

Intro to Scalable Systems - Self-practice

Part 1

1) We can do this using two arrays.

- i) An array of size n to store the elements. Because we know duplicates are not allowed, we can bound the size of the array to n . This array is not ordered. Let us call this $is_elements$.
- ii) An array of size $(n+1)$ to store the index of the element. In this array, we shall call $position$, $position[x]$ will contain the index of the element x in the $is_elements$ array. If an element is not added, we shall set its $position$ to -1 .

Apart from this, we shall also maintain a size variable, which shall contain the ~~not~~ number of elements in the data structure.

Size reduction : We first remove the last element added (~~some~~ $is_elements$) and then update the particular $position$ & decrement the size.

Adding an integer : Add ~~an~~ ^{the} integer to the end of the list, but check that the element does not exist using the $position$ array.

The C++ code is :-

```
int size;  
int elements[n];  
int positions[n+1];  
void init() // resets the arrays  
{  
    size = 0;  
    for(int pos = positions)  
        pos = -1;  
}
```

```
int add(int element)  
{  
    // check if element exists  
    if (positions[element] != -1)  
        return 1; // indicate error
```

```
    size++;  
    elements[size] = element;  
    positions[element] = size;  
    return 0; // indicate success  
}
```

```
int remove()  
{  
    // check if element exists  
    if (size == 0)  
        return 0; // error  
    positions[elements[size]]  
        = -1;  
    size--;  
    return 0;  
}
```

It can be seen, both operations happen in $O(1)$ (constant) time.

Part 2

2) The recurrence relation is:

$$T(n) = \begin{cases} c, & n \leq 1 \\ 2 * T(n-2) + d, & n > 1 \end{cases}$$

$$T(n-2) = 2T(n-4) + d$$

$$\begin{aligned} \therefore T(n) &= 2(2T(n-4) + d) + d \\ &= 4T(n-4) + 3d \end{aligned}$$

$$T(n-4) = 2 \cdot 2T(n-6) + d$$

$$\begin{aligned} \therefore T(n) &= 4(2T(n-6) + d) + 3d \\ &= 8T(n-6) + 7d \end{aligned}$$

$$\therefore T(n) = 2^k T(n-2k) + (2^k - 1)d$$

$$n - 2k = 1$$

$$2k = n$$

$$k = \frac{n}{2}$$

$$= 2^{n/2} T(1) + (2^{n/2} - 1)d$$

$$= 2^{n/2} + 2^{n/2}d - 1$$

$$= 2^{n/2} (1 + d) - 1$$

neglecting constant terms, $T(n) = O(2^{n/2})$

2) For n^k to be $O(n)$, $n^k \leq n$

$$n^k \leq n$$

$k \leq 1$ (We can log_n both sides because we know n is +ve)

$$\therefore 0 \leq k \leq 1$$

Hence, for all $k \in [0, 1]$, $n^k = O(n)$

Part 3

1) Proof by induction:

Tree w/ one node

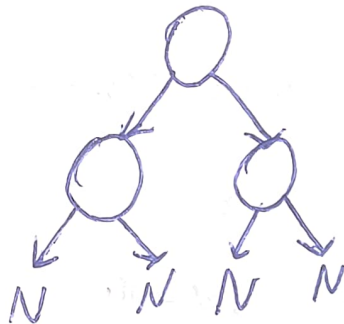


number
of roots
pointers

2

no. of
null pointers

2



6

4

(shown)

Proof by mathematics:

We know that the ~~top~~ only leaf nodes of a ^{complete} binary tree will have NULL pointers.

The number of leaf nodes = $\left\lfloor \frac{n+1}{2} \right\rfloor$, where n is the total no. of nodes.

~~If we consider to~~

$$\text{Hence no. of null nodes} = 2 \left\lfloor \frac{n+1}{2} \right\rfloor = n+1$$

Part 4

// Assuming A is stored in array H . Also, array is global.

modify-key (index, new-key)

{

$H[i] = \text{new-key};$ // $O(1)$

~~$\text{if } (H[i] - H[\lfloor \frac{i-1}{2} \rfloor])$ // (check against parent)~~

~~$\text{int temp} = H[i];$~~

~~$H[i] = H[\lfloor \frac{i-1}{2} \rfloor]$~~

adjust (i);

// $O(\log n)$

}

adjust (i) // Adjusts the tree

{ if $\left(H[i] < H\left[\left\lfloor \frac{i-1}{2} \right\rfloor\right] \right)$ // check against parent

int temp = H[i];

H[i] = H $\left[\left\lfloor \frac{i-1}{2} \right\rfloor\right]$;

H $\left[\left\lfloor \frac{i-1}{2} \right\rfloor\right]$ = temp;

adjust $\left(\left\lfloor \frac{i-1}{2} \right\rfloor\right)$;

else:

return;

}

The worst case time complexity is $O(\log n)$ because of the adjust sub-module.

Parts

i) // To find array to be of size n , array name is A
int ~~base~~ ternary-search (int key, int start, int end)

{

int one-third = $\frac{\text{end} - \text{start}}{3} + \text{start}$;

int two-third = $2 * \frac{\text{end} - \text{start}}{3} + \text{start}$;

if (A[one-third] == key) return one-third;

```

else if (A[two-third] == key) return two-third;
else if (A[one-third] > key)
    return ternary-search(key, start, one-third);
else if (A[two-third] > key)
    return ternary-search(key, one-third, two-third);
else
    return ternary-search(key, two-third, end);
}

```

~~2) ~~1)~~ Pseudo code:~~

~~1)~~

~~while (curr-s != null && curr-t != null)~~
~~hashmap.add~~

2) Algorithm

- 1) Create a hashmap to store element (key) & frequency.
- 2) Create a while loop which runs until either one of the list has been traversed in full.
 - a) ~~For~~ Add the element from S into the hashmap.
 - i) If the element is already in the hashmap, increment the frequency.
 - ii) If the element is not in the hashmap, add it ~~and~~ with frequency = 1.
 - b) "Remove the element" from ~~S~~ ^T from the hashmap.
 - i) If the element exists in the hashmap, decrement its frequency.
 - ii) Otherwise, add the element to the hashmap with frequency = -1.
 - iii) If the frequency after decrement is 0, delete the element from the hashmap.
- c) Increment the ~~pos~~ S-cur & T-cur pointers.

3) If ^{one} either of the lists has finished traversing, but the other has not, return 0 (not equal), because one has more elements than the other.

4) Check ~~if~~ the size (no of key-value pairs) on the hashmap

i) If no elements are remaining, $S = T$.

ii) otherwise $S \neq T$.

~~Part 6~~
~~i) or~~

~~Part 7~~

~~i) Because $A[1] < A[2] < \dots < A[n]$, we know that A is a sorted one-dimensional array. For such an array, we can use binary search. The steps of the algorithm are:~~

~~i) Identify the start and end indices of the array. Initially, they shall be 1 & n respectively.~~

~~2) Identify the midpoint: $\left\lfloor \frac{\text{start} + \text{end}}{2} \right\rfloor$~~

Part 7

1) Because the array is sorted in ascending orders we may use a modified version of binary search. The steps of the algorithm are as follows:

- 1) Identify the start & end indices of the search space. We shall be halving ~~the~~ the dimension of the search space in each iteration. Initially $\text{start} = 1$ and $\text{end} = n$.
- 2) Identify the midpoint of start & end: $m = \left\lfloor \frac{\text{end} + \text{start}}{2} \right\rfloor$
- 3) Check the element at index m
 - a) If $A[m] == m$, we have found the answer.
 - b) Else, if $A[m] > m$, we need to search between start and m . Hence update $\text{start} = m$.
 - c) Else, we need to search between m & end. Hence update $\text{end} = m$.
- 4) Continue steps 2 & 3 until either the element is found or $\text{start} = \text{end}$.

Because we are halving the interval, the TC is $O(\log n)$

2) Algorithm:

- 1) Perform a first BFS from the root. Obtain the node that ~~that~~ is the furthest from the root.
- 2) Perform a second BFS from the node found in step 1.
- 3) The distance between the u node found in step 1 and the furthest node in the BFS from step 2 will be the diameter.

Pseudocode:

Let n = no. of vertices & g = adj list representation of tree.

& root = root of tree.

if ($n \leq 1$): return 0;

$u = \text{BFS}(\text{root}, g)$

$\text{diameter} = \text{BFS}(u, g)$

print diameter

// code for BFS

~~function~~ BFS (start, return-dist)

queue q; dist[n] = $-1 \times n$;

q.enqueue(start)

dist[start] = 0 // dist is an array to contain distances from start

max-dist = 0

furthest = start

while queue is not empty:

u = q.dequeue()

for each neighbour v of u:

if dist[v] == -1: // unvisited node

q.enqueue(v);

dist[v] = dist[u] + 1

// Update furthest node

if dist[v] > max-dist:

max-dist = dist[v]

furthest = v

if (return-dist) return max-dist;

else

return furthest;