

Singular value Decomposition (SVD)

Applications :-

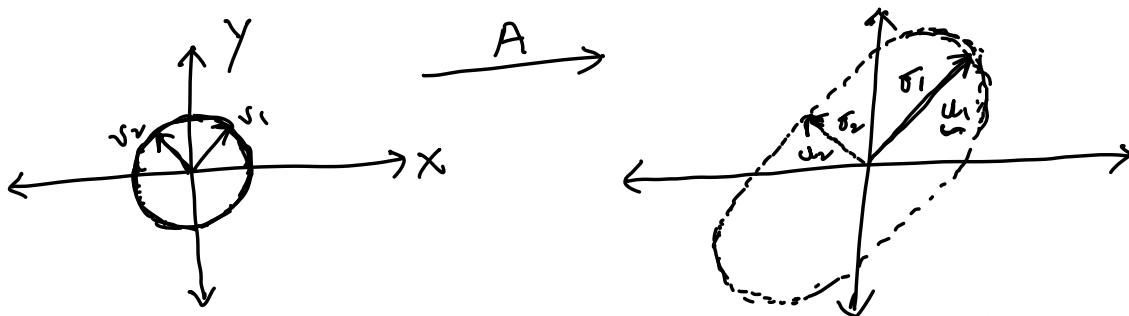
- Searching closest related images
- Image compression (Reducing image size)
- Image recovery
- Principal component analysis
(Find most representative/dominant features)
- Solution of least squares problems
- Find null-space, column-space
- Computing Matrix norm

Geometric Intuition:-

Let us consider for simplicity we are working in \mathbb{R}^2 .

→ Action of any matrix $A \in \mathbb{R}^{2 \times 2}$ on a unit circle → Gives an ellipse

A is a non-singular and hence full rank



The image of unit circle under the action of matrix A is ellipse

$A \underline{S} \rightarrow \text{ellipse}$

$\underline{u}_1, \underline{u}_2$ are the principal semi-axes of my ellipse with lengths σ_1, σ_2

$\underline{v}_1, \underline{v}_2$ are pre-image vectors generating images $\underline{u}_1, \underline{u}_2$ the axes of the ellipse.

$$A \underline{v}_1 = \sigma_1 \underline{u}_1$$

$$A \underline{v}_2 = \sigma_2 \underline{u}_2$$

There exists vectors $\underline{v}_1, \underline{v}_2$ which are orthogonal whose images $\underline{u}_1, \underline{u}_2$

$$A \begin{bmatrix} \underline{v}_1 & \underline{v}_2 \end{bmatrix} = \begin{bmatrix} \underline{u}_1 & \underline{u}_2 \end{bmatrix} \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{bmatrix}$$

are along the directions of ellipse axes]

$$A \underline{V} = \underline{U} \underline{\Sigma}$$

$$A \underline{V} \underline{V}^T = \underline{U} \underline{\Sigma} \underline{V}^T$$

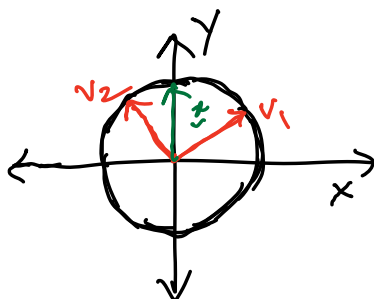
$$\Rightarrow A = \underline{U} \underline{\Sigma} \underline{V}^T$$

Consider action of any matrix on a

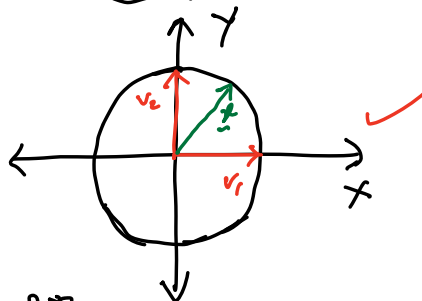
unit circle S - via - sequence of steps

$$A = U \Sigma V^T$$

$$A S = \underbrace{U \Sigma V^T}_{\text{Rotation } V^T} S$$



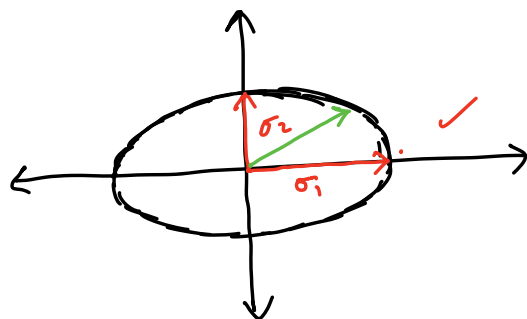
Rotation
 V^T



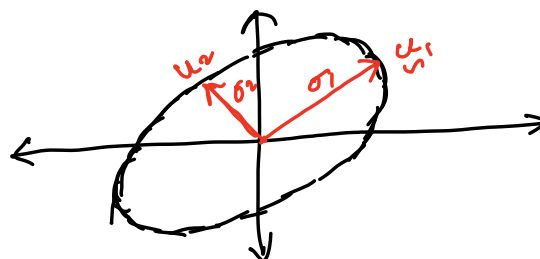
Action of any matrix $A \in \mathbb{R}^{2 \times 2}$
on a unit circle S

Stretching $\begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{bmatrix}$
 σ_1, σ_2

Rotation
↓
Stretching to Ellipse
↓
Rotation of Ellipse



Rotation
 U



This process can be generalized to higher dimension ≥ 2

Let S be unit hypersphere in \mathbb{R}^n .

The action of $A \in \mathbb{R}^{m \times n}$ ($m \geq n$) and full rank on S is a hyperellipse in \mathbb{R}^m with the following properties:-

$$(i) \quad A \underline{v}_j = \sigma_j \underline{u}_j$$

$\sigma_1, \sigma_2, \sigma_3 \dots \sigma_n$ are lengths of the principal semi-axes of $A S$ (hyperellipse in \mathbb{R}^m) and these σ_j 's are called singular values of A . By convention they are ordered in descending order

$$\sigma_1 \geq \sigma_2 \dots \geq \sigma_n$$

(ii) The set of unit vectors $\{\underline{u}_1, \underline{u}_2, \dots, \underline{u}_n\}$ are directions of principal semi axes of our hyperellipse and these are called

left singular vectors and are orthonormal vectors.

$\therefore \sigma_j \underline{u}_j$ is the j^{th} largest principal semi-axes of our hyperellipsoids $A \underline{x}$

ciii) The set of unit vectors $\{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_n\}$ which also form an orthonormal set are the pre-images of \underline{u}_i and are called right singular vectors A

$$A \underline{v}_j = \sigma_j \underline{u}_j \quad \text{--- (i)}$$

$$[A]_{m \times n} \left[\begin{array}{c|c|c|c|c} \underline{v}_1 & \underline{v}_2 & \underline{v}_3 & \dots & \underline{v}_n \\ \hline \end{array} \right] = \left[\begin{array}{c|c|c|c|c} \underline{u}_1 & \underline{u}_2 & \underline{u}_3 & \dots & \underline{u}_n \\ \hline \end{array} \right] \begin{bmatrix} \sigma_1 & & & & 0 \\ & \sigma_2 & & & \\ & & \ddots & & \\ 0 & & & \sigma_n & \\ & & & & 0 \end{bmatrix}$$

$\underbrace{\hspace{15em}}_{V \text{ } n \times n} \quad \underbrace{\hspace{15em}}_{U \text{ } m \times n} \quad \underbrace{\hspace{15em}}_{\Sigma \text{ } n \times n}$

$$A V = U \Sigma$$

$$A \in \mathbb{R}^{m \times n}$$

$$V \in \mathbb{R}^{n \times n}$$

$$U \in \mathbb{R}^{m \times n}$$

$$\Sigma \in \mathbb{R}^{n \times n}$$

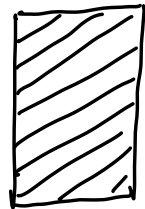
Since V is orthogonal matrix

$$\underline{A} \underline{V} \underline{V}^T = \underline{\hat{U}} \underline{\hat{\Sigma}} \underline{V}^T$$

$$\boxed{\underline{A} = \underline{\hat{U}} \underline{\hat{\Sigma}} \underline{V}^T}$$

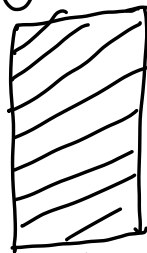


Reduced Singular Value Decomposition

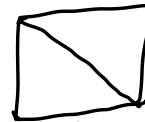


$\underline{A}_{m \times n}$

=



$\underline{\hat{U}}_{m \times n}$



$\underline{\hat{\Sigma}}_{n \times n}$



$\underline{V}_{n \times n}^T$