]$ one [$[[X]] \mapsto zero]s$
= $[[Y]] \mapsto one$] [$[[X]] \mapsto zero]s = s_1$

•
$$C[[Y := 1; X := 0]]s$$

= $C[[X := 0]] (C[[Y := 1]]s)$
= $C[[X := 0]] ([[Y]] \mapsto one]s)$
= $[[[X]] \mapsto zero] [[[Y]] \mapsto one]s = s_2$

• Are they the s_1 and s_2 the same store?



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Language with Contexts Block Structured Language Applicative Languag • Are they the $s_1 = [[[Y]] \mapsto one] [[[X]] \mapsto zero]s$ and $s_2 = [[[X]] \mapsto zero] [[[Y]] \mapsto one]s$ the same store?

```
• The argument is [[X]]: then s_1[[X]] = ([[[Y]] \mapsto one][[[X]] \mapsto zero]s)[[X]] = ([[[X]] \mapsto zero]s)[[X]] = zero; and s_2[[X]] = ([[[X]] \mapsto zero][[[Y]] \mapsto one]s)[[X]] = zero
```

• The argument is [[Y]]: then $s_1[[Y]] = ([[[Y]] \mapsto one][[[X]] \mapsto zero]s)[[Y]] = one$; and $s_2[[Y]] = ([[[X]] \mapsto zero][[[Y]] \mapsto one]s)[[Y]] = ([[[Y]] \mapsto one]s)[[Y]] = one$

• The argument is some identifier [[I]] other than [[X]] or [[Y]]: then $s_1[[I]] = s[[I]] = s[[I]]$.



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Summary

Consider again the example:

$$[[Z:=1; if A=0 then diverge; Z:=3]]$$

What is its meaning?

- It is a function: $Nat \rightarrow Nat_{\perp}$
- Its meaning is:

 $\lambda \textit{n.n}$ equals zero $\rightarrow \bot$ [] three

Prove.



Programs Are Functions

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Programs Are Functions

Consider again the example:

$$[[Z := 1; if A = 0 then diverge; Z := 3]]$$

What is its meaning? It is a function: $Nat \rightarrow Nat_{\perp}$

- P[[Z := 1; if A = 0 then diverge; Z := 3.]] $=\lambda n$. let s=update[A] n newstore in let s' = C[[Z := 1]] if A = 0 then diverge; Z := 3]]sin access[[Z]] s'
 - $=\lambda n.let\ s=update\ [[A]]\ n\ newstore\ in$ let $s' = (\lambda s.(\lambda s.C[[Z := 3]](C[[if A = 0 then diverge]]s))s)(C[[Z := 1]]s)$ in access [[Z]] s'
 - $=\lambda n.let\ s=update\ [[A]]\ n\ newstore\ in$ let $s' = (\lambda s.(\lambda s.update [[Z]] three s)$ $((\lambda s.(access [A])s) equals zero \rightarrow (\lambda s.\bot)s[s)s))$ $((\lambda s.update [[Z]] one s)s)$ in access [[Z]]s'which can be restated as:

 $\lambda n.let \ s = update \ [[A]] \ n \ newstore \ in$ let $s' = (lets'_1 = update [[Z]])$ one s in let $s_2' = (access [A] s_1')$ equals $zero \rightarrow (\lambda s. \bot) s'1 [s_1']$ in update [[Z]] three s_2' in access [[Z]]s'



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Programs Are Functions

```
• \lambda n.let s' = (let s'_1 = update[[Z]] one s_0 in
        let s_2' = (access [A] s_1') equals zero \rightarrow (\underline{\lambda}s.\bot)s_1' [] s'1
        in update [[Z]] three s_2')
      in access [[Z]] s'
```

```
(access [[A]] s_1) equals zero \rightarrow \bot [] s_1
= n \text{ equals zero} \rightarrow \bot [] s_1
```

The conditional can be simplified no further. We can make use of the following property:

```
"for e_2 \in Store_\perp such that e_2 \neq \perp.
let s = (e_1 \rightarrow \bot [] e_2) in e_3 equals e_1 \rightarrow \bot [] [e_2/s] e_3"
let s_2' = (n \text{ equals zero } \rightarrow \bot [] s_1) \text{ in update } [[Z]] \text{ three } s_2'
= n equals zero \rightarrow \bot [] update [[Z]] three s_1
```

 $\lambda n.let \ s' = (n \ equals \ zero \rightarrow \bot \ [] \ update \ [[Z]] \ three \ s_1) \ in \ access \ [[Z]]s'$

 $\lambda n.n \text{ equals zero } \rightarrow \bot \text{ [] access}[[Z]] \text{ (update } [[Z]] \text{ three } s_1\text{)}$

 $\lambda n.n$ equals zero $\rightarrow \bot$ [] three



Interactive File Editor

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Language with Contexts Block Structured Language Applicative Langua • The language is an interactive file editor

- A file is a list of records, where the domain of records is taken as primitive
- The file editor makes use of two levels of store
 - the primary store is a component holding the file being edited upon by the user (has a current record marker), and
 - \bullet the secondary store is a system of text files indexed by their names
- The edit process:
 - Load a file (identified by name) from secondary store to primary store. This initializes the current record to the first record of the file

This is skipped for new files

 Edit the file in the primary store (forward / remind – move current record marker forward or reverse, insert / delete record)

Alternately, the editor may Create a new file and start editing

• Save the file from primary store to secondary store



Interactive File Editor: Abstract Syntax

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Abstract Syntax:

Consider the entities as:

 $P \in Program_session$

 $S \in Command_sequence$

C ∈ *Command*

 $R \in Record$

 $B \in Boolean_expr$

 $I \in Identifier$

 $P ::= \operatorname{edit} I \operatorname{cr} S$

 $S ::= C \operatorname{cr} S \mid \operatorname{quit}$

 $C ::= newfile \mid moveforward \mid moveback \mid insert R \mid delete$



An Interactive File Editor: Openfile Representation

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Language with Contexts Block Structured

Block Structured Language Applicative Language The edited files are values from the Openfile domain

• An opened file r_1 , r_2 , \cdots , r_{last} is represented by two lists of text records; the lists break the file open in the middle:

$$r_{i-1}...r_2r_1$$
 $r_ir_{i+1}...r_{last}$

where r_i is the *current* record of the opened file

Note how the first list is written in the reverse order



An Interactive File Editor: newfile & copyin

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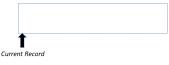
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Summai

• newfile represents a file with no records



newfile : Openfile newfile = (nil, nil)

• copyin takes a file from the file system and organizes it as:



 $\underline{r_1 r_2 ... r_{last}}$

where r_1 is the *current* record of the opened file $copyin : File \rightarrow Openfile$ $copyin = \lambda f.(nil, f)$



An Interactive File Editor: forward

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 The forwards operation makes the record following the current record the new current record. Pictorially, for:

$$r_1 r_2 \dots r_{i-1} r_i r_{i+1} \dots r_{last-1} r_{last}$$

$$Current Record$$

$$r_{i-1} \dots r_2 r_1 \qquad r_i r_{i+1} \dots r_{last}$$

a forwards move produces:

$$r_i r_{i-1} \dots r_2 r_1$$
 $r_{i+1} \dots r_{last}$

forwards : Openfile \rightarrow Openfile forwards = λ (front, back).null back \rightarrow (front, back) [] ((hd back) cons front, (tl back))



An Interactive File Editor: backward

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Summary

 The backwards operation makes the record preceding the current record the new current record. Pictorially, for:

a backward move produces:

$$r_1 r_2 \dots r_{i-1} r_i r_{i+1} \dots r_{last-1} r_{last}$$
 $backward$
 $Current Record$
 $r_i r_{i-1} \dots r_2 r_1 r_{i+1} \dots r_{last}$

$$backwards: Openfile \rightarrow Openfile \\ backwards = \lambda(front, back).null \ front \rightarrow (front, back) \\ [] \ (tl \ front, (hd \ front) \ cons \ back)$$



An Interactive File Editor: insert R

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• insert places a record R after the current record. Pictorially, for:

$$\underline{r_{i-1}...r_2r_1}$$
 $\underline{r_ir_{i+1}...r_{last}}$

an insertion of record R produces:

$$\underline{r_i...r_2r_1}$$
 R $r_{i+1}...r_{last}$

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The newly inserted record becomes current

insert : Record × Openfile
$$\rightarrow$$
 Openfile insert = $\lambda(r, (front, back))$.null back \rightarrow (front, r cons back) [] ((hd back) cons front), r cons (tl back))



An Interactive File Editor: delete

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Interactive File Editor

• delete removes the current record. Pictorially, for:

$$r_{i-1}...r_2r_1$$
 $r_ir_{i+1}...r_{last}$

deletion produces:

The record following the deleted record becomes current

$$delete: Openfile
ightarrow Openfile \ delete = \lambda(front, back).(front, (null back
ightarrow back [] tl back))$$



An Interactive File Editor: Test Operations

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The final three operations test whether

the first record in the file is current (at_first_record),

 $at_first_record : Openfile \rightarrow Tr$

 $at_first_record = \lambda(front, back).null front$

• the last record in the file is current (at_last_record), or if

 $at_last_record : Openfile \rightarrow Tr$ $at_last_record = \lambda(front, back).null\ back \rightarrow true$ $[]\ (null\ (tl\ back) \rightarrow true\ []\ false)$

• the file is empty (isempty)



isempty : Openfile \rightarrow Tr isempty = λ (front, back).(null front) and (null back)



An Interactive File Editor: copyout

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• An open file $r_1, r_2, \dots, r_{last}$ in the *Openfile* domain:

$$\underline{r_{i-1}...r_2r_1}$$
 $\underline{r_ir_{i+1}...r_{last}}$

needs to be written back to File System. *copyout* is the operation for it which should convert it to:

$$r_1 r_2 \dots r_{last}$$

and then write back:

```
copyout : Openfile \rightarrow File copyout = \lambda p. "appends fst(p) to snd(p) – defined later" // Recursive copyout = \lambda(front, back).null\ front \rightarrow back [] copyout((tl front), ((hd front) cons back))
```



Interactive File Editor: Semantic Algebra

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Block Structured Language Applicative Language Truth Values

Domain: $t \in Tr$ Operations:

true, false: $Tr = \mathcal{B}$

and : $Tr \times Tr \rightarrow Tr$

Identifiers

Domain: $i \in Id = Identifier$

Text records

Domain: $r \in Record$

Text file

Domain: $f \in File = Record^*$

File System

Domain: $s \in File_system = Id \rightarrow File$

Operations:

 $access: Id \times File_system \rightarrow File$

 $access = \lambda(i, s).s(i)$

 $update: Id \times File \times File_system \rightarrow File_system$

 $update = \lambda(i, f, s).[i \mapsto f]s$

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```
Open file
   Domain: p \in Openfile = Record^* \times Record^*
   Operations:
    newfile: Openfile
     newfile = (nil, nil)
    copyin : File \rightarrow Openfile
     copyin = \lambda f.(nil, f)
    copyout: Openfile \rightarrow File
     copyout = \lambda p. "appends fst(p) to snd(p) – defined later" // Recursive
     copyout = \lambda(front, back).null\ front \rightarrow back
       copyout((tl front), ((hd front) cons back))
    forwards : Openfile \rightarrow Openfile
     forwards = \lambda(front, back).null\ back \rightarrow (front, back)
       [] ((hd back) cons front, (tl back))
    backwards: Openfile \rightarrow Openfile
     backwards = \lambda(front, back).null\ front \rightarrow (front, back)
       [] (tl front, (hd front) cons back)
    insert : Record \times Openfile \rightarrow Openfile
     insert = \lambda(r, (front, back)).null\ back \rightarrow (front, r\ cons\ back)
       [] ((hd back) cons front), r cons (tl back))
    delete: Openfile \rightarrow Openfile
     delete = \lambda(front, back).(front, (null back \rightarrow back [] tl back))
```



Interactive File Editor: Semantic Algebra

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Block Structured Language Applicative Language Open file (Contd.)Operations:

 $\textit{at_first_record}: \textit{Openfile} \rightarrow \textit{Tr}$

 $at_first_record = \lambda(front, back).null\ front$

 $\textit{at_last_record}: \textit{Openfile} \rightarrow \textit{Tr}$

 $\textit{at_last_record} = \lambda(\textit{front}, \textit{back}).\textit{null back} \rightarrow \textit{true}$

[] $(null\ (tl\ back) \rightarrow true\ []\ false)$

 $isempty: Openfile \rightarrow Tr$

 $isempty = \lambda(front, back).(null\ front)\ and\ (null\ back)$

Character String

Domain: String =the strings formed from the elements of ${\cal C}$

(including an *error* string)

Operations:

A, B, C, ..., Z : String

empty : String

error : String

 $concat: String \times String \rightarrow String$

 $\textit{length}: \textit{String} \rightarrow \textit{Nat}$

 $substr: String \times Nat \times Nat \rightarrow String$

Output terminal log

Domain: $I \in Log = String^*$



Interactive File Editor: Valuation Functions

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Valuation Functions:

- P: Program_session → File_system → (Log × File_system)
 P[[edit I cr S]] =?
- S : $Command_sequence \rightarrow Openfile \rightarrow (Log \times Openfile)$ S[[C cr S]] =? S[[quit]] =?
- C : Command → Openfile → (String × Openfile)
 C[[newfile]] =?
 C[[moveforward]] =?
 C[[moveback]] =?
 C[[insert R]] =?
 C[[delete]] =?



Interactive File Editor: Valuation Functions

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Valuation Functions:

```
• P: Program\_session \rightarrow File\_system \rightarrow (Log \times File\_system)

P[[edit I cr S]]

= \lambda s.let \ p = copyin(access([[I]], s)) \ in

("edit I" cons fst(S[[S]]p),

update([[I]], copyout(snd(S[[S]]p)), s))
```

• S: Command_sequence \rightarrow Openfile \rightarrow (Log \times Openfile) S[[C cr S]] $= \lambda p.let (l', p') = C[[C]]p in$ ((l'cons fst(S[[S]]p')), snd(S[[S]]p'))S[[quit]] = $\lambda p.("quit" cons nil, p)$



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The S function collects the log messages into a list

S[[quit]] builds the very end of this list

 The equation for S[[C cr S]] deserves a bit of study. It says to:

- Evaluate C[[C]]p to obtain the next log entry I' plus the updated open file p'
- Cons I' to the log list and pass p' onto S[[S]]
- Evaluate S[[S]]p' to obtain the meaning of the remainder of the program, which is the rest of the log output plus the final version of the updated open file



Interactive File Editor: Valuation Functions

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```
• C: Command \rightarrow Openfile \rightarrow (String \times Openfile)
   C[[newfile]] = \lambda p.("newfile", newfile)
   C[[moveforward]]
   =\lambda p.let(k',p') = isempty(p) \rightarrow ("error: file is empty",p)
       [] (at\_last\_record(p) \rightarrow ("error: at back already", p)
          [] ("", forwards(p)))
   in ("moveforward" concat k', p'))
   C[[moveback]]
   = \lambda p.let(k', p') = isempty(p) \rightarrow ("error: file is empty", p)
       [] (at\_first\_record(p) \rightarrow ("error: at front already", p))
          [] ("", backwards(p))
   in ("moveback" concat k', p')
   C[[insert R]] = \lambda p.("insert R", insert(R[[R]], p))
   C[[delete]]
   =\lambda p.let(k',p') = isempty(p) \rightarrow ("error: file is empty", p)
        [] ("", delete(p))
   in ("delete" concat k', p')
```



Interactive File Editor: Example Program Workout 1

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```
• C[[delete]](newfile)
= let (k', p') = isempty(newfile) → ("error:
file is empty", newfile)

[] ("", delete(newfile))
in ("delete" concat k', p'))
= let (k', p') = ("error: file is empty", newfile)
in ("delete" concat k', p')
= ("delete" concat "error: file is empty", newfile)
= ("delete error: file is empty", newfile)
```



Interactive File Editor: Example Program Workout 2

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Language with Contexts Block Structured Language Let [[A]] be the name of a nonempty file in the file system s_0 .

- P[[edit A cr moveback cr delete cr quit]]s₀
 - = ("edit A" cons fst(S[[moveback cr delete cr quit]] p_0), $update([[A]], copyout(snd(S[[moveback cr delete cr quit]]<math>p_0$), s_0)) where $p_0 = copyin(access([[A]], s_0)$)
 - = ("edit A" cons "moveback error: at front already" cons fst(S[[delete cr quit]]p₀)), update([[A]], copyout(snd(S[[delete cr quit]]p₀), s₀)))



Interactive File Editor: Example Program Workout 2

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Let [A] be the name of a nonempty file in the file system s_0 .

- P[[edit A cr moveback cr delete cr quit]] s_0
 - = ("edit A" cons fst(S[[moveback cr delete cr quit]] p_0), $update([[A]], copyout(snd(S[[moveback cr delete cr quit]]<math>p_0$), s_0)) where $p_0 = copyin(access([[A]], s_0)$)
 - = ("edit A" cons "moveback error: at front already" cons fst(S[[delete cr quit]]p₀)), update([[A]], copyout(snd(S[[delete cr quit]]p₀))))

S[[delete cr quit]] p_0 simplifies to a pair ("delete quit", p_1), for $p_1 = delete(p_0)$, and the final result is: ("edit A moveback error: at front already delete quit," $update([[A]], copyout(p_1), s_0))$



Dynamically Typed Language with IO

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Language With Contexts Block Structured Language Applicative Langua An extension of the Language with assignment

 Languages like Python, SNOBOL allow variables to take on values from different data types during the course of evaluation

- This provides flexibility to the user but requires that type checking be performed at run-time
- The semantics of the language gives us insight into the type checking
- We use:
 - $Storable_value = Tr + Nat$
 - $Store = Id \rightarrow Storable_value$
- Since storable values are used in arithmetic and logical expressions, type errors are possible, as in an attempt to add a truth value to a number



Dynamically Typed Language with IO: Abstract Syntax

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Abstract Syntax:

Consider the entities as:

 $P \in Program_session$

 $C \in Command$

 $E \in Expression$

N ∈ Numeral

 $I \in Id$

P ::= C.

 $C ::= C_1; C_2 \mid I := E \mid$

if E then C_1 else C_2 | read I | write E | diverge

 $E ::= E_1 + E_2 \mid E_1 = E_2 \mid \neg E \mid (E) \mid I \mid N \mid \text{true}$



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Semantic Algebras:

Truth values

Domain: $t \in Tr = B$

Operations:

true, false : Tr

 $not: Tr \rightarrow Tr$

Natural Numbers

Domain: $n \in Nat = \mathcal{N}$

Operations:

zero, one, ...: Nat

plus : Nat \times Nat \rightarrow Nat

equals : Nat imes Nat o Tr

Identifiers

Domain: $i \in Id = Identifier$



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Semantic Algebras:

Character String

Domain: *String* = the strings formed from the elements of

 \mathcal{C} (including an *error* string)

Operations:

A, B, C, ..., Z: String

empty : String error : String

 $concat: String \times String \rightarrow String$

length: String o Nat

 $substr: String \times Nat \times Nat \rightarrow String$

Values that may be stored

Domain: $v \in Storable_value = Tr + Nat$



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Values that expressions may denote

```
Domain: x \in Expressible\_value = Storable\_value + Errvalue
where Frrvalue = Unit
Operations:
```

 $check_expr: (Store \rightarrow Expressible_value) \times$

 $(Storable_value \rightarrow Store \rightarrow Expressible_value) \rightarrow (Store \rightarrow$ Expressible_value)

 f_1 check_expr $f_2 = \lambda s$.let $z = (f_1 \ s)$ in cases z of $isStorable_value(v) \rightarrow (f_2 \ v \ s)$ [] $isErrvalue() \rightarrow inErrvalue()$ end

Note: check_expr performs error trapping at the expression level

The context of check_expr is when two expressions are used to build a bigger expression with an operator. For example, $E_1 + E_2$. f_1 is the valuation function $[[E_1]]$ of E_1 that takes the store s to produce $v \in Storable_value$ (or an Errvalue in which case we cannot proceed). If vis not a type error, f_2 , the valuation function $[[E_2]]$ of E_2 , takes the store s to produce $v' \in Storable_value$ (or an Errvalue). Finally, the operator (plus) is applied onto v and v' (if there is not type error) to produce the final result



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```
    Input buffer
    Domain: i ∈ Input = Expressible_value*
    Operations:
    get_value : Input → (Expressible_value × Input)
```

 $get_value = \lambda i.null \ i \rightarrow (inErrvalue(), i) \ [] \ (hd \ i, tl \ i)$

Output buffer

```
Domain: o \in Output = (Storable\_value + String)^*
Operations:
```

empty : Output

empty = nil

 $put_value : Storable_value \times Output \rightarrow Output$ $put_value = \lambda(v, o).inStorable_value(v) cons o$ $put_message : String \times Output \rightarrow Output$

 $put_message = \lambda(t,o).inString(t)$ cons o



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Store

Domain: $s \in Store = Id\beta \rightarrow Storable_value$

Operations:

newstore : Store

 $access: Id \rightarrow Store \rightarrow Storable_value$

 $access = \lambda(i, s).s(i)$

 $update: Id \rightarrow Storable_value \rightarrow Store \rightarrow Store$

 $update = \lambda(i, v, s).[i \mapsto v]s$

Program State

Domain: $a \in State = Store \times Input \times Output$

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```
    Post program state

   Domain: z \in Post\_state = OK + Err
   where OK = State and Err = State
   Operations:
   check\_result : (Store \rightarrow Expressible\_value) \times
   (Storable\_value \rightarrow State \rightarrow Post\_state_{\perp})
         \rightarrow (State \rightarrow Post_state)
   f check_result g = \lambda(s, i, o).let z = (f s) in cases z of
         isStorable\_value(v) \rightarrow (g \ v \ (s, i, o))
          [] isErrvalue() \rightarrow
          inErr(s,i,put_message("type error",o)) end
   check\_cmd : (State \rightarrow Post\_state_{\perp}) \times
       (State \rightarrow Post\_state_{\perp}) \rightarrow (State \rightarrow Post\_state_{\perp})
      h_1 check_cmd h_2 = \lambda a.let z = (h_1 \ a) in cases z of
         isOK(s,i,o) \rightarrow h_2(s,i,o)
         [] isErr(s, i, o) \rightarrow z end
```

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Dynamically Typed Language with IO

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- Program state (State) is a triple of store and input and output buffers
- The Post_state domain is used to signal when an evaluation is completed successfully and when a type error occurs
- The tag attached to the state is utilized by the *check_cmd* operation

The expression ($C[[C_1]]$ check_cmd $C[[C_2]]$) denotes the sequencing operation for the language and does the following:

- ① It gives the current state a to $C[[C_1]]$, producing a Post_state $z = C[[C_1]]a$
- ② If z is a proper state a', and then, if the state component is OK, it produces $C[[C_2]]a'$
- ③ If z is erroneous, $C[[C_2]]$ is ignored (it is *branched over*), and z is the result *check_result*, sequences an expression with a command:
 - lacksquare For example, for an assignment [[I:=E]], [[E]]'s value must be determined before a store update can occur
 - If Since [[E]]'s evaluation may cause a type error, the error must be detected before the update is attempted
 - Operation check_result performs this action

check_expr performs error trapping at the expression level



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Valuation Functions:

- P : $Program \rightarrow Store \rightarrow Input \rightarrow Post_state_{\perp}$ $P[[C.]] = \lambda s. \lambda i. C[[C]] (s, i, empty)$
- C : $Command \rightarrow State \rightarrow Post_state_{\perp}$ $C[[C_1; C_2]] = C[[C_1]] \ check_cmd \ C[[C_2]]$

```
check\_cmd: (State \rightarrow Post\_state_{\perp}) \times \\ (State \rightarrow Post\_state_{\perp}) \rightarrow (State \rightarrow Post\_state_{\perp}) \\ h_1 \ check\_cmd \ h_2 = \lambda a.let \ z = (h_1 \ a) \ in \ cases \ z \ of \\ isOK(s,i,o) \rightarrow h_2 \ (s,i,o) \\ \lceil \ isErr(s,i,o) \rightarrow z \ end \ \end{cases}
```



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Summary

```
• C[[I := E]] = E[[E]] \ check\_result \ (\lambda v.\lambda(s,i,o).inOK((update[[I]] \ v \ s),i,o))
C[[if \ E \ then \ C_1 \ else \ C_2]] = E[[E]] \ check\_result
(\lambda v.\lambda(s,i,o).cases \ v \ of \ isTr(t) \to (t \to C[[C_1]] \ [] \ C[[C_2]])(s,i,o)
[] \ isNat(n) \to inErr(s,i,put\_message("bad \ test",o)) \ end)
C[[read \ I]] = \lambda(s,i,o).let \ (x,i') = get\_value(i) \ in \ cases \ x \ of \ isStorable\_value(v) \to inOK((update[[I]] \ v \ s),i',o)
[] \ isErrvalue() \to inErr(s,i',put\_message("bad \ input",o)) \ end
C[[write \ E]] = E[[E]] \ check\_result \ (\lambda v.\lambda(s,i,o).inOK(s,i,put\_value(v,o)))
C[[diverge]] = \lambda a.\bot
```

```
 \begin{array}{l} \textit{check\_result}: \\ (\textit{Store} \rightarrow \textit{Expressible\_value}) \times (\textit{Storable\_value} \rightarrow \textit{State} \rightarrow \textit{Post\_state}_\perp) \\ \rightarrow (\textit{State} \rightarrow \textit{Post\_state}_\perp) \\ \textit{f} \ \textit{check\_result} \ g = \lambda(s, i, o). \\ \textit{let} \ z = (f \ s) \ \textit{in cases} \ z \ \textit{of} \\ \textit{isStorable\_value}(v) \rightarrow (g \ v \ (s, i, o)) \\ \text{[]} \ \textit{isErrvalue}() \rightarrow \\ \textit{inErr}(s, i, \textit{put\_message}("type \ \textit{error}", o)) \ \textit{end} \\ \end{array}
```



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Summary

```
• E: Expression \rightarrow Store \rightarrow Expressible_value

E[[E<sub>1</sub> + E<sub>2</sub>]] = E[[E<sub>1</sub>]] check_expr

(\lambda v. cases v of

isTr(t) \rightarrow \lambda s.inErrvalue()

[] isNat(n) \rightarrow E[[E<sub>2</sub>]] check_expr

(\lambda v'.\lambda s. cases v' of

isTr(t') \rightarrow inErrvalue()

[] isNat(n') \rightarrow inStorable\_value(inNat(n plus n')) end)

end)
```



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```
• E[[E1 = E2]] = "similar to above equation" 

E[[\neg E]] = E[[E]] check\_expr (\lambda v. \lambda s. \ cases \ v \ of \ is Tr(t) \rightarrow in Storable\_value(in Tr(not \ t)) [] \ is Nat(n) \rightarrow in Errvalue() \ end) 

E[[(E)]] = E[[E]] E[[I]] = \lambda s. in Storable\_value(access \ [[I]] \ s) E[[N]] = \lambda s. in Storable\_value(in Nat(N[[N]])) E[[true]] = \lambda s. in Storable\_value(in Tr(true)) N: Numeral \rightarrow Nat(omitted)
```

```
 \begin{array}{l} \textit{check\_expr}: (\textit{Store} \rightarrow \textit{Expressible\_value}) \times \\ (\textit{Storable\_value} \rightarrow \textit{Store} \rightarrow \textit{Expressible\_value}) \rightarrow (\textit{Store} \rightarrow \textit{Expressible\_value}) \\ \textit{f}_1 \ \textit{check\_expr} \ \textit{f}_2 = \lambda \textit{s.let} \ \textit{z} = (\textit{f}_1 \ \textit{s}) \ \textit{in cases} \ \textit{z} \ \textit{of} \\ \textit{isStorable\_value}(\textit{v}) \rightarrow (\textit{f}_2 \ \textit{v} \ \textit{s}) \\ & \text{[]} \ \textit{isErrvalue}() \rightarrow \textit{inErrvalue}() \\ & \textit{end} \\ \end{array}
```



Dynamically Typed Language with IO: Example Programs

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J**ontexts** Block Structured Language Applicative Language Compute the semantics (post-state) for the following:

```
P[[read X; X := X + 1; write X.]](\lambda i. zero, (3), ())
   = C[[read X; X := X + 1; write X]] (\lambda i. zero, (3), ())
   = (C[[read X]] check_cmd C[[X := X + 1; write X]]) (\lambda i. zero, (3), ())
   = (\lambda a.let z = (C[[read X;]] a) in cases z of
     isOK(s, i, o) \rightarrow C[[X := X + 1; write X]] (s, i, o)
     [] is Err(s, i, o) \rightarrow z end (\lambda i. zero, (3), ())
   = C[[X := X + 1; write X]] inOK((\lambda i.i equals X \rightarrow three [] zero, (), ()))
   = (C[[X := X + 1]] check\_cmd C[[write X]]) inOK((\lambda i.i equals X \rightarrow three [] zero, (), ()))
   = (\lambda a.let z = (C[[X := X + 1]] a) in cases z of
     isOK(s, i, o) \rightarrow C[[write X]] (s, i, o)
     [] is Err(s, i, o) \rightarrow z end) in OK((\lambda i.i \text{ equals } X \rightarrow three [] \text{ zero}, (), ()))
   = C[[write X]] inOK((\lambda i.i equals X \rightarrow four [] zero, (), ()))
   = inOK((\lambda i.i equals X \rightarrow four [] zero), (), (4))
C[[read X]] (\lambda i. zero, (3), ())
   = (\lambda(s, i, o).let(x, i') = get\_value(i) in
        cases x of isStorable_value(v) \rightarrow inOK((update[[X]] v s), i', o)
           [] isErrvalue() \rightarrow inErr(s, i', put\_message(''bad input'', o)) end) (\lambda i. zero, (3), ())
   = let(x, i') = get\_value((3)) in
        cases x of isStorable_value(v) \rightarrow inOK((update[[X]] v (\lambda i. zero)), i', ())
           [] is Errvalue() \rightarrow in Err(s, i', put\_message(''bad input'', ())) end
   = inOK((update[[X]] inStorable\_value(three) (\lambda i. zero)), (), ())
   = inOK(\lambda i.i.equals X \rightarrow three [] zero.(),())
```



Dynamically Typed Language with IO: Example Programs

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```
C[[X := X + 1]] inOK(\lambda i.i equals X \rightarrow three [] zero, (), ()))
   = \mathsf{E}[[X+1]] \ \textit{check\_result} \ (\lambda v. \textit{inOK}((\textit{update}[[X]] \ v \ \textit{inOK}((\lambda i.i \ \textit{equals} \ X \rightarrow \textit{three} \ [] \ \textit{zero})), (), ())))
   = let z = (E[[X + 1]] s_1) in cases z of isStorable_value(v) \rightarrow (g \ v \ (s_1, (), ()))
       [] isErrvalue() \rightarrow inErr(s_1, (), put\_message(''type error'', ())) end
       where s_1 = (\lambda i.i \text{ equals } X \rightarrow \text{three } [ \text{ zero}), (), ()) and
       g = \lambda v.inOK((update[X]) v (\lambda i.i equals X \rightarrow three [] zero)), (), ())
   = g inNat(four) (s_1, (), ())
   = inOK((update[[X]] inNat(four) (\lambda i.i equals X \rightarrow three [] zero)), (), ())
   = inOK(\lambda i.i equals X \rightarrow four [] zero), (), ())
E[[X+1]] s_1 = E[[X+1]] inOK((\lambda i.i equals X \rightarrow three [] zero, (), ()))
   = E[[X]] check_expr
     (\lambda v. cases \ v \ of \ isTr(t) \rightarrow \lambda s.inErrvalue()
       [] isNat(n) \rightarrow E[[1]] check_expr
         (\lambda v'.\lambda s. cases v' of isTr(t') \rightarrow inErrvalue()
            \exists isNat(n') \rightarrow inStorable\_value(inNat(n plus n')) end)
       end) in OK((\lambda i, i \text{ equals } X \rightarrow \text{three } [] \text{ zero, } (), ()))
   = inStorable_value(inNat(three plus one)) = inStorable_value(inNat(four))
C[[write X]] = E[[X]] check_result (\lambda v. \lambda(s, i, o).inOK(s, i, put\_value(v, o)))
   = inOK((\lambda i.i equals X \rightarrow four [] zero), (), (4))
```



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Summary

Compute the semantics (post-state) for the following:

- P[[read $X; X := X + 1; write X.]](\lambda i. zero, (3), ())$
- P[[read $X; X := X + 1; write X.]](\lambda i. zero, (), ())$
- P[[read X; read Y; if (X = Y) then M := true else $M := \neg \text{true}$; write $M := \text{l}(\lambda i. zero, (3 3), ())$
- P[[read X; read Y; if (X = Y) then M := true else $M := \neg \text{true}$; write M.]] ($\lambda i.$ zero, (3 4), ())
- P[[read X; read Y; if (X = Y) then $M := \text{true else } M := \neg \text{true}$; write M.]] ($\lambda i. zero$, (3), ())
- P[[read X; read Y; if (X = Y) then M := X = Y else $M := \neg(X = Y)$; write M.]] ($\lambda i. zero$, (3 4), ())
- P[[if (X = Y) then M := true else $M := \neg \text{true}$; write M.]] $(\lambda i. \ two, \ (), \ ())$
- P[[read X; read Y; X := X + Y; write X.]] (λi . zero, (3 false), ())



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Denotations (post-state) for the programs:

- P[[read X; X := X + 1; write X.]]($\lambda i.$ zero, (3), ()) = $inOK((\lambda i.i \text{ equals } X \rightarrow four \text{ [] zero, (), (4))})$
- P[[read $X; X := X + 1; write X.]](\lambda i. zero, (), ()) = inErr((\lambda i. zero, (), ("bad input")))$
- P[[read X; read Y; if (X = Y) then M := true else $M := \neg \text{true}$; write M.]] $(\lambda i. zero, (3 3), ()) = inOK((\lambda i.i equals <math>X \to three \ [] i equals \ Y \to three \ [] i equals \ M \to true \ [] zero, (), (true)))$
- P[[read X; read Y; if (X = Y) then M := true else $M := \neg \text{true}$; write M.]] $(\lambda i. zero, (3 4), ()) = inOK((\lambda i.i equals <math>X \to \text{three}$ [$i \text{ equals } Y \to \text{four}$ [$i \text{ equals } M \to \text{false}$ [i zero, (), (false)))
- P[[read X; read Y; if (X = Y) then M := true else $M := \neg \text{true}$; write M.]] $(\lambda i. zero, (3), ()) = inErr((\lambda i.i equals <math>X \to three [] zero, (), (''bad input'')))$
- P[[read X; read Y; if (X = Y) then M := X = Y else $M := \neg(X = Y)$; write M.]] $(\lambda i. zero, (3 4), ()) = inOK((\lambda i. i equals <math>X \to three \ [] i equals \ Y \to four \ [] i equals \ M \to true \ [] zero, (), (true)))$
- P[[if (X = Y) then M := true else M := ¬true; write M.]] (λi. two, (), ()) = inOK((λi.i equals M → false [] two, (), ()))
- P[[read X; read Y; X := X + Y; write X.]] (λi . zero, (3 false), ()) = $inErr((\lambda i.i \text{ equals } X \to \text{three } [] \text{ i equals } Y \to \text{false } [] \text{ zero, } (), ("type \text{ error"})))$



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Language with Contexts Block Structured Language Applicative Language The copyout function of File Editor, which concatenates two lists, could not be given. We can specify copyout using an iterative or recursive specification, but at this point neither is allowed in the function notation.

```
copyout : Openfile \rightarrow File

copyout = \lambda p. "appends fst(p) to snd(p)" // Recursive

copyout = \lambda (front, back).null\ front \rightarrow back

[] copyout((tl\ front),\ ((hd\ front)\ cons\ back))
```



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 A similar situation arises with the semantics of a Pascal-like while-loop:

B : Boolean_expression

C: Command

 $C ::= \cdots \mid \text{while } B \text{ do } C \mid \cdots$

Here is a recursive definition of its semantics: for

B : $Boolean_expression \rightarrow Store \rightarrow Tr$, and

 $C: Command \rightarrow Store_{\perp} \rightarrow Store_{\perp}:$

 $C[[\text{while } B \text{ do } C]] = \underline{\lambda} s.B[[B]]s \rightarrow C[[\text{while } B \text{ do } C]](C[[C]]s) [] s$



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 Unfortunately, the clause violates the rule that the meaning of a syntax phrase may be defined only in terms of the meanings of its proper sub-parts

We avoid this problem by stating:

$$C[[while B do C]] = w$$

where $w: Store_{\perp} \rightarrow Store_{\perp}$ is

$$w = \underline{\lambda} s.B[[B]]s \rightarrow w(C[[C]]s)[]s$$

 But the recursion remains, for the new version exchanges the recursion in the syntax for recursion in the function notation.



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Recursive Definitions

A recursive definition may not uniquely define a function

$$q(x) = x$$
 equals zero \rightarrow one [] $q(x$ plus one)

which apparently is $q: \mathcal{N} \to \mathcal{N}_{\perp}$.

The following functions all satisfy q's definition in the sense that they have exactly the behavior required by the equation:

- $f_1(x) = one$, if x = zero= | otherwise OR $f_1(x) = \lambda x.(x \text{ equals zero} \rightarrow \text{one } [] \perp)$ $= \{(zero, one)\} \& Ghosts: \{(one, \perp), (two, \perp), \cdots\}$
- $f_2(x) = one$, if x = zero= two, otherwise, OR $f_2(x) = \lambda x.(x \text{ equals zero} \rightarrow \text{one } [] \text{ two})$ $= \{(zero, one), (one, two), (two, two), \dots\}$
- $f_3(x) = \lambda x.(one)$ $= \{(zero, one), (one, one), (two, one), \dots\}$
- $g_k(x) = \{(zero, one), (one, k), (two, k), \dots\}, k \in Nat$
- and there are infinitely many others.



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Language With Contexts Block Structured Language Applicative Langua Given

$$q(x) = x$$
 equals zero \rightarrow one [] $q(x$ plus one)

Prove that $\forall n \in Nat$

- n equals zero \rightarrow one [] $f_1(n \text{ plus one}) = f_1(n) = q(n)$ where $f_1(x) = \lambda x.(x \text{ equals zero} \rightarrow \text{ one } [] \perp)$
- ② n equals $zero \rightarrow one$ [] $f_2(n \ plus \ one) = f_2(n) = q(n)$ where $f_2(x) = \lambda x.(x \ equals \ zero \rightarrow one$ [] two)
- **1** In equals zero \rightarrow one $[] f_3(n \text{ plus one}) = f_3(n) = q(n)$ where $f_3(x) = \lambda x.(one)$
- n equals zero \rightarrow one [] $g_k(n \text{ plus one}) = g_k(n) = q(n)$ where $g_k(x) = \lambda x.(x \text{ equals zero} \rightarrow \text{ one } [] k),$ $k \in N$ at



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```
n equals zero → one [] f<sub>1</sub>(n plus one)
             = n equals zero \rightarrow one \Pi
                    (\lambda x.(x \text{ equals zero} \rightarrow \text{one } [] \perp))(n \text{ plus one})
             = n equals zero \rightarrow one \Pi
                    ((n plus one) equals zero \rightarrow one [] \perp)
             = n equals zero \rightarrow one [] \perp
             = f_1(n) = \lambda x.(x \text{ equals zero} \rightarrow \text{one } [] \perp)
② n equals zero → one [] f<sub>2</sub>(n plus one)
             = n \text{ equals zero} \rightarrow one []
                    (\lambda x.(x \text{ equals zero} \rightarrow \text{one } [] \text{ two}))(n \text{ plus one})
             = n \text{ equals zero} \rightarrow one []
                    ((n plus one) equals zero \rightarrow one [] two)
             = n \text{ equals zero} \rightarrow \text{one} [] \text{ two}
             = f_2(n) = \lambda x.(x \text{ equals zero} \rightarrow \text{one} [] \text{ two})
3 n equals zero \rightarrow one [] f_3(n \text{ plus one})
             = n \text{ equals zero} \rightarrow one []
                    (\lambda x.(one))(n plus one)
             = n equals zero \rightarrow one [] one
             = one
             = f_3(n) = \lambda x.(one)
```

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Summary

• A large number of functions satisfy the recursive definition of q: q(x) = x equals zero \rightarrow one [] q(x plus one)



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 A large number of functions satisfy the recursive definition of q: q(x) = x equals zero → one [] q(x plus one)

• One choice is the function that maps zero to one and all other arguments to ⊥. We write this function's graph as {(zero, one)} (rather than {(zero, one), (one, ⊥), (two, ⊥), ...}, treating the (n, ⊥) pairs as ghost members). This choice is a natural one for programming, for it corresponds to what happens when the definition is run as a routine on a machine.

```
// Natural Operational Semantics in C
// q(n) = n equals zero -> one [] q(n plus one)
unsigned int q(unsigned int n) {
  if (n == 0) return 1;
  else return q(n + 1); // Never terminates -- bottom
}
```



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Language with Contexts Block Structured Language Applicative Language • But the graph {(zero, one), (one, four), (two, four), (three, four), ...} also denotes a function that also has the behavior specified by q: zero maps to one and all other arguments map to the same answer as their successors.

```
// Unnatural Operational Semantics in C
// q(n) = n equals zero -> one [] q(n plus one)
unsigned int q(unsigned int x) {
   if (x == 0) return 1;
   else return 4;
}
```

So we have multiple choices. Not all of them may be operationally acceptable.



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Language with Contexts Block Structured Language Applicative Languag But the graph {(zero, one), (one, four), (two, four), (three, four), ...}
 also denotes a function that also has the behavior specified by q:
 zero maps to one and all other arguments map to the same answer
 as their successors.

```
// Unnatural Operational Semantics in C
// q(n) = n equals zero -> one [] q(n plus one)
unsigned int q(unsigned int x) {
   if (x == 0) return 1;
   else return 4;
}
```

So we have multiple choices. Not all of them may be operationally acceptable.

• In general, any graph $\{(zero, one), (one, k), (two, k), \dots\}$, for some $k \in Nat_{\perp}$, represents a function that satisfies the specification.



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But the graph {(zero, one), (one, four), (two, four), (three, four), ...} also denotes a function that also has the behavior specified by q: zero maps to one and all other arguments map to the same answer as their successors.

```
// Unnatural Operational Semantics in C
// q(n) = n equals zero -> one [] q(n plus one)
unsigned int q(unsigned int x) {
   if (x == 0) return 1;
   else return 4;
}
```

So we have multiple choices. Not all of them may be operationally acceptable.

- In general, any graph $\{(zero, one), (one, k), (two, k), \cdots\}$, for some $k \in Nat_{\perp}$, represents a function that satisfies the specification.
- For a programmer, the last graph is an unnatural choice for the meaning of q, but a mathematician might like a function with the largest possible graph instead, the claim being that a fuller function



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Recursive Definitions

• A recursive specification may not define a unique function, so which one should be selected as the meaning of the specification?

- Choose the one that suits operational intuitions
- Theory of *least fixed point semantics* establishes the meaning of recursive specifications. The theory:
 - Guarantees that the specification has at least one function satisfying it.
 - 2 Provides a means for choosing a best function out of the set of all functions satisfying the specification.
 - Section 2 in the Sec corresponds to the operational treatment of recursion:

The function maps an argument a to a defined answer b iff the operational evaluation of the specification with the representation of argument a produces the representation of b in a finite number of recursive invocations



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Summary

Consider: $fac: Nat \rightarrow Nat_{\perp}$

fac(n) = n equals zero \rightarrow one [] n times (fac(n minus one)) = {(zero, one), (one, one), (two, two), (three, six), \cdots , (i, i!), \cdots }



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Finite Unfolding:

- ① Zero unfolding (fac₀): no argument $n \in Nat$ can produce an answer, for no form fac(n) can simplify to an answer without the initial unfolding. Hence $graph(fac_0) = \{ \}$
- ② One unfolding (fac₁): This allows fac to be replaced by its body only once. Thus, $fac(zero) \Rightarrow zero \ equals \ zero \rightarrow one \ [] \cdots = one$, but all other nonzero arguments require further unfoldings to simplify to answers. Hence $graph(fac_1) = \{(zero, one)\}$
- ③ Two unfolding's (fac₂): Since only one unfolding is needed for mapping argument zero to one, (zero, one) appears in the graph. The extra unfolding allows argument one to evaluate to one, for fac(one) ⇒ one equals zero → one [] one times (fac(one minus one)) = one times fac(zero) ⇒ one times (zero equals zero → one [] ···) = one times one = one
 - All other arguments require further unfoldings and do not produce answers at this stage. Hence $graph(fac_2) = \{(zero, one), (one, one)\}$
- (i+1) unfolding's (fac_{i+1}) , for $i \ge 0$: All arguments with values of i or less will simplify to answers i!, giving $graph(fac_{i+1}) = \{(zero, one), (one, one), (two, two), (three, six), \dots, (i, i!)\}$.



Unfolding of fac by Simulation

fac(9) = 362880 in 10 unfolds

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```
// Project: PoPL 2019. fac_unfold.cpp, \perp shown as -1
fac = \lambda n.n \text{ equals zero} \rightarrow \text{one } [] \text{ n times } (fac(n \text{ minus one}))
COMPUTING LFP of fac(n) =
n equals zero -> one[] n times (fac(n minus one))
fac(0) = 1 in 1 unfolds
fac(1) = 1 in 2 unfolds
fac(2) = 2 in 3 unfolds
fac(3) = 6 in 4 unfolds
fac(4) = 24 in 5 unfolds
fac(5) = 120 in 6 unfolds
fac(6) = 720 \text{ in } 7 \text{ unfolds}
fac(7) = 5040 in 8 unfolds
fac(8) = 40320 in 9 unfolds
```



Unfolding of fac by Simulation

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```
// Project: PoPL 2019, fac_unfold.cpp, \perp shown as -1
// fac(n) = n equals zero -> one[] n times (fac(n minus one))
#include <iostream>
using namespace std:
static unsigned int facCount = 0. maxUnfoldingLevel:
unsigned int fac(unsigned int x) {
   ++facCount:
   if (x == 0) return 1;
    else
    if (facCount == maxUnfoldingLevel) throw 1:
    else return x * fac(x - 1):
int fac unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false: unsigned int result: ::maxUnfoldingLevel = maxUnfoldingLevel:
    cout << "COMPUTING LFP of fac(n) = n equals zero -> one [] n times (fac(n minus one))\n":
    for (unsigned int n = 0: n < maxParam: ++n) {
        try {
            bottom = false; facCount = 0; result = fac(n);
        catch (int) { bottom = true; }
        cout << "fac(" << n << ") = "
             << (int)((bottom) ? -1 : result) << " in " << facCount << " unfolds" << endl:
    cout << endl << endl:
    return 0:
}
```



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Prove: $\bigcup_{i=0}^{\infty} graph(fac_i) = graph(factorial)$

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Language with Contexts Block Structured Language Applicative Language Prove: $\bigcup_{i=0}^{\infty} graph(fac_i) = graph(factorial)$

Forward direction:

- We get: $\forall i \geq 0$, $graph(fac_i) \subseteq graph(fac_{i+1})$
- Clearly, $\forall i \geq 0$, $graph(fac_i) \subseteq graph(factorial)$
 - Hence,

$$\cup_{i=0}^{\infty} graph(fac_i) \subseteq graph(factorial)$$

Backward direction:

• If some pair (a, b) is in graph(factorial), then there must be some finite i > 0 such that (a, b) is in $graph(fac_i)$ also. Thus:

$$graph(factorial) \subseteq \bigcup_{i=0}^{\infty} graph(fac_i)$$

Hence,

$$\bigcup_{i=0}^{\infty} graph(fac_i) = graph(factorial)$$

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Recursive Definitions

Language with Contexts Block Structured Language Applicative Languag The fundamental principle of least fixed point semantics:

- The meaning of any recursively defined function is exactly the union of the meanings of its finite sub-functions
- It is easy to produce a non-recursive representation of each sub-function

For example: Define each $fac_i : Nat \rightarrow Nat_{\perp}$, for $i \geq 0$, as:

- $fac_0 = \lambda n. \bot$
- $fac_{i+1} = \lambda n.n$ equals zero \rightarrow one [] n times $fac_i(n \text{ minus one})$, for all $i \geq 0$

The graph of each fac_i is the one produced at stage i of the fac unfolding



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Language with Contexts Block Structured Language Applicative Languag This has two advantages:

- Each fac; is a non-recursive definition, which suggests that a recursive specification can be understood in terms of a family of non-recursive ones; and
- ② A format common to all the fac_i 's can be extracted. Let:

$$F = \lambda f.\lambda n.n$$
 equals zero \rightarrow one []
 n times $f(n \text{ minus one})$
 $= \lambda f.\lambda n.n$ equals zero \rightarrow one []
 $let \ n' = f(n \text{ minus one})$ in n times n'

Each
$$fac_{i+1} = F(fac_i), \forall i \geq 0.$$



Recursive Functions Definitions: factorial

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• The non-recursive $F:(Nat \to Nat_{\perp}) \to (Nat \to Nat_{\perp})$ is called a *functional*, because it takes a function as an argument and produces one as a result. Thus:

$$graph(factorial) = \bigcup_{i=0}^{\infty} graph(F^{i}(\Phi))$$

where $F^i = F \circ F \circ \cdots \circ F$, i times, and $\Phi = (\lambda n. \bot)$

- Also, graph(F(factorial)) = graph(factorial), which implies F(factorial) = factorial, by the extensionality principle.
- The factorial function is a fixed point of F, as the answer F produces from argument factorial is exactly factorial again

$$factorial = fix F$$



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Recursive Definitions

Consider:

$$q: \mathsf{Nat} o \mathsf{Nat}_\perp, \ q(x) = x \ \mathsf{equals} \ \mathsf{zero} o \mathsf{one} \ [] \ q(x \ \mathsf{plus} \ \mathsf{one})$$

Then,
$$Q:(\mathit{Nat} o \mathit{Nat}_\perp) o (\mathit{Nat} o \mathit{Nat}_\perp)$$

$$Q = \lambda g.\lambda n.n$$
 equals zero o one [] $g(n$ plus one)

Compute the fixed point of *Q*



Recursive Functions Definitions: q Function

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Consider:

$$q: \mathcal{N} \to \mathcal{N}_{\perp}$$
, $q(x) = x$ equals zero \to one [] $q(x$ plus one)

Then,
$$Q: (Nat \rightarrow Nat_{\perp}) \rightarrow (Nat \rightarrow Nat_{\perp})$$

 $Q = \lambda g. \lambda n. n \ equals \ zero \rightarrow one \ [] \ g(n \ plus \ one)$

We get:

$$Q^0(\Phi) = (\lambda n. \perp)$$
, where $\Phi = (\lambda n. \perp)$ graph($Q^0(\Phi)$) = { }

$$Q^1(\Phi) = Q(Q^0(\Phi)) = \lambda n.n \text{ equals zero } \rightarrow \text{ one } [] (\lambda n.\perp)(n \text{ plus one})$$

= $\lambda n.n \text{ equals zero } \rightarrow \text{ one } [] \perp$
 $graph(Q^1(\Phi)) = \{(zero, one)\}$

$$Q^2(\Phi) = Q(Q^1(\Phi)) = \lambda n.n$$
 equals zero \rightarrow one []
 $((n \text{ plus one}) \text{ equals zero } \rightarrow \text{ one } [] \perp)$
 $= \lambda n.n$ equals zero \rightarrow one [] $\perp = Q^1(\Phi)$
 $graph(Q^2(\Phi)) = \{(zero, one)\}$

Hence, $\forall i \geq 1, graph(Q^i(\Phi)) = \{(zero, one)\}$. It follows that:

$$\bigcup_{i=0}^{\infty} graph(Q^{i}(\Phi)) = \{(zero, one)\}$$



Recursive Functions Definitions: q Function

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Let *qlimit* denote the function that has this graph. It is easy to show that Q(qlimit) = qlimit, that is, *qlimit* is a fixed point of Q. Or, *qlimit* = fix Q.

Unlike the specification *fac*, q has many possible solutions. Recall that each one must have a graph of the form $\{(zero, one), (one, k), \cdots, (i, k), \cdots\}$ for some $k \in \mathit{Nat}_{\perp}$.

Let qk be one of these solutions. We can show that:

- \bigcirc qk is a fixed point of Q, that is, Q(qk) = qk
- 2 $graph(qlimit) \subseteq graph(qk)$
 - Fact 1 says that the act of satisfying a specification is formalized by the fixed point property – only fixed points of the associated functional are possible meanings of the specification
 - Fact 2 states that the solution obtained using the stages of unfolding method is the smallest of all the possible solutions

So, we call it the *least fixed point* of the functional.

Try to prove Fact 1 and Fact 2 above.



Unfolding of q by Simulation

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```
// Project: PoPL 2019. q_unfold.cpp, \perp shown as -1
q = \lambda x.x equals zero \rightarrow one [] q(x \text{ plus one})
COMPUTING LFP of q(n) =
n equals zero -> one [] q(n plus one)
a(0) = 1 in 1 unfolds
q(1) = -1 in 100 unfolds
q(2) = -1 in 100 unfolds
q(3) = -1 in 100 unfolds
q(4) = -1 in 100 unfolds
q(5) = -1 in 100 unfolds
q(6) = -1 in 100 unfolds
a(7) = -1 in 100 unfolds
q(8) = -1 in 100 unfolds
q(9) = -1 in 100 unfolds
```



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```
// Project: PoPL 2019. g_unfold.cpp. \perp shown as -1
// g(n) = n equals zero -> one [] g(n plus one)
#include <iostream>
using namespace std:
static unsigned int gCount = 0, maxUnfoldingLevel:
unsigned int q(unsigned int x) {
   ++aCount:
   if (x == 0) return 1;
    else
    if (gCount == maxUnfoldingLevel) throw 1:
    else return q(x + 1);
int q unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false; unsigned int result; ::maxUnfoldingLevel = maxUnfoldingLevel;
    cout << "COMPUTING LFP of q(n) = n equals zero -> one [] q(n plus one)" << endl;
    for (unsigned int n = 0: n < maxParam: ++n) {
        trv {
            bottom = false; qCount = 0; result = q(n);
        catch (int) { bottom = true: }
        cout << "q(" << n << ") = " << (int)((bottom) ? -1 : result)</pre>
             << " in " << qCount << " unfolds" << endl;
    cout << endl << endl:
    return 0:
}
```

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Let a recursive specification f = F(f) denote the least fixed point of functional F, that is, the function associated with $\bigcup_{i=0}^{\infty} graph(F^{i}(\Phi))$, as obtained by the stages of unfolding.

The three desired properties follow:

- A solution to the specification exists;
- The criterion of least-ness is used to select from the possible solutions; and,
- Since the method for constructing the function exactly follows the usual operational treatment of recursive definitions, the solution corresponds to the one determined computationally.



Recursive Functions Definitions: copyout

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Language with Contexts Block Structured Language Applicative Languag copyout function:

- The domains:
 File = Record* and Openfile = Record* × Record*
- Function copyout converts an open file into a file by appending the two record lists
- A specification of copyout: Openfile \rightarrow File $_{\perp}$ is: copyout = $\lambda(front, back).null\ front \rightarrow back\ []$ copyout((tl front),((hd front) cons back))
- Construct functional F such that copyout = (fix F).
- Prove that the function $F^i(\perp)$ is capable of appending list pairs whose first component has length i-1 or less.
- This implies that the *lub* of the $F^i(\bot)$ functions, (fix F), is capable of concatenating all pairs of lists whose first component has finite length.

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Recursive Functions Definitions: copyout

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copyout function:

```
• copyout^0 = \lambda(front, back).\bot
```

- $copyout^1 = \lambda(front, back).null \ front \rightarrow back \ []$ $copyout^0((tl \ front), ((hd \ front) \ cons \ back))$ $= \lambda(front, back).null \ front \rightarrow back \ [] \ \bot$
- $copyout^2 = \lambda(front, back).null\ front \rightarrow back\ []$ $copyout^1((tl\ front), ((hd\ front)\ cons\ back))$ $= \lambda(front, back).null\ front \rightarrow back\ []$ $(\lambda(front, back).null\ front \rightarrow back\ []\ \bot)$ $((tl\ front), ((hd\ front)\ cons\ back))$ $= \lambda(front, back).null\ front \rightarrow back\ []$ $(null\ (tl\ front) \rightarrow ((hd\ front)\ cons\ back)\ []\ \bot)$
- $copyout^{i+1} = \lambda(front, back).null \ front \rightarrow back \ [] \ copyout^i((tl\ front), ((hd\ front)\ cons\ back))$
- Functional $F: (Openfile \rightarrow File_{\perp}) \rightarrow (Openfile \rightarrow File_{\perp})$: $F = \lambda f.\lambda(front, back).null\ front \rightarrow back\ []$ $f((tl\ front), ((hd\ front)\ cons\ back))$
- copyout = fix F = F(copyout)



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Consider the specification for $g: \mathit{Nat} \to \mathit{Nat}_\perp:$

 $g = \lambda n.n$ equals zero \rightarrow one [] (g(n minus one) plus g(n minus one)) minus one

What is g?

Hint: Construct F and compute the graphs of $F^i(\bot)$



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```
Consider the specification for g: Nat \rightarrow Nat_{\perp}:
g = \lambda n.n equals zero \rightarrow one []
(g(n \text{ minus one}) \text{ plus } g(n \text{ minus one})) \text{ minus one}
F = \lambda f.\lambda n.n equals zero \rightarrow one []
(f(n \text{ minus one}) \text{ plus } f(n \text{ minus one})) \text{ minus one}
Using \perp for (\lambda n. \perp)
graph(F^{0}(\bot)) = \{\}
graph(F^1(\bot)) = \{(zero, one)\}
graph(F^2(\bot)) = \{(zero, one)\}
graph(F^3(\bot)) = \{(zero, one), (one, one)\}
graph(F^4(\perp)) = \{(zero, one), (one, one)\}
graph(F^5(\bot)) = \{(zero, one), (one, one)\}
graph(F^6(\bot)) = \{(zero, one), (one, one)\}
```

 $graph(F^7(\bot)) = \{(zero, one), (one, one), (two, one)\}$



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Hence: $(fix F) = \lambda n.one$

Prove:

```
graph(F^{0}(\bot)) = \{\}
graph(F^1(\bot)) = \{(zero, one)\}
graph(F^2(\bot)) = \{(zero, one)\}
graph(F^3(\bot)) = \{(zero, one), (one, one)\}
graph(F^4(\bot)) = \{(zero, one), (one, one)\}
graph(F^5(\perp)) = \{(zero, one), (one, one)\}
graph(F^6(\bot)) = \{(zero, one), (one, one)\}
graph(F^7(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{8}(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{9}(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{10}(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{11}(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{12}(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{13}(\perp)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{14}(\perp)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{15}(\bot)) = \{(zero, one), (one, one), (two, one), (three, one)\}
\forall i, i > 0, graph(F^i(\bot)) = \{(zero, one), (one, one), (two, one), \dots, (i, one)\}
```

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Summary

 $F = \lambda f.\lambda n.n$ equals zero \rightarrow one [] (f(n minus one) plus f(n minus one)) minus one

Prove:

Exponential number of unfoldings are required for this graph:

$$\begin{array}{lcl} \mathit{graph}(F^0(\bot)) & = & \{ \ \} \\ \mathit{graph}(F^i(\bot)) & = & \cup_{k=0}^j \{(k,\mathit{one})\}, \ 2^{j+1}-1 \leq i \leq 2^{j+2}-2, \ j \geq 0 \end{array}$$

• (fix F) = $\lambda n.one$



Unfolding of g (Double) by Simulation

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```
// Project: PoPL 2019. g_double_unfold.cpp, \perp shown as -1
g = \lambda n.n equals zero \rightarrow one [] (g(n minus one) plus g(n minus one)) minus one
COMPUTING LFP of g(n) = n equals zero -> one []
          (g(n minus one) plus g(n minus one)) minus one
g_double(0) = 1 in 1 unfolds
g_double(1) = 1 in 3 unfolds
g double(2) = 1 in 7 unfolds
g_double(3) = 1 in 15 unfolds
g double(4) = 1 in 31 unfolds
g_double(5) = 1 in 63 unfolds
g_double(6) = 1 in 127 unfolds
g_double(7) = 1 in 255 unfolds
g_double(8) = 1 in 511 unfolds
```

This is till 1000 unfolds. g_double(9) gets 1 in 1023 unfolds

g double(9) = -1 in 1000 unfolds



Unfolding of g (Double) by Simulation

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Recursive Definitions

```
// Project: PoPL 2019, g_double_unfold.cpp, \perp shown as -1
// g(n) = n equals zero -> one [] (g(n minus one) plus g(n minus one)) minus one
#include <iostream>
using namespace std:
static unsigned int g_doubleCount = 0, maxUnfoldingLevel;
unsigned int g double(unsigned int x) {
   ++g doubleCount:
    if (g_doubleCount == maxUnfoldingLevel) throw 1;
    if (x == 0) return 1:
    else trv {
            return g_double(x - 1) + g_double(x - 1) - 1;
    } catch (int) { throw; }
}
int g_double_unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false; unsigned int result; ::maxUnfoldingLevel = maxUnfoldingLevel;
    cout << "COMPUTING LFP of g(n)":
    cout << " = n equals zero -> one [] (g(n minus one) plus g(n minus one)) minus one\n";
    for (unsigned int n = 0; n < maxParam; ++n) {
        trv {
            bottom = false: g doubleCount = 0: result = g double(n):
        catch (int) { bottom = true: }
        cout << "g_double(" << n << ") = " << (int)((bottom) ? -1 : result)</pre>
             << " in " << g_doubleCount << " unfolds" << endl;
    cout << endl << endl:
    return 0;
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```



Recursive Functions Definitions: Simultaneous Definition

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Summary

Consider the specifications $f: Nat \rightarrow Nat_{\perp}$ and $g: Nat \rightarrow Nat_{\perp}$:

 $f = \lambda x.x$ equals zero \rightarrow g(zero) [] f(g(x minus one)) plus two

 $g = \lambda y.y$ equals zero \rightarrow zero [] y times f(y minus one)

Build a functional for function pairs as:

$$\textit{F}: ((\textit{Nat} \rightarrow \textit{Nat}_{\perp}) \times (\textit{Nat} \rightarrow \textit{Nat}_{\perp})) \rightarrow ((\textit{Nat} \rightarrow \textit{Nat}_{\perp}) \times (\textit{Nat} \rightarrow \textit{Nat}_{\perp}))$$

 $F = \lambda(f,g).(\lambda x.x \text{ equals zero} \rightarrow g(\text{zero}) [] f(g(x \text{ minus one})) \text{ plus two},$ $\lambda y.y \text{ equals zero} \rightarrow \text{zero} [] y \text{ times } f(y \text{ minus one}))$

Find a pair of functions (α, β) such that $F(\alpha, \beta) = (\alpha, \beta)$



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```
Consider the specifications f: Nat \rightarrow Nat_{\perp} and g: Nat \rightarrow Nat_{\perp}:
f = \lambda x.x equals zero \rightarrow g(zero) [ f(g(x minus one)) plus two
g = \lambda y. y equals zero \rightarrow zero [] y times f(y \text{ minus one})
F = \lambda(f,g).(\lambda x.x \text{ equals zero} \rightarrow g(\text{zero}) [f(g(x \text{ minus one}))] \text{ plus two},
      \lambda y.y equals zero \rightarrow zero [] y times f(y \text{ minus one}))
Using \perp for ((\lambda n, \perp), (\lambda n, \perp))
F^0(\perp) = (\{ \}, \{ \})
F^{1}(\bot) = (\{ \}, \{(zero, zero)\})
F^{2}(\bot) = (\{(zero, zero)\}, \{(zero, zero)\})
F^3(\perp) = (\{(zero, zero)\}, \{(zero, zero), (one, zero)\})
F^4(\perp) = (\{(zero, zero), (one, two)\}, \{(zero, zero), (one, zero)\})
F^5(\perp) = \{\{(zero, zero), (one, two)\}, \{(zero, zero), (one, zero), (two, four)\}\}
F^6(\perp) = (\{(zero, zero), (one, two), (two, two)\}, \{(zero, zero), (one, zero), (two, four)\})
F^{7}(\perp) = \{\{(zero, zero), (one, two), (two, two)\}, \{(zero, zero), (one, zero), (two, four), (three, six)\}\}
\forall i, i > 7, F^{i}(\bot) = F^{7}(\bot)
f = fst(fix F), g = snd(fix F)
```



Unfolding of f & g (Simultaneous) by Simulation

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```
// Project: PoPL 2019, f_g_unfold.cpp, \perp shown as -1
f = \lambda x.x equals zero \rightarrow g(zero) [ f(g(x minus one)) plus two
g = \lambda v.v equals zero \rightarrow zero \prod v times f(v \text{ minus one})
COMPUTING LFP of f g simul
f(x) = x \text{ equals zero->}g(zero) [] f(g(x minus one)) plus two
g(y) = y equals zero -> zero[] y times f(y minus one)
g(0) = 0 in 1 unfolds
g(1) = 0 in 3 unfolds
g(2) = 4 in 5 unfolds
g(3) = 6 in 7 unfolds
g(4) = -1 in 1001 unfolds
g(5) = -1 in 1001 unfolds
g(6) = -1 in 1001 unfolds
g(7) = -1 in 1001 unfolds
g(8) = -1 in 1001 unfolds
g(9) = -1 in 1001 unfolds
f(0) = 0 in 2 unfolds
f(1) = 2 in 4 unfolds
f(2) = 2 in 6 unfolds
f(3) = -1 in 1001 unfolds
f(4) = -1 in 1001 unfolds
f(5) = -1 in 1001 unfolds
f(6) = -1 in 1001 unfolds
f(7) = -1 in 1001 unfolds
f(8) = -1 in 1001 unfolds
f(9) = -1 in 1001 unfolds
```



Unfolding of f & g (Simultaneous) by Simulation

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```
// Project: PoPL 2019, f_g_unfold.cpp, \perp shown as -1
//f(x) = x \text{ equals zero } \Rightarrow g(zero)[] f(g(x minus one)) plus two
//g(y) = y equals zero -> zero[] y times f(y minus one)
#include <iostream>
using namespace std;
static unsigned int fCount = 0, gCount = 0, maxUnfoldingLevel:
unsigned int g(unsigned int x):
//f(x) = x \text{ equals zero } -> g(zero)[] f(g(x minus one)) plus two
unsigned int f(unsigned int x) {
    ++fCount:
    if (fCount + gCount > maxUnfoldingLevel) throw 1;
    if (x == 0) \{ // \text{ return } g(0); 
        try { int t = g(0); return t; }
        catch (int) { throw: }
    else try { int t = g(x - 1); t = f(t); return t + 2; }
        catch (int) { throw: }
//g(y) = y equals zero -> zero[] y times f(y minus one)
unsigned int g(unsigned int x) {
    ++gCount:
    if (fCount + gCount > maxUnfoldingLevel) throw 2;
    if (x == 0) return 0:
    else try { int t = f(x - 1); return x * t; }
        catch (int) { throw; }
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```



Unfolding of f & g (Simultaneous) by Simulation

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```
// Project: PoPL 2019, f_g_unfold.cpp, \perp shown as -1
//f(x) = x \text{ equals zero } \Rightarrow g(zero)[] f(g(x minus one)) plus two
//g(y) = y equals zero -> zero[] y times f(y minus one)
int f g unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false; unsigned int gResult, fResult;
    ::maxUnfoldingLevel = maxUnfoldingLevel;
    cout << "COMPUTING LFP of f_g_simul" << endl;
    cout << "f(x) = x equals zero->g(zero) [] f(g(x minus one)) plus two" << endl;
    cout << "g(v) = v equals zero -> zero[] v times f(v minus one)" << endl:</pre>
    for (unsigned int n = 0; n < maxParam; ++n) {
        try { bottom = false; fCount = gCount = 0; gResult = g(n); }
        catch (int) { bottom = true: }
        cout << "g(" << n << ") = " << (int)((bottom) ? -1 : gResult) << " in "
             << fCount + gCount << " unfolds" << endl;
    cout << endl:
    for (unsigned int n = 0; n < maxParam; ++n) {
        try { bottom = false; fCount = gCount = 0; fResult = f(n); }
        catch (int) { bottom = true; }
        cout << "f(" << n << ") = " << (int)((bottom) ? -1 : fResult) << " in "
             << fCount + gCount << " unfolds" << endl;
    cout << endl << endl:
   return 0:
}
```



Recursive Functions Definitions: Simultaneous Definition

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```
This is the solution given in the book. This is wrong. Consider the specifications f: Nat \rightarrow Nat_{\perp} and g: Nat \rightarrow Nat_{\perp}: f = \lambda x.x equals zero \rightarrow g(zero) [] f(g(x minus one)) plus two g = \lambda y.y equals zero \rightarrow zero [] y times f(y minus one)
```

 $F = \lambda(f,g).(\lambda x.x \text{ equals zero} \rightarrow g(\text{zero}) [] f(g(x \text{ minus one})) \text{ plus two}, \\ \lambda y.y \text{ equals zero} \rightarrow \text{zero} [] y \text{ times } f(y \text{ minus one}))$

```
F^{0}(\bot) = (\{\ \}, \{\ \})
F^{1}(\bot) = (\{\ \}, \{(zero, zero)\})
F^{2}(\bot) = (\{(zero, zero), \{(zero, zero)\})
F^{3}(\bot) = (\{(zero, zero), (one, two)\}, \{(zero, zero), (one, zero)\})
F^{4}(\bot) = (\{(zero, zero), (one, two), (two, two)\}, \{(zero, zero), (one, zero), (two, four)\})
F^{5}(\bot) = (\{(zero, zero), (one, two), (two, two)\}, \{(zero, zero), (one, zero), (two, four), (three, six)\})
\forall i, i > 5, F^{i}(\bot) = F^{5}(\bot)
```

$$f = fst(fix F), g = snd(fix F)$$

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Using \perp for $((\lambda n. \perp), (\lambda n. \perp))$



Recursive Functions Definitions: Simultaneous Definition

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Applicative Language Any finite set of mutually recursive function definitions can be handled in this manner.

 Thus, the least fixed point method is powerful enough to model the most general forms of computation, such as general recursive equation sets and flowcharts.



Unfolding of odd-even by Simulation

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```
// Project: PoPL 2019. odd_even_unfold.cpp. \perp shown as -1
oe = \lambda x.x equals zero \rightarrow one [] (x equals one \rightarrow one [] (odd <math>x \rightarrow oe(x plus one) [] oe(x div two)))
COMPUTING LFP of oe(x) =
x equals zero -> one [] (x equals one -> one [] (odd x -> oe(x plus one) [] oe(x div two)))
odd_even(0) = 1 in 1 unfolds
odd even(1) = 1 in 1 unfolds
odd_even(2) = 1 in 2 unfolds
odd_even(3) = 1 in 4 unfolds
odd even(4) = 1 in 3 unfolds
odd even(5) = 1 in 6 unfolds
odd even(6) = 1 in 5 unfolds
odd even(7) = 1 in 5 unfolds
odd even(8) = 1 in 4 unfolds
odd_even(9) = 1 in 8 unfolds
Hence, oe = \lambda x, one
```



Unfolding of odd-even by Simulation

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Recursive Definitions

```
// Project: PoPL 2019. odd_even_unfold.cpp. \perp shown as -1
// oe(x) = x equals zero -> one [] (x equals one -> one
          [] (odd x -> oe(x plus one) [] oe(x div two)))
#include <iostream>
using namespace std:
static unsigned int odd evenCount = 0. maxUnfoldingLevel:
unsigned int odd_even(unsigned int x) {
    ++odd evenCount:
    if (odd_evenCount == maxUnfoldingLevel) throw 1;
    if (x == 0) return 1:
    else if (x == 1) return 1:
    else if (x % 2) return odd even(x + 1):
    else return odd_even(x / 2);
int odd even unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false; unsigned int result; ::maxUnfoldingLevel = maxUnfoldingLevel;
    cout << "COMPUTING LFP of oe(x) = x equals zero -> one [] (x equals one -> one"
         << "[] (odd x -> oe(x plus one) [] oe(x div two)))" << endl;
    for (unsigned int n = 0; n < maxParam; ++n) {
        try { bottom = false; odd_evenCount = 0; result = odd_even(n); }
        catch (int) { bottom = true: }
        cout << "odd even(" << n << ") = " << (int)((bottom) ? -1 : result) << " in "
             << odd_evenCount << " unfolds" << endl;
    cout << endl << endl;
    return 0:
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```



Unfolding of odd-even (bottom) by Simulation

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```
tim

co = \lambda x.x \ equals \ zero \rightarrow one \ [] \ (odd \ x \rightarrow oe(x \ plus \ one) \ [] \ oe(x \ div \ two))

computing \ LFP \ of \ oe(x) = x \ equals \ zero \rightarrow one \ [] \ (odd \ x \rightarrow oe(x \ plus \ one) \ [] \ oe(x \ div \ two))

codd\_even\_bot(0) = 1 \ in \ 1 \ unfolds

codd\_even\_bot(1) = -1 \ in \ 1000 \ unfolds

codd\_even\_bot(2) = -1 \ in \ 1000 \ unfolds

codd\_even\_bot(3) = -1 \ in \ 1000 \ unfolds

codd\_even\_bot(6) = -1 \ in \ 1000 \ unfolds

codd\_even\_bot(6) = -1 \ in \ 1000 \ unfolds

codd\_even\_bot(7) = -1 \ in \ 1000 \ unfolds

codd\_even\_bot(8) = -1 \ in \ 1000 \ unfolds

codd\_even\_bot(9) = -1 \ in \ 1000 \ unfolds

codd\_even\_bot(9) = -1 \ in \ 1000 \ unfolds

codd\_even\_bot(9) = -1 \ in \ 1000 \ unfolds
```

// Project: PoPL 2019. odd_even_bot_unfold.cpp. \perp shown as -1



Unfolding of odd-even (bottom) by Simulation

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Recursive Definitions

```
// Project: PoPL 2019. odd_even_bot_unfold.cpp. \perp shown as -1
// oe(x) = x equals zero -> one [] (odd x -> oe(x plus one) [] oe(x div two))
#include <iostream>
using namespace std;
static unsigned int odd even botCount = 0. maxUnfoldingLevel:
unsigned int odd_even_bot(unsigned int x) {
    ++odd_even_botCount;
    if (odd even botCount == maxUnfoldingLevel) throw 1:
    if (x == 0) return 1:
    else if (x % 2) return odd_even_bot(x + 1);
    else return odd even bot(x / 2):
}
int odd even bot unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false: unsigned int result: ::maxUnfoldingLevel = maxUnfoldingLevel:
    cout << "COMPUTING LFP of oe(x) = x equals zero -> one "
         << "[] (odd x -> oe(x plus one) [] oe(x div two))" << endl:</pre>
    for (unsigned int n = 0; n < maxParam; ++n) {
        try { bottom = false; odd_even_botCount = 0; result = odd_even_bot(n); }
        catch (int) { bottom = true: }
        cout << "odd even bot(" << n << ") = " << (int)((bottom) ? -1 : result) << " in "
             << odd even botCount << " unfolds" << endl:
    cout << endl << endl:
    return 0:
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```



Unfolding of Simple Simultaneous by Simulation

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Summary

```
// Project: PoPL 2019, f_g_simple_unfold.cpp, \perp shown as -1
f = \lambda x.x equals zero \rightarrow g(zero) [ ] f(g(x)) plus two
g = \lambda v.v equals zero \rightarrow zero \prod v times f(v)
COMPUTING LFP of f g simple
f(x) = x \text{ equals zero->} g(zero)[] f(g(x)) plus two
g(y) = y equals zero -> zero [] y times f(y)
g s(0) = 0 in 1 unfolds
g_s(1) = -1 in 1001 unfolds
g_s(2) = -1 in 1001 unfolds
g s(3) = -1 in 1001 unfolds
g_s(4) = -1 in 1001 unfolds
g_s(5) = -1 in 1001 unfolds
g s(9) = -1 in 1001 unfolds
f s(0) = 0 in 2 unfolds
f s(1) = -1 in 1001 unfolds
f s(2) = -1 in 1001 unfolds
f_s(3) = -1 in 1001 unfolds
f s(4) = -1 in 1001 unfolds
f_s(5) = -1 in 1001 unfolds
f s(9) = -1 in 1001 unfolds
```

Hence, $f = g = \lambda x.x$ equals zero \rightarrow zero $\uparrow \downarrow$



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Summary

```
// Project: PoPL 2019, f_g_simple_unfold.cpp, \perp shown as -1
//f(x) = x \text{ equals zero } \Rightarrow g(zero) [] f(g(x)) plus two
//g(y) = y \text{ equals zero } \Rightarrow \text{zero } [] y \text{ times } f(y)
#include <iostream>
using namespace std;
static unsigned int fCount = 0, gCount = 0, maxUnfoldingLevel;
unsigned int g s(unsigned int x):
//f = x:x = quals zero -> g(zero) [] f(g(x)) plus two
unsigned int f s(unsigned int x) {
    ++fCount:
    if (fCount + gCount > maxUnfoldingLevel) throw 1;
    if (x == 0)  { // return g(0):
        try { int t = g_s(0); return t; }
        catch (int) { throw; }
    else trv { int t = g s(x): t = f s(t): return t + 2: }
        catch (int) { throw: }
//g = y : y equals zero -> zero [] y times f(y)
unsigned int g_s(unsigned int x) {
    ++gCount;
    if (fCount + gCount > maxUnfoldingLevel) throw 2:
    if (x == 0) return 0:
    else try { int t = f_s(x); return x * t; }
        catch (int) { throw: }
}
```



Unfolding of Simple Simultaneous by Simulation

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Summary

```
// Project: PoPL 2019, f_g_simple_unfold.cpp, \perp shown as -1
//f(x) = x \text{ equals zero } \Rightarrow g(zero) [] f(g(x)) plus two
//g(y) = y \text{ equals zero } \Rightarrow \text{zero } [] y \text{ times } f(y)
int f_g_simple_unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false; unsigned int gResult, fResult;
    ::maxUnfoldingLevel = maxUnfoldingLevel;
    cout << "COMPUTING LFP of f_g_simple" << endl;
    cout << "f(x) = x equals zero->g(zero)[] f(g(x)) plus two" << endl;
    cout << "g(v) = v equals zero -> zero [] v times f(v)" << endl:
    for (unsigned int n = 0; n < maxParam; ++n) {
        try { bottom = false; fCount = gCount = 0; gResult = g_s(n); }
        catch (int) { bottom = true: }
        cout << "g s(" << n << ") = " << (int)((bottom) ? -1 : gResult) << " in "
             << fCount + gCount << " unfolds" << endl;
    cout << endl:
    for (unsigned int n = 0; n < maxParam; ++n) {
        try { bottom = false; fCount = gCount = 0; fResult = f_s(n); }
        catch (int) { bottom = true; }
        cout << "f_s(" << n << ") = " << (int)((bottom) ? -1 : fResult) << " in "
             << fCount + gCount << " unfolds" << endl;
    cout << endl << endl:
    return 0:
}
```



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Summary

Specification of the semantics of while loop:

 $C[[\text{while } B \text{ do } C]] = \underline{\lambda} s.B[[B]]s \rightarrow C[[\text{while } B \text{ do } C]](C[[C]]s) [] s$

In terms of fix operations:

 $C[[while B do C]] = fix(\lambda f.\underline{\lambda}s.B[[B]]s \rightarrow f(C[[C]]s)[]s)$

The functional is $Store_{\perp} \rightarrow Store_{\perp}$, where $Store = Id \rightarrow Nat$



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Let us unfold the loop C[[while A > 0 do (A := A - 1; B := B + 1)]] and capture the transformation to the $Store_{\perp}$ at every stage. The functional is:

$$F = \lambda f \underline{\lambda} s.test \ s \rightarrow f(adjust \ s) \ [] \ s$$

where test = B[[A>0]] and adjust = C[[A:=A-1;B:=B+1]]. To unfold the functional of the while loop, we need to compute on the store s. Let us assume that initially the store is: $s_0 = \lambda i.zero$ That is, all identifiers are initialized to 0. Additionally, we may assume that before entry to the loop, the store may have been changed (for A, B, as well as other identifiers) to s_{loop_start} , where A and B may have any pair of Nat values that will impact the computation of F^i . Now only identifiers A and B are involved in the computation of F^i . Hence, at some stage of the loop if A has value a and B has value b, the store is:

$$s=\lambda i.i$$
 equals $A o a$ [] i equals $B o b$ [] s_{loop_start}

For the purpose of computation of F^i , we can represent this s as a pair (a,b) that actually stands for an infinite class of mappings for s as given by all possible mappings for s_{loop_start} . We enumerate all such pairs (a,b) at every loop entry and loop exit during unfolding.



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Summary

Let us unfold the loop C[[while A>0 do (A:=A-1;B:=B+1)]] and capture the transformation to the $Store_{\perp}$ at every stage. The functional is: $F=\lambda f.\underline{\lambda}s.test\ s \rightarrow f(adjust\ s)\ []\ s$, where test=B[[A>0]] and adjust=C[[A:=A-1;B:=B+1]]

 \rightarrow_1

 \rightarrow_2

 \rightarrow_3

On loop Entry

0,0	0,1	0,2	0,3	0,4		
1,0	1,1	1,2	1,3	1,4		
2,0	2,1	2,2	2,3	2,4		
3,0	3,1	3,2	3,3	3,4		
4,0	4,1	4,2	4,3	4,4		

ſ	0,0	0,1	0,2	0,3	0,4
Ì	1,0	1,1	1,2	1,3	1,4
Ī	2,0	2,1	2,2	2,3	2,4
ſ	3,0	3,1	3,2	3,3	3,4
r	4.0	4.1	4.2	12	4.4

0,0	0,1	0,2	0,3	0,4
1,0	1,1	1,2	1,3	1,4
2,0	2,1	2,2	2,3	2,4
3,0	3,1	3,2	3,3	3,4
4,0	4,1	4,2	4,3	4,4

0,0	0,1	0,2	0,3	0,4
1,0	1,1	1,2	1,3	1,4
2,0	2,1	2,2	2,3	2,4
3,0	3,1	3,2	3,3	3,4
4,0	4,1	4,2	4,3	4,4

On loop Exit

(A, D)						
		1	Т			
	1	Ι Τ				
		Т				
		1				
	1	Ι Τ		T		

0,0	0,1	0,2	0,3	0,4
1	Τ.	Τ.	1	Ι Τ
1	Τ.	Τ.	Τ.	1
		T	1	Т

[0,0	0,1	0,2	0,3	0,4
Ì	0,1	0,2	0,3	0,4	0,5
Ī					T
ĺ			1		
ı					

0,0	0,1	0,2	0,3	0,4
0,1	0,2	0,3	0,4	0,5
0,2	0,3	0,4	0,5	0,6
		1		

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```
Consider: C[[while A > 0 do (A := A - 1; B := B + 1)]]
Let test = B[[A > 0]] and adjust = C[[A := A - 1; B := B + 1]]
```

The functional is: $F = \lambda f \underline{\lambda} s.test \ s \rightarrow f(adjust \ s)$ [] s

```
\begin{split} & \textit{graph}(F^0(\bot)) = \{\} \\ & \textit{graph}(F^1(\bot)) = \{ \\ & (\{([[A]], \textit{zero}), ([[B]], \textit{zero}), \cdots\}, \{([[A]], \textit{zero}), ([[B]], \textit{zero}), \cdots\}), \cdots, \\ & (\{([[A]], \textit{zero}), ([[B]], \textit{four}), \cdots\}, \{([[A]], \textit{zero}), ([[B]], \textit{four}), \cdots\}), \cdots \} \end{split}
```

Since the result is a member of $Store_{\perp} \to Store_{\perp}$, $graph(F^1(\perp))$ contains pairs of function graphs. Each pair shows a store prior to its *loop entry* and the store after *loop exit*. The members shown in the graph at this step are those stores whose [[A]] value equals zero. Thus, those stores that already map [[A]] to zero fail the test upon loop entry and exit immediately. The store is left unchanged. Those stores that require loop processing are mapped to \perp .

```
\begin{split} & graph(F^2(\bot)) = \{ \\ & \{ ([[A]], zero), ([[B]], zero), \cdots \}, \{ ([[A]], zero), ([[B]], zero), \cdots \} ), \cdots, \\ & \{ ([[A]], zero), ([[B]], four), \cdots \}, \{ ([[A]], zero), ([[B]], four), \cdots \} ), \cdots, \\ & \{ ([[A]], one), ([[B]], zero), \cdots \}, \{ ([[A]], zero), ([[B]], one), \cdots \} ), \cdots, \\ & \{ (([A]], one), ([[B]], four), \cdots \}, \{ (([A]], zero), ([[B]], five), \cdots \} ), \cdots \} \end{split}
```



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```
\begin{split} & \textit{graph}(F^2(\bot)) = \{ \\ & (\{([[A]], \textit{zero}), ([[B]], \textit{zero}), \cdots\}, \{([[A]], \textit{zero}), ([[B]], \textit{zero}), \cdots\}), \cdots, \\ & (\{([[A]], \textit{zero}), ([[B]], \textit{four}), \cdots\}, \{([[A]], \textit{zero}), ([[B]], \textit{four}), \cdots\}), \cdots, \\ & (\{([[A]], \textit{one}), ([[B]], \textit{zero}), \cdots\}, \{([[A]], \textit{zero}), ([[B]], \textit{one}), \cdots\}), \cdots, \\ & (\{([[A]], \textit{one}), ([[B]], \textit{four}), \cdots\}, \{([[A]], \textit{zero}), ([[B]], \textit{five}), \cdots\}), \cdots \} \end{split}
```

Those input stores that require one or fewer iterations to process appear in the graph. For example, the fourth illustrated pair denotes a store that has [[A]] set to one and [[B]] set to four upon loop entry. Only one iteration is needed to reduce [[A]] down to zero, the condition for loop exit. In the process [[B]] is incremented to five:

```
\begin{split} & graph(F^3(\bot)) = \{ \\ & (\{([[A]], zero), ([[B]], zero), \cdots\}, \{([[A]], zero), ([[B]], zero), \cdots\}), \cdots, \\ & (\{([[A]], zero), ([[B]], four), \cdots\}, \{([[A]], zero), ([[B]], four), \cdots\}), \cdots, \\ & (\{([[A]], one), ([[B]], zero), \cdots\}, \{([[A]], zero), ([[B]], one), \cdots\}), \cdots, \\ & (\{([A]], one), ([[B]], four), \cdots\}, \{([[A]], zero), ([[B]], five), \cdots\}), \cdots, \\ & (\{([A]], two), ([[B]], zero), \cdots\}, \{([[A]], zero), ([[B]], two), \cdots\}), \cdots, \\ & (\{([A]], two), ([[B]], four), \cdots\}, \{([[A]], zero), ([[B]], six), \cdots\}), \cdots \} \end{split}
```



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```
\begin{split} & graph(F^3(\bot)) = \{\\ & (\{([[A]], zero), (([[B]], zero), \cdots\}, \{(([[A]], zero), (([[B]], zero), \cdots\}), \cdots, \\ & (\{([[A]], zero), (([[B]], four), \cdots\}, \{(([[A]], zero), (([[B]], four), \cdots\}), \cdots, \\ & (\{([[A]], one), (([[B]], zero), \cdots\}, \{(([[A]], zero), (([[B]], one), \cdots\}), \cdots, \\ & (\{([[A]], one), (([[B]], four), \cdots\}, \{(([[A]], zero), (([[B]], two), \cdots\}), \cdots, \\ & (\{([[A]], two), (([[B]], zero), \cdots\}, \{(([[A]], zero), (([[B]], six), \cdots\}), \cdots\} \end{split}
```

All stores that require two iterations or less for processing are included in the graph. The $graph(F^{i+1}(\bot))$ contains those pairs whose input stores finish processing in i iterations or less. The least fixed point of the functional contains mappings for those stores that conclude their loop processing in a finite number of iterations



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Language with Contexts Block Structured Language Applicative Language The while-loop's semantics makes a good example for restating the important principle of least fixed point semantics:

The meaning of a recursive specification is totally determined by the meanings of its finite subfunctions. Each subfunction can be represented non-recursively in the function notation.

In this case:

The family of expressions makes apparent that iteration is an unwinding of a loop body; this corresponds to the operational view.



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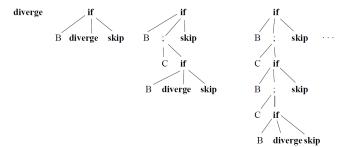
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Can we restate this idea even more directly? Recall that C[[diverge]] = $\lambda s. \perp$. Substituting the commands into the set just constructed gives us:

```
C[[while B do C]] = \sqcup {C[[diverge]],
C[[if B then diverge else skip]],
C[[if B then (C; if B then diverge else skip) else skip]],
C[[if B then (C; if B then
(C; if B then diverge else skip) else skip) else skip]], \cdots}
```

A family of finite non-iterative programs represents the loop. It is easier to see what is happening by drawing the abstract syntax trees:





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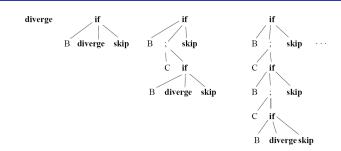
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At each stage, the finite tree becomes larger and better defined. The obvious thing to do is to place a partial ordering upon the trees: for all commands C, diverge $\sqsubseteq C$, and for commands C_1 and C_2 , $C_1 \sqsubseteq C_2$ iff C_1 and C_2 are the same command type (have the same root node) and all subtrees in C_1 are less defined than the corresponding trees in C_2 . This makes families of trees like the one above into chains. What is the lub of such a chain? It is the infinite tree corresponding to:

if B then (C; if B then (C; if B then (C; \cdots) else skip) else skip)



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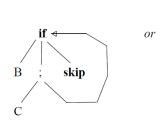
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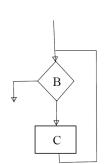
Draw this tree, and define L = if B then (C; L) else skip.

The while-loop example has led researchers to study languages that contain infinite programs that are represented by recursive definitions, such as L. The goal of such studies is to determine the semantics of recursive and iterative constructs by studying their circularity at the syntax level. The fundamental discovery of this research is that, whether the recursion is handled at the syntax level or at the semantics level, the result is the same:

$$C[[while B do C]] = C[[L]]$$

Finally, the infinite tree L is abbreviated:







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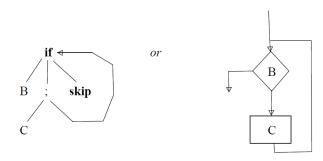
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Summarv



Every flowchart loop can be read as an abbreviation for an infinite program. This brings us back to representations of functions again, for the use of finite loops to represent infinite flowcharts parallels the use of finite function expressions to denote infinite objects – functions. The central issue of computability theory might be stated as the search for finite representations of infinite objects.



Recursive Functions Definitions: End Sem 2019-20

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Recursive Definitions

Consider a recursive definition $h: Nat \rightarrow Nat$ as:

 $h = \lambda n$. (n mod two) equals zero \rightarrow zero

[] (n mod three) equals zero \rightarrow one [] h(h(n minus one) mult h(n plus two))

Compute the first 9 finite unfoldings for h.

2 Formulate the functional F for h such that F(h) = h.

Resolve h as fix(F).

4 Using extensionality prove that g = h where $g : Nat \rightarrow Nat$ is a

non-recursive definition:

 $g = \lambda n$. ((n minus three) mod six) equals zero \rightarrow one [] zero

[9]

[2]

[1]

[3]



Recursive Functions Definitions:

End Sem 2019-20

Consider a recursive definition $h \cdot Nat \rightarrow Nat$ as:

Clearly, $domain(G_1 \cup G_2 \cup G_3 \cup G_4) = Nat$

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Now let us construct the following functions from h: $h^1 = \lambda n$. (n mod two) equals $zero \rightarrow zero$ [] \bot $h^2 = \lambda n$. (n mod two) equals $zero \rightarrow zero$ [] (n mod three) equals $zero \rightarrow zero$ [] \bot Clearly, $graph(h^1) = G_1$ and $graph(h^2) = G_1 \cup G_2$

Now we are ready to unfold h:

 $(i-5) \mod 6 = 0$

$$\begin{array}{l} h_0 = \{ \ \} \\ h_1 = h_2 = h_3 = G_1 \ \cup \ G_2 \\ h_4 = h_5 = h_6 = G_1 \ \cup \ G_2 \ \cup \ G_3 \\ h_7 = G_1 \ \cup \ G_2 \ \cup \ G_3 \ \cup \ G_4 \end{array}$$

As $domain(G_1 \cup G_2 \cup G_3 \cup G_4) = Nat, h_i = h_7, \forall i \geq 7.$



Recursive Functions Definitions: **End Sem 2019-20**

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Consider a recursive definition $h: Nat \rightarrow Nat$ as:

 $h = \lambda n$. (n mod two) equals zero \rightarrow zero

[] (n mod three) equals zero \rightarrow one [] h(h(n minus one) mult h(n plus two))

|| h(h(n minus one) mult h(n plus two))

1 Formulate the functional F for h such that F(h) = h.

 $F = \lambda f$. λn . (n mod two) equals zero \rightarrow zero [] (n mod three) equals zero \rightarrow one

[] f(f(n minus one) mult f(n plus two))

2 Resolve h as fix(F).

From unfolding we get: $g = h_7 = (F \ g) = (F \ h_7) = (F \ h) = fix(F)$

Simplifying for G_1 , G_2 , G_3 , and G_4 , we get: $g = \lambda n$. ($n \mod two$) equals $zero \rightarrow zero$

 $[] ((n minus three) mod six) equals zero \rightarrow one$

Simplifying on remainders while dividing with 6, we get: $g = \lambda n$. ((n minus three) mod six) equals zero \rightarrow one [] zero

③ Using extensionality prove that g = h where $g : Nat \rightarrow Nat$ is a non-recursive definition: $g = \lambda n$. ((n minus three) mod six) equals zero \rightarrow one [] zero

We have: g = (F g) = fix(F) = (F h) = h

[3]

[2]



Recursive Functions Definitions: **End Sem 2019-20: Simulation**

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Summar

```
// h(n) = (n mod two) equals zero -> zero
//
       [] (n mod three) equals zero -> one
          [] h(h(n minus one)) mult h(n plus two))
//
#include <iostream>
using namespace std;
static unsigned int h_Count = 0, maxUnfoldingLevel;
unsigned int h(unsigned int x) { ++h Count: int result = 0:
    if (h Count == maxUnfoldingLevel) throw 1;
    if (x % 2 == 0) return 0: // else if (x == 1) return 1:
    else if (x % 3 == 0) return 1:
    else try { return h(h(x - 1) * h(x + 2)); }
    // What happens for else try { return h(h(x - 1) * h(x + 6)); }
    catch (int) { throw: }
int modulo_six_unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false: unsigned int result: ::maxUnfoldingLevel = maxUnfoldingLevel:
    cout << "COMPUTING LFP of h(n) = (n mod two) equals zero -> zero"
         << "[] (n mod three) equals zero -> one"
         << "[] h(h(n minus one)) mult h(n plus two))" << endl:
    for (unsigned int n = 0: n < maxParam: ++n) {
        try { bottom = false; h_Count = 0; result = h(n); }
        catch (int) { bottom = true: }
        cout << "h(" << n << ") = " << (int)((bottom) ? -1 : result)
             << " in " << h Count << " unfolds" << endl:
    cout << endl << endl:
    return 0;
```



Recursive Functions Definitions:

Bonus

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Recursive Definitions

Consider a recursive definition $h: Nat \rightarrow Nat_{\perp}$ as:

 $h = \lambda n$. (n mod two) equals zero \rightarrow zero [] (n mod three) equals zero \rightarrow one

[] h(h(n minus one) mult h(n plus k))

• What is the smallest value of k for which h maps to \perp for some values of n?

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For k = 6

 $h = \lambda n$. (n mod two) equals zero \rightarrow zero [] (n mod three) equals zero \rightarrow one [] \perp



Language with Contexts

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Language with Contexts

• Languages rely on notions of context which influences the meanings of phrases - attributes meanings to identifiers

Programming language contexts can have different notions

Store as Context

Store establishes the context for a phrase - but it does suggest that the context within the block is constantly changing which is counter-intuitive. Surely the declarations of the identifiers X and Y establish the context of the block, and the commands within the block operate within that context

begin

end

```
integer X; integer Y;
Y:=0; // X = bot, Y = 0
X := Y; // X = 0, Y = 0
Y:=1: // X = 0, Y = 1
X:=Y+1 // X = 2, Y = 1
```

Block as Context

The meaning of an identifier is not just its storeable value. There are two definitions of X outer (inner) is an integer (real) object. Any ambiguity in using X is handled by the scope rules. These are actually computer storage locations, and the primary meaning of an identifier is the location bound to it

```
begin integer X;
    X := 0:
                  // integer X
    begin real X;
        X:=1.5
                  // real X
    end:
    X := X + 1
                  // integer X
end
```



Language with Contexts: Environment

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Summary

The context we choose to use is

- the set of identifier and storage location pairs that are
 - accessible at a textual position

Each position in the program

- resides within a unique context, and
- the context can be determined without running the program



Language with Contexts: Environment

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Language with Contexts Block Structured Language Applicative Language In denotational semantics, the context of a phrase is modeled by a value called an **environment**. Environments possess several distinctive properties:

- An environment establishes a context for a syntactic phrase, resolving any ambiguities concerning the meaning of identifiers.
- There are as many environment values as there are distinct contexts in a program. Multiple environments may be maintained during program evaluation.
- An environment is (usually) a static object. A phrase uses the same environment each time it is evaluated with the store.



Language with Contexts: Environment & Store

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Language with Contexts

 An environment argument was not needed for the languages so far, because the programs in the languages used exactly one environment

- The single environment was pasted onto the store, giving a map from identifiers to storable values.
- Now, that simple model is split apart into two separate components:
 - the environment and
 - the store



Language with Contexts: Symbol Table

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Block Structured

Block Structured Language Applicative Languag The primary real-life example of an environment is a compiler's symbol table used to translate a source program into compiled code

- The symbol table contains an entry for each identifier in the program, listing:
 - the identifier's data type,
 - its mode of usage (variable, constant, parameter, . . .), and
 - its relative location in the run-time computer store
- Since a block-structured language allows multiple uses of the same identifier, the symbol table is responsible for resolving naming conflicts.



Language with Contexts: Symbol Table

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Language with Contexts Block Structured Language The schemes for implementation are many:

- one is to keep a different symbol table for each block of the program (the portions in common between blocks may be shared);
- another is to build the table as a single stack, which is incremented and decremented upon respective entry and exit for a block.
- Symbol tables may be
 - compile-time objects, as in ALGOL68, standard Pascal, C, C++, or
 - run-time objects, as in SNOBOL4, LISP or
 - used in both phases, as in ALGOL60, Java, Python



Language with Contexts: Static & Dynamic Semantics

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Language with Contexts Block Structured Language Applicative Language Those portions of a semantics definition that use an environment to resolve context questions are sometimes called the Static Semantics

- The term traditionally describes compile-time actions such as type-checking, scope resolution, and storage calculation
- Static semantics may be contrasted with the *real* production of meaning, which takes the name **Dynamic** Semantics
 - Code generation and execution comprise the implementation-oriented version of dynamic semantics
- In general, the separation of static from dynamic semantics is rarely clear cut, and will be skipped here



Language with Contexts: Commands

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Language with Contexts Block Structured Language Applicative Language Environments are used as arguments by the valuation functions. The meaning of a command is now determined by the function:

 $C: Command \rightarrow Environment \rightarrow Store \rightarrow Store_{\perp}$

instead of the earlier:

 $C: Command \rightarrow Store \rightarrow Store_{\perp}$

- The meaning of a command as a Store → Store
 function is determined once an environment establishes the context for the command.
- An environment belongs to the domain:

 $Environment = Identifier \rightarrow Denotable_value$

- The Denotable_value domain contains all the values that identifiers may represent.
- This domain varies widely from language to language and its structure largely determines the character of the language



Language with Contexts: Block-structured and Applicative languages

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Language with Contexts Block Structured

Block Structured Language Applicative Language We study language features whose semantics are understood in terms of environments

- These features include:
 - declarations,
 - block structure,
 - scoping mechanisms,
 - recursive bindings, and
 - compound data structures
- The concepts are covered within the framework of two languages:
 - an imperative block-structured language and
 - an applicative language



Block Structured Language: Abstract Syntax

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Abstract Syntax:

• $P \in Program$

 $K \in Block$

 $D \in Declaration$

 $C \in Command$

 $E \in Expression$

 $B \in Boolean_expr$

 $I \in Identifier$

N ∈ *Numeral*

P ::= K.

K ::= begin D; C end

 $D ::= D_1$; $D_2 \mid \text{const } I = N \mid \text{var } I$

 $C ::= C_1; \ C_2 \mid I := E \mid \text{ while } B \text{ do } C \mid K$

 $E ::= E_1 + E_2 \mid I \mid N$

 $B ::= E_1 = E_2 \mid \neg B$



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Semantic Algebras:

Truth values

Domain: $t \in Tr = B$

Operations:

true, false: Tr not: $Tr \rightarrow Tr$

Natural Numbers

Domain: $n \in Nat = \mathcal{N}$

Operations:

zero, one, ... : Nat

plus : Nat \times Nat \rightarrow Nat equals : Nat \times Nat \rightarrow Tr

Identifiers

Domain: $i \in Id = Identifier$



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Summary

Expressible value

Domain: $x \in Expressible_value = Nat + Errvalue$ where Errvalue = Unit

- Expressible value errors occur when an expressible value is inappropriately used
- For example, a truth value is added to a natural number expression



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Summar

Storage Location

Domain: $I \in Location$

Operations:

first_locn : Location

 $next_locn : Location \rightarrow Location$

equal_locn : Location \rightarrow Location \rightarrow Tr lessthan_locn : Location \rightarrow Location \rightarrow Tr

- first_locn is a constant, marking the first usable location in a store
- next_locn maps a location to its immediate successor in a store
- equal_locn checks for equality of two values, and
- lessthan_locn compares two locations and returns a truth value based on the locations' relative values



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Denotable values
 Domain:

 $d \in Denotable_value = Location + Nat + Errvalue$ where Errvalue = Unit

- Of the three components of the *Denotable_value* domain:
 - Location holds the denotations of variable identifiers,
 - Nat holds the meanings of constant identifiers, and
 - Errvalue holds the meaning for undeclared identifiers
- Since the Denotable_value domain contains both natural numbers and locations, denotable value errors may occur in a program; for example, an identifier with a number denotation might be used where an identifier with a location denotation is required
- An identifier with an erroneous denotable value always induces an error



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```
    Environment: a map to denotable values and the
maximum store location
    Domain:
```

 $e \in Environment = (IdB \rightarrow Denotable_value) \times Location$ Operations:

```
emptyenv : Location \rightarrow Environment
emptyenv = \lambda I.((\lambda I.inErrvalue()), I)
accessenv : Id \rightarrow Environment \rightarrow Denotable_value
accessenv = \lambda i.\lambda(map, I).map(i)
```

 $updateenv: Id \rightarrow Denotable_value \rightarrow$ $Environment \rightarrow Environment$

$$updateenv = \lambda i.\lambda d.\lambda (map, l).([i \mapsto d]map, l)$$

reserve_locn : Environment
$$\rightarrow$$
 (Location \times Environment) reserve_locn = λ (map, I).(I, (map, next_locn(I)))

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Block Structured

- An environment is a pair
 - The first component is the function that maps identifiers to their denotable values
 - The second component is a location value, which marks the extent of the store reserved for declared variables
- The environment takes the responsibility for assigning locations to variables. This is done by the reserve_locn operation, which returns the next usable location
- Although it is not made clear by the algebra, the structure of the language will cause the locations to be used in a stack-like fashion
- The *emptyenv* must be given the location marking the beginning of usable space in the store so that it can build the initial environment



Block Structured Language: Semantic Algebras

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Storable values

Domain: $v \in Storable_value = Nat$

Store

Domain: $s \in Store = Location \rightarrow Storable_value$ Operations:

 $access: Location \rightarrow Store \rightarrow Storable_value$

 $access = \lambda(I, s).s(i)$

 $update : Location \rightarrow Storable_value \rightarrow Store \rightarrow Store$ $update = \lambda(I, v, s).[I \mapsto v]s$

- The store is a map from storage locations to storable values, and the operations are the obvious ones
- Errors during evaluation are possible, so the store will be labeled with the status of the evaluation
- The check operation uses the tags to determine if evaluation should continue



Block Structured Language: Semantic Algebras

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```
    Run-time store, labeled with status of computation

   Domain: p \in Poststore = OK + Err
   where OK = Err = Store
   Operations:
   return : Store \rightarrow Poststore
     return = \lambda s.inOK(s)
   signalerr: Store \rightarrow Poststore
     signalerr = \lambda s.inErr(s)
   check: (Store \rightarrow Poststore_{\perp}) \rightarrow
             (Poststore_{\perp} \rightarrow Poststore_{\perp})
      check f = \lambda p. cases p of
         isOK(s) \rightarrow (f \ s) \ [] \ isErr(s) \rightarrow p \ end
```



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Summa

Valuation Functions:

• P: Program \rightarrow Location \rightarrow Store \rightarrow Poststore $_{\perp}$

$$P[[K.]] = \lambda I.K[[K]]$$
 (emptyenv I)

- The P valuation function requires a store and a location value, the latter marking the beginning of the store's free space
- K: Block \rightarrow *Environment* \rightarrow *Store* \rightarrow *Poststore*

$$K[[begin D; C end]] = \lambda e.C[[C]](D[[D]]e)$$

• The K function establishes the context for a block



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Valuation Functions:

• D: Declaration → *Environment* → *Environment*

$$D[[D_1; D_2]] = D[[D_2]] \circ D[[D_1]]$$

- The D function augments an environment
- The composition of declarations parallels the composition of commands

$$D[const \ I = N]] = updateenv \ [[I]] \ inNat(N[[N]]) \ e$$

 A constant identifier declaration causes an environment update, where the identifier is mapped to its numeral value in the environment



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Summary

Valuation Functions:

• D: Declaration \rightarrow *Environment* \rightarrow *Environment*

$$D[var I]] = \lambda e.let(I', e') =$$

$$(reserve_locn e) in (updateenv [[I]] inLocation(I') e')$$

- The denotation of a variable declaration is more involved: a new location is reserved for the variable
- This location, I', plus the current environment, e', are used to create the environment in which the variable [[I]] binds to inLocation(I')
- What happens on duplicate declaration of the same identifier in the same block?



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Valuation Functions:

• C: Command \rightarrow Environment \rightarrow Store \rightarrow Poststore $_{\perp}$

$$C[[C_1; C_2]] = \lambda e.(check(C[[C_2]]e)) \circ (C[[C_1]]e)$$

- First, consider the *check* operation. If command C[[C₁]]e maps a store into an erroneous *Poststore*, then *check* traps the error and prevents C[[C₂]]e from altering the store
- Note that the commands [[C₁]] and [[C₂]] are both evaluated in the context represented by e. This is important, for [[C₁]] could be a block with local declarations that would need its own local environment to process its commands while C[[C₂]] retains its own copy of e. (Of course, whatever alterations C[[C₁]]e makes upon the store are passed to C[[C₂]]e.)
- This language feature is called static scoping. The context for a
 phrase in a statically scoped language is determined solely by the
 textual position of the phrase and any identifier declared within a
 block may be referenced only by the commands within that block
- Dynamically scoped languages, whose contexts are not totally determined by textual position, will be discussed later.



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Valuation Functions:

• C: Command \rightarrow Environment \rightarrow Store \rightarrow Poststore_ \perp

```
C[[I := E]] = \lambda e.\lambda s. cases (accessenv [[I]] e) of isLocation(I) <math>\rightarrow (cases(E[[E]]e s) of isNat(n) \rightarrow (return(update I n s))
[] isErrValue() \rightarrow (signalerr s) end)
[] isNat(n) \rightarrow (signalerr s)
[] isErrValue() \rightarrow (signalerr s) end
```

 Note that, if identifier I has not been declared in this environment, then accessenv will return a Errvalue as the Denotational_value. On this, a signalerr is rightly done putting the store s as Err



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Summar

Valuation Functions:

• C: Command \rightarrow Environment \rightarrow Store \rightarrow Poststore $_{\perp}$

C[[while
$$B$$
 do C]] = $\lambda e. fix(\lambda f. \lambda s. cases (B[[B]]e s) of is Tr(t) \rightarrow (t \rightarrow (check \ f) \circ (C[[C]]e) \ [] return)(s)$
[] $is Err Value(I) \rightarrow (signalerr \ s) \ end)$

$$C[[K]] = K[[K]]$$



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Summary

Valuation Functions:

• E:

 $\mathsf{Expression} {\to} \ \mathit{Environment} \ {\to} \ \mathit{Store} \ {\to} \ \mathit{Expressible_value}$

```
egin{aligned} & \mathsf{E}[[E_1 + E_2]] = \lambda e.\lambda s. cases \ & \mathsf{E}[[E_1]] e \ s) \ of \ & \mathsf{isNat}(n_1) 
ightarrow (cases \ & \mathsf{E}[[E_2]] e \ s) \ of \ & \mathsf{isNat}(n_2) 
ightarrow \mathsf{inNat}(n_1 \ \mathsf{plus} \ n_2) \ & \mathsf{[]} \ \mathsf{isErrvalue}() 
ightarrow \mathsf{inErrvalue}() \ end \ & \mathsf{[]} \ \mathsf{isErrvalue}() 
ightarrow \mathsf{inErrvalue}() \ end \end{aligned}
```

$$\mathsf{E}[[I]] = \lambda e.\lambda s. cases \ (accessenv \ [[I]] \ e) \ of \ isLocation(I)
ightarrow inNat(access \ I \ s) \ [] \ isNat(n)
ightarrow inNat(n) \ [] \ isErrValue()
ightarrow inErrvalue() \ end$$

$$\underset{\mathsf{PoPL-08}}{\mathsf{E}}[[\mathsf{N}]] = \lambda e.\lambda s. \mathit{inNat}(\underbrace{\mathsf{N}[[\mathsf{N}]])}_{\mathsf{Partha}})_{\mathsf{Pratim}}$$



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Valuation Functions:

• B : $Boolean_expr \rightarrow Environment \rightarrow Store \rightarrow (Tr + Errvalue)$

$$\mathsf{B}[[E_1 = E_2]] = \lambda e.\lambda s. cases \ (\mathsf{E}[[E_1]] e \ s) \ of$$
 $[] \ isNat(n_1) \rightarrow (cases \ (\mathsf{E}[[E_2]] e \ s) \ of$
 $isNat(n_2) \rightarrow inTr(n_1 \ equals \ n_2)$
 $[] \ isErrvalue() \rightarrow inErrvalue() \ end)$
 $[] \ isErrvalue() \rightarrow inErrvalue() \ end$

$$B[[\neg B]] = \lambda e.\lambda s. cases (B[[B]]e s) of$$

 $[] isTr(t) \rightarrow inTr(not t)$
 $[] isErrvalue() \rightarrow inErrvalue() end$

• N : Numeral \rightarrow Nat (omitted)



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Summary

Perform the valuation for:

P[[begin D_0 ; D_1 ; C_0 end]] where

 $D_0 = \operatorname{const} A = 1$

 $D_1 = \operatorname{var} X$

 $C_0 = C1; C2; C3$

 $C_1 = X := A+2$

 C_2 = begin var A; C4 end

 $C_3 = X := A$

 C_4 = while X = 0 do A := X



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```
\mathsf{P}[[\mathsf{begin}\ D_0;\ D_1;\ C_0\ \mathsf{end}]] =
```

 $\lambda I.K[[\text{begin } D_0; D_1; C_0 \text{ end}]](emptyenv I) =$ where $e_0 = emptyenv I$

 $C[[C_0]](D[[D_0; D_1]]e_0) =$

 $D[[D_0; D_1]]e_0 = D[[D_1]](D[[const A = 1]]e_0)$

 $D[[D_0]] = D[[\mathsf{const}\ A = 1]]e_0 = (\mathit{updateenv}\ [[A]]\ \mathit{inNat}(\mathit{one})\ e_0) = e_1$

$$\begin{split} \mathsf{D}[[D_1]] &= \mathsf{D}[[\mathsf{var}\ X]] \mathsf{e}_1 = (\mathit{updateenv}\ [[A]]\ \mathit{inLocation}(\mathit{l})\ \mathsf{e}_2) = \mathsf{e}_3 \\ &\quad \mathsf{where}\ \mathit{let}(\mathit{l'}, \mathsf{e'}) = (\mathit{reserve_locn}\ \mathsf{e}_1)\ \mathit{in}\ \mathsf{e}_2 = (\mathit{l},\ (\mathit{map}, (\mathit{next_locn}\ \mathit{l}))) \end{split}$$



 $(check(C[[C_2; C_3]]e_3)) \circ (C[[C_1]]e_3) =$

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```
 \begin{aligned} &(\mathit{check}(\mathsf{C}[[\mathit{C}_2;\; \mathit{C}_3]] e_3)) \circ (\mathsf{C}[[\mathit{X} := \mathit{A} + 2]] e_3) = \\ & \mathsf{C}[[\mathit{X} := \mathit{A} + 2]] = \lambda \mathit{s.cases} \; (\mathit{accessenv} \; [[\mathit{X}]] \; e_3) \; \mathit{of} \; \mathit{isLocation}(\mathit{I}) \to \\ & \; \; (\mathit{cases}(\mathsf{E}[[\mathit{A} + 2]] e_3 \; \mathit{s}) \; \mathit{of} \; \mathit{isNat}(\mathit{n}) \to (\mathit{return}(\mathit{update} \; \mathit{I} \; \mathit{n} \; \mathit{s})) \; ...end) \; ...end = \\ & \; \mathit{inOK}([\mathit{I} \mapsto \mathit{three}] \mathit{s}), \; \mathit{where} \; e_3 = [\mathit{X} \mapsto \mathit{inLocation}(\mathit{I}), \; \mathit{A} \mapsto \mathit{inNat}(\mathit{three})] \\ \\ & \mathsf{E}[[\mathit{A} + 2]] e_3 = \lambda \mathit{s.cases} \; (\mathsf{E}[[\mathit{A}]] e_3 \; \mathit{s}) \; \mathit{of} \; [] \; \mathit{isNat}(\mathit{n}_1) \to (\mathit{cases} \; (\mathsf{E}[[2]] e_3 \; \mathit{s}) \; \mathit{of} \\ & \; \mathit{isNat}(\mathit{n}_2) \to \mathit{inNat}(\mathit{n}_1 \; \mathit{plus} \; \mathit{n}_2) \; ...end) \; ...end = \\ & \; \mathit{inNat}(\mathit{one} \; \mathit{plus} \; \mathit{two}) = \mathit{inNat}(\mathit{three}) \end{aligned}
```

 $E[[A]]e_3 = \lambda s. cases (accessenv [[A]] e_3) of isLocation(I) <math>\rightarrow$ inNat(access I s) [] isNat(n) \rightarrow inNat(n) ...end = inNat(one)

 $E[[2]]e_3 = inNat(N[[2]]) = inNat(two)$



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```
(check(C[[C_2; C_3]]e_3)) =
(check(C[[C_3]]e_3)) \circ (C[[while X = 0 do A := X]]e_3) =
  C[[while X = 0 \text{ do } A := X]]e_3) = C[[C_4]](D[[var A]]e_3) =
  C[[while X = 0 do A := X]]e_5 =
   fix(\lambda f. \lambda s. cases (B[[X = 0]]e_5 s) of ...end
     ((access\ l\ s)\ equals\ zero \rightarrow (check\ f) \circ (C[[A:=X]]e_5)\ []\ return)\ s
     \lambda s. return(update(next\_locn \ l) (access \ l \ s) \ s)
     B[[X = 0]]e_5 s = inTr((access \ l \ s) equals \ zero) = false
   D[[var A]]e_3 = (updateenv [[A]] inLocation(next_locn I) e_4) = e_5
 C[[C_3]]e_3 = C[[X := A]]e_3
   \lambda s. \ return(update \ l \ one \ s) = inOK([l \mapsto one]s)
```



Block Structured Language: Stack-Managed Storage

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 The store of a block-structured language is used in a stack-like fashion:

- Locations are bound to identifiers sequentially using next_locn, and
- A location bound to an identifier in a local block is freed for re-use when the block is exited
- The re-use of locations happens automatically due to the equation for $C[[C_1; C_2]]$
- Any locations bound to identifiers in $[[C_1]]$ are reserved by the environment built from e for $C[[C_1]]$, but $C[[C_2]]$ re-uses the original e (and its original location marker), effectively deallocating the locations.



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Block Structured Language

Summary

- Stack-based storage is a significant characteristic of block-structured programming languages, and
- the Store algebra deserves to possess mechanisms for stack-based allocation and deallocation
- Next we start to move the storage calculation mechanism over to the store algebra



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Summary

Stack-based store
 Domain:

 $s \in \mathit{Store} = (\mathit{Location} \rightarrow \mathit{Storable_value}) \times \mathit{Location}$

• The new store domain uses the

 $Location \rightarrow Storable_value$

component as the data space of the stack, and

- the Location component indicates the amount of storage in use: it is the
 - stack top marker



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Stack-based store

Domain:

 $s \in Store = (Location \rightarrow Storable_value) \times Location$ Operations:

 $access: Location \rightarrow Store \rightarrow (Storable_value + Errvalue)$ $access = \lambda(I, s). s(i)$

 $update: Location \rightarrow Storable_value \rightarrow Store \rightarrow Poststore$ update = λI . λv . λ (map, top). I lessthan_locn top \rightarrow $inOK([I \mapsto v]map, top)$ [] inErr(map, tops)

• Operations access and update verify that any reference to a storage location is a valid one, occurring at an active location beneath the stack top



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Stack-based store
 Domain:

 $s \in \mathit{Store} = (\mathit{Location} \rightarrow \mathit{Storable_value}) \times \mathit{Location}$ Operations:

 $mark_locn : Store \rightarrow Location$ $mark_locn = \lambda(map, top).top$

 $allocate_locn : Store \rightarrow Location \times Poststore$ $allocate_locn =$ $\lambda(map, top).(top, inOK(map, next_locn(top)))$

 The purposes of mark_locn and allocate_locn should be clear; the latter is the run-time version of the environment's reserve_locn operation



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Summa

Stack-based store Operations:

```
deallocate\_locns : Location \rightarrow Store \rightarrow Poststore \ deallocate\_locns = \lambda I.(map, top). \ (I less than\_locn top) or (I equal\_locn top) \rightarrow inOK(map, I) [] inErr(map, top)
```

- The deallocate_locns operation releases stack storage from the stack top to the value indicated by its argument. Freed from storage management, the environment domain takes the form Environment = Id → Denotable_value
- The operations are adjusted accordingly, and the operation reserve_locn is dropped
- If the environment leaves the task of storage calculation to the store operations, then processing of declarations requires the store as well as the environment



Block Structured Language: Stack-Managed Storage: Valuation Functions

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Summary

The functionality of the valuation function for declarations becomes:

• D: Declaration \rightarrow Environment \rightarrow Store \rightarrow (Environment \times Poststore)

$$D[var I]] = \lambda e.\lambda s.let(I, p) = (allocate_locns)$$

$$in ((updateenv [[I]] inLocation(I) e), p)$$

$$D[[D_1; D_2]] == \lambda e.\lambda s.let(e', p) = (D[[D_1]]e s)$$
 in (check $D[[D_2]]e')(p)$ check : (Store \rightarrow (Environment \times Poststore)) \rightarrow (Poststore \rightarrow (Environment \times Poststore))

- This version of declaration processing makes the environment into a run-time object, for the binding of location values to identifiers cannot be completed without the run-time store
- Contrast this with the arrangement in the last model, where location binding is computed by the environment operation reserve_locn, which produced a result relative to an arbitrary base address
- A solution for freeing the environment from dependence upon allocate_locn
 is to provide it information about storage management strategies, so that
 the necessary address calculations can be performed independently of the
 value of the run-time store



Block Structured Language: Stack-Managed Storage: Valuation Functions

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Summary

• K: Block \rightarrow Environment \rightarrow Store \rightarrow Poststore $_{\perp}$

The K function manages the storage for the block:

```
\begin{split} &\mathsf{K}[[\mathsf{begin}\ D; C\ \mathsf{end}]] = \lambda e.\ \lambda s.\ \mathsf{let}\ \mathit{l} = \mathsf{mark\_locn}\ s\ \mathsf{in} \\ &\mathsf{let}\ (e',p) = \mathsf{D}[[D]]e\ s\ \mathsf{in} \\ &\mathsf{let}\ p' = (\mathsf{check}(\mathsf{c}[[C]]e'))(p)\ \mathsf{in}\ (\mathsf{check}(\mathsf{deallocate\_locns}\ \mathit{l}))(p') \end{split}
```

 The deallocate_locns operation frees storage down to the level held by the store prior to block entry, which is (mark_locn s)



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Language Applicative Langua The notion of context can be even more subtle than we first imagined. Consider the Pascal assignment statement

$$X := X+1$$

- The meaning of X on the right-hand side of the assignment is decidedly different from X's meaning on the left-hand side. Specifically,
 - the left-hand side value is a location value, while
 - the *right-hand side value* is the *storable value* associated with that location.
 - Apparently the context problem for identifiers is found even at the primitive command level



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Summary

- One way out of this problem would be to introduce two environment arguments for the semantic function for commands:
 - a left-hand side one and
 - a right-hand side one

This arrangement is hardly natural; commands are the sentences of a program, and sentences normally operate in a single context



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Summary

- Another option is to say that any variable identifier actually denotes a pair of values:
 - a location value, or,
 - identifier's *L-value* which is kept in the
 - environment and
 - a storable value, or,
 - identifier's *R-value* which is kept in the
 - store



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Summary

We introduce a valuation function

$$I: \textit{Id} \rightarrow \textit{Environment} \rightarrow \textit{Store} \rightarrow (\textit{Location} \times \textit{Storable_value})$$

. In practice, the I function is split into two semantic functions

$$L: Id \rightarrow Environment \rightarrow Location$$

and

$$\mathsf{R}: \textit{Id} \rightarrow \textit{Environment} \rightarrow \textit{Store} \rightarrow \textit{Storable_value}$$

such that:

- L[[I]] = accessenv [[I]]
- $R[[I]] = access \circ accessenv [[I]]$
- We restate the semantic equations using variables as:

$$C[[I := E]] = \lambda e. \ \lambda s. \ return(update(L[[I]]e)(E[[E]]e \ s) \ s)$$
$$E[[I]] = R[[I]]$$



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 The definitions are a bit simplistic because they assume that all identifiers are variables.

- Constant identifiers can be integrated into the scheme
- a declaration such as $[[const \ A = N]]$ suggests L[[A]]e = inErrvalue()
- What should (R[[A]]e s) be?
- Yet another view to take is that the *R-value* of a variable identifier is a function of its *Lvalue*
- The true meaning of a variable is its Lvalue, and a coercion occurs when a variable is used on the right-hand side of an assignment
- This coercion is called dereferencing



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We formalize this view as:

```
J: Id \rightarrow Environment \rightarrow Denotable\_value

J[[/]] = \lambda e. (accessenv [[/]] e)

C[[/] := E]] = \lambda e. \lambda s. return(update(J[[/]]e)(E[[E]]e s) s)

E[[/]] = \lambda e. \lambda s. dereference(J[[/]]e) s
```

where

 $dereference : Location \rightarrow Store \rightarrow Storable_value$ dereference = access



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Summary

- An identifier's meaning is just its denotable value
- Those identifiers with locations as their meanings (the variables) are dereferenced when an expressible value is needed.
- The implicit use of dereferencing is so common in general purpose programming languages that we take it for granted, despite the somewhat unorthodox appearance of commands such as

$$X = X + 1$$

in FORTRAN



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Summary

Systems-oriented programming languages such as BCPL,
 Bliss, and C use an explicit dereferencing operator

 For example, in BCPL expressible values include locations, and the appropriate semantic equations are:

$$\begin{split} \mathsf{E}[[I]] &= \lambda e. \ \lambda s. \ inLocation(\mathsf{J}[[I]]e) \\ \mathsf{E}[[@E]] &= \lambda e. \ \lambda s. \ cases \ (\mathsf{E}[[E]]e \ s) \ of \\ isLocation(I) &\rightarrow (dereference \ I \ s) \\ []...end \end{split}$$

- The @ symbol is the dereferencing operator
- The meaning of

$$X := X + 1$$

in BCPL is decidedly different from that of

$$X := @X+1$$



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- An applicative language contains no variables
- All identifiers are constants and can be given attributes but once, at their point of definition
- Without variables, mechanisms such as assignment are superfluous and are dropped
- Arithmetic is an applicative language.
- Another example is the minimal subset of LISP known as pure LISP
- The function notation that we use to define denotational definitions can also be termed an applicative language.
 Since an applicative language has no variables, its semantics can be specified without a *Store domain*
- The environment holds the attributes associated with the identifiers



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Language with Contexts Block Structured Language Applicative Language It is similar to pure LISP – a list processing language

A program in the language is just an expression

An expression can be

a LET definition;

a LAMBDA form;

representing a function routine with parameter I

a function application;

• a list expression using CONS, HEAD, TAIL, or NIL;

an identifier; or

an atomic symbol



Applicative Language: Abstract Syntax

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Abstract Syntax:

• $E \in Expression$ $A \in Atomic_symbol$ $I \in Identifier$

$$E ::= LET \mid I = E_1 \mid IN \mid E_2 \mid$$
 $LAMBDA \mid I \mid E \mid$
 $E_1 \mid E_2 \mid$
 $E_1 \mid CONS \mid E_2 \mid HEAD \mid E \mid TAIL \mid E \mid NIL \mid$
 $I \mid$
 $A \mid (E)$

Note: (let
$$x = e_1$$
 in e_2) for $(\lambda x. e_2)e_1$



Applicative Language: Semantic Algebras

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Semantic Algebras:

Atomic answer values

Domain: $a \in Atom$

Operations: (Omitted)

 Atom is a primitive answer domain and its internal structure will not be considered

Identifiers

Domain: $i \in Id = Identifier$

Operations: (Usual)



Applicative Language: Semantic Algebras

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Semantic Algebras:

Denotable values, functions, and lists
 Domain:

```
d \in Denotable\_value = (Function + List + Atom + Error)_{\perp}

f \in Function = Denotable\_value \rightarrow Denotable\_value

t \in List = Denotable\_value

Error = Unit
```

- The language also contains a domain of functions, which map denotable values to denotable values; a denotable value can be a function, a list, or an atom
- For the first time, we encounter a semantic domain defined in terms of itself. By substitution, we see that:

```
Denotable\_value = ((Denotable\_value \rightarrow Denotable\_value) + Denotable\_value^* + Atom + Error)_{\perp}
```



Applicative Language: Semantic Algebras

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Semantic Algebras:

Expressible value
 Domain: x ∈ Expressible_value = Denotable_value



Applicative Language: Semantic Algebras

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Semantic Algebras:

Environment

Domain: $e \in Environment = Id \rightarrow Denotable_value$

Operations:

 $accessenv: Id \rightarrow Environment \rightarrow Denotable_value$

 $accessenv = \lambda i.\lambda e. \ e(i)$

 $updateenv: Id \rightarrow Denotable_value \rightarrow$

 $Environment \rightarrow Environment$

 $update env = \lambda i.\lambda d.\lambda e. \ [i \mapsto d]e$



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Valuation Functions:

ullet E: Expressiono Environment o Expressible_value

$$\begin{split} \mathsf{E}[[\mathsf{LET}\ I = E_1\ \mathsf{IN}\ E_2]] = \\ \lambda \mathsf{e}.\ \mathsf{E}[[E_2]](\mathsf{updateenv}\ [[I]]\ (\mathsf{E}[[E_1]]\mathsf{e})\ \mathsf{e}) \end{split}$$

Note: (let
$$x = e_1$$
 in e_2) for $(\lambda x. e_2)e_1$

- E determines the meaning of an expression, a denotable value, with the aid of an environment
- An atom, list, or even a function can be a legal answer
- The LET expression provides a definition mechanism for augmenting the environment
- Static scoping is used



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Valuation Functions:

■ E: Expression → Environment → Expressible_value

```
\begin{split} & \mathsf{E}[[E_1\ E_2]] = \lambda e.\ let\ x = (\mathsf{E}[[E_1]]e)\ in\ cases\ x\ of\\ & isFunction(f) \to f(\mathsf{E}[[E_2]]e)\\ & []\ isList(t) \to inError()\\ & []\ isAtom(a) \to inError()\\ & []\ isError() \to inError()\ end \end{split}
```

- Functions are created by the LAMBDA construction
- A function body is evaluated in the context that is active at the point of function definition, augmented by the binding of an actual parameter to the binding identifier
- This definition is also statically scoped



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Summary

Valuation Functions:

• E: Expression \rightarrow Environment \rightarrow Expressible_value

```
E[[E_1 \ CONS \ E_2]] = \lambda e. \ let \ x = (E[[E_2]]e) \ in \ cases \ x \ of
   isFunction(f) \rightarrow inError()
   [] isList(t) \rightarrow inList(E[[E_1]]e \ cons \ t)
   [] isAtom(a) \rightarrow inError()
   [] is Error() \rightarrow in Error() end
E[[HEAD\ E]] = \lambda e. let x = (E[[E]]e) in cases x of
   isFunction(f) \rightarrow inError()
   [] isList(t) \rightarrow (null\ t \rightarrow inError()\ []\ (hd\ t))
   [] is Atom(a) \rightarrow inError()
   [] isError() \rightarrow inError() end
E[[TAIL\ E]] = . let x = (E[[E]]e) in cases x of
   isFunction(f) \rightarrow inError()
   [] isList(t) \rightarrow (null t \rightarrow inError() [] inList(tl t))
   [] isAtom(a) \rightarrow inError()
   [] is Error() \rightarrow in Error() end
E[[NIL]] = \lambda e. inList(nil)
```



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Valuation Functions:

■ E: Expression → Environment → Expressible_value

$$E[[I]] = accessenv [[I]]$$

$$\mathsf{E}[[A]] = \lambda e. \; \mathit{inAtom}(\mathsf{A}[[A]])$$

$$\mathsf{E}[[(E)]] = \mathsf{E}[[E]]$$

A:Atomic-symbol \rightarrow *Atom*



Applicative Language: Scoping Rule

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Static Scoping

- The applicative language uses static scoping; that is, the context of a phrase is determined by its physical position in the program
- Consider (let a_0 and a_1 be atomic symbols):

Note: (let $x = e_1$ in e_2) for $(\lambda x. e_2)e_1$

 The occurrence of the first F in the body of the function bound to the second F refers to the atom a₀ - the function is not recursive. The meaning of the entire expression is the same as

which equals

 $(a_0 CONS (a_1 CONS NIL))$

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Applicative Language: Scoping Rule

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Dynamic Scoping

- An alternative to static scoping is dynamic scoping, where the context of a phrase is determined by the place(s) in the program where the phrase's value is required
- The most general form of dynamic scoping is macro definition and invocation. A definition LET I = E binds identifier I to the text E; E is not assigned a context until its value is needed
- When I's value is required, the context where I appears is used to acquire
 the text that is bound to it. I is replaced by the text, and the text is
 evaluated in the existing context
- The version of dynamic scoping found in LISP limits dynamic scoping just to LAMBDA forms. The semantics of [[LAMBDA (I) E]] shows that the construct is evaluated within the context of its application to an argument (and not within the context of its definition)



Applicative Language: Scoping Rules

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.

Semantic Algebras:

Function

Domain: $f \in Function = Environment \rightarrow$ $Denotable \ value \rightarrow Denotable \ value$

Valuation Functions:

E: Expression→ Environment → Expressible_value

```
E[[LAMBDA (I) E]] = \lambda e. inFunction(\lambda e'. \lambda d. E[[E]](updateenv [[I]] d e'))
```

```
\begin{split} \mathsf{E}[[E_1\ E_2]] &= \lambda e.\ \mathit{let}\ x = (\mathsf{E}[[E_1]]e)\ \mathit{in\ cases}\ x\ \mathit{of}\\ \mathit{\mathit{isFunction}}(f) &\to (f\ e\ (\mathsf{E}[[E_2]]e))\\ []\ \mathit{\mathit{isList}}(t) &\to \mathit{inError}()\\ []\ \mathit{\mathit{isAtom}}(a) &\to \mathit{inError}()\\ []\ \mathit{\mathit{isError}}() &\to \mathit{inError}()\ \mathit{end} \end{split}
```



Principles of Programming Languages: Summary

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Applicative Lang

• λ -Calculus: Syntax

• λ -Calculus: Semantics

λ-Calculus: Typed

ullet Programming Languages with λ

• Functional: Haskell,Scheme, Lisp, ML

• Multi-Paradigm: λ in C++

Type Systems

Denotational Semantics

Definition

• Relationship with Operational and Axiomatic Semantics

Semantics of Imperative Languages



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- Module 01: Course Information
 - Why PoPL?
 - ② Prerequisites
 - Syllabus (This has changed substantially with the Module plan)
 - Module 01
 - Module 02
 - Module 03
 - Module 04
 - Module 05
 - Module 06
 - Module 07
 - Module 08
 - Module 00
 Module 09
 - Module 09
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 - TA Teacher



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2 Module 02: λ -Calculus: Syntax

Relations

Functions

Composition

Currying

 \bullet λ -Calculus

• Concept of λ

Syntax

• λ -expressions

* Notation

Examples

* Simple

* Composition

* Boolean

* Numerals

* Recursion

* Curried Functions

* Higher Order Functions



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3 Module 03: λ -Calculus: Semantics

- Semantics
 - Free and Bound Variables
 - Substitution
 - Reduction
 - * α-Reduction
 - * β-Reduction
 - * η -Reduction
 - * δ -Reduction
 - Order of Evaluation
 - * Normal and Applicative Order



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- **4** Module 04: Typed λ -Calculus
 - - Type Expression
 - Pre-Expression Expression
 - Type-checking Rules
 - * Example
 - * Practice Problems
- Types
- * Tuple Type
 - * Record Type
- * Sum Type
- * Reference Type
- * Array Type
- Type Expression
- Pre-Expression
- Type-checking Rules
- * Derived Rules



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5 Module 05: λ in C++

¶ Functors

Callable Entities

Function Pointers

* Replace Switch / IF Statements

* Late Binding

* Virtual Function

* Callback

* Issues

Basic Functors

* Elementary Example

* Examples from STL

 λ in C++

λ Expression

Closure Object

Examples

* Factorial

* Fibonacci

* Pipeline

Curry Function

3 More on λ in C++



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Module 06: Denotational Semantics of Imperative Languages

Type Systems

Type Type Error

Type Safety

Type Checking

Type Inference

2 Type Inference

add x = 2 + x

• apply (f, x) = f x

Inference Algorithm

* Unification

Second Examples

sum

length

append

Homework

Polymorphism

* Ad-hoc

* Parametric* Subtype

• C++11....

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Module 07: Denotational Semantics

Semantic Styles

Syntax

Semantic Domains

Set. Functions, and Domains

* Product

* Sum

Rat

4 Semantic Algebras

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String

Unit

Product Dom

Sum Dom

Lists

Function

Arrays

Lifted Domains

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Denotational Definitions

Binary

Calculator

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- Imperative Languages
- 2 Language + Assignment
- Opening Programs Are Functions
- Interactive File Editor
- 5 Dynamically Typed Language
- 6 Recursive Definitions
- Canguage with Contexts
 - Block Structured Language
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- Summary