An $L(1/3 + \varepsilon)$ Algorithm for the Discrete Logarithm Problem for Low Degree Curves

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Abstract. The discrete logarithm problem in Jacobians of curves of high genus g over finite fields \mathbb{F}_q is known to be computable with subexponential complexity $L_{q^g}(1/2, O(1))$. We present an algorithm for a family of plane curves whose degrees in X and Y are low with respect to the curve genus, and suitably unbalanced. The finite base fields are arbitrary, but their sizes should not grow too fast compared to the genus. For this family, the group structure can be computed in subexponential time of $L_{q^g}(1/3, O(1))$, and a discrete logarithm computation takes subexponential time of $L_{q^g}(1/3 + \varepsilon, o(1))$ for any positive ε . These runtime bounds rely on heuristics similar to the ones used in the number field sieve or the function field sieve algorithms.

1 Introduction

The discrete logarithm problem in algebraic curves over finite fields has been receiving particular attention since elliptic curves and subsequently Jacobian groups of further algebraic curves have been proposed for discrete logarithm based public key cryptosystems. Although it is now clear that high genus curves are unsuitable for cryptographical use, it remains crucial to study algorithms for solving the discrete logarithm problem in those curves for several reasons. The first reason is that having a better understanding of the situation for high genus curves might lead to algorithmic improvements also in the small genus case. The second reason is that the Weil descent strategy of attacking the discrete logarithm problem in elliptic curves defined over extension fields leads to a discrete logarithm problem in the Jacobian of a high genus curve. Therefore a better algorithm for high genus discrete logarithms becomes naturally a potential threat for some elliptic curves.

It turned out very early that the discrete logarithm problem in high genus hyperelliptic curves (for instance in the sense that the size q of the base field is fixed, while the genus g tends to infinity) can be solved by a subexponential algorithm of complexity $L_{q^g}(1/2, O(1))$. The first such algorithm was proposed in [1]. As other subexponential algorithms, it consists of fixing a factor base of small prime elements (here, prime divisors) and of creating relations that correspond to the zero element modulo an equivalence relation (here, equivalence

of divisors modulo principal divisors). After collecting sufficiently many relations and somehow introducing the base of the discrete logarithm and the element whose logarithm is sought, linear algebra yields the desired result. Assuming that smooth elements, that are elements decomposing over the factor base, have the same density as for instance smooth integers or polynomials, such algorithms usually end up with a complexity of $L_{qg}(1/2, O(1))$.

The algorithm in [1] creates relations by randomly taking low degree functions (that are linear in Y for the curve $Y^2 = f(X)$), whose divisors are relations. Its analysis is only heuristic. The first proven algorithms are given in [15] for the infrastructure of real-quadratic hyperelliptic function fields and in [5] for Jacobians of hyperelliptic curves. Relations are obtained in a process similar to that of [11] by taking random linear combinations of factor base elements, reducing modulo the equivalence relation and checking for smoothness. A rigorous analysis is derived from the lower bound on the density of smooth divisors in [7]. A generic description of a similar algorithm can be found in [6]; it applies to all class groups in which a smoothness result is known. Heuristically, it obtains a running time of $L_{q^g}(1/2, O(1))$ for the discrete logarithm problem in arbitrary high genus curves, the smoothness result needed for a proof of the complexity is however only available for hyperelliptic curves.

A proven algorithm of complexity $L_{q^g}(1/2 + \varepsilon, O(1))$ for very general curves over a fixed field \mathbb{F}_q and with genus g tending to infinity (with the only restriction that the curves contain a rational point and that the cardinality of the Jacobian group is bounded by $q^{g+O(\sqrt{g})}$) is given in [3]. Unlike previous algorithms, it appears to be specific to algebraic curves and relies on a double randomisation, taking random combinations of factor base elements and a random function in a Riemann–Roch space. A relation is obtained whenever the divisor of this function is smooth. A more general algorithm is proposed in [13] that yields a proven $L_{q^g}(1/2, O(1))$ complexity without any restriction on the input curve.

Another line of research on the discrete logarithm problem for algebraic curves, started in [8] and not pursued in this article, consists of fixing g and having q tend to infinity. This leads to algorithms that are exponential, but faster than generic algorithms of square root complexity as soon as $g \geq 3$, see [9, 4].

In the light of algorithms of complexity L(1/3) for the discrete logarithm problem in finite fields as well as for factoring integers, it has been an open problem to determine whether this complexity can be achieved also for algebraic curves. In this article, we present the first probabilistic algorithm of heuristic complexity $L_{q^g}(1/3, O(1))$ to compute the group structure of certain curves whose total degree is relatively small compared to their genus. When introducing the two elements of the Jacobian for which the discrete logarithm problem is to be solved, some sacrifice has to be made; we obtain an algorithm of complexity bounded by $L_{q^g}(1/3 + \varepsilon, o(1))$ for any positive constant ε .

The relation collection phase is the same as in [1] and consists of looking for smooth divisors of functions linear in Y. By applying it to the curves of our special family, one readily obtains a lower degree of the affine part of the intersection

divisor than in the general case, from which a complexity of $L_{q^g}(1/3, O(1))$ is derived. For smoothing the two divisors involved in the discrete logarithm problem, a process is employed that is similar to the one used in the number field sieve or in the function field sieve. This is the general special-Q descent strategy (also related to the so-called lattice sieving). Each divisor is partially smoothed into prime divisors of degree less than the starting divisor. Then each such prime divisor Q is smoothed again into smaller prime divisors, and we iterate until every divisor is rewritten in terms of elements of the factor base. However, in our case it is necessary to add an arbitrarily small constant ε to the 1/3 parameter to obtain a proper descent phenomenon; otherwise, the process would get stuck after one step.

Let us mention that subsequently to our algorithm, Diem has presented at the 10th Workshop on Elliptic Curve Cryptography (ECC 2006) an algorithm based on similar ideas, but with a quite different point of view. He manages to obtain a complexity of L(1/3, O(1)) for the discrete logarithm phase, for which our algorithm takes $L(1/3 + \varepsilon, o(1))$. We will show how to reach a complexity of L(1/3, O(1)) for discrete logarithms in our setting in the long, journal version.

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2 Main idea

Before describing our algorithm with all its technical details on a general class of curves, we sketch in this section the main idea yielding a complexity of $L_{q^g}(1/3, O(1))$ for the relation collection phase for a restricted class of curves. We provide a simplified analysis by hand waving; Section 3 is devoted to a more precise description of the heuristics used and of the smoothness properties needed for the analysis.

Let \mathbb{F}_q be a fixed finite field. We consider a family of C_{ab} curves over \mathbb{F}_q , that is, curves of the form

$$C: Y^n + X^d + f(X, Y)$$

without affine singularities such that $\gcd(n,d)=1$ and any monomial X^iY^j occurring in f satisfies ni+dj < nd. Such a curve has genus $g=\frac{(n-1)(d-1)}{2}$; we assume that g tends to infinity, and that $n \approx g^{1/3}$ and $d \approx g^{2/3}$ (we use the symbol \approx , meaning "about the same size" with no precise definition). The non-singular model of a C_{ab} curve has a unique point at infinity, and it is \mathbb{F}_q -rational; so there is a natural bijection between degree zero divisors and affine divisors, and in the following, we shall only be concerned with effective affine divisors. Choose as factor base \mathcal{F} the $L_{q^g}(1/3, O(1))$ prime divisors of smallest degree (that is, the prime divisors up to a degree of $B \approx \log_q L_{q^g}(1/3, O(1))$). To obtain relations, consider functions linear in Y of the form

$$\varphi = a(X) + b(X)Y$$

with $a, b \in \mathbb{F}_q[X]$, gcd(a, b) = 1 and deg a, $deg b = \delta \approx g^{1/3}$. Whenever the affine part $div(\varphi)$ of the divisor of φ is smooth with respect to the factor base, it yields a relation, and we have to estimate the probability of this event.

Let N be the norm of the function field extension $\mathbb{F}_q(\mathcal{C}) = \mathbb{F}_q(X)[Y]/(Y^n + X^d + f(X,Y))$ relative to $\mathbb{F}_q(X)$. The norm of φ is computed as

$$N(\varphi) = N(b) N \left(Y + \frac{a}{b} \right)$$

$$= b^n \left(\left(-\frac{a}{b} \right)^n + X^d + f \left(X, -\frac{a}{b} \right) \right)$$

$$= (-a)^n + b^n X^d + f^*(X),$$

where each monomial X^iY^j occurring in f is transformed into a monomial $X^i(-a)^jb^{n-j}$ in f^* .

Since φ is linear in Y, all prime divisors it contains are totally split over $\mathbb{F}_q(X)$, and φ is B-smooth if and only if its norm is. We have

$$\deg_X N(\varphi) \le \max(n \deg a, n \deg b + d) = n\delta + d \approx g^{2/3}.$$

Heuristically, we assume that the norm behaves like a random polynomial of degree about $g^{2/3}$. Then it is B-smooth with probability $1/L_{q^g}(1/3, O(1))$ (this is the same theorem as the one stating that a random polynomial of degree g is $\log_q L_{q^g}(1/2, O(1))$ -smooth with probability $1/L_{q^g}(1/2, O(1))$, cf., for instance, Theorem 2.1 of [2]). Equivalently, we may observe that $\deg(\operatorname{div}(\varphi)) = \deg_X(\mathrm{N}(\varphi))$ and assume heuristically that $\operatorname{div}(\varphi)$ behaves like a random effective divisor of the same degree. Then the standard results on arithmetic semigroups (cf. Section 3) yield again that $\operatorname{div}(\varphi)$ is smooth with probability $1/L_{q^g}(1/3, O(1))$.

Thus, the expected time for obtaining $|\mathcal{F}| = L_{q^g}(1/3, O(1))$ relations is $L_{q^g}(1/3, O(1))$, which is also the complexity of the linear algebra step for computing the Smith normal form and thus the group structure of the Jacobian. The complexity of the discrete logarithm problem is not considered here, an analysis for the full algorithm is given in Section 5.

It remains to show that the search space is sufficiently large to yield the required $L_{q^g}(1/3, O(1))$ relations, or otherwise said, that the number of candidates for φ is at least $L_{q^g}(1/3, O(1))$. The number of φ is about

$$\begin{split} q^{2\delta} &= q^{2g^{1/3}} = \exp(2\log q g^{1/3}) \\ &< \exp(2(g^{1/3}(\log q)^{1/3})(\log(g\log q))^{2/3}) = L_{q^g}(1/3, O(1)). \end{split}$$

The previous inequality in the place of the desired equality shows that a more rigorous analysis requires a more careful handling of the $\log q$ factors; in particular, δ has to be slightly increased. Moreover, the constant exponent in the subexponential function needs to be taken into account. This motivates the following section, in which we examine in more detail the smoothness heuristics and results that are needed for the algorithm.

3 Smoothness

The algorithm presented in this article relies on finding relations as smooth divisors of random polynomial functions of low degree. We suppose that all curves are given by an absolutely irreducible plane affine model

with $F \in \mathbb{F}_q[X,Y]$, where \mathbb{F}_q is the exact constant field of the function field of \mathcal{C} . The factor base \mathcal{F} consists essentially of the places of degree bounded by some parameter μ , with a few technical modifications. Precisely, \mathcal{F} is composed of the following places:

- the places corresponding to the resolution of singularities, regardless of their degrees, whose number is bounded by $\frac{(d-1)(d-2)}{2}$ with $d=\deg F$. By including them in \mathcal{F} , the algorithm can be described as if the curves were non-singular.
- the infinite places corresponding to non-singularities, regardless of their degrees, whose number is bounded by d by Bézout's theorem. By adding them, it becomes sufficient to only examine the affine part of any divisor.
- places of degree bounded by some parameter μ and of inertia degree 1 with respect to the function field extension $\mathbb{F}_q(X)[Y]/(F)$ over $\mathbb{F}_q(X)$. Otherwise said, places corresponding to prime ideals of the form (u, Y v) with $u \in \mathbb{F}_q[X]$ irreducible of degree at most μ and $v \in \mathbb{F}_q[X]$ of degree less than deg u; the inertia degree is in fact the degree of the second generator in Y. Due to the way relations are obtained in the algorithm, no places of higher inertia degree may occur.

A divisor is called \mathcal{F} -smooth if it can be decomposed over the factor base; thus only its affine part plays a role, and for polynomial functions, this is an effective (i.e. non-negative) divisor. An effective divisor is called μ -smooth if it is composed only of places of degree up to μ . To be able to analyse the smoothness probability, we need the following reasonable assumption.

Heuristic 1. Let D be the divisor of a uniformly randomly chosen polynomial of the form b(X)Y - a(X) and ν the degree of its affine part. Then the probability of D to be \mathcal{F} -smooth is the same as that of a random effective divisor of degree ν to be μ -smooth.

Heuristic 1 covers the relation collection phase. For computing discrete logarithms, arbitrary non-principal divisors need to be smoothed, and another assumption is needed.

Heuristic 2. The probability of a uniformly randomly chosen effective divisor of degree ν to be \mathcal{F} -smooth is essentially the same as that of being μ -smooth.

Heuristic 2 claims in fact that places of inertia degree larger than 1 do not play a role for smoothness considerations. In the analogous case of number fields

this is justified by the observation that these places have a Dirichlet density of 0, and the situation is completely analogous for function fields: A place of degree μ and inertia degree f dividing μ corresponds to a closed point on \mathcal{C} with X-coordinate in $\mathbb{F}_{q^{\mu/f}}$ and Y-coordinate in $\mathbb{F}_{q^{\mu}}$, of which there are on the order of $q^{\mu/f}$. Clearly, places with $f \geq 2$ are completely negligible.

The probability of μ -smoothness is ruled by the usual results on smoothness probabilities in arithmetic semigroups such as the integers or polynomials over a finite field, cf. [14].

Unfortunately, most results in the literature assume a fixed semigroup and give asymptotics for μ and ν tending to infinity, whereas we need information that is uniform over an infinite family of curves. Theorem 13 of [13] provides such a result:

Theorem 3 (HeB). Let $0 < \varepsilon < 1$, $\gamma = \frac{3}{1-\varepsilon}$ and ν , μ and $u = \frac{\nu}{\mu}$ such that $3\log_q(14g+4) \le \mu \le \nu^{\varepsilon}$ and $u \ge 2\log(g+1)$. Denote by $\psi(\nu,\mu)$ the number of μ -smooth effective divisors of degree ν . Then for μ and ν sufficiently large (with an explicit bound depending only on ε , but not on q or g),

$$\frac{\psi(\nu,\mu)}{q^{\nu}} \ge e^{-u\log u\left(1 + \frac{\log\log u + \gamma}{\log u}\right)} = e^{-u\log u(1 + o(1))}.$$

Notice that the proof of Theorem 3, similar in spirit to that for hyperelliptic curves in [7], is entirely combinatorial and relies on the fact that there are essentially q^{μ}/μ places of degree μ . So we expect the result to hold even if one restricts to places of inertia degree 1.

Denote by

$$L(\alpha, c) = L_{q^g}(\alpha, c) = e^{c(g \log q)^{\alpha} (\log(g \log q))^{1-\alpha}}$$

for $0 \le \alpha \le 1$ and c > 0 the subexponential function with respect to $g \log q$, and let

$$\mathcal{M} = \mathcal{M}_{q^g} = \log_q(g \log q) = \frac{\log(g \log q)}{\log q}.$$

The parameter $g \log q$ will be the input size for the class of curves we consider; more intrinsically, this is the logarithmic size of the group in which the discrete logarithm problem is defined.

Proposition 4. Let $\nu = \lfloor \log_q L(\alpha, c) \rfloor = \lfloor cg^{\alpha} \mathcal{M}^{1-\alpha} \rfloor$ and $\mu = \lceil \log_q L(\beta, d) \rceil = \lceil dg^{\beta} \mathcal{M}^{1-\beta} \rceil$ with $0 < \beta < \alpha \le 1$ and c, d > 0. Assume that there is a constant $\delta > \frac{1-\alpha}{\alpha-\beta}$ such that $g \ge (\log q)^{\delta}$. Then for g sufficiently large,

$$\frac{\psi(\nu,\mu)}{q^{\nu}} \ge L\left(\alpha - \beta, -\frac{c}{d}(\alpha - \beta) + o(1)\right),\,$$

where o(1) is a function that is bounded in absolute value by a constant (depending on α , β , c, d and δ) times $\frac{\log \log(g \log q)}{\log(g \log q)}$.

Proof. One computes

$$u = \frac{\nu}{\mu} \le \frac{c}{d} \left(\frac{g \log q}{\log(g \log q)} \right)^{\alpha - \beta}$$

(the inequality being due only to the rounding of ν and μ),

$$\log u = (\alpha - \beta) \log(g \log q)(1 + o(1))$$

and

$$\frac{\log\log u}{\log u} = o(1),$$

with both o(1) terms being of the form stipulated in the proposition. Applying Theorem 3 yields the desired result. Its prerequisites are satisfied since

$$\begin{split} \overline{\lim}_{g \to \infty} \frac{\log \mu}{\log \nu} &= \overline{\lim}_{g \to \infty} \frac{\beta \log g - (1 - \beta) \log \log q}{\alpha \log g - (1 - \alpha) \log \log q} \\ &\leq \overline{\lim}_{g \to \infty} \frac{\beta \log g}{\alpha \log g - \frac{1 - \alpha}{\delta} \log g} \\ &= \frac{\beta}{\alpha - \frac{1 - \alpha}{\delta}} =: \varepsilon < 1 \end{split}$$

because of the definition of δ . Notice further that $g \to \infty$ is equivalent to $g \log q \to \infty$, and that also μ and ν tend to infinity when g does.

The choice of μ shall insure that the factor base size, that is about q^{μ} , becomes subexponential. But the necessary rounding of μ , which may increase q^{μ} by a factor of almost q, may result in more than subexponentially many elements in the factor base when q grows too fast compared to q.

Proposition 5. Let $0 < \beta < 1$ and $\delta > \frac{1-\beta}{\beta}$. If $g \ge (\log q)^{\delta}$, then $q = L(\beta, o(1))$ for $g \to \infty$. In particular, $\delta > \max\left(\frac{1-\alpha}{\alpha-\beta}, \frac{1-\beta}{\beta}\right)$ in Proposition 4 implies that $q^{\mu} = L(\beta, d + o(1))$.

Proof. To verify the first assertion, one computes

$$q = e^{\log q} = e^{(\log q)^{1-\beta} (\log q)^{\beta}}$$

$$\leq e^{g^{(1-\beta)/\delta} (\log q)^{\beta} (\log(g \log q))^{1-\beta}}$$

$$= e^{(g \log q)^{\beta} (\log(g \log q)^{1-\beta})} e^{\frac{1-\beta}{\delta} - \beta}.$$

and $g^{\frac{1-\beta}{\delta}-\beta} \to 0$ since $\frac{1-\beta}{\delta}-\beta < 0$. The second assertion is obvious.

4 Computing the group structure

This section is concerned with the relation collection phase of the discrete logarithm algorithm; an immediate application is the computation of the cardinality and the group structure of the Jacobian of the curve. Relation collection is virtually identical to the process described for hyperelliptic curves in [1]; the running time of L(1/3, O(1)) is obtained by applying it to a particular class of curves that are of relatively low degree with respect to their genus and for which the degrees in X and Y of a plane model are balanced in a certain way.

We consider absolutely irreducible curves over finite fields \mathbb{F}_q of characteristic p of the form

$$C: Y^n + F(X,Y)$$

with $F(X,Y) \in \mathbb{F}_q[X]$ of degree d in X and at most n-1 in Y. The function field extension $\mathbb{F}_q(\mathcal{C}) = \mathbb{F}_q(X)[Y]/(Y^n + F(X,Y))$ over $\mathbb{F}_q(X)$ is supposed to be separable (which is for instance the case if $p \nmid n$).

Most importantly, the degrees n and d are related to the genus g by

$$n \le n_0 g^{1/3} \mathcal{M}^{-1/3}$$
 and $d \le d_0 g^{2/3} \mathcal{M}^{1/3}$

where $\mathcal{M} = \frac{\log(g \log q)}{\log q}$ and n_0 , d_0 are some positive constants.

For instance, \mathcal{C} may be a C_{ab} curve of degree $n \sim g^{1/3} \mathcal{M}^{-1/3}$ in Y and $d \sim 2g^{2/3} \mathcal{M}^{1/3}$ in X.

For the running time analysis, we will want to apply Propositions 4 and 5 with $\alpha = 2/3$ and $\beta = 1/3$; so we have to assume that the curves belong to a family satisfying $g \ge (\log q)^{\delta}$ for some $\delta > 2$.

Algorithm 6 (Group structure).

Input: a curve C as above

Output: $h = |J_{\mathcal{C}}(\mathbb{F}_q)|$ and divisors D_1, \ldots, D_r with their orders h_1, \ldots, h_r s.t. $J_{\mathcal{C}}(\mathbb{F}_q) = \langle D_1 \rangle \times \cdots \times \langle D_r \rangle$

1. Compute an approximation of h within a factor of 2, that is, h_- and h_+ s.t.

$$h_{-} < h < h_{+} \text{ and } h_{+} \leq 2h_{-}.$$

- 2. Fix a smoothness bound $B = \lceil \log_q L(1/3, \rho) \rceil$ (with a parameter ρ to be determined later) and compute the factor base \mathcal{F} consisting of all affine prime divisors of \mathcal{C} of degree at most B as well as all infinite prime divisors and prime divisors corresponding to singularities regardless of their degrees. Let $t = |\mathcal{F}|$ and $\mathcal{F} = \{P_1, \ldots, P_t\}$.
- 3. Start with an empty matrix of relations R and repeat the following step until $s \geq 2t$ relations are obtained (in practice, s slightly larger than t should suffice):

Draw uniformly at random a function

$$\varphi = b(X)Y - a(X) \in \mathbb{F}_q(\mathcal{C})$$

with $a, b \in \mathbb{F}_q[X]$ of degree at most

$$m = |\sigma g^{1/3} \mathcal{M}^{2/3}|$$

(with a parameter σ to be determined later). If its divisor is \mathcal{F} -smooth, that is,

$$\operatorname{div}\varphi = \sum_{i=1}^{t} e_i P_i,$$

add a column $(e_1, \ldots, e_t)^T$ to the matrix R.

- 4. Compute the rank of R; if it is less than t, declare failure and stop.
- 5. Compute the Smith normal form $S = \operatorname{diag}(h_r, \ldots, h_1, 1, \ldots, 1)$ of R, where $1 \neq h_1 | h_2 | \cdots | h_r$, and unimodular transformation matrices $T \in \mathbb{Z}^{t \times t}$ and $U \in \mathbb{Z}^{s \times s}$ s.t. TRU = (S|0).

Let $h = h_1 \cdots h_r$. If $h \ge h_+$, declare failure and stop. Otherwise return h, D_1, \dots, D_r s.t.

$$(D_1, \ldots, D_r, 0, \ldots, 0) = (P_1, \ldots, P_t) T^{-1}$$

and h_1, \ldots, h_r .

That the algorithm is correct follows from standard arguments such as given in [1, 5, 6]. It remains to prove its failure probability and running time. We also have to show that there actually are subalgorithms to carry out the different steps; these are given together with the following running time analysis.

- 1. An approximation \tilde{h} of h can be obtained by appropriately truncating the L-series of the curve as in [13, Section 6]. The necessary counting of the number of points on the curve over a small number of extension fields is shown in [13] to be polynomial in g and $\log q$ for curves of degree in O(g). The bounds on h are then given by $h_- = \tilde{h}/\sqrt{2}$ and $h_+ = \sqrt{2}\tilde{h}$.
- 2. The affine prime divisors of degree up to B are obtained by enumerating all irreducible monic polynomials $f \in \mathbb{F}_q[X]$ of degree up to B and factoring $Y^n + F(X,Y)$ over $\mathbb{F}_q[X]/(f)[Y]$. Each factor of degree w yields a prime divisor of degree w deg f. Altogether, these factorisations can be carried out by $O(q^B)$ repetitions of a randomised algorithm with an expected running time that is polynomial in n, B and $\log q$, and thus ultimately in $g \log q$. Since polynomial terms are in L(1/3, o(1)), they can be neglected, and we retain only the term $O(q^B)$ for the remainder of the analysis.

The number of singular places is bounded by $O((nd)^2) = O(g^2)$ using the genus formula for a plane curve. They can be fully described in polynomial time, by computing the desingularisation trees of the singular points (see for instance [10]).

The non-singular places at infinity are included in the intersection of the projective curve with the line Z=0, which has at most O(nd)=O(g) elements by Bézout's theorem, and these are also computable in polynomial time.

So this step terminates with a factor base of size

$$t = O(nq^B) = L(1/3, \rho + o(1))$$

that is computed in time $L(1/3, \rho + o(1))$.

3. To estimate the smoothness probability of div φ under Heuristic 1, we need to compute the degree of its affine part. Denote the affine degree of a divisor by \deg_{aff} . Let $\sigma_1, \ldots, \sigma_n$ be the different embeddings of $\mathbb{F}_q(\mathcal{C})$ into its Galois closure (that exists because the function field extension is assumed to be separable). The σ_i fixing $\mathbb{F}_q(X)$, they send affine to affine and infinite to infinite prime divisors. Hence, all the $\deg_{\text{aff}}(\varphi^{\sigma_i})$ are the same and given by

$$\deg_{\mathrm{aff}} \varphi = \frac{1}{n} \deg_{\mathrm{aff}} \mathrm{N}_{\mathbb{F}_q(\mathcal{C})/\mathbb{F}_q(X)}(\varphi) = \deg_X \mathrm{N}(\varphi).$$

The norm of φ is computed as $N(\varphi) = \text{Res}_Y(\varphi, Y^n + F(X, Y))$, and its degree in X is bounded from above by

$$\deg_X \varphi \cdot \deg_Y \mathcal{C} + \deg_Y \varphi \cdot \deg_X \mathcal{C} = nm + d.$$

The divisor of φ is B-smooth if and only if its norm is; this test as well as the decomposition of a smooth div φ into prime divisors boils down to a factorisation of the norm in $\mathbb{F}_q[X]$ and takes random polynomial time. Let $\tau = (n_0\sigma + d_0)/3$. Applying Propositions 4 and 5 under Heuristic 1 with $nm + d \leq 3\tau g^{2/3}\mathcal{M}^{1/3}$ in the place of ν and $B = \lceil \rho g^{1/3}\mathcal{M}^{2/3} \rceil$ in the place of μ shows that a relation is obtained on average in time $L\left(1/3, \frac{\tau}{\rho} + o(1)\right)$, so that this step takes overall

$$L\left(1/3, \frac{\tau}{\rho} + \rho + o(1)\right).$$

4. and 5. Since all entries of the matrix are of bit size polynomial in $g \log q$, its rank and Smith normal form can be computed in quartic time according to [16, Proposition 8.10], that is in

$$L(1/3, 4\rho + o(1)).$$

The total running time of the algorithm thus becomes

$$L\left(1/3, \max\left(\frac{\tau}{\rho} + \rho, 4\rho\right) + o(1)\right)$$

with $\tau = (n_0 \sigma + d_0)/3$.

For any fixed σ (and thus τ), the value of ρ that minimises the running time is $\rho = \sqrt{\tau/3}$ and we get a complexity of $L\left(1/3, \frac{4\sqrt{\tau}}{\sqrt{3}} + o(1)\right)$.

Now τ is not a completely free parameter; it is connected to the success probability of the algorithm. It is in fact not clear whether the algorithm has a non-zero success probability at all; as in [1], it is already unknown whether

the principal divisors of the special form considered in Step 3. generate the full relation lattice. The analysis of the proven subexponential algorithm in [5], for instance, exploits the fact that the created relations are essentially uniformly distributed among all possible relations in a hypercube of side length about $|J_{\mathcal{C}}(\mathbb{F}_q)|$. Since all our relations are sparse, this line of argumentation definitely cannot be applied; as in [1], the non-negligible success probability of the algorithm can only be conjectured (and notice also that it does not follow from a smoothness assumption such as Heuristic 1).

A necessary condition for the success of the algorithm is nonetheless that the number of potential functions φ tested for smoothness in Step 3. must be at least as large as the number of tests, since otherwise the matrix is filled with redundant multiple relations. Thus we need $q^{2m} \geq L\left(1/3, \frac{4\sqrt{\tau}}{\sqrt{3}}\right)$ or, taking logarithms,

$$2\sigma \ge \frac{4}{\sqrt{3}}\sqrt{\tau} = \frac{4}{3}\sqrt{n_0\sigma + d_0},$$

which holds asymptotically for $\sigma \to \infty$. Precisely, the optimal value of σ is the positive solution of the quadratic equation $\sigma^2 - \frac{4}{9}n_0\sigma - \frac{4}{9}d_0 = 0$.

5 Computing discrete logarithms

In order to smooth the basis of the discrete logarithm and the element whose logarithm is sought, we are going to perform a special-Q descent with a slightly larger subexponentiality parameter $1/3 + \varepsilon$. Let us first describe an algorithm that does one step of the special-Q descent and that will be used as a building block by the final algorithm.

Heuristic Result 7. Let Q be an affine prime divisor of the curve \mathcal{C} of the form $\operatorname{div}(u(X), Y - v(X))$, with $\operatorname{deg} u(X) \leq \log_q L(1/3 + t, c)$ for some constants c > 0 and $\varepsilon < t \leq 1/3 - \varepsilon$. There is an algorithm that finds a divisor R equivalent to Q such that all prime divisors of R are either in \mathcal{F} or have a degree bounded by $\log_q L(1/3 + t - \varepsilon, c')$, and such that all these prime divisors are of the form $\operatorname{div}(u_i(X), Y - v_i(X))$. The heuristic expected running time is bounded by $L(1/3 + \varepsilon, \frac{cn_0}{c'}(1/3 + \varepsilon + o(1)))$.

Justification. Let us consider the set \mathcal{L}_Q of functions of the form a(X) + b(X)Y whose divisors contain Q in their support. In other words, this is the $\mathbb{F}_q[X]$ -lattice

$$\mathcal{L}_{O} = \{ a(X) + b(X)Y : u(X)|a(X) + v(X)b(X) \}.$$

A basis of this lattice is given by the two vectors $b_1 = u(X)$ and $b_2 = -v(X) + Y$. Hence,

$$\mathcal{L}_Q = \{\lambda(X)b_1 + \mu(X)b_2 : \lambda, \mu \in \mathbb{F}_q[X]\}.$$

When λ and μ are taken of degree at most $\delta = \log_q L(1/3 + t, c)$, the function φ corresponding to $\lambda(X)b_1 + \mu(X)b_2$ has the form a(X) + b(X)Y with a and b

of degree $\Delta \leq 2 \log_q L(1/3 + t, c)$. The degree of the norm of φ is then $\Delta n + d$, which is dominated by $\log_q L(2/3 + t, cn_0)$.

We rely now on Heuristic 1 that says that the zero divisor of the function has the same smoothness properties as a random effective divisor of the same degree, and apply Proposition 4. Therefore the expected number of functions one has to try before having found one whose divisor is $\log_q L(1/3+t-\varepsilon,c')$ -smooth is

$$L\left(1/3+\varepsilon,\frac{cn_0}{c'}(1/3+\varepsilon+o(1))\right).$$

The fact that the prime divisors that we obtain are of the same form as Q comes from the shape of the function we have chosen.

It remains to check that the number of functions we can test in the lattice is large enough compared to this expected number of tests. With our choice of δ , the size of the sieving space is L(1/3+t,2c), which is larger than any $L(1/3+\epsilon)$ since t is greater than ε .

This result suffices to carry out a full descent if one can initialise the process and finish it once smoothness is reached up to a $t < \varepsilon$. The next two heuristic results explain these steps.

Heuristic Result 8. Assume that $\rho > (\frac{1}{3} + \varepsilon)\frac{n_0}{2}$. Let Q be an affine prime divisor of C of the form $\operatorname{div}(u(X), Y - v(X))$, with $\operatorname{deg} u(X) \leq \operatorname{log}_q L(1/3 + t, c)$, for some constants c > 0 and $0 < t \leq \varepsilon$. There is an algorithm that finds a divisor R equivalent to Q such that all prime divisors of R are in \mathcal{F} (defined with this value of ρ), and such that all these prime divisors are of the form $\operatorname{div}(u_i(X), Y - v_i(X))$. The heuristic expected running time is bounded by $L\left(1/3 + t, (1/3 + t)\frac{cn_0}{\rho} + o(1)\right)$.

Justification. Let us consider the same lattice \mathcal{L}_Q as in the proof of Proposition 7. Assume that λ and μ are taken of degree at most $\delta = \log_q L(1/3 + t, c)$, then, as before, the norm of the corresponding functions are of degree bounded by $\log_q L(2/3 + t, cn_0)$. Using again Heuristic 1, one gets by Proposition 4 that a $\log_q L(1/3, \rho)$ -smooth divisor can be obtained in heuristic expected time

$$L\left(1/3+t, (1/3+t)\frac{cn_0}{\rho}+o(1)\right).$$

One has to check that we have enough possibilities for λ and μ to cover this search. The sieving space is $q^{2\delta} = L(1/3+t,2c)$. Therefore it is large enough if $2c > (1/3+t)\frac{cn_0}{\rho}$, that is if $\rho > (1/3+t)\frac{n_0}{2}$. Since $\varepsilon > t$, this is guaranteed by our hypothesis on ρ .

Heuristic Result 9. Let D be a degree 0 divisor and $\sum_{P} e_{P} P$ its decomposition into prime divisors such that $\sum_{P} |m_{P}| \in O(g)$. Then there is an algorithm that finds a divisor R equivalent to D such that all prime divisors of R are of the form $\operatorname{div}(u_{i}(X), Y - v_{i}(X))$ with $\operatorname{deg} u_{i}(X) \leq \operatorname{log}_{q} L(2/3 - \varepsilon, c)$. The heuristic expected running time is bounded by $L(1/3 + \varepsilon, (1/3 + \varepsilon) \frac{1}{c} + o(1))$.

Justification. In order to smooth D, we apply the classical Hafner-McCurley strategy: a random linear combination of elements of the factor base is added to D, and the obtained divisor is tested for smoothness. Each test takes polynomial time since the effective group law in the Jacobian reduces to computing Riemann-Roch spaces as in [12].

Following Heuristic 2, the additional restriction on the form of the prime divisors has no influence on the running time, and the desired result follows from Proposition 4.

Armed with these heuristic partial smoothing results, we can now derive a full special-Q descent algorithm. Let us fix a constant $\varepsilon > 0$, a parameter of the algorithm. This ε is to be thought of as small (and of course $\varepsilon < 1/6$). The algorithm assumes that Algorithm 6 has been run as a precomputation, with a value of ρ that is larger than a bound given below. Similarly, the constants c_0 and c_K are made explicit below.

Algorithm 10 (Discrete logarithm).

- 1. Use Heuristic Result 9 to build a list L of prime divisors of degree at most $\log_q L(2/3-\varepsilon,c_0)$, such that if we know their discrete logarithms, the discrete logarithm of D is implied.
- 2. While there is a Q in L of degree more than $\log_q L(1/3+\varepsilon, c_K)$, use Heuristic Result 7 to replace Q in L by a list of prime divisors of degree bounded by a subexponential function with parameter reduced by ε .
- 3. For each Q in L that is not in \mathcal{F} , use Heuristic Result 8 to decompose Q in \mathcal{F} .

In order to analyse the algorithm, let us model it by a tree: the root is the divisor D, its sons are the prime divisors coming from its decomposition using Heuristic Result 9, then each internal node corresponds to a prime divisor and its sons are the prime divisors obtained using Heuristic Result 7 or Heuristic Result 8. The depth of the tree is bounded by $1/(3\varepsilon)$ since at each intermediate step the subexponential parameter is reduced by at least ε and one has to cover a range of 1/3. The number of sons of each node is bounded by g. Hence the total number of nodes is bounded by $g^{1/(3\varepsilon)}$. Since ε is a fixed constant, this is a polynomial in $g \log q$ and therefore contributes only for a o(1) in the subexponential complexity.

Let us allow a computation time of $L(1/3 + \varepsilon, \nu + o(1))$, for fixed positive constants ε and ν . Then the first step that uses Heuristic Result 9 can decompose D in prime divisors of degree at most $\log_q L(2/3-\varepsilon,c_0)$ in time $L(1/3+\varepsilon,\nu+o(1))$ for $c_0 = (1/3+\varepsilon)/\nu$. Going one step down the tree, one can decompose these primes using Heuristic Result 7 in primes of degrees at most $\log_q L(2/3-2\varepsilon,c_1)$ in the same time, for $c_1 = c_0 n_0 (1/3+\varepsilon)/\nu$. Going from level k to level k+1 in the tree will decompose in primes of degree at most $\log_q L(2/3-(k+2)\varepsilon,c_{k+1})$ in the same time, for $c_{k+1} = c_k n_0 (1/3+\varepsilon)/\nu$. Finally, each last step will be feasible in the same running time if $\rho > c_K n_0 (1/3+\varepsilon)/\nu$, where K is the depth of the tree.

This value of ρ is feasible and does not affect the overall complexity. It only changes the exponent in the L(1/3) runtime of the group structure algorithm, whose complexity remains negligible compared to the $L(1/3 + \varepsilon)$ of the present algorithm. Therefore, a suitable choice of ρ , c_0 and c_K in Algorithm 10 results in a running time of $L(1/3 + \varepsilon, \nu + o(1))$ for any given ε and ν .

Choosing $\varepsilon/2$ in the place of ε (and an arbitrary ν) shows that even a complexity of $L(1/3 + \varepsilon, o(1))$ is achievable.

Remark. In the analysis, we have remained silent about the exact nature of the o(1) terms. As long as a fixed number of them is involved, this does not pose any problem. But at first sight, since Heuristic Result 7 is used a non-constant number of times, one apparently needs to make the o(1) terms explicit to check that they do not sum up to something that is not tending to zero. However, although the number of nodes in the tree of Algorithm 10 is in $g^{1/(3\varepsilon)}$, the o(1) term is the same for any given level in the tree, so that actually only the depth of the tree is important for these o(1)-terms considerations. The depth of the tree is in $1/(3\varepsilon)$, which is a constant, so that we actually consider a constant number of o(1) terms and need not make them explicit.

6 Extensions to wider families of curves

6.1 Highly singular curves

Consider the case where the curve has an equation of the appropriate form, but with a genus that is much smaller than nd. Then letting g' = nd, one may apply the exact same algorithms yielding an $L(1/3+\varepsilon)$ complexity. However, the subexponential function is now taken with respect to $q^{g'}$. This may still result in a subexponential complexity in q^g , depending on the relation between q, g and q'.

6.2 Different balancing between n and d

Here we consider the case where $n \approx g^{\alpha}$ and $d \approx g^{1-\alpha}$ for $\alpha \in \left[\frac{1}{3}, \frac{1}{2}\right]$. We shall just give an informal description of an algorithm that yields an L(1/3) complexity for the group structure. Note that to obtain the claimed complexity without ε , the bounds on n and d should resemble the ones we have in Section 4. For instance, bounds of the form $n \leq n_0 g^{\alpha} \mathcal{M}^{-\alpha}$ and $d \leq d_0 g^{1-\alpha} \mathcal{M}^{\alpha}$ would suffice. For the sake of better readability, we content ourselves with approximate bounds.

Let us restrict to C_{ab} curves for simplicity, and let us call P_{∞} the unique place at infinity. We proceed as in Algorithm 6, but the functions we consider are of the more general form:

$$\varphi = a_0(X) + a_1(X)Y + \dots + a_k(X)Y^k,$$

where the $a_i(X)$ have a degree bounded by g^{β} and k is taken of the form g^{γ} , for some β and γ to be determined. Then the divisor of φ is of the form $E - (\deg E)P_{\infty}$, with E effective of degree bounded by $g^{\gamma+1-\alpha} + g^{\beta+\alpha}$.

Fix a smoothness bound of $g^{\beta+\gamma}$; with the usual heuristic, one can find E that is smooth in time about $g^{\max(\alpha-\gamma,(1-\alpha)-\beta)}$. The consistency check that the sieving space must be larger than the factor base yields the condition

$$\beta + \gamma \ge \max(\alpha - \gamma, (1 - \alpha) - \beta),$$

which gives $\beta + 2\gamma \ge \alpha$ and $\gamma + 2\beta \ge 1 - \alpha$. This in turn imposes that $\beta + \gamma \ge 1/3$. Therefore, in this setting we can not hope to get something better than an L(1/3) complexity. We now show that this complexity is achievable: taking $\beta = 2/3 - \alpha$ and $\gamma = \alpha - 1/3$, all the conditions are verified, and the complexity is as announced.

In the particular case of $\alpha=1/3$, we recover $\beta=1/3$ and $\gamma=0$, which corresponds to Algorithm 6. In the other extremal case $\alpha=1/2$, we get $\beta=\gamma=1/6$.

If α gets smaller than 1/3, then the L(1/3) complexity is not achievable with this algorithm. In fact, for each value of $\alpha \in [0,1/3]$, there is an L(x) complexity with $x \in [1/3,1/2]$, and finally, for hyperelliptic curves one essentially recovers Adleman-Demarrais-Huang's L(1/2) algorithm.

All of this concerns only the group structure. For the special-Q descent however, things get more complicated and the $L(1/3 + \varepsilon)$ complexity is lost when α is bigger than 1/3. More precisely, the same kind of computations as above yields a complexity of $L(\alpha + \varepsilon)$ for $\alpha \in [1/3, 1/2]$.

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