

Eigenvalue Problems

Let $A \in \mathbb{R}^{m \times m}$, $\underline{x} \neq 0 \in \mathbb{C}^m$ (\mathbb{C} is set of complex nos.)
then \underline{x} is an eigenvector of A and
 $\lambda \in \mathbb{C}$ is its corresponding eigenvalue

if

$$\boxed{A\underline{x} = \lambda \underline{x}}$$

* The set of all eigenvalues of a matrix A is called the spectrum of A denoted by $\Lambda(A)$

Application areas:-

- * Insights into evolution of system
 - vibration analysis
 - study of resonance
 - stability of structure
 - fluid flows subjected to small perturbations

- * Quantum mechanical modeling of matter
(Solving Schrödinger equation)
- * Principal stresses in solid mechanics
- * PCA in data driven modeling
- * Page rank algorithm used in search engines is an eigenvalue problem
- * Eigenvectors of graph Laplacian matrix actually help in construction of efficient filters Graph convolution Neural Network!

Eigenvalue decomposition!

An eigenvalue decomposition of

$\underline{A} \in \mathbb{R}^{m \times m}$ is a factorization

$$\underline{A} = \underline{X} \underline{\Lambda} \underline{X}^{-1} \text{ where}$$

\underline{X} is nonsingular and $\underline{\Lambda}$ is diagonal with \underline{X} comprising of eigenvectors of \underline{A} as columns!

Note: Such decomposition may not always exist!

$$\underline{A} \underline{X} = \underline{X} \underline{\Lambda}$$

$$[\underline{A}] \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ x_1 & x_2 & x_3 & \dots & x_m \\ | & | & | & & | \\ 1 & 1 & 1 & \dots & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 1 & \dots \\ x_1 & x_2 & x_3 & \dots \\ | & | & | & \\ 1 & 1 & 1 & \dots \end{bmatrix} \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_m \end{bmatrix}$$

$$\underline{A} \underline{x}_j = \lambda_j \underline{x}_j$$

i.e. j^{th} column of \underline{X} is j^{th} eigenvector

and $c_{j,j}$) entry of Λ is corresponding eigenvalue!

→ Geometric multiplicity :- The geometric multiplicity of an eigenvalue λ is the number of linearly independent eigenvectors associated with that eigenvalue λ . If $\lambda \in \Lambda(A)$, eigenspace E_λ is an invariant subspace of A

$$\text{i.e } A E_\lambda \subseteq E_\lambda$$

The dimension of E_λ is the geometric multiplicity of λ i.e maximum number of linearly

independent eigenvectors that can be found for a given λ

$$\begin{aligned}
 \underline{x} &= \alpha_1 \underline{v}_1 + \alpha_2 \underline{v}_2 \\
 A \underline{x} &= A(\alpha_1 \underline{v}_1 + \alpha_2 \underline{v}_2) \\
 &= \alpha_1 \lambda \underline{v}_1 + \alpha_2 \lambda \underline{v}_2 \\
 &= \lambda [\alpha_1 \underline{v}_1 + \alpha_2 \underline{v}_2] \\
 &= \lambda \underline{x}
 \end{aligned}
 \quad \textcircled{2}$$

* Characteristic Polynomial :-

The characteristic polynomial p_A of $A \in \mathbb{R}^{m \times m}$ is the m^{th} degree monic polynomial $\boxed{p_A(z) = \det(zI - A)}$ ✓
 (coefficient of z^m is 1 → monic polynomial)

Thm :- λ is eigenvalue of A if and only if $p_A(\lambda) = 0$

$$Ax = \lambda x$$

Note :- $A \in \mathbb{R}^{m \times m}$ $(A - \lambda I)x = 0$
 λ can be complex
 any complex λ must Eigenvector of A lies
 appears in complex in the null space of $(A - \lambda I)$
 conjugate pairs i.e. $\lambda = a + ib$ is an eigenvalue
 $\lambda^* = a - ib$ is an eigenvalue

* Algebraic multiplicity :-

Since $p_A(z)$ is monic m-degree polynomial, it can be written as

$$p_A(z) = (z - \lambda_1)(z - \lambda_2) \dots (z - \lambda_m)$$

for some $\lambda_j \in \mathbb{C}$ (roots of $p_A(z)$)

Each λ_j is an eigenvalue and in general may be repeated

"The multiplicity of λ as a root of $p_A(z)$ is the algebraic multiplicity of an eigenvalue λ "

Remark:- ① If $A \in \mathbb{R}^{m \times m}$ then A has m eigenvalues counting algebraic multiplicity. In particular if roots of $p_A(z)$ are simple, then A has m distinct eigenvalues.

(b) The algebraic multiplicity of an eigenvalue λ is always at least as large as its geometric multiplicity.

* Similarity transformation :-

If $\underline{X} \in \mathbb{R}^{m \times m}$ is non singular, then

$\underline{A} \rightarrow \underline{X}^{-1} \underline{A} \underline{X}$ is called a similarity transformation of $\underline{A} \in \mathbb{R}^{m \times m}$

We say that two matrices \underline{A} and \underline{B} are similar if there is a similarity transformation of one to another

i.e. if there is a nonsingular $\underline{X} \in \mathbb{R}^{m \times m}$ such that $\underline{B} = \underline{X}^{-1} \underline{A} \underline{X}$

then \underline{A} and \underline{B} are said to be similar!

Thm:- If \underline{X} is nonsingular, then \underline{A} and $\underline{X}^{-1}\underline{A}\underline{X}$ have the same characteristic polynomial, eigenvalues and algebraic multiplicity and geometric multiplicity!

$$\begin{aligned}
 \text{Pf:- } p(z) &= \det(z\underline{I} - \underline{X}^{-1}\underline{A}\underline{X}) \\
 \underline{X}^{-1}\underline{A}\underline{X} &= \det(z\underline{X}^{-1}\underline{X} - \underline{X}^{-1}\underline{A}\underline{X}) \\
 &= \det(\underline{X}^{-1}(z\underline{I} - \underline{A})\underline{X}) \\
 &= (\det \underline{X}^{-1})(\det(z\underline{I} - \underline{A}))(\det \underline{X}) \\
 &= (\det \underline{X})^{-1}(\det(z\underline{I} - \underline{A}))(\det \underline{X}) \\
 &= \det(z\underline{I} - \underline{A}) = p_A(z)
 \end{aligned}$$

Hence \underline{A} , $\underline{X}^{-1}\underline{A}\underline{X}$ have the same eigenvalues (same roots of $p_A(z)$) and

hence same algebraic multiplicity
 Build a matrix E_λ whose column vectors span the eigenspace for the matrix A , corresponding to the eigen value λ

$$(\underbrace{X^{-1} A X}_{\text{matrix } A}) (\underbrace{X^{-1} E_\lambda}_{\text{eigenspace } E_\lambda}) = \underbrace{X^{-1} A E_\lambda}_{X^{-1} E_\lambda \lambda}$$

$X^{-1} E_\lambda$ is the eigenspace for $X^{-1} A X$ corresponding to the eigenvalue λ .

Hence geometric multiplicity of

A and $X^{-1} A X$ are the same.

($\because E_\lambda$ and $X^{-1} E_\lambda$ has the same rank)

Defective eigenvalues and matrices

* A generic matrix need not have distinct eigenvalues i.e algebraic multiplicity need not be 1 and geometric multiplicity need not be 1 as well and need not be equal to algebraic multiplicity as well)

$$A = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}; B = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{bmatrix}$$

Both A and B eigenvalue

$$\lambda = 2.$$

Algebraic multiplicity of $\lambda = 2$ for A ?

$$\xrightarrow{3} 3$$

Algebraic multiplicity of $\lambda = 2$ for B ?

$$\xrightarrow{3} 3$$

For A , we can choose 3 linearly independent eigenvectors e_1, e_2, e_3 and geometric multiplicity is also 3-

For B , we can only have only linearly independent eigenvectors e_1 , the geometric multiplicity of B is 1

* An eigenvalue whose algebraic multiplicity is greater than its geometric multiplicity is called a defective eigenvalue!

- * A matrix that has atleast one defective eigenvalue is a defective matrix i.e it does not possess a full set of m linearly independent eigenvectors
- * A diagonal matrix is non-defective
 $(\text{algebraic multiplicity of eigenvalue } \lambda = \text{geometric multiplicity of } \lambda)$

Diagonalizability
Thm: $A \in \mathbb{R}^{m \times m}$ is non-defective

if and only if it has eigenvalue decomposition $\underline{A} = \underline{X} \underline{\Delta} \underline{X}^{-1}$ where

$\underline{X} \in \mathbb{R}^{m \times m}$
non singular matrix.

\rightarrow A non-defective matrix is diagonalizable

Proof: To show given $\underline{A} = \underline{X} \underline{\Delta} \underline{X}^{-1}$, \underline{A} is non-defective!

$$\underline{A} = \underline{X} \underline{\Delta} \underline{X}^{-1} \rightarrow \underline{A} \text{ is similar to } \underline{\Delta}$$

\underline{A} and $\underline{\Delta}$ has the same eigenvalues and same multiplicities.

Since $\underline{\Delta}$ is a diagonal matrix,

it is non-defective and thus

\underline{A} is non-defective.

→ To show if \tilde{A} is non-defective

then $\tilde{A} = \underline{X} \Delta \tilde{X}^{-1}$

* Since \tilde{A} is non-defective, it must have m linearly independent eigenvectors!

If $\underline{X} = \begin{bmatrix} \underline{x}_1 & | & \underline{x}_2 & | & \cdots & | & \underline{x}_m \end{bmatrix}$

comprises of these m linearly independent vectors, \underline{X} is full rank

$$\tilde{A} \underline{X} = \tilde{A} \begin{bmatrix} \underline{x}_1 & | & \underline{x}_2 & | & \cdots & | & \underline{x}_m \end{bmatrix}$$

$$= \begin{bmatrix} \underline{x}_1 & | & \underline{x}_2 & | & \cdots & | & \underline{x}_m \end{bmatrix} \begin{bmatrix} \lambda_1 & & & & \\ & \lambda_2 & & & \\ & & \ddots & & \\ & & & & \lambda_m \end{bmatrix}$$

$$= \underline{X} \Delta$$

$$\begin{array}{l} \boxed{\underline{A} \underline{X} = \underline{X} \underline{\Lambda}} \\ \boxed{\underline{A} = \underline{X} \underline{\Lambda} \underline{X}^{-1}} \end{array}$$

Thm: Trace of $\underline{A} \in \mathbb{R}^{m \times m}$

$$\text{tr}(\underline{A}) = \sum_{j=1}^m a_{jj} = \sum_{\substack{j=1 \\ m \times m}}^m \lambda_j$$

Determinant of $\underline{A} \in \mathbb{R}^{m \times m}$

$$\det(\underline{A}) = \prod_{j=1}^m \lambda_j$$

Unitary / orthogonal diagonalization:-

* $\underline{Q} \in \mathbb{C}^{m \times m}$ is a unitary matrix

$$\text{if } \underline{Q}^+ \underline{Q} = \underline{Q} \underline{Q}^+ = \underline{I}$$

when \underline{Q}^+ is conjugate transpose of \underline{Q}

* Unitary matrix reduces to
 orthogonal matrices if Q is
 real i.e. $Q^T Q = Q Q^T = I$ is
 satisfied.

For a non-defective matrix
 $A \in \mathbb{R}^{m \times m}$, it is possible not only
 to have m linearly independent
 eigenvectors, but these vectors
 can be orthogonal as well.

[If $A \in \mathbb{R}^{m \times m}$ eigenvalues can be
 complex and corresponding eigenvectors
 have to be complex as well]

Now in general for a non-defective
 $A \in \mathbb{R}^{m \times m}$, we define unitary
 diagonalizability i.e. there exists

a unitary matrix \underline{Q} , such that

$$\underline{A} = \underline{Q} \Delta \underline{Q}^+$$
 where

\underline{Q}^+ is conjugate transpose
of \underline{Q} and columns of \underline{Q}

are eigenvectors of \underline{A}

Unitary diagonalizability reduces to
orthogonal diagonalizability if \underline{Q} is
real matrix and λ are real

$$\text{i.e. } \underline{A} = \underline{Q} \Delta \underline{Q}^T$$

Eg:- A symmetric matrix $\underline{S} \in \mathbb{R}^{m \times m}$
satisfies $\underline{S} = \underline{S}^T$ & has real eigen values

$$\rightarrow \underline{S} \underline{x} = \lambda \underline{x}$$

Take complex
conjugate
both sides

$$\underline{S} \underline{x}^* = \lambda^* \underline{x}^*$$

where \underline{x}^* is
complex conjugate of \underline{x}

$$\begin{aligned} S \underline{x} = \lambda \underline{x} &\Rightarrow \underline{x}^* S \underline{x} = \lambda \underline{x}^* \underline{x} \\ &\Rightarrow \underbrace{(S \underline{x})^T}_{\text{--- (1)}} \underline{x}^* = \lambda \underline{x}^* \underline{x} \end{aligned}$$

$$\begin{aligned} S \underline{x}^* = \lambda^* \underline{x}^* &\Rightarrow \underline{x}^T S \underline{x}^* = \lambda^* \underline{x}^T \underline{x}^* \\ &\Rightarrow \underline{x}^T \underbrace{S^T}_{\text{--- (2)}} \underline{x}^* = \lambda^* \underline{x}^T \underline{x}^* \\ &\Rightarrow \underbrace{(S \underline{x})^T}_{\text{--- (2)}} \underline{x}^* = \lambda^* \underline{x}^T \underline{x}^* \end{aligned}$$

$$\begin{aligned} (1) - (2) \Rightarrow 0 &= \lambda \underline{x}^* \underline{x} - \lambda^* \underline{x}^* \underline{x}^* \\ &= (\lambda - \lambda^*) (\underline{x}^* \underline{x}) \end{aligned}$$

$$\begin{aligned} \text{Since } \underline{x}^* \underline{x} \neq 0 &\Rightarrow \lambda - \lambda^* = 0 \\ &\Rightarrow \boxed{\lambda = \lambda^*} \end{aligned}$$

Hence eigenvalues of a symmetric matrix real.

Consider the case where S is symmetric $(\lambda_1, \underline{x}_1)$ and $(\lambda_2, \underline{x}_2)$ are two eigenpairs of S where $\lambda_1 \neq \lambda_2$

$$\begin{aligned} S \underline{x}_1 &= \lambda_1 \underline{x}_1, \quad S \underline{x}_2 = \lambda_2 \underline{x}_2 \\ \Rightarrow \underline{x}_2^T S \underline{x}_1 &= \lambda_1 \underline{x}_2^T \underline{x}_1, \quad \underline{x}_1^T S \underline{x}_2 = \lambda_2 \underline{x}_1^T \underline{x}_2 \end{aligned}$$

$$\begin{aligned}
 \underline{x}_2^T S \underline{x}_1 &= \lambda_1 \underline{x}_2^T \underline{x}_1 && | \\
 \Rightarrow \underline{x}_2^T S^T \underline{x}_1 &= \lambda_1 \underline{x}_2^T \underline{x}_1 && | \\
 \Rightarrow (S \underline{x}_2)^T \underline{x}_1 &= \lambda_1 \underline{x}_2^T \underline{x}_1 && - \textcircled{1} \\
 &&& | \\
 \underline{x}_1^T S \underline{x}_2 &= \lambda_2 \underline{x}_1^T \underline{x}_2 && | \\
 (S \underline{x}_2)^T \underline{x}_1 &= \lambda_2 \underline{x}_1^T \underline{x}_2 && - \textcircled{2}
 \end{aligned}$$

$\textcircled{1} - \textcircled{2}$

$$0 = (\lambda_1 - \lambda_2) \underline{x}_1^T \underline{x}_2$$

$$\lambda_1 - \lambda_2 \neq 0 \Rightarrow \underline{x}_1^T \underline{x}_2 = 0$$

i.e. the eigenvectors $\underline{x}_1, \underline{x}_2$

are orthogonal to each other.

Let us say Algebraic multiplicity of $S \in \mathbb{R}^{m \times n}$ is $n < m$
 for an eigenvalue you can find $(m-n)$ distinct eigenvalues and
 the corresponding eigenvectors are orthogonal. It is possible to
 find ' n ' linearly independent eigenvectors corresponding to the
 eigenvalue λ whose algebraic multiplicity

is n . This means I can find ' n ' orthogonal vectors which span this ' n ' dimensional invariant subspace which are the eigenvectors for my S .

Thm :- A symmetric matrix $S \in \mathbb{R}^{n \times n}$ is always non-defective and is orthogonally diagonalizable with real eigenvalues i.e $S = Q \Lambda Q^T$ where Q is orthogonal matrix and Λ is a diagonal matrix.

Thm :- A skew symmetric matrix $b \in \mathbb{R}^{n \times n}$ which satisfies $b = -b^T$. This skew symmetric is non-defective and has purely imaginary eigenvalues.

and is unitarily diagonalizable

$$\text{i.e. } \underline{A} = \underline{Q} \underline{\Lambda} \underline{Q}^T$$

It turns out that there is a class of unitarily diagonalizable matrices and these set of matrices satisfy the property $\underline{A}^T \underline{A} = \underline{A} \underline{A}^T$

* A matrix is normal if

$$\underline{A}^T \underline{A} = \underline{A} \underline{A}^T$$

Thm:- A matrix is unitarily diagonalizable if and only if $\underline{A}^T \underline{A} = \underline{A} \underline{A}^T$ for $\underline{A} \in \mathbb{R}^{m \times m}$

Pf:- Direction 1

If a matrix is unitary diagonalizable then we need to show $\underline{A}^T \underline{A}^T = \underline{A} \underline{A}^T$

Since the given matrix is unitarily diagonalizable we know

$$A = Q \Delta Q^+$$

$$\begin{aligned} A^T A - A A^T &= A^+ A - A A^+ \\ &= (Q \wedge Q^+)^+ (Q \wedge Q^+) - (Q \wedge Q^+) (Q \wedge Q^+)^+ \\ &= (Q^+)^+ \underbrace{Q^+}_{Q \wedge Q^+} Q \wedge Q^+ - Q \wedge Q^+ (Q^+)^+ \wedge Q^+ \\ &= Q \wedge^+ I \wedge Q^+ - Q \wedge Q^+ Q \wedge^+ Q^+ \\ &= Q \wedge^+ \wedge Q^+ - Q \wedge \wedge^+ Q^+ \end{aligned}$$

Since $\wedge^+ \wedge = \wedge \wedge^+$ as \wedge is a diagonal matrix

$$= 0$$

$$\Rightarrow \boxed{A^T A - A A^+ = 0}$$

To show that $A^T A = AA^T$ implies unitary diagonalizability.

Every $A \in \mathbb{R}^{m \times m}$ can be decomposed

$$\text{as } A = A_S + A_{SS}$$

$$A_S = \frac{1}{2}(A + A^T)$$

$$A_{SS} = \frac{1}{2}(A - A^T)$$

What does

$$A_S^T A_S - A_S A_S^T = 0 \quad \text{result in?}$$

$$A_S^T A_S - A_S A_S^T = (A_S + A_{SS})(A_S + A_{SS})^T - (A_S + A_{SS})(A_S + A_{SS})^T$$

$$= (A_S - A_{SS})(A_S + A_{SS}) - (A_S + A_{SS})(A_S - A_{SS})$$

$$= \underbrace{2(A_S A_{SS} - A_{SS} A_S)}_{\text{--}}$$

We have $\underline{A}^T \underline{A} - \underline{A} \underline{A}^T = \underline{\Theta}$

$$(\underline{A}_S \underline{A}_{SS} - \underline{A}_{SS} \underline{A}_S) = \underline{0}$$

$$\Rightarrow \boxed{\underline{A}_S \underline{A}_{SS} = \underline{A}_{SS} \underline{A}_S}$$

(This means \underline{A}_S and \underline{A}_{SS} commute with each other)

Note :-

* Two matrices commute if and only if they have same eigenvectors!
Here Q is a unitary matrix

$$\underline{A}_S = \underbrace{Q \underline{\Lambda}_S Q^+}, \quad \underline{A}_{SS} = \underbrace{Q \underline{\Lambda}_{SS} Q^+}$$

$$\Rightarrow \underline{\Lambda}_S = \underbrace{Q^+ \underline{A}_S Q}, \quad \Rightarrow \underline{\Lambda}_{SS} = \underbrace{Q^+ \underline{A}_{SS} Q}$$

Consider

$$\underline{Q}^+ \underline{A} \underline{Q} = \underline{Q}^+ (\underline{A}_S + \underline{A}_{SS}) \underline{Q}$$

$$= \underline{\Lambda}_S + \underline{\Lambda}_{SS} = \underline{\Lambda}$$

Hence $\underline{Q}^+ \underline{A} \underline{Q} = \underline{\Lambda}$

$$\Rightarrow \boxed{\underline{A} = \underline{Q} \underline{\Lambda} \underline{Q}^+}$$

Schur factorization

A factorization of $\underline{A} \in \mathbb{C}^{m \times m}$

of the form $\underline{A} = \underline{Q} \underline{T} \underline{Q}^+$

where \underline{Q} is unitary ($\underline{Q}^+ \underline{Q} = I$)

and \underline{T} is upper triangular

is called Schur factorization

Note:- Since \underline{A} and \underline{T} are similar, the eigenvalues of \underline{A} and \underline{T} are same.

Thm: Every square matrix $\underline{A} \in \mathbb{C}^{n \times n}$ has a Schur factorization of the form

$$\underline{A} = \underline{Q} \underline{J} \underline{Q}^+$$

as discussed before.

If $\underline{A} \in \mathbb{R}^{n \times n}$, a factorization with real matrices exist $\underline{A} = \underline{U} \underline{J} \underline{U}^T$ where $\underline{U}^T \underline{U} = \underline{U} \underline{U}^T = I$ where \underline{J} is quasi upper triangular.

Quasi upper triangular matrices are those with diagonals with 1×1 block or 2×2 block

Summary:-

(i) A diagonalization $\underline{A} = \underline{X} \underline{\Lambda} \underline{X}^{-1}$ exists if and only if \underline{A} is non-defective

(ii) A unitary diagonalization $\underline{A} = \underline{Q} \underline{\Lambda} \underline{Q}^+$

exists if \underline{A} is normal

(iii) A unitary triangulization
(Schur Factorization)

$$\underline{A} = \underline{Q} \underline{T} \underline{Q}^+ \text{ always exists}$$