

Singular value Decomposition (SVD)

Applications :-

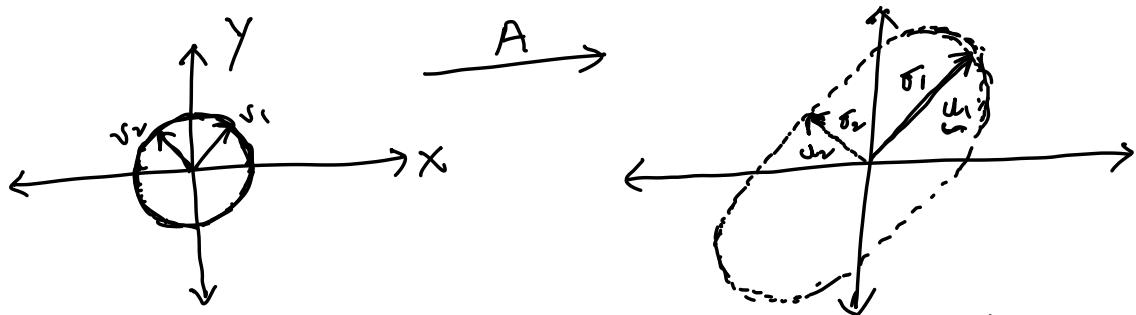
- Searching closest related images
- Image compression (Reducing image size)
- Image recovery
- Principal component analysis
(Find most representative dominant features)
- Solution of Least squares problems
- Find null-space, column-space
- Computing Matrix norm

Geometric Intuition:-

Let us consider for simplicity we are working in \mathbb{R}^2 .

→ Action of any matrix $A \in \mathbb{R}^{2 \times 2}$ on a unit circle → gives an ellipse

A is a non-singular and hence full rank



The image of unit circle under the action of matrix \underline{A} is ellipse
 $\underline{A} \underline{S} \rightarrow \text{ellipse}$

$\underline{u}_1, \underline{u}_2$ are the principal semi-axes of my ellipse with lengths σ_1, σ_2

$\underline{v}_1, \underline{v}_2$ are pre-image vectors generating images $\underline{u}_1, \underline{u}_2$ the axes of the ellipse.

$$\underline{A} \underline{v}_1 = \sigma_1 \underline{u}_1$$

$$\underline{A} \underline{v}_2 = \sigma_2 \underline{u}_2$$

$$\underline{A} \begin{bmatrix} \underline{v}_1 & \underline{v}_2 \end{bmatrix} = \begin{bmatrix} \underline{u}_1 & \underline{u}_2 \end{bmatrix} \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{bmatrix}$$

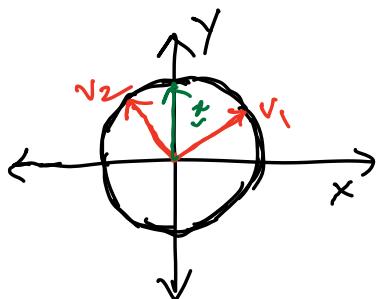
$$\begin{aligned} \underline{A} \begin{bmatrix} \underline{v}_1 & \underline{v}_2 \end{bmatrix} &= \underline{U} \underline{\Sigma} \begin{bmatrix} \underline{v}_1 & \underline{v}_2 \end{bmatrix}^T \\ \underline{A} \underline{V} \underline{V}^T &= \underline{U} \underline{\Sigma} \underline{V}^T \Rightarrow \underline{A} = \underline{U} \underline{\Sigma} \underline{V}^T \end{aligned}$$

Consider action of any matrix on a

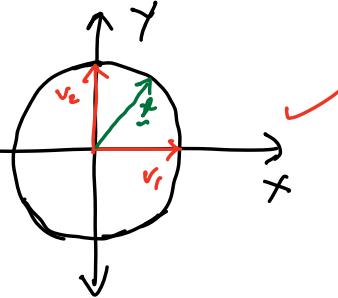
unit circle S - via - sequence of steps

$$A = U \Sigma V^T$$

$$\Sigma$$



Rotation
 V^T



Action of any matrix $A \in \mathbb{R}^{2 \times 2}$
on a unit circle S

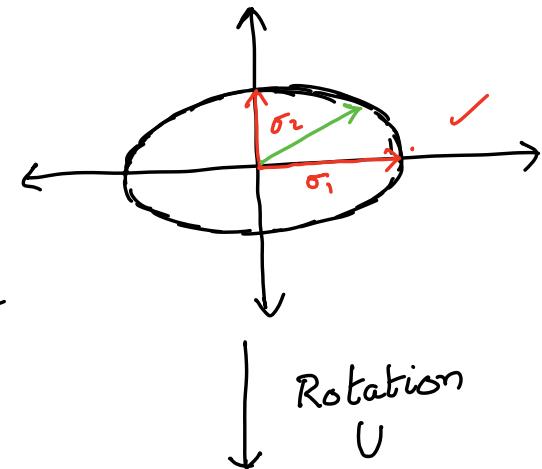
$$\Sigma \quad \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{bmatrix} \quad \sigma_1 > \sigma_2$$

Stretching

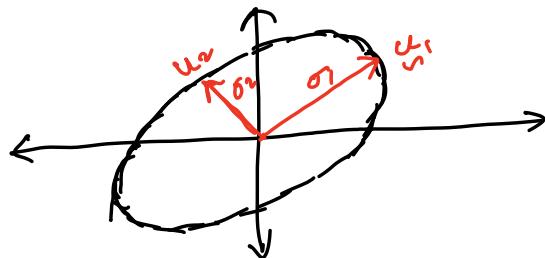
Rotation

Stretching to Ellipse

Rotation of Ellipse



Rotation U



This process can be generalized to higher dimension ≥ 2

Let S be unit hypersphere in \mathbb{R}^n .
 The action of $A \in \mathbb{R}^{m \times n}$ ($m \geq n$) and full rank on S is a hyperellipse in \mathbb{R}^m with the following properties :-

$$(i) \quad A u_j = \sigma_j u_j$$

$\sigma_1, \sigma_2, \sigma_3, \dots, \sigma_n$ are lengths of the principal semi-axes of $A S$ (hyperellipse in \mathbb{R}^m) and these σ_j 's are called singular values of A . By convention they are ordered in descending order

$$\sigma_1 \geq \sigma_2 \dots \geq \sigma_n$$

(ii) The set of unit vectors $\{u_1, u_2, \dots, u_n\}$ are directions of principal semi-axes of our hyperellipse and these are called

left singular vectors and are orthonormal vectors.

$\therefore \sigma_j \underline{u}_j$ is the j^{th} largest principal semi-axes of our hyperellipsoid A^S

(iii) The set of unit vectors $\{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_n\}$ which also form an orthonormal set are the pre-images of \underline{u}_i and are called right singular vectors of A

$$A \underline{v}_j = \sigma_j \underline{u}_j \quad \text{--- (1)}$$

$$\begin{aligned} [A]_{m \times n} &= \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ \underline{v}_1 & \underline{v}_2 & \underline{v}_3 & \cdots & \underline{v}_n \end{bmatrix}_{n \times n} \\ &= \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ \underline{u}_1 & \underline{u}_2 & \underline{u}_3 & \cdots & \underline{u}_n \end{bmatrix}_{m \times n} \begin{bmatrix} \sigma_1 & \sigma_2 & \cdots & 0 \\ 0 & 0 & \cdots & \sigma_n \end{bmatrix}_{n \times n} \\ A \underline{v} &= \hat{U} \hat{\Sigma} \end{aligned}$$

$A \in \mathbb{R}^{m \times n}$ $\hat{U} \in \mathbb{R}^{m \times n}$
 $\underline{v} \in \mathbb{R}^{n \times 1}$ $\hat{\Sigma} \in \mathbb{R}^{n \times n}$

Since \underline{V} is orthogonal matrix

$$A \tilde{U} \tilde{\Sigma} \tilde{V}^T = \hat{U} \hat{\Sigma} \hat{V}^T$$

$$\boxed{A = \hat{U} \hat{\Sigma} \hat{V}^T}$$



Reduced Singular Value Decomposition

$$\begin{matrix} \text{---} \\ \text{---} \\ \text{---} \end{matrix} = \begin{matrix} \text{---} \\ \text{---} \\ \text{---} \end{matrix} + \begin{matrix} \text{---} \\ \text{---} \\ \text{---} \end{matrix} \hat{\Sigma}_{n \times n} \begin{matrix} \text{---} \\ \text{---} \\ \text{---} \end{matrix} \quad V_{n \times n}^T$$

$A_{m \times n}$ $O_{m \times n}$

Full Singular value decomposition :-

\hat{U} is made of n orthonormal vectors in \mathbb{R}^m and hence this cannot be a basis for \mathbb{R}^m . Now to make \hat{U} to be orthogonal, we add additional $m-n$ orthonormal columns to \hat{U} and call this new matrix $U \in \mathbb{R}^{m \times m}$

Now we write SVD of $A \in \mathbb{R}^{m \times n}$ in terms of orthogonal matrix $U \in \mathbb{R}^{m \times m}$

but for factorization not to change
we must change Σ to $m \times n$ matrix

by introducing $n - r$ additional rows of D^P

$$\begin{matrix} A \\ \in \mathbb{R}^{m \times n} \end{matrix} = \begin{matrix} U \\ \in \mathbb{R}^{m \times m} \end{matrix} \begin{matrix} \Sigma \\ \in \mathbb{R}^{m \times n} \end{matrix} \begin{matrix} V^T \\ \in \mathbb{R}^{n \times n} \end{matrix}$$

$$\boxed{A = U \Sigma V^T}$$

is called full SVD

- ① We no longer need
 A to be full rank.

$$\text{If } \text{rank}(A) = r < n$$

$$\begin{aligned} A &\in \mathbb{R}^{m \times n} \\ U &\in \mathbb{R}^{m \times m} \\ \Sigma &\in \mathbb{R}^{m \times n} \\ V &\in \mathbb{R}^{n \times n} \end{aligned}$$

only r singular vectors will be determined
by geometry of hyperellipse and we
will add $m - r$ orthonormal columns to
build U and $n - r$ arbitrary columns to
extend r columns determined by the geometry

The matrix $\tilde{\Sigma}$ will now have r positive diagonal entries with remaining $n-r$ values to be equal to zero.

In fact reduced SVD of A less than full rank and this is given as

$$\tilde{A} = \tilde{U}_{m \times r} \tilde{\Sigma}_{r \times r} \tilde{V}_{r \times n}^T$$

Definition of SVD formally can be stated as follows:-

The singular value decomposition of $A \in \mathbb{R}^{m \times n}$ is a factorization of the form $A = U \Sigma V^T$ where $U \in \mathbb{R}^{m \times m}$, $V \in \mathbb{R}^{n \times n}$ are orthogonal matrices and Σ has $n \times n$ diagonal matrix block (Σ_d) and is of dimension $m \times n$ matrix.

- (1) There is no assumption that $m \geq n$
or A has to be full rank.
- (2) All diagonal elements of Σ^d are non-negative and increasing order
 $\sigma_1 \geq \sigma_2 \geq \sigma_3 \dots \geq \sigma_p \geq 0$
where $p = \min(m, n)$
- (3) Σ has the same shape as A
but U, V are square matrices
- (4) Every matrix $A \in \mathbb{R}^{m \times n}$ has a full SVD, $A = U \Sigma V^T$. The singular values $\{\sigma_j\}$ are uniquely determined for a give matrix A .
- (5) If A is a square matrix and if $(\sigma_i \neq \sigma_j)$ (for all i and j), then the left singular vectors $\{u_{ij}\}$ and the right singular vectors $\{v_{ij}\}$ are uniquely

determined to within a factor of ± 1 .

Change of basis - via - SVD

$$\underline{A} \in \mathbb{R}^{m \times n}, \quad \underline{b} \in \mathbb{R}^m, \quad \underline{x} \in \mathbb{R}^n$$

$$\underline{A} \underline{x} = \underline{b}$$

Let $\underline{b} \in \mathbb{R}^m$ be expanded using the left singular vectors of \underline{A} (columns of \underline{U})

and $\underline{x} \in \mathbb{R}^n$ be expanded in basis of right singular

$$\underline{b} = \sum_{i=1}^m b_i' \underline{u}_i, \text{ vectors } \underline{v} \Rightarrow \underline{b} = \underline{U} \underline{b}', \quad \underline{b}' = \begin{bmatrix} b_1' \\ b_2' \\ \vdots \\ b_m' \end{bmatrix}$$

$$\underline{x} = \sum_{i=1}^n x_i' \underline{v}_i$$

$$\Rightarrow \underline{x} = \underline{V} \underline{x}' \quad \underline{x}' = \begin{bmatrix} x_1' \\ x_2' \\ \vdots \\ x_n' \end{bmatrix}$$

$$\underline{A} \underline{x} = \underline{b}$$

$$\underline{U} \sum_{i=1}^n \underline{V}^T \underline{V} \underline{x}' = \underline{U} \underline{b}'$$

$$\Rightarrow \underline{U} \sum_{i=1}^n \underline{x}' = \underline{U} \underline{b}'$$

$$\Rightarrow \underline{U}^T \underline{\Sigma} \underline{x}' = \underline{U}^T \underline{\Sigma} \underline{b}'$$

$$\Rightarrow \underline{\Sigma} \underline{x}' = \underline{b}'$$

whenever we have $\underline{b} = \underline{A} \underline{x}$.

we have $\underline{b}' = \underline{\Sigma} \underline{x}'$ i.e \underline{A}

reduced to a diagonal matrix $\underline{\Sigma}$
when range is expressed in basis
of columns of \underline{U} and domain
is expressed in basis of columns
of \underline{V}

Matrix properties via SVD

Let $\underline{A} \in \mathbb{R}^{m \times n}$ and let p be the minimum
of m and n where $\sigma \leq p$ denote the
number of non-zero singular values of \underline{A}

Thm 1 :- The number of non-zero singular
values is the rank of the matrix \underline{A} .

Pf:- $\underline{A} = \underline{U} \underline{\Sigma} \underline{V}^T$

$\underline{U} \in \mathbb{R}^{m \times m}$
 $\underline{\Sigma} \in \mathbb{R}^{m \times n}$
 $\underline{V} \in \mathbb{R}^{n \times n}$

$$\text{rank}(\underline{A}) = \text{rank}(\underline{U} \underline{\Sigma} \underline{V}^T)$$

Recall from Assgn 2, if a matrix
 Q is non-singular then $\text{rank}(PQ) = \text{rank}(P)$

$$\text{rank}(\underbrace{U}_{m \times m} \underbrace{\Sigma}_{\infty \times \infty} \underbrace{V^T}_{n \times n}) = \text{rank}(\underbrace{U}_{m \times m} \underbrace{\Sigma}_{\infty \times \infty}) \quad - (1) \quad P \in \mathbb{R}^{m \times m}, Q \in \mathbb{R}^{n \times n}$$

Again if you have two matrices $X \in \mathbb{R}^{m \times r}$;

$$Y \in \mathbb{R}^{r \times p}, \text{rank}(X) + \text{rank}(Y) - r \leq \text{rank}(XY) \leq \min(\text{rank}(X), \text{rank}(Y))$$

$$X \rightarrow U \text{ and } Y \rightarrow \Sigma \quad U \in \mathbb{R}^{m \times r} \text{ and } \Sigma \in \mathbb{R}^{r \times n}$$

$$\text{rank}(U) + \text{rank}(\Sigma) - r \leq \text{rank}(US) \leq \min(\text{rank}(U), \text{rank}(\Sigma))$$

$$m + r - r \leq \text{rank}(US) \leq \min(m, r)$$

$$r \leq \text{rank}(US) \leq r$$

$$\Rightarrow \text{rank}(US) = r$$

$$\text{rank}(A) = \text{rank}(USV^T) = r$$

Thm 2:- $\text{range}(A)$ i.e column space of A is same as the space spanned by $\langle \underline{u}_1, \underline{u}_2, \dots, \underline{u}_r \rangle$

and $\text{null}(\underline{A})$ is the space spanned
by $\langle \underline{v}_{r+1}, \underline{v}_{r+2}, \dots, \underline{v}_n \rangle$

Pf:- $\underline{A} = \underline{U} \underline{\Sigma} \underline{V}^T$
 $\underline{A} \underline{v} = \underline{U} \underline{\Sigma}$ multiply by \underline{v} on
both sides

$$\begin{aligned} \underline{A} &= \left[\underbrace{\underline{v}_1 \underline{v}_2 \underline{v}_3 \dots \underline{v}_r}_{\underline{U}} \quad \underbrace{\underline{v}_{r+1} \dots \underline{v}_n}_{\underline{\Sigma}} \right]_{n \times n} \\ &= \left[\underbrace{\underline{u}_1 \underline{u}_2 \dots \underline{u}_r}_{\underline{U}} \quad \underbrace{\underline{u}_{r+1} \dots \underline{u}_m}_{\underline{\Sigma}} \right]_{m \times m} \\ &\quad \left[\begin{array}{cccccc} \sigma_1 & \sigma_2 & \sigma_3 & \dots & \sigma_r & 0 \\ \vdots & \vdots & \vdots & & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & 0 \end{array} \right]_{m \times n} \end{aligned}$$

$$\underline{A} \underline{v}_j = \sigma_j \underline{u}_j \text{ for } j=1 \dots r$$

$\frac{1}{\sigma_j} \underline{A} \underline{v}_j = \underline{u}_j'$
clearly \underline{u}_j' lies in the column-space
of \underline{A} for $j=1 \dots r$
show $\langle \underline{u}_1, \dots, \underline{u}_r \rangle$
spans the
column-space
of \underline{A} ?

$\begin{aligned} A \underline{v}_{r+1} &= 0 \\ A \underline{v}_{r+2} &= 0 \\ \vdots \\ A \underline{v}_n &= 0 \end{aligned}$
 are in the null-space
 of A and form a
 basis for $n-r$
 dimensional space.
 i.e. $\text{null}(A)$ is spanned
 by $\langle \underline{v}_{r+1}, \underline{v}_{r+2}, \dots, \underline{v}_n \rangle$

$$\text{Thm 3 :- } \|\underline{\underline{A}}\|_2 = \max_{\|\underline{x}\|_2=1} \|\underline{\underline{A}} \underline{\underline{x}}\|_2 = \sigma_1$$

$$\|\underline{\underline{A}}\|_F = \left(\sum_{i=1}^m \sum_{j=1}^n |A_{ij}|^2 \right)^{1/2}$$

$$= \sqrt{\sigma_1^2 + \sigma_2^2 + \dots + \sigma_n^2}$$

$$\begin{aligned}
 \text{Pf :- } \|A\|_2 &= \|\underline{U} \underline{\Sigma} \underline{V}^T\|_2 = \|\underline{\Sigma} \underline{V}^T\|_2 \\
 &= \|\underline{\Sigma}\|_2 \\
 &= \max \{\sigma_j\} \\
 &= \sigma_1
 \end{aligned}$$

$$\|A\|_F = \|\Sigma^{-1/2} \Sigma^T \Sigma^{-1/2}\|_F = \|\Sigma\|_F$$

$$= \sqrt{\sigma_1^2 + \sigma_2^2 + \dots + \sigma_s^2}$$

SVD and eigenvalue decomposition :-

eigen decomposition :-

If $\underline{A} \in \mathbb{R}^{m \times m}$ is non-defective, then it has complete set of m linearly independent eigenvectors.

$$\begin{aligned} \underline{A} \underline{x}_1 &= \lambda_1 \underline{x}_1 \\ \underline{A} \underline{x}_2 &= \lambda_2 \underline{x}_2 \\ &\vdots \\ \underline{A} \underline{x}_m &= \lambda_m \underline{x}_m \end{aligned} \quad \left\{ -\textcircled{1} \right.$$

$$\underline{A} \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ \underline{x}_1 & \underline{x}_2 & \underline{x}_3 & \dots & \underline{x}_m \\ 1 & 1 & 1 & \dots & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ \underline{x}_1 & \underline{x}_2 & \underline{x}_3 & \dots & \underline{x}_m \\ 1 & 1 & 1 & \dots & 1 \end{bmatrix} \begin{bmatrix} \lambda_1 & & & & 0 \\ & \lambda_2 & & & \\ & & \ddots & & \\ & & & \ddots & \lambda_m \end{bmatrix}$$

$$\underline{A} \underline{x} = \underline{x} \Delta \quad -\textcircled{2}$$

$$\Rightarrow \underline{A} = \underline{x} \Delta \underline{x}^{-1} \Rightarrow \Delta = \underline{x}^{-1} \underline{A} \underline{x} \quad -\textcircled{3}$$

For $\underline{A} \in \mathbb{R}^{m \times m}$, $\underline{A} \underline{x} = \underline{b}$ and

we expand $\underline{b}, \underline{x} \in \mathbb{R}^m$ in the

basis of eigenvectors $\underline{b} = \sum_{i=1}^m b_i \underline{x}_i$

$$\underline{b} = \underline{x} \underline{b}' \quad \underline{b}' = \begin{bmatrix} b_1' \\ b_2' \\ \vdots \\ b_m' \end{bmatrix}$$

$$\text{and } \underline{x} = \sum_{i=1}^m \underline{x}_i' \underline{x}_i \quad \Rightarrow \underline{x} = \underline{x} \underline{x}'$$

where $\underline{x}' = \begin{bmatrix} x_1' \\ x_2' \\ \vdots \\ x_m' \end{bmatrix}$

$$\begin{aligned} \underline{A} \underline{x} &= \underline{b} \\ \underline{A} \underline{X} \underline{x}' &= \underline{X} \underline{b}', \\ \Rightarrow \underbrace{\underline{X}^{-1} \underline{A} \underline{X}}_{\underline{A}' = \underline{b}'} \underline{x}' &= \underline{b}' \\ \underline{A}' &= \underline{b}' \end{aligned}$$

Comparison of SVD and eigen-decomp:-

- * SVD uses two different bases
(left singular vectors basis and right singular vectors basis)
- wheras eigen decomposition uses just one basis ie basis of eigenvectors
- * SVD results in orthonormal bases whereas \underline{X} in eigen-decomposition is generally not orthogonal.
- * SVD exists for all matrices no matter dimension; eigen-decomposition

exist for square non-defective matrices.

Thm 4: Non zero singular values of $A \in \mathbb{R}^{m \times n}$ are square roots of non-zero eigenvalues of $A^T A$ or $A A^T$.

$$A = U \Sigma V^T$$

$$A^T A = (U \Sigma V^T)^T (U \Sigma V^T)$$

$$= (V^T)^T \Sigma^T U^T U \Sigma V^T$$

$$= V \Sigma^T \Sigma V^T = V \tilde{\Sigma} V^T$$

where $\tilde{\Sigma}$ is diag matrix

of squares of
singular values

$V \tilde{\Sigma} V^T$ is eigendecomp of $A^T A$

comprising $\sigma_1^2, \sigma_2^2, \dots, \sigma_p^2$ as diagonal
entries of $\tilde{\Sigma}$ with $n-p$ additional
zero eigenvalues if $n > p$

Thm 5: If $A = A^T$ singular values of A
are absolute values of eigenvalues of A .

Pf:-

$$\begin{aligned} A &= \underline{\lambda} \Delta \underline{\lambda}^{-1} \\ &= \underline{Q} \underline{\Lambda} \underline{Q}^{-1} \quad (\text{where } \underline{Q} \text{ is an orthogonal matrix for symmetric matrices}) \\ &= \underline{Q} \underline{\Lambda} \underline{Q}^T \\ &= \underline{Q} |\Lambda| \underbrace{\text{sgn}(\Lambda)}_{\text{where } |\Lambda| \text{ and } \text{sgn}(\Lambda) \text{ are diagonal}} \underline{Q}^T \end{aligned}$$

where $|\Lambda|$ and $\text{sgn}(\Lambda)$ are diagonal matrices whose entries are $|\lambda_j|$ and $\text{sgn}(\lambda_j)$.

$$\begin{aligned} A &= \underline{Q} |\Lambda| \underbrace{\text{sgn}(\Lambda)}_{\text{is SVD of } A} \underline{Q}^T \\ &= \underline{Q} |\Lambda| \bar{\underline{Q}}^T \end{aligned}$$

$A = \underline{Q} |\Lambda| \bar{\underline{Q}}^T$ is SVD of A

Thm 6: $A \in \mathbb{R}^{m \times m}; |\det(A)| = \prod_{i=1}^m \sigma_i$

$$\begin{aligned} |\det(A)| &= |\det(\underline{U} \underline{\Sigma} \underline{V}^T)| \\ &= |\det(\underline{U})| |\det(\underline{\Sigma})| |\det(\underline{V}^T)| \\ &= |\det(\underline{\Sigma})| = \prod_{i=1}^m \sigma_i \end{aligned}$$

$$[|\det(\underline{V})| = |\det(\underline{U})| = 1]$$

Low rank approximations:-

Thm 2:- A $\in \mathbb{R}^{m \times n}$ of rank " r " can be written as sum of " r " rank-one matrices of the form $\tilde{A} = \sum_{j=1}^r \sigma_j u_j v_j^T$

where $\{\sigma_j\}$ are singular values

and $\{u_j\}, \{v_j\}$ are the appropriate singular vectors.

Pf:- Recall $u v^T$ is a rank-one matrix

$$\tilde{A} = \tilde{U} \tilde{\Sigma} \tilde{V}^T$$

$$\tilde{\Sigma} = \sum_{j=1}^r \tilde{\Sigma}_j \quad \text{where}$$

$$\tilde{\Sigma}_j = \begin{bmatrix} 0 & 0 & \dots & \sigma_j & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 & \dots & 0 \end{bmatrix}_{m \times n}$$

$$\tilde{A} = \tilde{U} \tilde{\Sigma} \tilde{V}^T$$

$$= \tilde{U} \left\{ \sum_{j=1}^r \tilde{\Sigma}_j \right\} \tilde{V}^T$$

$$= \sum_{j=1}^r \tilde{U} \tilde{\Sigma}_j \tilde{V}^T = \sum_{j=1}^r \sigma_j \tilde{u}_j \tilde{v}_j^T$$

$$A = \sum_{j=1}^{\infty} \sigma_j u_j v_j^T$$

$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_\infty$

Then k^{th} partial sum $\sum_{j=1}^k \sigma_j u_j v_j^T$ has as much energy (information) of A as possible

Thm 8:- For any k with $1 \leq k \leq \infty$

define $A_k = \sum_{j=1}^k \sigma_j u_j v_j^T$

then $\|A - A_k\|_2 = \min_{\substack{B \in \mathbb{R}^{m \times n} \\ \text{rank}(B) \leq k}} \|A - B\|_2 = \sigma_{k+1}$

Eckhart-Touring Theorem

Proof:- Let there be some $C(B)$ whose $\text{rank}(B) \leq k$ such that $\|A - B\|_2 < \|A - A_k\|_2$

$$\dim(N(CB)) \geq n-k$$

$= \sigma_{k+1}$

as $\text{rank}(B) \leq k$

Consider the subspaces

(i) W_1 : The null space of $C(B)$ which is of dimension of at least $n-k$

(ii) W_2 : The space spanned by $k+1$ right singular vectors of A i.e. $v_1, v_2, v_3, \dots, v_{k+1}$

These two subspaces have to intersect?
why?

Dimensions of the two subspaces

add to $(n-k) + (k+r)$ i.e. the subspaces
must atleast have 1 common vector.

Let such a non-zero vector be \underline{x} i.e.
 $\underline{x} \in W_1 \cap W_2$

$$\underline{x} \neq 0; \underline{x} \in N(CB) \text{ i.e. } B\underline{x} = 0 \text{ and } \underline{x} \in W_2$$

$$\underline{x} = \sum_{i=1}^{k+1} c_i \underline{u}_i$$

$$\begin{aligned} \|A\underline{x}\|_2 &= \|(A-B)\underline{x}\|_2 \\ &\leq \|A-B\|_2 \|\underline{x}\|_2 < \sigma_{k+1} \|\underline{x}\|_2 - \textcircled{1} \end{aligned}$$

$$A\underline{v}_i = \underbrace{\sigma_i}_{\textcircled{2}} \underbrace{\underline{u}_i}_{\textcircled{3}}$$

$$\begin{aligned} \|A\underline{x}\|_2^2 &= \left\| A \sum_{i=1}^{k+1} c_i \underline{v}_i \right\|_2^2 \\ &= \left\| \sum_{i=1}^{k+1} c_i \sigma_i \underline{u}_i \right\|_2^2 = \left[\sum_{i=1}^{k+1} c_i \sigma_i \underline{u}_i \right]^T \left[\sum_{i=1}^{k+1} c_i \sigma_i \underline{u}_i \right] \\ &= \sum_{i=1}^{k+1} c_i^2 \sigma_i^2 \quad (\text{use ortho normality of } \underline{u}_i) \end{aligned}$$

$$\underbrace{\sum_{i=1}^{k+1} c_i^2 \sigma_i^2}_{\textcircled{1}} \geq \underbrace{\sum_{i=1}^{k+1} c_i^2 \sigma_{k+1}^2}_{\textcircled{2}}$$

$$= \left(\sum_{i=1}^{k+1} c_i^2 \right) \sigma_{k+1}^2$$

$$= \|\underline{x}\|^2 \sigma_{k+1}^2$$

$$\|A\underline{x}\|_2^2 \geq \|\underline{x}\|^2 \sigma_{k+1}^2 \text{ i.e. } \|A\underline{x}\|_2 \geq \sigma_{k+1} \|\underline{x}\|_2 - \textcircled{2}$$

① & ② is a contradiction which means you cannot have a matrix B with $\text{rank}(B) \leq k$ such that $\|A - B\|_2 \leq \|A - A_k\|_2$

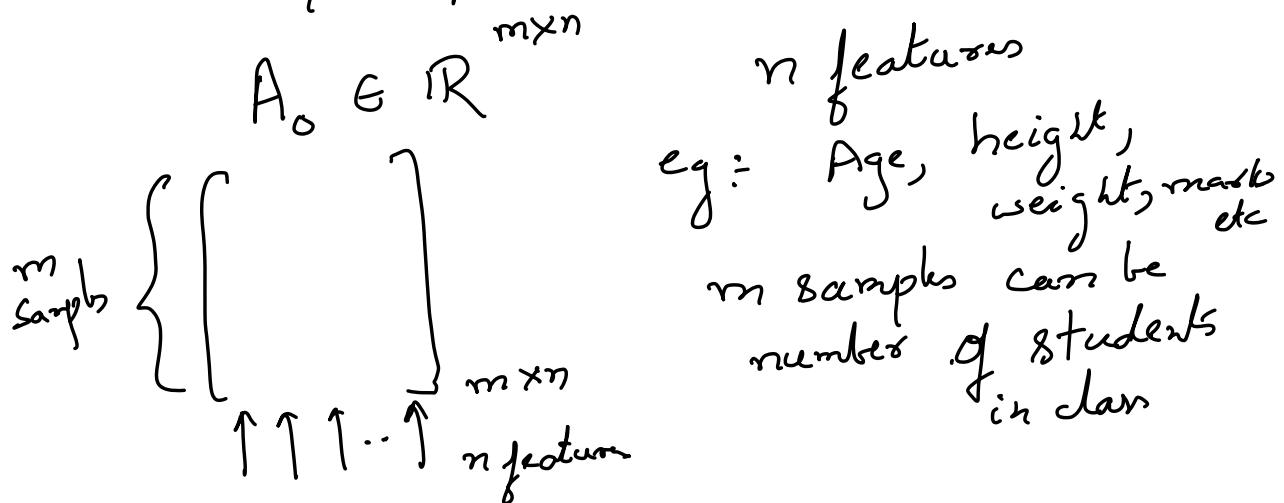
Lickhardt-Young in Frobenius norm:-

Theorem For any k , with $1 \leq k \leq \infty$, the matrix $A_k = \sum_{j=1}^k \sigma_j u_j v_j^T$ also satisfies $\|A - A_k\|_F = \min_{\substack{B \in \mathbb{R}^{m \times n} \\ \text{rank}(B) \leq k}} \|A - B\|_F$

$$= \sqrt{\sigma_{k+1}^2 + \sigma_{k+2}^2 + \dots \sigma_\infty^2}$$

Principal components :-

u_i, v_i are called principal components!



→ Mean is the average of the data (in each column). Subtract these means of each of these columns of A_0 and reconstruct the data matrix which produces centered matrix \underline{A} .

→ Variance as sum of squares of distances from the mean — along each column of \underline{A}

$$v_i \propto \|a_{i\cdot}\|_2^2 \left(\frac{1}{m-1}\right)$$

→ Total variance in the full data is the sum of variances of individual columns.

$$\underline{A} = \begin{bmatrix} 1 & 1 & \dots & 1 \\ a_1 & a_2 & \dots & a_n \\ 1 & 1 & \dots & 1 \end{bmatrix}$$

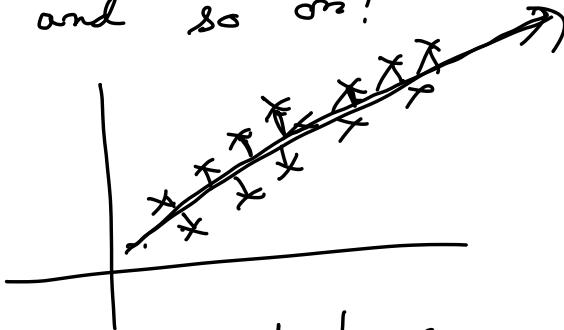
$$T \propto \underbrace{\left(\|a_1\|_2^2 + \|a_2\|_2^2 + \dots + \|a_n\|_2^2 \right)}_{T \propto \|A\|_F^2}$$

$$\propto \left(\sigma_1^2 + \sigma_2^2 + \dots + \sigma_n^2 \right)$$

σ_1^2 accounts for maximum contribution to the total variance, σ_2^2 accounts for next largest contribution to total variance and so on!

The first component u_1 is along (left singular vec)
the direction of maximum variance,
 u_2 is along the next largest variance
and so on!

Geometrically first principal component corresponds to a line that minimizes the sum of squares of orthogonal distances of the points from the line!



The key point is that $k < n$ singular vectors explain most of the data than any other set of k vectors. So

we can choose u_1, u_2, \dots, u_k as a basis for k -dimensional subspace closest to n -dimensional subspace corresponding to our m -data points.