

3) a) For a matrix to be orthogonal, it should satisfy the following:

$$\underset{\sim}{Q}^{-1} = \underset{\sim}{Q}^T, \text{ i.e. inverse of } \underset{\sim}{Q} = \text{transpose of } \underset{\sim}{Q}$$

First let us calculate $\underset{\sim}{Q}^T$: - $\underset{\sim}{Q}$ is given as $\left[\underset{\sim}{I} - \underset{\sim}{S}\right]^{-1} \left[\underset{\sim}{I} + \underset{\sim}{S}\right]$

$$\begin{aligned} \underset{\sim}{Q}^T &= \left[\left(\underset{\sim}{I} - \underset{\sim}{S} \right)^{-1} \left(\underset{\sim}{I} + \underset{\sim}{S} \right) \right]^T \\ &= \left(\underset{\sim}{I} + \underset{\sim}{S} \right)^T \left[\left(\underset{\sim}{I} - \underset{\sim}{S} \right)^{-1} \right]^T \quad (\text{reversal law, i.e. } (AB)^T = B^T A^T) \\ &= \left(\underset{\sim}{I}^T + \underset{\sim}{S}^T \right) \left[\left(\underset{\sim}{I} - \underset{\sim}{S} \right)^T \right]^T \quad ((A+B)^T = A^T + B^T) \\ &= \left(\underset{\sim}{I}^T + \underset{\sim}{S}^T \right) \left[\left(\underset{\sim}{I} - \underset{\sim}{S} \right)^T \right]^{-1} \quad ((\tilde{A})^T = (\tilde{A}^T)^{-1}) \\ &= \left(\underset{\sim}{I} - \underset{\sim}{S} \right) \left(\underset{\sim}{I}^T - \underset{\sim}{S}^T \right)^{-1} \quad (\underset{\sim}{I}^T = \underset{\sim}{I} \text{ and } \underset{\sim}{S}^T = -\underset{\sim}{S}) \\ &= \left(\underset{\sim}{I} - \underset{\sim}{S} \right) \left(\underset{\sim}{I} + \underset{\sim}{S} \right)^{-1} \end{aligned}$$

To prove $\underset{\sim}{Q}$'s orthogonality, we should prove $\underset{\sim}{Q} \cdot \underset{\sim}{Q}^T = \underset{\sim}{I}$. For this we need to rearrange ~~$\underset{\sim}{Q} \cdot \underset{\sim}{Q}^T$~~

Proof of commutability :

In this proof, I want to prove that $(\underset{\sim}{I} + \underset{\sim}{S})(\underset{\sim}{I} - \underset{\sim}{S}) = (\underset{\sim}{I} - \underset{\sim}{S})(\underset{\sim}{I} + \underset{\sim}{S})$

$$\left(\underset{\sim}{I} + \underset{\sim}{S} \right) \left(\underset{\sim}{I} - \underset{\sim}{S} \right) = \underset{\sim}{I}^2 + \underset{\sim}{S} - \underset{\sim}{S} - \underset{\sim}{S}^2 = \underset{\sim}{I} - \underset{\sim}{S}^2$$

$$\left(\underset{\sim}{I} - \underset{\sim}{S} \right) \left(\underset{\sim}{I} + \underset{\sim}{S} \right) = \underset{\sim}{I}^2 - \underset{\sim}{S} + \underset{\sim}{S} - \underset{\sim}{S}^2 = \underset{\sim}{I} - \underset{\sim}{S}^2$$

∴ Hence, the commutability is proved.

This proof shall help us to rearrange $\underset{\sim}{Q}$ & $\underset{\sim}{Q}^T$.

Rearranging \underline{Q}^T :

For this, we have to ~~use the~~ prove commutativity:

$$\underline{(I-S)(I+S)} = \underline{(I+S)(I-S)}$$

$$\underline{(I-S)^{-1}(I-S)(I+S)} = \underline{(I-S)^{-1}(I+S)(I-S)} \quad \begin{matrix} \text{(left multiply} \\ \text{by } (I-S)^{-1}) \end{matrix}$$

$$\underline{I} = \underline{(I+S)^{-1}(I+S)(I-S)}$$

$$\underline{(I+S)(I-S)^{-1}} = \underline{(I-S)^{-1}(I+S)(I-S)(I-S)^{-1}} \quad \begin{matrix} \text{(right} \\ \text{multiply} \\ \text{by } (I-S)^{-1}) \end{matrix}$$

$$\underline{(I+S)(I-S)^{-1}} = \underline{(I-S)^{-1}(I+S)}$$

Hence, \underline{Q} can be written as ~~$(I+S)(I-S)^{-1}$~~

$$\underline{(I+S)(I-S)^{-1}}$$

Now, we can prove $\underline{Q}^T \cdot \underline{Q} = \underline{I}$

$$Q^T Q = [(I-S)(I+S)^{-1}] [(I+S)(I-S)^{-1}]$$

$$= (I-S) [(I+S)^{-1} (I+S)] (I-S)^{-1} \quad \begin{matrix} \text{(distributive} \\ \text{property} \\ \text{of matrix} \\ \text{multiplication}) \end{matrix}$$

$$= (I-S) I (I-S)^{-1}$$

$$= (I-S) (I-S)^{-1}$$

$$= \underline{I}$$

\therefore Hence proven, $\underline{Q} = \underline{Q}^T$, or long as S is skew-symmetric

3-b) Since this is an "if and only if" statement, we shall have to prove both ways.

Proof #1: If $\underline{s} = \underline{0}$, then $\underline{u}^T \underline{s} \underline{u} = \underline{0}$.

This is easy to prove. If $\underline{s} = \underline{0}$, then

$$\begin{aligned}\underline{u}^T \underline{s} \underline{u} &= (\underline{u}^T \underline{s}) \underline{u} && \text{(Distributive property of matrix-vector multiplication)} \\ &= (\underline{u}^T \underline{0}) \underline{u} \\ &= \underline{0} \cdot \underline{u} \\ &= \underline{0} \quad (\text{proven})\end{aligned}$$

Proof #2: If $\underline{u}^T \underline{s} \underline{u} = \underline{0}$, then $\underline{s} = \underline{0}$

This proof has to be done in two stages. In the first stage, we need to prove that all diagonal elements of \underline{s} are 0. In the second phase, we prove all non-diagonal elements of \underline{s} to be 0. This shall hence prove $\underline{s} = \underline{0}$.

Phase #1: Prove $\{ \forall s_{ii} = 0 \mid i = j \}$

Assume $\underline{u} = \underline{e}_i$, then (\underline{e}_i represents a canonical basis vector)

$$\underline{e}_i^T \underline{s} \underline{e}_i = 0$$

$$s_{ii} = 0 \quad (\underline{s}_{ii} = \underline{e}_i^T \underline{s} \underline{e}_i)$$

Since i can be any index $1 \leq i \leq m$, all diagonal elements of \underline{s} are hence proven to be 0.

Hence, $s_{ii} = 0$.

Phase #2: Prove all non-diagonal elements of \tilde{S} are 0.

Assume $u = \underbrace{e_i}_{\sim} + \underbrace{e_j}_{\sim} \quad \& \quad i \neq j$

$$\text{Hence } u^T \underbrace{\tilde{S} u}_{\sim} = (\underbrace{e_i + e_j}_{\sim})^T \underbrace{\tilde{S} (e_i + e_j)}_{\sim}$$

$$0 = \underbrace{e_i^T e_j}_{\sim} + \underbrace{e_j^T e_j}_{\sim} + \underbrace{e_i^T e_j}_{\sim} + \underbrace{e_j^T e_i}_{\sim}$$

$$(S_{ii} \& S_{jj} \text{ are } 0, \text{ as proven in phase #1}) \quad 0 = S_{ii} + S_{jj} + S_{ij} + S_{ji}$$

$$(S_{ij} = S_{ji}, \text{ because } S \text{ is given to be symmetric}) \quad 0 = S_{ij} + S_{ji}$$

$$(S_{ij} = S_{ji}, \quad 0 = 2S_{ij})$$

$$S_{ij} = 0$$

is given to be

symmetric) Hence, $S_{ij} = 0 \text{ for } i \neq j$.

Combining results of both phases, it can be stated that

$$\underbrace{S}_{\sim} = \underbrace{0}_{\sim}$$

- c) Why Because this statement is an "if and only if" statement, both directions need to be proven.

Proof #1: If S is skew-symmetric, $\underbrace{u^T S u}_{\sim} = 0$.

Now we know that $(\underbrace{u^T S u}_{\sim}) = (\underbrace{u^T S u}_{\sim})^T$ because $\underbrace{u^T S u}_{\sim}$ is a 1×1 matrix, i.e. a scalar value, which has no effect on transpose.

(contd.)

$$\underbrace{u^T}_{\sim} \underbrace{S}_{\sim} \underbrace{u}_{\sim} = (\underbrace{u^T}_{\sim} \underbrace{S}_{\sim} \underbrace{u}_{\sim})^T$$

$$\underbrace{u^T}_{\sim} \underbrace{S}_{\sim} \underbrace{u}_{\sim} = \underbrace{u^T}_{\sim} \underbrace{S^T}_{\sim} (\underbrace{u^T}_{\sim})^T \quad (\text{Law of reversal, i.e. } (ABC)^T = C^T B^T A^T)$$

$$\underbrace{u^T}_{\sim} \underbrace{S}_{\sim} \underbrace{u}_{\sim} = \underbrace{u^T}_{\sim} \underbrace{S^T}_{\sim} \underbrace{u}_{\sim} \quad ((\underbrace{u^T}_{\sim})^T = \underbrace{u}_{\sim})$$

$$\underbrace{u^T}_{\sim} \underbrace{S}_{\sim} \underbrace{u}_{\sim} = \underbrace{u^T}_{\sim} (-\underbrace{S}_{\sim}) \underbrace{u}_{\sim} \quad (\text{Since } S \text{ is skew-symmetric, } \underbrace{S^T}_{\sim} = -\underbrace{S}_{\sim})$$

$$\underbrace{u^T}_{\sim} \underbrace{S}_{\sim} \underbrace{u}_{\sim} = -\underbrace{u^T}_{\sim} S \underbrace{u}_{\sim}$$

$$n = -x \quad (\text{Assume } n = \underbrace{u^T}_{\sim} \underbrace{S}_{\sim} \underbrace{u}_{\sim})$$

$$2n = 0$$

$$n = 0 \quad (\text{Hence proven})$$

\therefore If \underbrace{S}_{\sim} is skew-symmetric, $n = \underbrace{u^T}_{\sim} \underbrace{S}_{\sim} \underbrace{u}_{\sim} = 0$.

Proof#2: If $\underbrace{u^T}_{\sim} \underbrace{S}_{\sim} \underbrace{u}_{\sim} = 0$, then S is skew-symmetric.

Any square matrix can be split into a symmetric & skew symmetric portion as follows:

$$A = \underbrace{\frac{1}{2}(A + A^T)}_{\text{symmetric part}} + \underbrace{\frac{1}{2}(A - A^T)}_{\text{skew-symmetric part}}$$

Hence, S can be represented as $\frac{1}{2}(\underbrace{S + S^T}_{\sim}) + \frac{1}{2}(\underbrace{S - S^T}_{\sim})$.

If we assume $\underbrace{S}_{\sim} \text{symm} = \frac{1}{2}(\underbrace{S + S^T}_{\sim})$ and $\underbrace{S}_{\sim} \text{skew} = \frac{1}{2}(\underbrace{S - S^T}_{\sim})$,

\underbrace{S}_{\sim} can be re-written as $\underbrace{S}_{\sim} \text{symm} + \underbrace{S}_{\sim} \text{skew}$.

$$\text{Hence, } \underbrace{\mathbf{u}^T}_{\sim} \underbrace{\mathbf{S}}_{\sim} \underbrace{\mathbf{u}}_{\sim} = \mathbf{0}$$

$$\underbrace{\mathbf{u}^T}_{\sim} \left(\underbrace{\mathbf{S}_{\text{symm}}}_{\sim} + \underbrace{\mathbf{S}_{\text{skew}}}_{\sim} \right) \underbrace{\mathbf{u}}_{\sim} = \mathbf{0}$$

$$\underbrace{\mathbf{u}^T}_{\sim} \underbrace{\mathbf{S}_{\text{symm}}}_{\sim} \underbrace{\mathbf{u}}_{\sim} + \underbrace{\mathbf{u}^T}_{\sim} \underbrace{\mathbf{S}_{\text{skew}}}_{\sim} \underbrace{\mathbf{u}}_{\sim} = \mathbf{0}$$

$$\underbrace{\mathbf{u}^T}_{\sim} \underbrace{\mathbf{S}_{\text{symm}}}_{\sim} \underbrace{\mathbf{u}}_{\sim} = \mathbf{0} \quad (\text{Because } \underbrace{\mathbf{u}^T}_{\sim} \underbrace{\mathbf{S}_{\text{skew}}}_{\sim} \underbrace{\mathbf{u}}_{\sim} = \mathbf{0}, \\ \text{as proven in proof \#1 of Question 3) b(c)})$$

$$\therefore \underbrace{\mathbf{S}_{\text{symm}}}_{\sim} = \mathbf{0} \quad (\text{This has been proven in proof \#2 of Question 3) b)})$$

$$\frac{1}{2} \left(\underbrace{\mathbf{S}}_{\sim} + \underbrace{\mathbf{S}^T}_{\sim} \right) = \mathbf{0} \quad (\text{Substituting definition of } \underbrace{\mathbf{S}_{\text{symm}}}_{\sim})$$

$$\underbrace{\mathbf{S}}_{\sim} + \underbrace{\mathbf{S}^T}_{\sim} = \mathbf{0}$$

$$\underbrace{\mathbf{S}^T}_{\sim} = -\underbrace{\mathbf{S}}_{\sim}$$

Since this is the fundamental property of a skew-symmetric matrix, we can henceforth prove that \mathbf{S} is a skew-symmetric matrix.