

Singular value Decomposition (SVD)

Applications :-

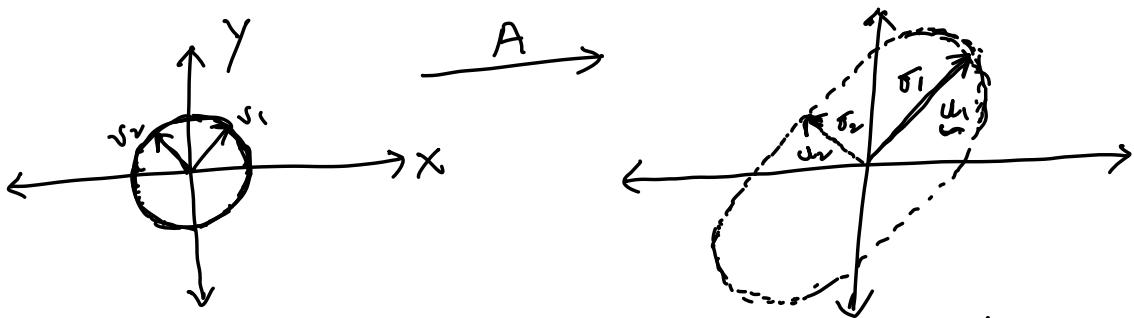
- Searching closest related images
- Image compression (Reducing image size)
- Image recovery
- Principal component analysis
(Find most representative dominant features)
- Solution of Least squares problems
- Find null-space, column-space
- Computing Matrix norm

Geometric Intuition:-

Let us consider for simplicity we are working in \mathbb{R}^2 .

→ Action of any matrix $A \in \mathbb{R}^{2 \times 2}$ on a unit circle → gives an ellipse

A is a non-singular and hence full rank



The image of unit circle under the action of matrix A is ellipse

$$AS \rightarrow \text{ellipse}$$

$\underline{u}_1, \underline{u}_2$ are the principal semi-axes of my ellipse with lengths σ_1, σ_2

$\underline{v}_1, \underline{v}_2$ are pre-image vectors generating images $\underline{u}_1, \underline{u}_2$ the axes of the ellipse.

$$A \underline{v}_1 = \sigma_1 \underline{u}_1$$

$$A \underline{v}_2 = \sigma_2 \underline{u}_2$$

[These exist vectors $\underline{v}_1, \underline{v}_2$ which are orthogonal whose images $\underline{u}_1, \underline{u}_2$

$$A \begin{bmatrix} \underline{v}_1 & \underline{v}_2 \end{bmatrix} = \begin{bmatrix} \underline{u}_1 & \underline{u}_2 \end{bmatrix} \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{bmatrix}$$

are along the directions of

$$\begin{array}{c} A \underline{v} \\ \underline{v}^T \end{array} = \begin{array}{c} U \\ \Sigma \\ V^T \end{array}$$

$$A \underline{v} \underline{v}^T = U \Sigma V^T \Rightarrow A = U \Sigma V^T$$

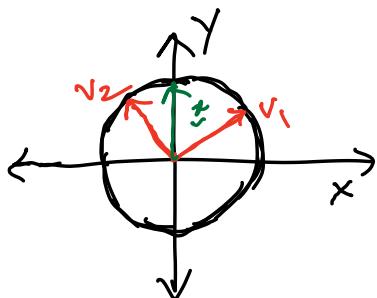
ellipse axes]

Consider action of any matrix on a

unit circle S - via - sequence of steps

$$\underline{A} = \underline{U} \Sigma \underline{V}^T$$

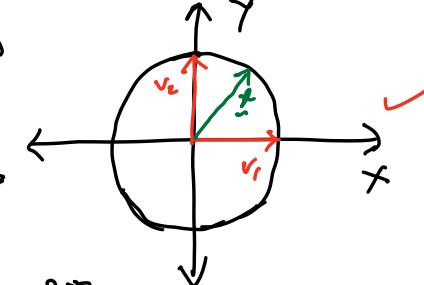
$$\underline{A} S =$$



Rotation
 \underline{V}^T

Rotation

$$\underline{V}^T$$



Action of any matrix $\underline{A} \in \mathbb{R}^{2 \times 2}$
on a unit circle S

Σ
Stretching

$$\begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{bmatrix}$$

$\sigma_1 > \sigma_2$

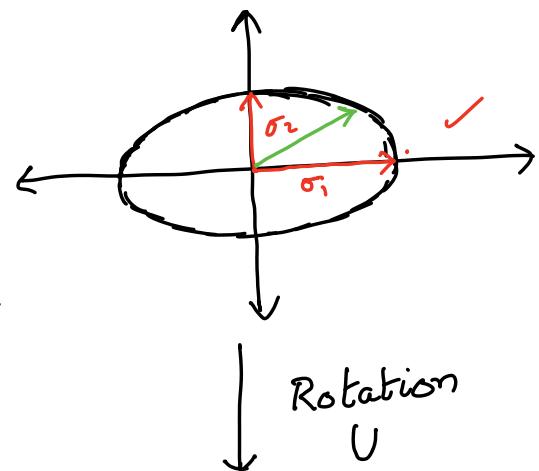
Rotation



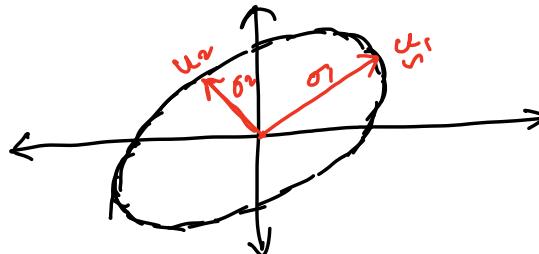
Stretching to Ellipse



Rotation of Ellipse



Rotation
 \underline{U}



This process can be generalized to higher dimensions ≥ 2

Let S be unit hypersphere in \mathbb{R}^n .
 The action of $A \in \mathbb{R}^{m \times n}$ ($m \geq n$) and full rank on S is a hyperellipse in \mathbb{R}^m with the following properties :-

$$(i) \quad A v_j = \sigma_j u_j$$

$\sigma_1, \sigma_2, \sigma_3, \dots, \sigma_n$ are lengths of the principal semi-axes of $A S$ (hyperellipse in \mathbb{R}^m) and these σ_j 's are called singular values of A . By convention they are ordered in descending order

$$\sigma_1 \geq \sigma_2 \dots \geq \sigma_n$$

(ii) The set of unit vectors $\{u_1, u_2, \dots, u_n\}$ are directions of principal semi-axes of our hyperellipse and these are called

left singular vectors and are orthonormal vectors.

$\therefore \sigma_j \underline{u}_j$ is the j^{th} largest principal semi-axes of \underline{A} 's hyperellipses

(iii) The set of unit vectors $\{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_n\}$ which also form an orthonormal set are the pre-images of \underline{u}_j and are called right singular vectors of \underline{A}

$$\underline{A} \underline{v}_j = \sigma_j \underline{u}_j \quad \text{--- (1)}$$

$$\begin{aligned} [\underline{A}]_{m \times n} &= \underbrace{\begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ \underline{v}_1 & \underline{v}_2 & \underline{v}_3 & \cdots & \underline{v}_n \end{bmatrix}}_{V^{n \times n}} \\ &= \underbrace{\begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ \underline{u}_1 & \underline{u}_2 & \underline{u}_3 & \cdots & \underline{u}_n \end{bmatrix}}_{U^{m \times n}} \underbrace{\begin{bmatrix} \sigma_1 & & & 0 \\ \sigma_2 & \ddots & & 0 \\ 0 & & \ddots & 0 \\ & & & \sigma_n \end{bmatrix}}_{\Sigma^{n \times n}} \\ \underline{A} \underline{v} &= \hat{U} \Sigma \end{aligned}$$

$\underline{A} \in \mathbb{R}^{m \times n}$ $\hat{U} \in \mathbb{R}^{m \times m}$ $\Sigma \in \mathbb{R}^{n \times n}$
 $\underline{V} \in \mathbb{R}^{n \times n}$ $\hat{U} \in \mathbb{R}^{m \times m}$ $\Sigma \in \mathbb{R}^{n \times n}$

Since V is orthogonal matrix

$$\tilde{A} \tilde{U} \tilde{V}^T = \hat{U} \hat{\Sigma} \hat{V}^T$$

$$\boxed{\tilde{A} = \hat{U} \hat{\Sigma} \hat{V}^T}$$



Reduced Singular Value Decomposition

$$\begin{matrix} \text{---} & = & \text{---} & \hat{\Sigma}_{n \times n} & V^T_{n \times n} \\ \text{---} & & \text{---} & & \text{---} \\ \tilde{A}_{m \times n} & & U_{m \times n} & & \end{matrix}$$