

REAL TIME IoT FOR DISTRIBUTED MACHINE LEARNING

Electrical Engineering

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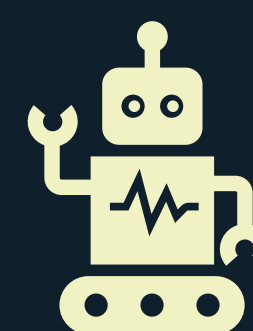
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INTRODUCTION

An intelligent good-delivering IoT system for industry

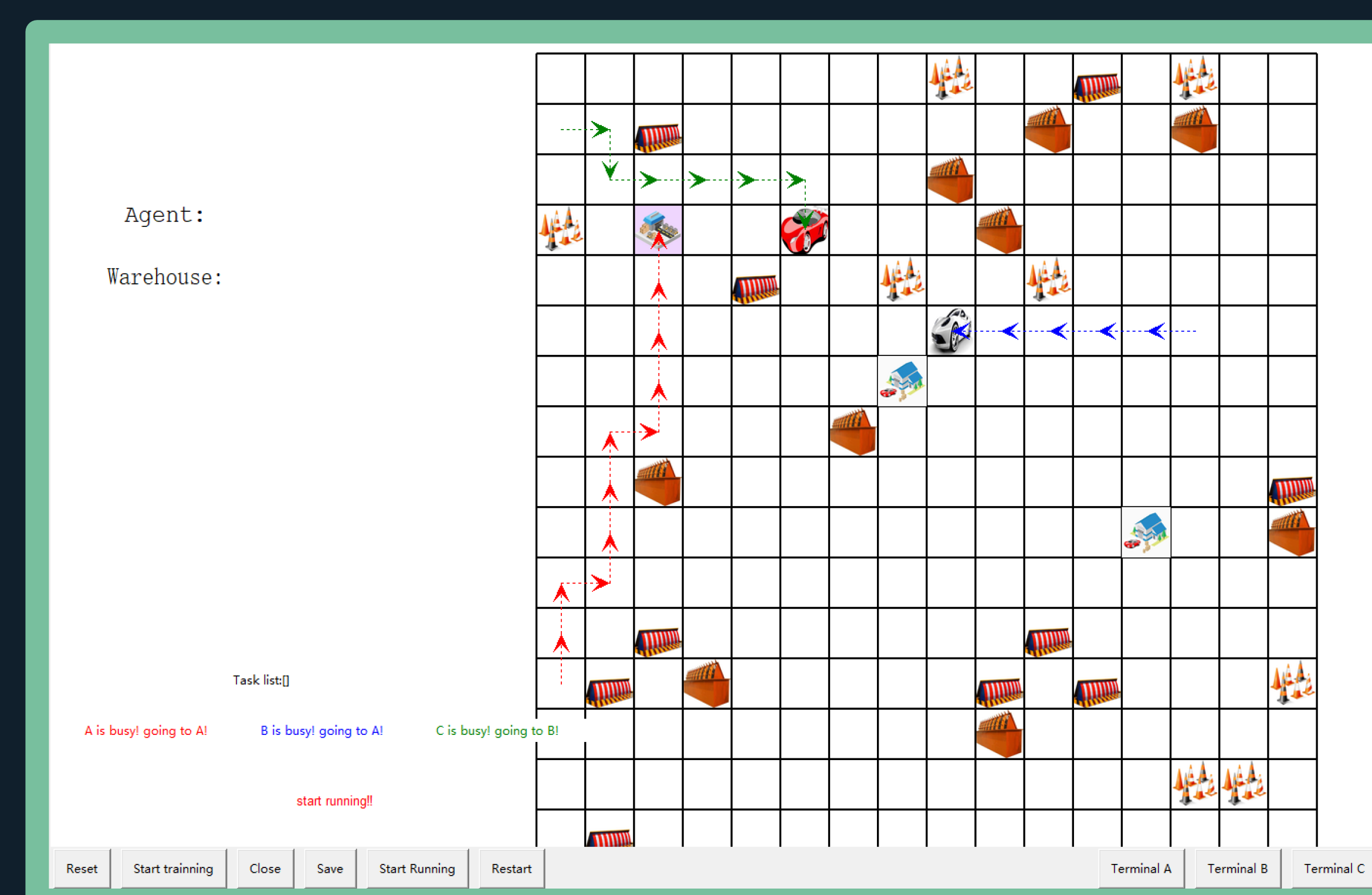


- Multiple robotic cars that can learn the maps by themselves and choosing the shortest path without any crashing
 - reinforcement learning (Q-learning and DQN algorithm)
- Real-time information exchanging between robotic cars
 - communication by WIFI
- Simulations of algorithms
 - visualization simulation tool (grid world)
- Prototype of multi-agent intelligent warehouse distribution system
 - multi-agent DQN algorithm

ALGORITHMS

- **Classic Q-learning**
single agent with static environment
q values store in Q table
need less time to train
- **Classic DQN**
single agent with static environment
q values store in deep neural network
more accurate
- **Multi-agent Q-learning**
multi agent with dynamic environment
reduce of state
need less time to train
- **Multi-agent DQN**
multi agent with dynamic environment
can handle 'state explosion'
more accurate
over-train

A prototype of
multi-agent intelligent warehouse distribution system



Training the model using reinforcement learning
& A prototype of multi-agent intelligent warehouse distribution system

SIMULATION

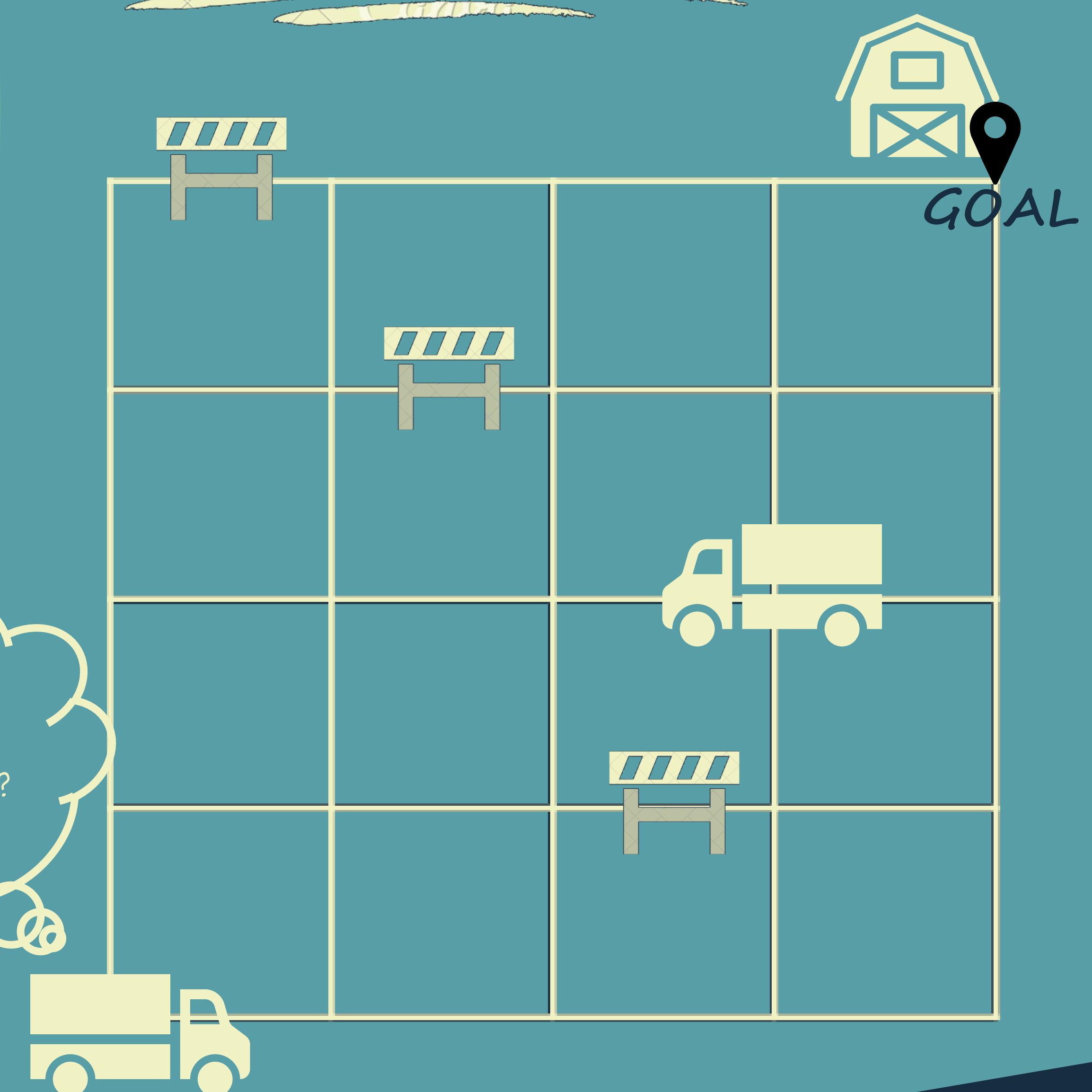
On our laptop!!

What's our project?

Smart robot cars
for delivering
goods in factory

Self-learning!
Shortest path!
Communication!

How can I go to the
destination
in the shortest path
without any crashing?



FUNCTIONS

- **Line Following**
Grid map with path and using triple reflectance sensor to make cars follow the line
- **Real-Time Communication**
TCP WebSocket with WIFI connection between server and clients
- **Real-Time QR Scan**
QR code as path guide for localization
- **Self-decision Making**
Upload the trained Q-table for routing

Look at the floor!!

A simple realistic model with two GoPiGo&Raspberry Pi cars



TESTS ON HARDWARE