

DS284: NLA Final Exam (25th January, 2021)

9 AM to 12 Noon

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 Total: 100 Marks

1. State with clear reason whether the following statements are true or false: **[6 × 3 = 18 Marks]**

- (a) Let $\mathbf{A} \in \mathbb{R}^{m \times n}$ ($m < n$) be a full rank matrix and \mathbf{A} admits $\mathbf{U}\Sigma\mathbf{V}^T$ as its full SVD. If $\mathbf{V} = [\mathbf{V}_1, \mathbf{V}_2]$, where $\mathbf{V}_1 \in \mathbb{R}^{n \times m}$ and $\mathbf{V}_2 \in \mathbb{R}^{n \times (n-m)}$, then the system of equations $\mathbf{V}_2\mathbf{x} = \mathbf{b}$ has a unique solution $\mathbf{x} \in \mathbb{R}^{n-m}$ for all vectors $\mathbf{b} \in \mathbb{R}^n$ satisfying $\mathbf{Ab} = \mathbf{0}$
- (b) If $\mathbf{A} \in \mathbb{R}^{m \times n}$ is a full rank matrix, $\mathbf{Ax} = \mathbf{0} \implies \mathbf{x} = \mathbf{0}$.
- (c) All projector matrices which are not orthogonal projectors are always rank deficient matrices.
- (d) Let a full rank matrix $\mathbf{A} \in \mathbb{R}^{m \times m}$ be decomposed as $\mathbf{A} = \mathbf{TR}$ where \mathbf{T} is a lower triangular matrix (not necessarily unit lower triangular) and \mathbf{R} is an upper triangular matrix. Such a decomposition is always unique.
- (e) If $\mathbf{A} \in \mathbb{R}^{m \times m}$ is a symmetric positive definite matrix and $\mathbf{X} \in \mathbb{R}^{m \times n}$ is a full rank matrix, then $\mathbf{X}^T \mathbf{AX}$ is always symmetric positive definite.
- (f) If $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ are linearly independent eigenvectors of \mathbf{A} corresponding to an eigenvalue λ with algebraic multiplicity 3, then all the vectors lying in the subspace spanned by $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ are eigenvectors of \mathbf{A} for that eigenvalue λ .

2. If $\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \\ 2 & 3 & 3 \end{bmatrix}$, answer the following questions: **[2 + 5 + 5 + 6 = 18 Marks]**

- (a) Write the characteristic equation associated with the above matrix \mathbf{A} and subsequently compute its eigenvalues.
- (b) Set up the Arnoldi iteration with the starting vector $\mathbf{b} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ to find the orthonormal basis vectors $\{\mathbf{q}_1, \mathbf{q}_2\}$ spanning the two dimensional Krylov subspace $\mathcal{K}_2 = \langle \mathbf{b}, \mathbf{Ab} \rangle$
- (c) Find the orthogonal projection \mathbf{H} of \mathbf{A} onto \mathcal{K}_2 represented in the basis $\{\mathbf{q}_1, \mathbf{q}_2\}$ obtained in (b) above, and then compute the eigenvalues of this \mathbf{H} (also called Ritz values). Find the absolute error between the smallest Ritz value and the smallest eigenvalue of \mathbf{A} and similarly compute the absolute error between the largest Ritz value and largest eigenvalue of \mathbf{A} .

- (d) Consider the system of equations $\mathbf{Ax} = \mathbf{b}$ where $\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \\ 2 & 3 & 3 \end{bmatrix}$ as given above and $\mathbf{b} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

as given in (b). Find the exact solution \mathbf{x}^* which solves $\mathbf{Ax} = \mathbf{b}$ using forward substitution. Subsequently find the vector $\hat{\mathbf{x}} \in \mathcal{K}_2$ that minimizes the norm $\|\mathbf{Ac} - \mathbf{b}\|_2$ over all possible vectors $\mathbf{c} \in \mathcal{K}_2$, where \mathcal{K}_2 is the Krylov subspace constructed in (b). Finally, find the norm of error between exact solution \mathbf{x}^* and $\hat{\mathbf{x}}$.

3. If \mathbf{u} and \mathbf{v} are two non-parallel vectors in \mathbb{R}^n , then the $n \times n$ matrix $\mathbf{A} = \mathbf{I} + \mathbf{u}\mathbf{v}^T$ is known as the rank one perturbation of the $n \times n$ identity matrix \mathbf{I} . [3 × 5 = 15 Marks]
- If \mathbf{A} is non-singular, show that \mathbf{A} has an eigenvalue 1 with geometric multiplicity $n - 1$.
[Hint: Consider the space orthogonal to the vector \mathbf{v}]
 - If \mathbf{A} is non-singular, show that an eigenvector of \mathbf{A} for an eigenvalue $\lambda \neq 1$ must be of the form $c\mathbf{u}$ for some scalar c . Find this eigenvalue λ in terms of the vectors \mathbf{u} and \mathbf{v} .
 - If $\mathbf{v}^T\mathbf{u} = -1$, show that \mathbf{A} is singular. What can you say about the null space of \mathbf{A} ?
4. The matrices $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{n \times n}$ are called orthogonally similar matrices if there is an orthogonal matrix $\mathbf{Q} \in \mathbb{R}^{n \times n}$ such that $\mathbf{A} = \mathbf{QBQ}^T$. [4 × 5 = 20 Marks]
- If \mathbf{A} and \mathbf{B} are orthogonally similar matrices, show that (i) $\mathbf{A}^T\mathbf{A}$ is similar to $\mathbf{B}^T\mathbf{B}$ and (ii) \mathbf{AA}^T is similar to \mathbf{BB}^T .
 - If \mathbf{A} and \mathbf{B} are orthogonally similar, show that they have the same singular values.
 - If $\mathbf{B} \in \mathbb{R}^{n \times n}$ is an orthogonal matrix, show that \mathbf{AB} and \mathbf{BA} are orthogonally similar matrices.
 - If $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{n \times n}$ are two symmetric matrices with same eigenvectors, then show that $\mathbf{AB} = \mathbf{BA}$.
5. Let $\mathbf{A} = \mathbf{U}\Sigma\mathbf{V}^T$ be the full SVD of $\mathbf{A} \in \mathbb{R}^{m \times m}$. Use this SVD of \mathbf{A} to obtain the eigen-decomposition of the $2m \times 2m$ symmetric matrix $\mathbf{B} = \begin{bmatrix} 0 & \mathbf{A}^T \\ \mathbf{A} & 0 \end{bmatrix}$. [Hint: Let λ be the eigenvalue of \mathbf{B} and denote the corresponding eigenvector to be $\begin{bmatrix} \mathbf{x} \\ \zeta \end{bmatrix}$, where $\mathbf{x} \in \mathbb{R}^m$ and $\zeta \in \mathbb{R}^m$] [15 Marks]
6. If $\mathbf{A} \in \mathbb{R}^{m \times m}$ be a symmetric matrix with one eigenvalue much smaller than others, i.e. if $\lambda_1, \lambda_2, \dots, \lambda_m$ are eigenvalues of \mathbf{A} in increasing order, then $\lambda_1 << \lambda_2 \leq \lambda_3 \dots \leq \lambda_m$ (This means that \mathbf{A} is an ill-conditioned matrix). Let $\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_m$ be the corresponding eigenvectors. Now answer the following questions: [4 + 5 + 5 = 14 Marks]
- If the system of equations $\mathbf{Aw} = \mathbf{v}$ is solved using a backward stable algorithm for some $\mathbf{v} \in \mathbb{R}^m$ yielding a computed vector $\tilde{\mathbf{w}} = \mathbf{w} + \delta\mathbf{w}$, show that $\delta\mathbf{w} = -(\mathbf{A} + \delta\mathbf{A})^{-1}(\delta\mathbf{A})\mathbf{w}$ for some $\delta\mathbf{A}$ such that $\|\delta\mathbf{A}\| = O(\epsilon_M)\|\mathbf{A}\|$.
 - Assuming that \mathbf{v} is a vector with components in the directions of all eigenvectors $\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_m$ of \mathbf{A} , show that $\frac{\mathbf{w}}{\|\mathbf{w}\|} \approx \mathbf{q}_1$, where $\mathbf{w} = \mathbf{A}^{-1}\mathbf{v}$ is the exact solution of the system of equations given in (a). [Hint: First show that \mathbf{w} is approximately in the direction of \mathbf{q}_1]
 - Using the Taylor series expansion $(\mathbf{A} + \delta\mathbf{A})^{-1} = \mathbf{A}^{-1} - \mathbf{A}^{-1}(\delta\mathbf{A})\mathbf{A}^{-1} + O(\epsilon_M^2)$, show that $\frac{\tilde{\mathbf{w}}}{\|\tilde{\mathbf{w}}\|} \approx \mathbf{q}_1$. [Hint: Using the expression $\delta\mathbf{w}$ derived in (a) and the fact $\delta\mathbf{A}$ is random roundoff perturbation, show that $\delta\mathbf{w}$ is in the direction of \mathbf{q}_1]
- [This sequence of steps in (a), (b) and (c) show that, though the computed solution $\tilde{\mathbf{w}}$ is far away from \mathbf{w} for the ill-conditioned system $\mathbf{Aw} = \mathbf{v}$, $\frac{\tilde{\mathbf{w}}}{\|\tilde{\mathbf{w}}\|}$ need not be far from $\frac{\mathbf{w}}{\|\mathbf{w}\|}$.]