

Intro to Scalable systems - Self-practice

Part 1

i) We can do this using two arrays.

i) An array of size n to store the elements. Because we know duplicates are not allowed, we can bound the size of the array to n . This array is not ordered. Let us call this as elements.

ii) An array of size $(n+1)$ to store the index of the element. In this array, we shall call position, position[ℓ]. It will contain the index of the element m in the elements array. If an element is not added, we shall set its position to -1.

Apart from this, we shall also maintain a size variable, which shall contain the total number of elements in the data structure.

Size reduction : We first remove the last element added (~~sooner the streak~~) and then update the particular position & decrement the size.

Adding an integer : Add ^{the} integer to the end of the list, but check that the element does not exist using the position array.

The C++ code is :-

```
int size;  
int elements[n];  
int positions [n+1];  
void init() // reset the arrays  
{  
    size = 0;  
    for(int pos = positions)  
        pos = -1;  
}
```

int add (int element)

```
{  
    // check if element exists  
    if (positions[element] != -1)  
        return 1; // indicate error  
    size++;
```

```
    elements[size] = element;  
    positions[element] = size;  
    return 0; // indicate success
```

```
}  
int remove()  
{  
    // check if element exists  
    if (size == 0)  
        return 0; // error  
    positions [element [size]]  
    = -1;  
    size--;  
    return 0;
```

It can be seen, both operations happen in $O(1)$ (constant) time.

Part 2

2) The recurrence relation is:

$$T(n) = \begin{cases} c & , n \leq 1 \\ 2 * T(n-2) + d, & n > 1 \end{cases}$$

$$T(n-2) = 2T(n-4) + d$$

$$\begin{aligned} \therefore T(n) &= 2(2T(n-4) + d) + d \\ &= 4T(n-4) + 3d \end{aligned}$$

$$T(n-4) = \cancel{2} \cdot 2T(n-6) + d$$

$$\begin{aligned} \therefore T(n) &= 4(2T(n-6) + d) + 3d \\ &\sim 8T(n-6) + 7d \end{aligned}$$

$$\therefore T(n) = 2^n T(n-2^{\lfloor \frac{n}{2} \rfloor}) + (2^{\lfloor \frac{n}{2} \rfloor} - 1)d$$

$$\left. \begin{array}{l} n-2^{\lfloor \frac{n}{2} \rfloor} = 1 \\ 2^{\lfloor \frac{n}{2} \rfloor} = 2^{\frac{n}{2}} \\ \lfloor \frac{n}{2} \rfloor = \frac{n}{2} \end{array} \right| \begin{aligned} &\sim 2^{\frac{n}{2}} T(1) + (2^{\frac{n}{2}} - 1)d \\ &\sim 2^{\frac{n}{2}} + 2^{\frac{n}{2}} d - 1 \\ &\sim 2^{\frac{n}{2}} (1+d) - 1 \end{aligned}$$

Ignoring constant terms, $T(n) = O(2^{\frac{n}{2}})$

2) For n^{κ} to be $O(n)$, $n^{\kappa} \leq n$

$$n^{\kappa} \leq n$$

$\kappa \leq 1$ (We can log_n both sides because we know n is true)

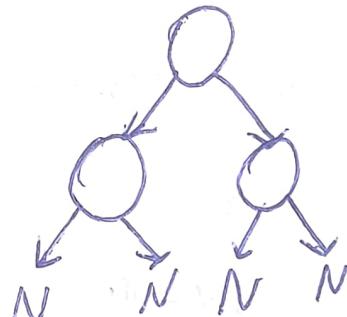
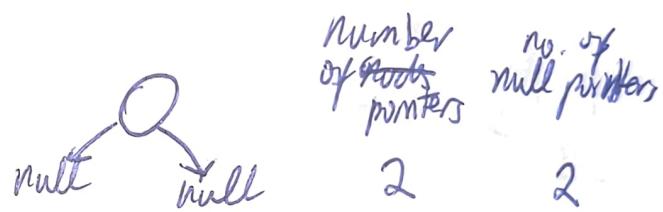
$$\therefore 0 \leq \kappa \leq 1$$

Hence, for all $\kappa \in [0, 1]$, $n^{\kappa} = O(n)$

Part 3

1) Proof by induction:

Tree w/ one node



6 4

(shown)

Proof by mathematics

We know that the top only leaf nodes of a binary tree complete will have NULL pointers.

The number of leaf nodes = $\left\lfloor \frac{n+1}{2} \right\rfloor$, where n is the total no. of nodes.

~~by observation~~

$$\text{Hence no. of null nodes} = 2 \left\lfloor \left\lfloor \frac{n+1}{2} \right\rfloor \right\rfloor = n+1$$

Part 4

// Assuming B is stored in array H. Also, array is global.

modify-key (index, new-key)

{

$$H[i] = \text{new-key}; \quad // O(1)$$

~~$H[i] = H\left[\left\lfloor \frac{i-1}{2} \right\rfloor\right]$ // character assignment~~

~~int temp = H[i];~~

~~$H[i] = H\left[\left\lfloor \frac{i-1}{2} \right\rfloor\right]$~~

adjust (i); $\quad // O(\log n)$

g

adjust(1) // Adjusts the tree

{ if ($A[i] < H\left[\left\lfloor \frac{i-2}{2} \right\rfloor\right]$) // check against parent

int temp = $H[i];$

$H[i] = H\left[\left\lfloor \frac{i-2}{2} \right\rfloor\right];$

$H\left[\left\lfloor \frac{i-2}{2} \right\rfloor\right] = \text{temp};$

adjust($\left\lfloor \frac{i-2}{2} \right\rfloor$);

else:

return;

}

The worst case time complexity is $O(\log n)$ because of the adjust sub-module.

Part 5

i) // Turn array to be of size $\Theta(n)$, array name is A
int ~~one~~ memory-search (int key, int start, int end)

{

int one-third = $\frac{\text{end}-\text{start}}{3} + \text{start};$

int two-third = $2 * \frac{\text{end}-\text{start}}{3} + \text{start};$

if ($A[\text{one_third}] == \text{key}$) return one-third;

```
else if (A[two-third] == key) return two-third;  
else if (A[one-third] > key)  
    return ternary-search(key, start, one-third);  
else if (A[two-third] > key)  
    return ternary-search(key, one-third, two-third);  
else  
    return ternary-search(key, two-third, end);
```

2) ~~2.7~~ Pseudo code:

~~while (curr-s != null & curr-t != null)~~
~~hashmap.add~~

2) Algorithm

1) Create a hash map to store element (key) & frequency.

2) Create a while loop which runs until either one of the list has been traversed in full.

a) ~~For~~ Add the element from S into the hash map.

i) If the element is already in the hash map, increment the frequency.

ii) If the element is not in the hash map, add it ~~and~~ with frequency = 1.

b) "Remove the element" from T ^{from} ~~from~~ the hash maps.

i) If the element exists in the hash map, decrement its frequency.

ii) Otherwise, add the element to the hash map with frequency = -1;

iii) If the frequency after decrement is 0, delete the element from the hash map.

c) Increment the ~~for~~ S-cur & T-cur pointers.

- one
- 3) If either of the lists has finished traversing, but the other has not, return 0 (not equal), because one has more elements than the other.
- 4) Check if the size (no of key-value pairs) in the hashmap
- If no elements are remaining, $S = T$.
 - Otherwise $S \neq T$.

Part 6
D. O)

Part 7

- 1) Because $A[1] < A[2] < \dots < A[n]$, we know that it is a sorted one-dimensional array. For such an array, we can use binary search. The steps of the algorithm are:
- Identify the start and end indexes of the array. It initially, they shall be 1 & n respectively.

~~2) Identify the mid point : $\left\lfloor \frac{\text{start} + \text{end}}{2} \right\rfloor$~~

Part 2

1) Because the array is sorted in descending order we may use a modified version of binary search. The steps of the algorithm are as follows :

- 1) Identify the start & end indices of the search space. We shall be halving the dimension of the search space in each iteration. Initially start = 1 and end = n.
- 2) Identify the midpoint of start & end : $m = \left\lfloor \frac{\text{end} + \text{start}}{2} \right\rfloor$
- 3) Check the element at index m
 - a) If $A[m] \neq m$, we have found the answer.
 - b) Else, if $A[m] > m$, we need to search between start and m. Hence update start = m.
 - c) Else, we know to search between m & end. Hence update end = m.
- 4) Continue steps 2 & 3 until either the element is found or start = end.

Because we are halving the interval, the T.C is $O(\log n)$

2) Algorithms:

- 1) Perform a first BFS from the root. Obtain the node that is the furthest from the root.
- 2) Perform a second BFS from the node found in step 1.
- 3) The distance between the node found in step 1 and the furthest node in the BFS from step 2 will be the diameter.

Pseudocode:

Let $n = \text{no. of vertices}$ & $g = \text{adj list representation of tree}$.

& $\text{root} = \text{root of tree}$.

if ($n \leq 1$) : return 0;

$u = \text{BFS}(root, p)$

$\text{diameter} = \text{BFS}(u, 1)$

print diameter

// code for BFS

~~function~~ BFS (start, return-dist)

queue q; dist[n] = -1 * n;

f. enqueue (start)

dist[start] = 0 // dist is an array to contain distances from start

max-dist = 0

furthest = start

while queue is not empty:

u = q.dequeue()

for each neighbour v of u:

if dist[v] == -1: // unvisited node

q.enqueue(v);

dist[v] = dist[u] + 1

// Update furthest node

if dist[v] > max-dist:

max-dist = dist[v]

furthest = v

if (return-dist) return max-dist;

else return furthest;