

MPI – Message Passing Interface

Source: <http://www.netlib.org/utk/papers/mpi-book/mpi-book.html>

Message Passing Principles

- Explicit communication and synchronization
- Programming complexity is high
- But widely popular
- More control with the programmer

MPI Introduction

- A standard for explicit message passing in MIMD machines.
- Need for a standard
 - >> portability
 - >> for hardware vendors
 - >> for widespread use of concurrent computers
- Started in April 1992, MPI Forum in 1993, 1st MPI standard in May 1994, MPI-2 in 1997, MPI-3 in 2012

MPI contains...

- Point-Point (1.1)
- Collectives (1.1)
- Communication contexts (1.1)
- Process topologies (1.1)
- Profiling interface (1.1)
- I/O (2)
- Dynamic process groups (2)
- One-sided communications (2)
- Extended collectives (2)

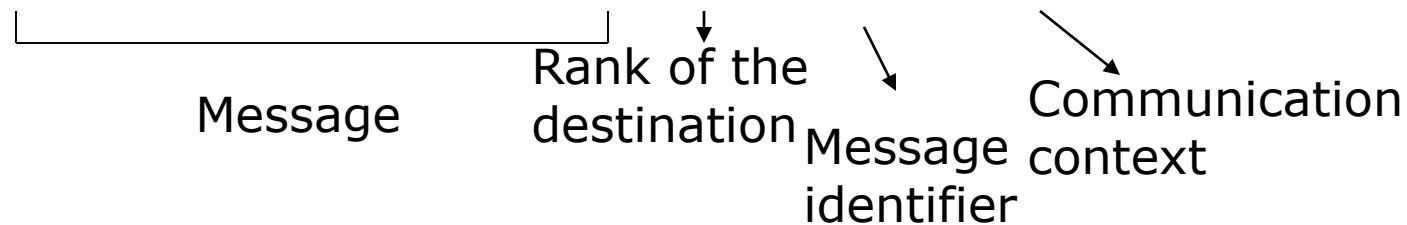


Communication Primitives

- Communication scope
- Point-point communications
- Collective communications

Point-Point communications – send and recv

MPI_SEND(buf, count, datatype, dest, tag, comm)



MPI_RECV(buf, count, datatype, source, tag, comm, status)

MPI_GET_COUNT(status, datatype, count)

A Simple Example

```
comm = MPI_COMM_WORLD;
rank = MPI_Comm_rank(comm, &rank);
for(i=0; i<n; i++) a[i] = 0;
if(rank == 0){
    MPI_Send(a+n/2, n/2, MPI_INT, 1, tag, comm);
}
else{
    MPI_Recv(b, n/2, MPI_INT, 0, tag, comm, &status);
}
/* process array a */

/* do reverse communication */
```

Communication Scope

- Explicit communications
- Each communication associated with communication scope
- Process defined by
 - *Group*
 - Rank within a group

Message label by

- Message *context*
- Message tag

A communication handle called *Communicator* defines the scope

Communicator

- Communicator represents the communication domain
- Helps in the creation of process groups
- Can be intra or inter (more later).
- Default communicator – MPI_COMM_WORLD includes all processes
- Wild cards:
 - The receiver source and tag fields can be wild carded – MPI_ANY_SOURCE, MPI_ANY_TAG

Utility Functions

- MPI_Init, MPI_Finalize
- MPI_Comm_size(comm, &size);
- MPI_Comm_rank(comm, &rank);
- MPI_Wtime()

Example 1: Finding Maximum using 2 processes

```
1 #include "mpi.h"
2 int main(int argc, char** argv){
3     int n;
4     int *A, *local_array;
5     int max, local_max, rank1_max, i;
6     MPI_Comm comm;
7     MPI_Status status;
8     int rank, size;
9     int LARGE_NEGATIVE_NUMBER = -999999;
10
11     MPI_Init(&argc, &argv);
12
13     comm = MPI_COMM_WORLD;
14     MPI_Comm_rank(comm, &size);
15     MPI_Comm_rank(comm, &rank);
16
17     if(size != 2){
18         printf("This program works with only two processes.\n");
19         exit(0);
20     }
21 }
```

Example 1: Finding Maximum using 2 processes

```
22 if( rank == 0){
23     /* Read N from console */
24     MPI_Send(&N,1,MPI_INT,1,5,comm);
25     /* Do dynamic allocation of A array with N elements */
26     /* Initialize an array $A$ of $N$ elements */
27     /* Do dynamic allocation of local_array with N/2 elements */
28     for(i=0; i<N/2; i++){
29         local_array [ i ] = A[ i ];
30     }
31     MPI_Send(A+N/2,N/2,MPI_INT,1,10,comm);
32 }
33 else{
34     MPI_Recv(&N,1,MPI_INT,0,5,comm,&status);
35     /* Do dynamic allocation of local_array with N/2 elements */
36     MPI_Recv(local_array ,N/2,MPI_INT,0,10,comm,&status);
```

Example 1: Finding Maximum using 2 processes

```
39 local_max = LARGE_NEGATIVE_NUMBER;
40 for(i=0; i<N/2; i++){
41     if(local_array [i] > local_max){
42         local_max = local_array [i];
43     }
44 }
45
46 if(rank == 1){
47     MPI_Send(&local_max ,1 ,MPI_INT ,0 ,15 ,comm);
48 }
49 else {
50     max = local_max;
51     MPI_Recv(&rank1_max ,1 ,MPI_INT ,1 ,15 ,comm);
52     if(rank1_max > max){
53         max = rank1_max;
54     }
55 }
56
57 printf( "Maximum number is %d\n" , max);
58
59 MPI_Finalize ();
60 }
61 }
```

Buffering and Safety

The previous send and receive are **blocking**. Buffering mechanisms can come into play.

Safe buffering:

OK

Process 0

MPI_Send
MPI_Recv
.....

Process 1

MPI_Recv
MPI_Send
.....

Leads to deadlock

MPI_Recv
MPI_Send
.....

MPI_Recv
MPI_Send
.....

May or may not succeed. Unsafe

MPI_Send
MPI_Recv
.....

MPI_Send
MPI_Recv
.....

Non-blocking communications

- A *post* of a send or recv operation followed by *complete* of the operation
- **MPI_ISEND(buf, count, datatype, dest, tag, comm, request)**
- **MPI_IRecv(buf, count, datatype, dest, tag, comm, request)**
- **MPI_WAIT(request, status)**
- **MPI_TEST(request, flag, status)**
- **MPI_REQUEST_FREE(request)**

Non-blocking

- A post-send returns before the message is copied out of the send buffer
- A post-recv returns before data is copied into the recv buffer
- Efficiency depends on the implementation

Other Non-blocking communications

- **MPI_WAITANY(count, array_of_requests, index, status)**
- **MPI_TESTANY(count, array_of_requests, index, flag, status)**
- **MPI_WAITALL(count, array_of_requests, array_of_statuses)**
- **MPI_TESTALL(count, array_of_requests, flag,
array_of_statuses)**
- **MPI_WAITSOME(incount, array_of_requests, outcount,
array_of_indices, array_of_statuses)**
- **MPI_TESTSOME(incount, array_of_requests, outcount,
array_of_indices, array_of_statuses)**

Buffering and Safety

Process 0

```
MPI_Send(1)  
MPI_Send(2)  
.....
```

Process 1

```
MPI_Irecv(2)  
MPI_Irecv(1)  
.....
```

Safe

```
MPI_Isend  
MPI_Recv  
.....
```

```
MPI_Isend  
MPI_Recv  
.....
```

Safe

Example: Finding a Particular Element in an Array

```
#include "mpi.h"
int main(int argc, char** argv){
    ...
    ...
    int other_i, other_rank, flag;
    MPI_Request request;
    ...
    ...

    ...
    ...
    other_rankif(rank == 0) other\_rank=1
    other_rank = (rank==0)?1:0;
    MPI_Irecv(&other_i ,1 ,MPI_INT ,other_rank ,10 ,comm,&request );
    for(i=0; i<N/2; i++){
        if(A[ i ] == elem){
            /* Ah, found it! Inform the other process of the index
               position*/
            MPI\_Send(&i ,1 ,MPI_INT ,other_rank ,10 ,comm);
            if(rank == 0){
                global_pos = i ;
            }
            /* Cancel the posted Irecv posted by this process */
            MPI_Cancel(&request );
            break;
        }
    }
}
```

Example: Finding a Particular Element in an Array

```
24     else {
25         MPI_Test(&request ,&flag ,&status );
26         if( flag == 1){
27             /* Ah, the other process has found it. */
28             MPI_Wait(&request ,&status );
29             if(rank == 0){
30                 global_pos = other_i + N/2;
31             }
32             break;
33         }
34     }
35 }
36
37 if(rank == 0){
38     printf("Found the element %d in position %d\n", elem ,
39             global_pos );
40 }
41 MPI_Finalize () ;
```

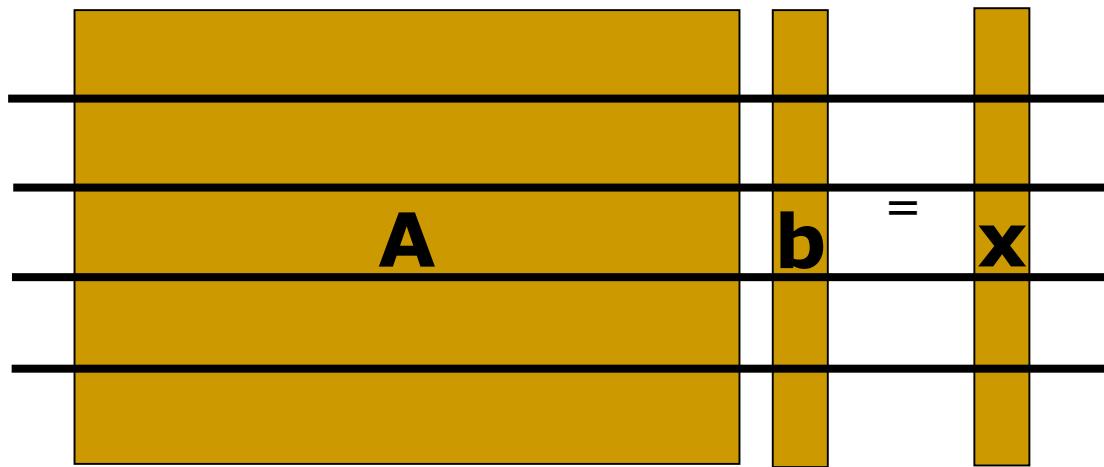
Communication Modes

Mode	Start	Completion
Standard (MPI_Send)	Before or after recv	Before recv (buffer) or after (no buffer)
Buffered (MPI_Bsend) (Uses MPI_Buffer_Attach)	Before or after recv	Before recv
Synchronous (MPI_Ssend)	Before or after recv	Particular point in recv
Ready (MPI_Rsend)	After recv	After recv



Collective Communications

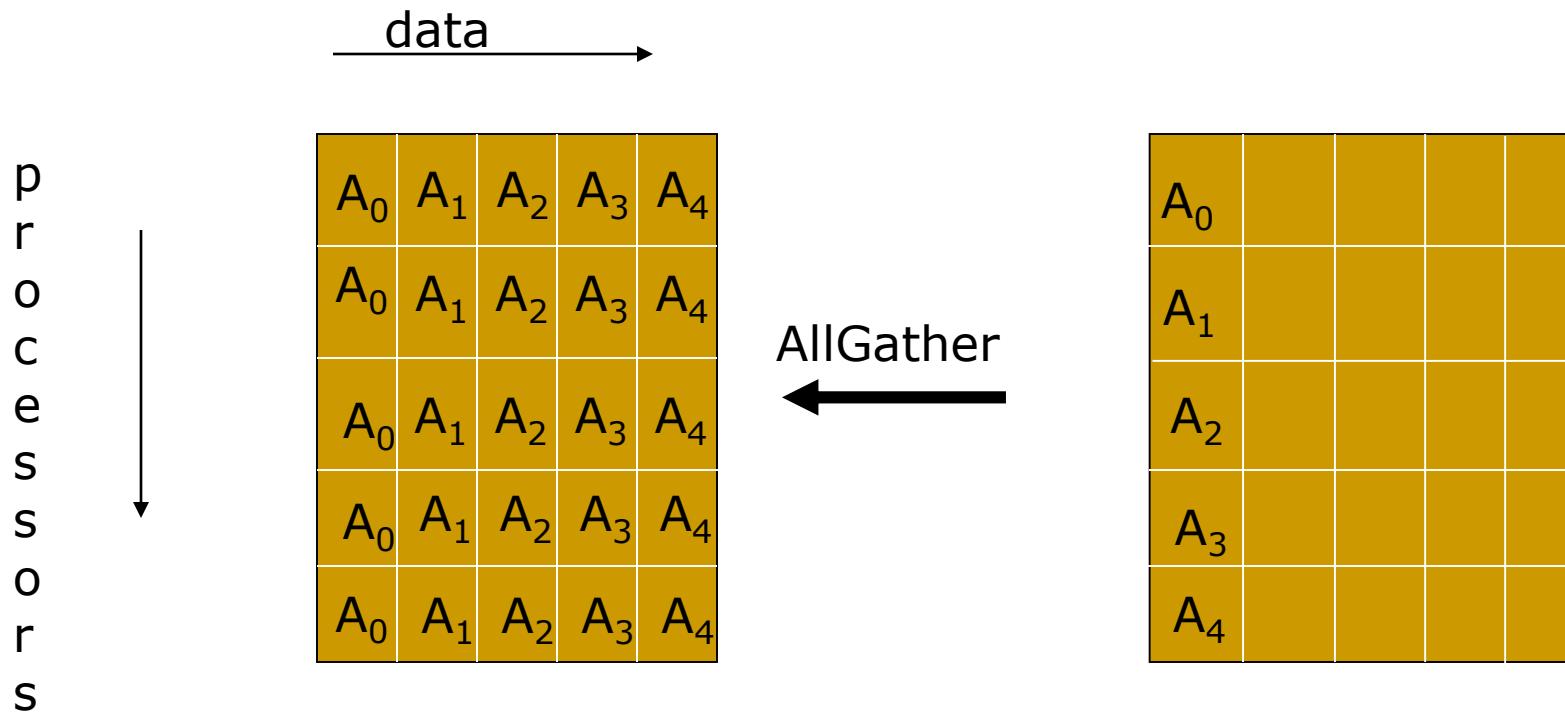
Example: Matrix-vector Multiply



Communication:

All processes should gather all elements of **b**.

Collective Communications – AllGather



MPI_ALLGATHER(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, comm)

MPI_ALLGATHERV(sendbuf, sendcount, sendtype, array_of_recvbuf, array_of_displ, recvcount, recvtype, comm)

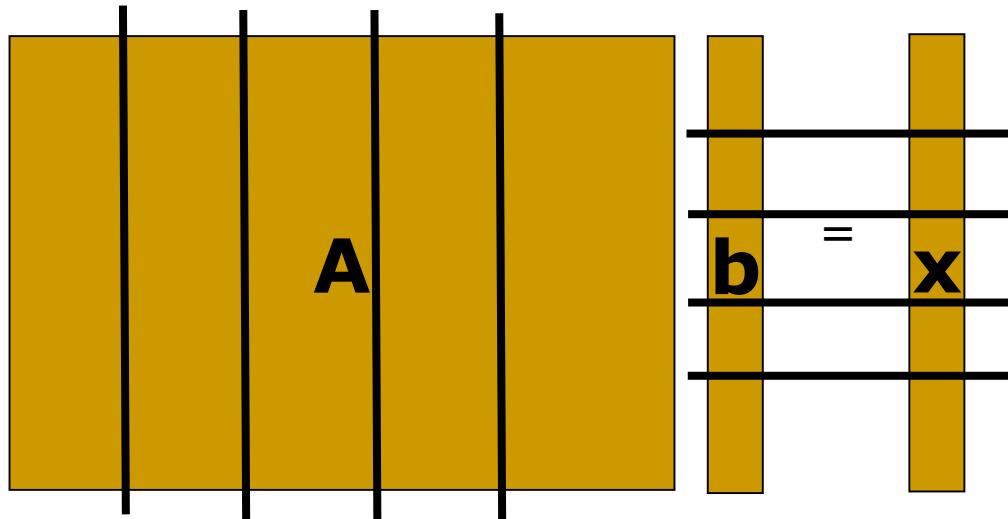
Example: Row-wise Matrix-Vector Multiply

```
MPI_Comm_size(comm, &size);
MPI_Comm_rank(comm, &rank);
nlocal = n/size ;
```

```
MPI_Allgather(local_b,nlocal,MPI_DOUBLE, b, nlocal,
    MPI_DOUBLE, comm);
```

```
for(i=0; i<nlocal; i++){
    x[i] = 0.0;
    for(j=0; j<n; j+=)
        x[i] += a[i*n+j]*b[j];
}
```

Example: Column-wise Matrix-vector Multiply



Dot-products corresponding to each element of x will be parallelized

Steps:

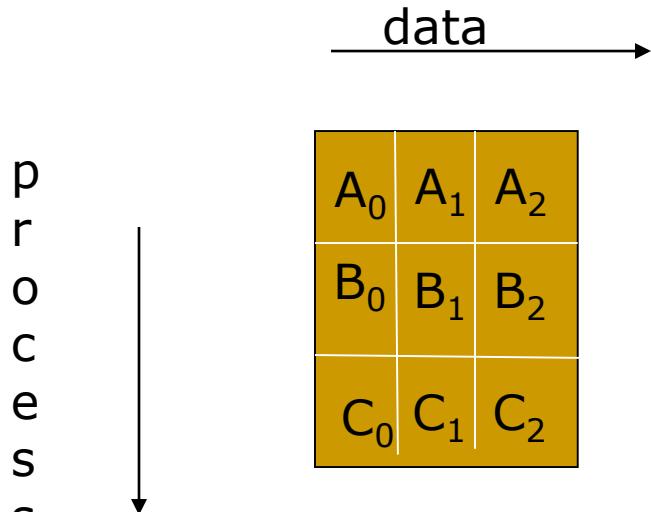
1. Each process computes its contribution to x
2. Contributions from all processes are added and stored in appropriate process.

Example: Column-wise Matrix-Vector Multiply

```
MPI_Comm_size(comm, &size);
MPI_Comm_rank(comm, &rank);
nlocal = n/size;

/* Compute partial dot-products */
for(i=0; i<n; i++){
    px[i] = 0.0;
    for(j=0; j<nlocal; j+=)
        px[i] += a[i*nlocal+j]*b[j];
}
```

Collective Communications – Reduce, Allreduce



Reduce →

A ₀ +B ₀ +C ₀	A ₁ +B ₁ +C ₁	A ₂ +B ₂ +C ₂

MPI_REDUCE(sendbuf, recvbuf, count, datatype, op, root, comm)

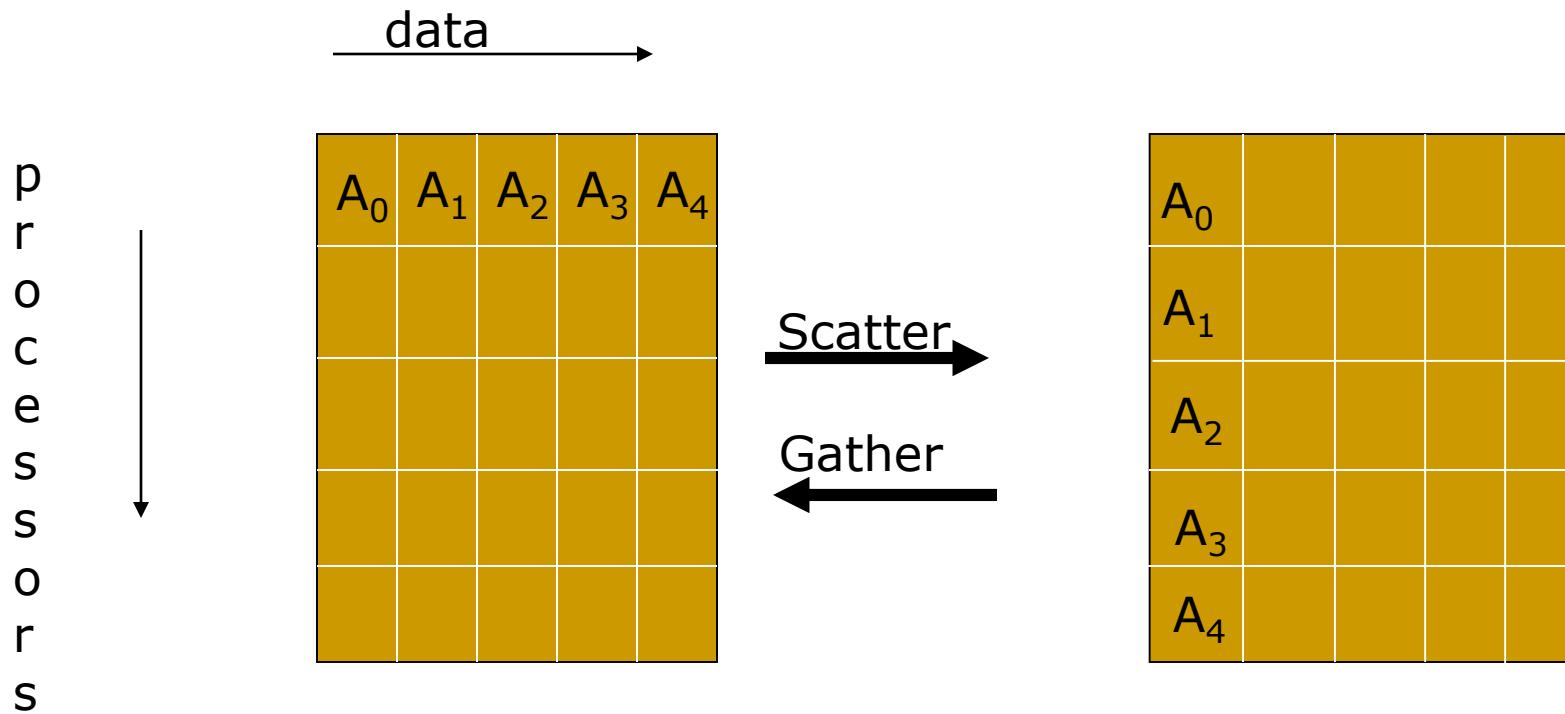
A ₀	A ₁	A ₂
B ₀	B ₁	B ₂
C ₀	C ₁	C ₂

AllReduce →

A ₀ +B ₀ +C ₀	A ₁ +B ₁ +C ₁	A ₂ +B ₂ +C ₂
A ₀ +B ₀ +C ₀	A ₁ +B ₁ +C ₁	A ₂ +B ₂ +C ₂
A ₀ +B ₀ +C ₀	A ₁ +B ₁ +C ₁	A ₂ +B ₂ +C ₂

MPI_ALLREDUCE(sendbuf, recvbuf, count, datatype, op, comm)

Collective Communications – Scatter & Gather



```
MPI_SCATTER(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, root, comm)
MPI_SCATTERV(sendbuf, array_of_sendcounts, array_of_displ, sendtype, recvbuf,
recvcount, recvtype, root, comm)
```

```
MPI_GATHER(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, root, comm)
MPI_GATHERV(sendbuf, sendcount, sendtype, recvbuf, array_of_recvcounts,
array_of_displ, recvtype, root, comm)
```

Example: Column-wise Matrix-Vector Multiply

```
/* Summing the dot-products */  
MPI_Reduce(px, fx, n, MPI_DOUBLE,  
           MPI_SUM, 0, comm);  
  
/* Now all values of x is stored in process 0.  
   Need to scatter them */  
MPI_Scatter(fx, nlocal, MPI_DOUBLE, x,  
            nlocal, MPI_DOUBLE, 0, comm);
```

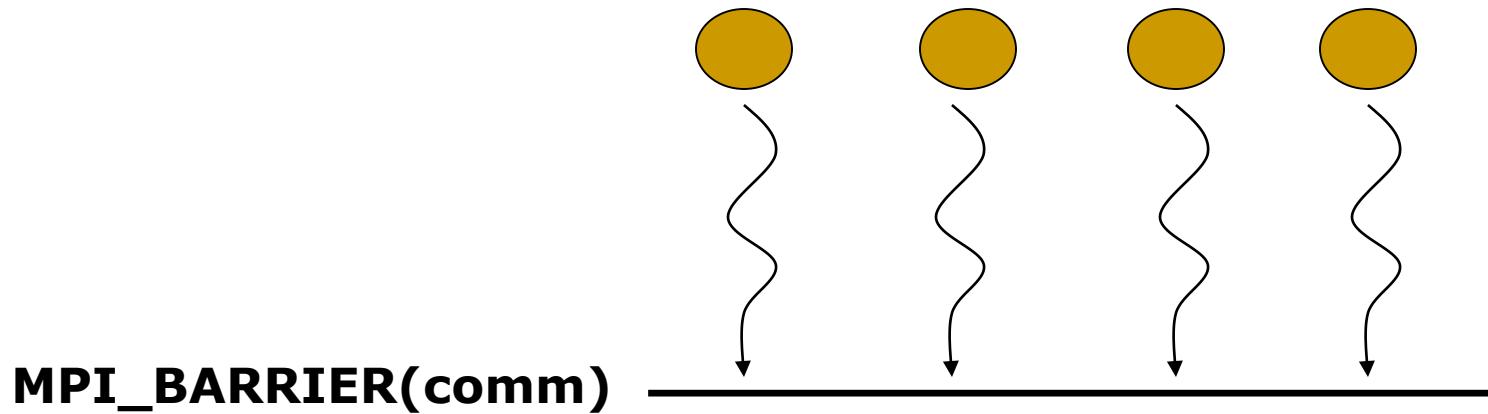
Or...

```
for(i=0; i<size; i++){  
    MPI_Reduce(px+i*nlocal, x, nlocal,  
    MPI_DOUBLE, MPI_SUM, i, comm);  
}
```

Collective Communications

- Only blocking; standard mode; no tags
- Simple variant or “vector” variant
- Some collectives have “root”s
- Different types
 - One-to-all
 - All-to-one
 - All-to-all

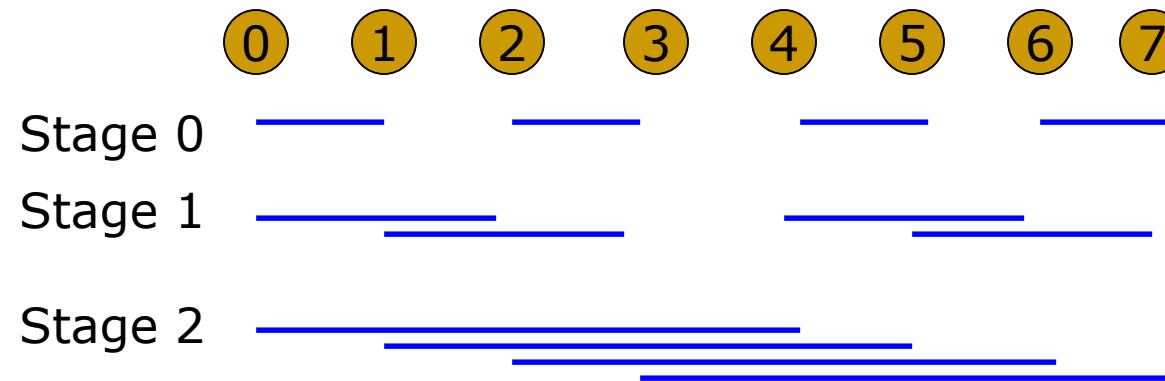
Collective Communications - Barrier



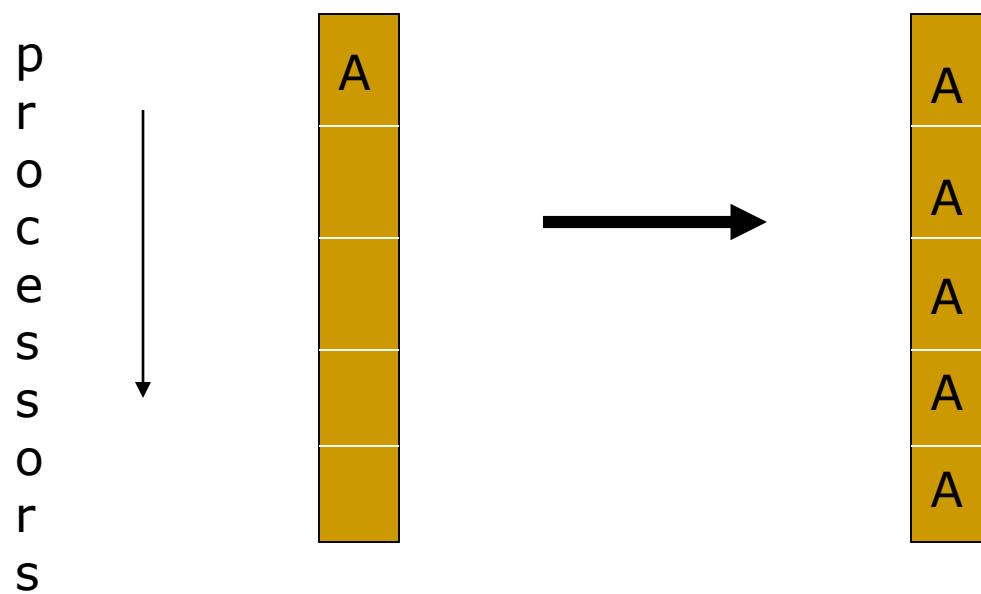
A return from barrier in one process tells the process that the other processes have **entered** the barrier.

Barrier Implementation

- **Butterfly barrier** by Eugene Brooks II
- In round k , i synchronizes with $i+2^k$ pairwise.
- Worstcase – $2\log P$ pairwise synchronizations by a processor



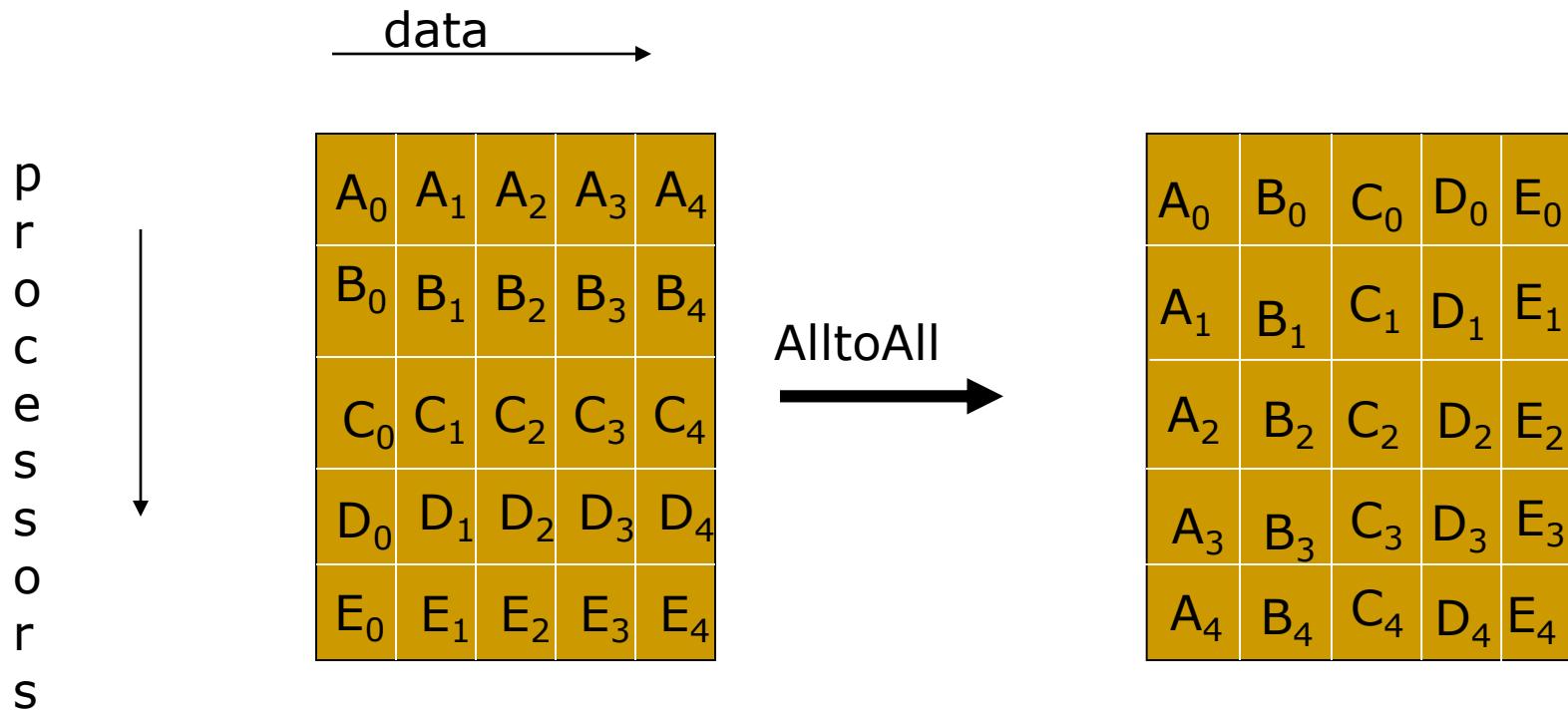
Collective Communications - Broadcast



Can be implemented as
trees

`MPI_BCAST(buffer, count, datatype, root, comm)`

Collective Communications – AlltoAll



MPI_ALLTOALL(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, comm)

**MPI_ALLTOALLV(sendbuf, array_of_sendcounts, array_of_displ, sendtype,
array_of_recvbuf, array_of_displ, recvcount, recvtype, comm)**

AlltoAll

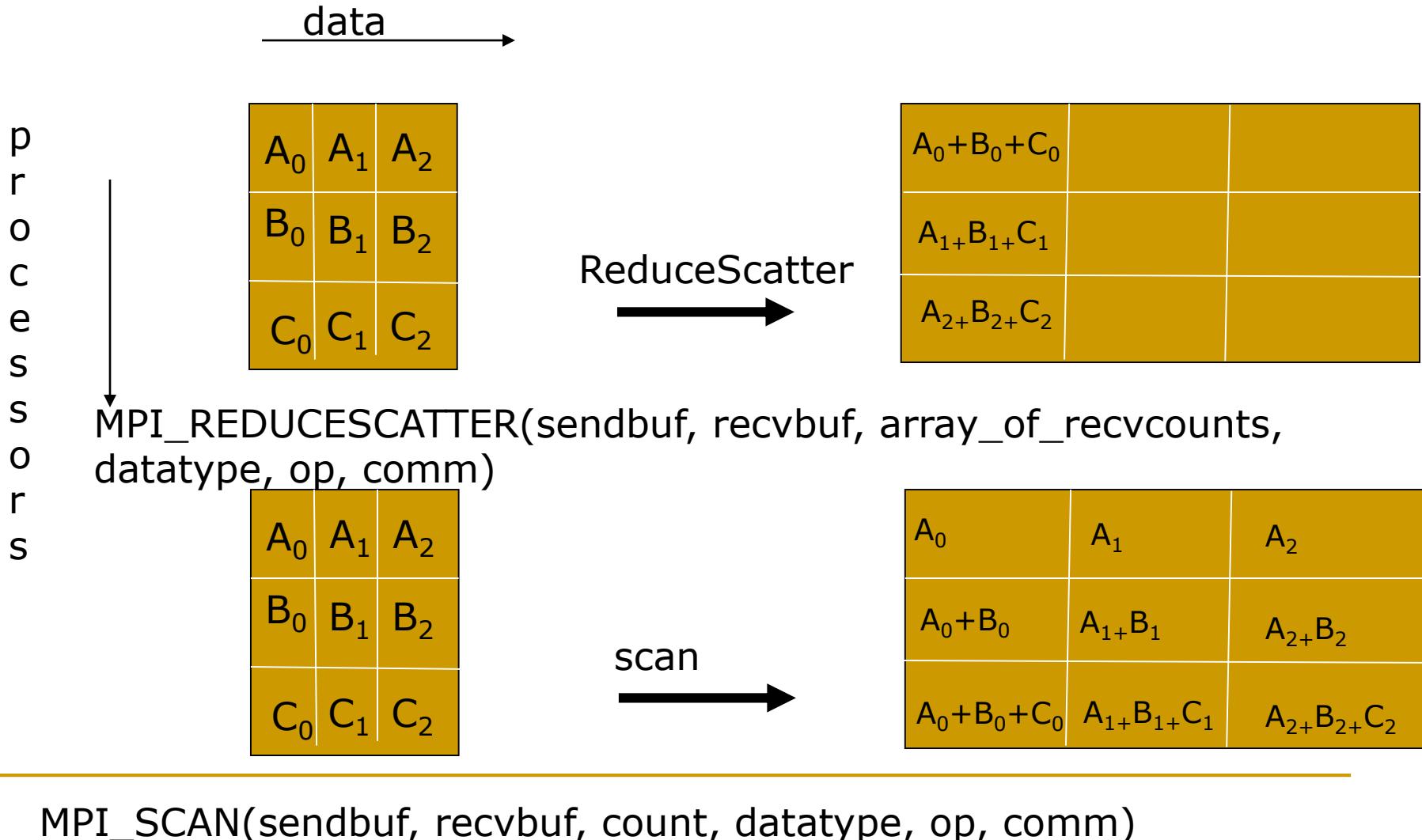
■ The naive implementation

```
for all procs. i in order{  
    if i # my proc., then send to i and recv from i  
}
```

■ MPICH implementation – similar to naïve, but doesn't do it in order

```
for all procs. i in order{  
    dest = (my_proc+i)modP  
    src = (myproc-i+P)modP  
    send to dest and recv from src  
}
```

Collective Communications – ReduceScatter, Scan



Allgather implementation

- In general, optimized allxxx operations depend on hardware topology, network contentions etc.
- Circular/ring allgather
- Each process receives from left and sends to right
- P steps

