

DS 288: NUMERICAL METHODS

OCT-26-2021.

ADAMS METHODS

- CLASS OF MULTI-STEP METHODS

* ADAMS-BASCH FORTH METHODS:

"OPEN" OR EXPLICIT METHODS
i.e. DO NOT INVOLVE f_{i+1}

* ADAMS-MOULTON METHODS:

"CLOSED" OR IMPLICIT METHODS
i.e. DO INVOLVE f_{i+1}

IDEA

$$y_{i+1} = y_i + h f_i + \frac{h^2}{2!} f_i' + \frac{h^3}{3!} f_i'' + \dots$$

APPROXIMATE DERIVATIVES

WITH $f_{i+1}, f_i, f_{i-1}, f_{i-2}, \dots$

EXPLICIT METHODS
IMPLICIT METHODS (ADAMS-BASCH FORTH)
(ADAMS-MOULTON)

ADAMS-BASCHFORTH 2 STEP METHOD

$$y_{i+1} = y_i + h f_i + \underbrace{\frac{h^2}{2!} f'_i}_{\text{FIRST FORWARD DIFFERENCE APPROXIMATION}} + \underbrace{\frac{h^3}{3!} f''_i}_{\text{SECOND FORWARD DIFFERENCE APPROXIMATION}} + \dots$$

FIRST BACKWARD DIFFERENCE APPROXIMATION

$$f'_i = \frac{f_i - f_{i-1}}{h} + O(h)$$

$$w_{i+1} = w_i + h f_i + \frac{h}{2} [f_i - f_{i-1}] + O(h^3)$$

$$w_{i+1} = w_i + h \left[\frac{3}{2} f_i - \frac{1}{2} f_{i-1} \right] + O(h^3)$$

GLOBALLY $O(h^2)$.

SAME ORDER AS RIC-2, BUT NO HALF-INTERVALS

- KEEPS TRACK OF PREVIOUS FUNCTION EVALUATION AND ONLY ONE NEW FUNCTION EVALUATION IS REQUIRED AT EACH STEP.

ADAMS-BASCHFORTH 3 STEP METHOD

USE 3 POINTS TO APPROXIMATE

$$\left. \begin{array}{l} f'_i \rightarrow O(h^2) \\ f''_i \rightarrow O(h) \end{array} \right\} \begin{array}{l} \text{USE ONLY} \\ \text{BACKWARD} \\ \text{DIFFERENCE} \end{array}$$

$$\Rightarrow O(h^4) \text{ / STEP } \Rightarrow O(h^3) \text{ / GLOBALLY}$$

$$w_{i+1} = w_i + \frac{h}{12} [23f_i - 16f_{i-1} + 5f_{i-2}]$$

A-B 3 STEP METHOD

* CAN CONTINUE IN THIS FASHION.

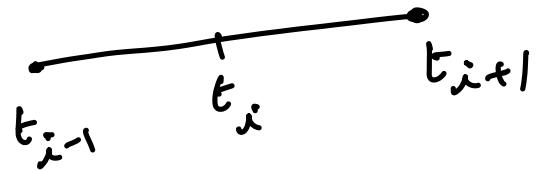
A-B 2-5 STEP METHODS IN TEXTBOOK

[HANDOUT TO BE MADE]

* ADAMS-MOULTON METHODS

INVOLVE f'_i , SO WE CAN USE CENTERED DIFFERENCE APPROXIMATIONS
i.e. $f' \rightarrow O(h^2)$ WITH ONLY 2 STEPS

ADAMS-MOULTON 2 STEP METHOD



USE CENTERED DIFFERENCE SCHEME ·
TO APPROXIMATE f' & f''

TERMS FROM TAYLOR SERIES (REF. #)

$$\frac{h^2}{2!} f'_i \approx \frac{h^2}{2} \left[\frac{f_{i+1} - f_{i-1}}{2h} + O(h^2) \right] \quad \left. \begin{array}{l} O(h^4) \\ \text{locally} \end{array} \right\}$$

$$\frac{h^3}{3!} f''_i \approx \frac{h^3}{6} \left[\frac{f_{i+1} - 2f_i + f_{i-1}}{h^2} + O(h^2) \right]$$

SUBSTITUTE THESE IN #

$$w_{i+1} = w_i + hf_i + \frac{h^2}{2} \left[\frac{f_{i+1} - f_{i-1}}{2h} \right] + \frac{h^3}{3!} \left[\frac{f_{i+1} - 2f_i + f_{i-1}}{h^2} \right]$$

COLLECT TERMS

$$w_{i+1} = w_i + \frac{h}{12} [5f_{i+1} + 8f_i - f_{i-1}] \quad \begin{array}{l} A-M \\ 2 STEP \\ METHOD \end{array}$$

$O(h^4)$ LOCALLY
 $O(h^3)$ GLOBALLY

$$LTE = -\frac{h^4}{24} f'''(y_i, t_i) \quad t_i \in [t_{i-1}, t_{i+1}]$$

IN TEXT BOOK: GTE IN CLASS IS
BEING CALLED AS LTE

$$f_{i+1} \equiv f(w_{i+1}, t_{i+1})$$

TWO SOLUTIONS:

(1) y APPEARS LINEARLY IN $f(y, t)$.

$$\text{i.e. } y' = -\underline{\underline{y + t - 1}} -$$

THEN f_{i+1} EVALUATION PRESENTS
NO PROBLEM

$$\text{Ex: } w_{i+1} = w_i + \frac{h}{c2} [5(-w_{i+1} + t_{i+1}) + \dots]$$

SOLVE FOR w_{i+1}

$$w_{i+1} \left(1 + \frac{5h}{12}\right) = w_i + \frac{h}{12} \{5(e_{i+1})\} + \dots$$

CALCULATE w_{i+1}

(ii) γ APPEARS NON-LINEARALLY IN
 $f(\gamma, t)$.

$$\text{i.e. } \gamma^1 = \cos(\gamma) + t$$

THEN f_{i+1} EVALUATION PRESENTS A
PROBLEM
* USING 2 STEP A-M

$$w_{i+1} = w_i + \frac{h}{12} \left\{ 5 \underbrace{\left[\cos(w_{i+1}) + e_{i+1} \right] \dots}_{f_{i+1}} \right.$$

* NOT POSSIBLE TO COLLECT w_{i+1} TERMS

* INSTEAD WE MUST PREDICT w_{i+1}
AND CORRECT USING A-M METHOD

PREDICTOR / CORRECTOR SCHEME

* USE AN EXPLICIT METHOD TO

PREDICT w_{i+1}

THEN USE IMPLICIT METHOD

TO IMPROVE / CORRECT w_{i+1}

* WE DID THIS TO GET EXPLICIT

FORM OF THE TRAPEZOIDAL METHOD

IN THE FORM OF MODIFIED
EULER'S METHOD

$$w_{i+1} = w_i + \frac{h}{2} [f_i + f_{i+1}] \quad \begin{matrix} \text{TRAPEZOIDAL} \\ \text{METHOD} \end{matrix}$$

$f_{i+1} = f(w_{i+1}, t_{i+1})$ USE

$$w_{i+1} = w_i + h f_i \quad \begin{matrix} \text{EULER} \\ \text{STEP} \end{matrix}$$

E.X: - AB/A-M PREDICTOR / CORRECTOR

$$\hat{w}_{i+1} = w_i + \frac{h}{2} (3f_i - f_{i-1})$$

A-B 2 STEP
PREDICTOR
 $O(h^2)$ / GLOBALLY

$$w_{i+1} = w_i + \frac{h}{12} [5f_i(t_{i+1}, t_{i+1}) + 8f_i(t_i, t_{i+1}) + 2f_i(t_i, t_{i-1})]$$

A-M 2 STEP CORRECTOR
 $O(h^3)$ / GLOBALLY

PREDICTOR
OUTPUT

* THINK OF THIS AS A FIXED POINT
ITERATION

$$w_{i+1} = g(\hat{w}_{i+1})$$

\hookrightarrow PREDICTOR
(EXPLICIT METHOD)

* MULTIPLE STEPS OF CORRECTION?

- IN MOST CASES THERE IS NOT
MUCH ADVANTAGE OF "CORRECTIONS"
MORE THAN ONCE.

- IF WE DO ITERATE (CORRECT

MULTIPLE TIMES) THEN FOR CONVERGENCE TO w_{i+1} WE REQUIRE
 $|g'(w_{i+1})| < 1$. IS REQUIRED

2-STEP A-B/A-M P/C:

$$|g'(w_{i+1})| = \left| \frac{5h}{\tau_2} \underbrace{\frac{\partial f}{\partial y}(w_i)}_{J = \text{JACOBIAN}} \right| < 1.$$

*RECALL J FORMS THE AMPLIFICATION FACTOR WHEN DERIVING THE ERROR BEHAVIOR OF EULER'S METHOD.

* IF J IS LARGE \Rightarrow WE REQUIRE SMALL ' h ' \Rightarrow WE REQUIRE MORE STEPS \Rightarrow MORE COMPUTATIONAL COMPLEXITY.

* we could use other types of
fixed point iterations
(i.e. other 'g' functions).

Ex: NEWTON's METHOD.

- Rewrite $g(\omega_{i+1}) = \omega_{i+1}$ as $f(\omega_{i+1}) = 0$

2 STEP A-B) A-M PIC EXAMPLE:

$$\omega_{i+1} - \left\{ \omega_i + \frac{h}{12} [5f(\omega_{i+1}, t_{i+1}) + 8f_i - f_{i-1}] \right\} = 0$$

$f(z) = 0$ WHERE $z = \omega_{i+1}$

$$z^{k+1} = z^k - \frac{f(z^k)}{f'(z^k)} \quad \text{NEWTON'S METHOD}$$

WRITE IT OUT

$$\omega_{i+1}^{k+1} = \omega_{i+1}^k - \frac{\left\{ \omega_{i+1}^k - \omega_i - \frac{h}{12} [5f(\omega_{i+1}^k, t_{i+1}) + 8f_i - f_{i-1}] \right\}}{1 - \frac{5h}{12} \frac{\partial f}{\partial \omega} |_{\omega_{i+1}^k}}$$

- * CONVERGENCE IS FASTER
BUT REQUIRES A GOOD GUESS OF
 w_{it+1}^0 (PREDICTOR)
- IN PRACTICAL PROBLEMS,
IMPROVING THE CORRECTED VALUE
IS NOT WORTH IT. MUCH BETTER
TO CUT THE STEP SIZE (' h ' AS
SMALL).
- * FOR "STIFF" EQUATIONS
 ↳ (LARGE J)
 THERE IS A BENEFIT TO
MULTIPLE CORRECTIONS
(ITERATIVE CORRECTOR)
- DEFINITELY SHOULD USE
NEWTON'S METHOD SINCE
 $g'(w_{it+1}) = 0$ (AS OPPOSED TO
 $\frac{\sqrt{h}}{r_2} J$ FOR GENERAL)

FIXED POINT ITERATION

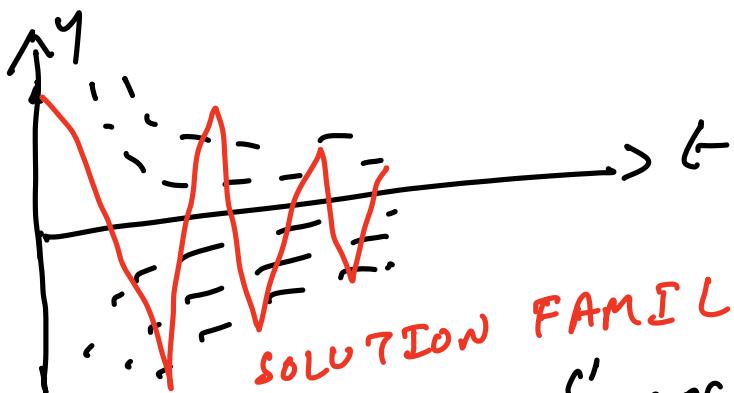
EX: OF A STIFF EQUATION

$$y' = \underbrace{-ky}_{f} \Rightarrow y = y_0 e^{-kt}$$

$$J = \frac{\partial f}{\partial y} = -k$$

FOR LARGE k ,
 J IS LARGE

SLOPE IS STEEP FOR LARGER y



SOLUTION FAMILIES

SLOPE $\rightarrow 0$ FOR $y=0$ "CAN OSCILLATE"

* MORE LARGER ON "STIFF"
EQUATIONS WHEN WE DISCUSS
STABILITY,