<u>Video Reflection Removal</u>

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Problem:

Videos are often taken behind a reflective surface causing undesired reflections to exist. We design an algorithm to separate reflection from the background.

Applications:

- 1. Photography
- 2. Self-driving cars
- 3. Pre-processing of CV tasks

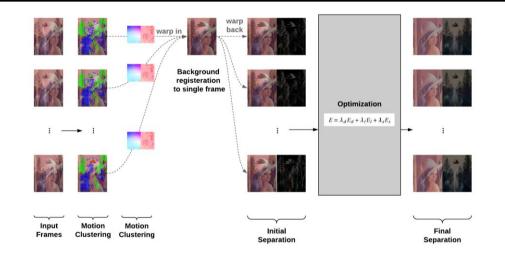


Our Approach:

Utilize motion information in the video:

- (i) Feature tracking and segmentation
- (ii) Background registration
- (iii) Background initial estimation
- (iv) Reflection initial estimation
- (v) Optimization

$$\begin{split} E_{d} &= \sum_{t=1}^{N} (||B_{t} - W_{t,\rho}^{B} \cdot B_{\rho}||_{1} + ||R_{t} - W_{t,\rho}^{R} \cdot R_{\rho}||_{1}) \\ E_{l} &= \sum_{t=1}^{N} (M_{t}^{B} \cdot |\nabla B| + M_{t}^{R} \cdot |\nabla (I_{t} - B_{t})|) \\ E_{s} &= \sum_{t=1}^{N} (|\nabla B_{t}| + \nabla (I_{t} - B_{t})|) \end{split}$$



Results:











Background



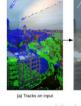


Reflection

Limitations:

Since our approach relies on motion segmentation at the initial stage, it might fails if we got incorrectly clustered feature points in some cases.







Failure Case 2: Non-planar Motion

Solution 1: User Assistance

Designing a user friendly GUI for annotating and tracking weak features.

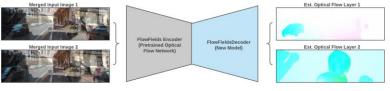
- Week feature points -> Get more features from a user
- Non-planar motion -> Refine clustering by a user



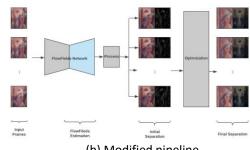
User Annotated Feature Points

Solution 2: Enhanced Flow-Fields

We can estimate motion field estimation with deep neural network, and then plug it into our pipeline.



(a) Deep Neural Networks estimating two-layered flow fields



(b) Modified pipeline