#### CS61B Lecture #22

**Today:** Backtracking searches, game trees (DSIJ, Section 6.5)

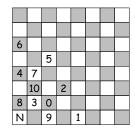
# Searching by "Generate and Test"

- We've been considering the problem of searching a set of data stored in some kind of data structure: "Is  $x \in S$ ?"
- But suppose we don't have a set S, but know how to recognize what we're after if we find it: "Is there an x such that P(x)?"
- If we know how to enumerate all possible candidates, can use approach of *Generate and Test*: test all possibilities in turn.
- Can sometimes be more clever: avoid trying things that won't work, for example.
- What happens if the set of possible candidates is infinite?

Last modified: Thu Oct 11 15:10:22 2018 C5618: Lecture #22 1 Last modified: Thu Oct 11 15:10:22 2018

#### **Backtracking Search**

- Backtracking search is one way to enumerate all possibilities.
- Example: Knight's Tour. Find all paths a knight can travel on a chessboard such that it touches every square exactly once and ends up one knight move from where it started.
- In the example below, the numbers indicate position numbers (knight starts at 0).
- Here, knight (N) is stuck; how to handle this?



# General Recursive Algorithm

CS61B: Lecture #22 2

CS61B: Lecture #22 4

```
/** Append to PATH a sequence of knight moves starting at ROW, COL
* that avoids all squares that have been hit already and
 * that ends up one square away from ENDROW, ENDCOL. B[i][j] is
\ast true iff row i and column j have been hit on PATH so far.
\ast~ Returns true if it succeeds, else false (with no change to PATH).
   Call initially with PATH containing the starting square, and
* the starting square (only) marked in B. */
boolean findPath(boolean[][] b, int row, int col,
                int endRow, int endCol, List path) {
 if (path.size() == 64)    return isKnightMove(row, col, endRow, endCol);
 for (r, c = all possible moves from (row, col)) {
   if (!b[r][c]) {
     b[r][c] = true; // Mark the square
     path.add(new Move(r, c));
      if (findPath(b, r, c, endRow, endCol, path)) return true;
     b[r][c] = false; // Backtrack out of the move.
     path.remove(path.size()-1);
 return false;
```

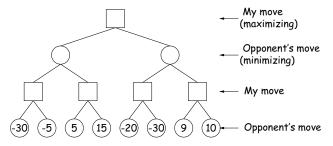
### Another Kind of Search: Best Move

- Consider the problem of finding the best move in a two-person game.
- One way: assign a heuristic value to each possible move and pick highest (aka static evaluation). Examples:
  - number of black pieces number of white pieces in checkers.
  - weighted sum of white piece values weighted sum of black pieces in chess (Queen=9, Rook=5, etc.)
  - Nearness of pieces to strategic areas (center of board).
- But this is misleading. A move might give us more pieces, but set up a devastating response from the opponent.
- So, for each move, look at *opponent's* possible moves, assume he picks the best one for him, and use that as the value.
- But what if you have a great response to his response?
- How do we organize this sensibly?

### Game Trees

- Think of the space of possible continuations of the game as a tree.
- Each node is a position, each edge a move.

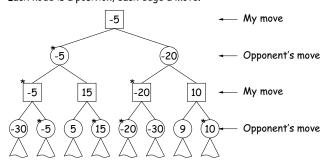
Last modified: Thu Oct 11 15:10:22 2018



- Suppose numbers at the bottom are the values of those final positions to me. Smaller numbers are of more value to my opponent.
- What should I move? What value can I get if my opponent plays as well as possible?

#### Game Trees, Minimax

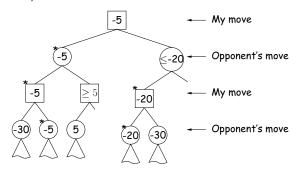
- Think of the space of possible continuations of the game as a tree.
- Each node is a position, each edge a move.



- Numbers are the values we guess for the positions (larger means better for me). Starred nodes would be chosen.
- I always choose child (next position) with maximum value; opponent chooses minimum value ("Minimax algorithm")

# Alpha-Beta Pruning

• We can prune this tree as we search it.



- $\bullet$  At the ' $\geq 5$ ' position, I know that the opponent will not choose to move here (since he already has a -5 move).
- At the ' $\leq -20$ ' position, my opponent knows that I will never choose to move here (since I already have a -5 move).

# Cutting off the Search

- If you could traverse game tree to the bottom, you'd be able to force a win (if it's possible).
- Sometimes possible near the end of a game.
- Unfortunately, game trees tend to be either infinite or impossibly large.
- So, we choose a maximum depth, and use a heuristic value computed on the position alone (called a static valuation) as the value at that depth.
- Or we might use *iterative deepening*, repeating the search at increasing depths until time is up.
- Much more sophisticated searches are possible, however (take CS188).

# Overall Search Algorithm

- Depending on whose move it is (maximizing player or minimizing player), we'll search for a move estimated to be optimal in one direction or the other.
- Search will be exhaustive down to a particular depth in the game tree; below that, we guess values.
- ullet Also pass lpha and eta limits:
  - High player does not care about exploring a position further once he knows its value is larger than what the minimizing player knows he can get  $(\beta)$ , because the minimizing player will never allow that position to come about.
  - Likewise, minimizing player won't explore a positions whose value is less than what the maximizing player knows he can get  $(\alpha)$ .
- To start, a maximizing player will find a move with

findMax(current position, search depth  $-\infty$ ,  $+\infty$ )

• minimizing player:

findMin(current position, search depth  $-\infty$ ,  $+\infty$ )

Last modified: Thu Oct 11 15:10:22 2018 CS61B: Lecture #22 10

### Some Pseudocode for Searching (One Level)

• The most basic kind of game-tree search is to assign some heuristic value to any given position, looking at just the next possible move:

```
Move simpleFindMax(Position posn, double alpha, double beta) {
    if (posn.maxPlayerWon())
        return artificial "Move" with value +\infty;
    else if (posn.minPlayerWon())
        return artificial "Move" with value -\infty;
    Move bestSoFar = artificial "Move" with value -\infty;
    for (each M = a legal move for maximizing player from posn) {
          Position next = posn.makeMove(M);
          next.setValue(heuristicEstimate(next));
          if (next.value() >= bestSoFar.value()) {
                bestSoFar = next;
                alpha = max(alpha, next.value());
                if (beta <= alpha) break;</pre>
    return bestSoFar;
Last modified: Thu Oct 11 15:10:22 2018
                                                        CS61B: Lecture #22 11
```

### One-Level Search for Minimizing Player

```
Move simpleFindMin(Position posn, double alpha, double beta) {
    if (posn.maxPlayerWon())
        return artificial "Move" with value +\infty;
    else if (posn.minPlayerWon())
        return artificial "Move" with value -\infty;
    Move bestSoFar = artificial "Move" with value +\infty;
    for (each M = a legal move for minimizing player from posn) {
        Position next = posn.makeMove(M);
        next.setValue(heuristicEstimate(next));
        if (next.value() <= bestSoFar.value()) {
            bestSoFar = next;
            beta = min(beta, next.value());
            if (beta <= alpha) break;
        }
    }
    return bestSoFar;
}</pre>
```

Last modified: Thu Oct 11 15:10:22 2018

CS61B: Lecture #22 12

# Some Pseudocode for Searching (Maximizing Player)

```
/** Return a best move for maximizing player from POSN, searching
 * to depth DEPTH. Any move with value >= BETA is also
* "good enough". */
Move findMax(Position posn, int depth, double alpha, double beta) {
    if (depth == 0 || gameOver(posn))
       return simpleFindMax(posn, alpha, beta);
    Move bestSoFar = artificial "Move" with value -\infty;
    for (each M = a legal move for maximizing player from posn) {
         Position next = posn.makeMove(M);
Move response = findMin(next, depth-1, alpha, beta);
          if (response.value() >= bestSoFar.value()) {
               bestSoFar = next;
               next.setValue(response.value());
               alpha = max(alpha, response.value());
               if (beta <= alpha) break;</pre>
          }
    return bestSoFar;
Last modified: Thu Oct 11 15:10:22 2018
                                                       CS61B: Lecture #22 13
```

# Some Pseudocode for Searching (Minimizing Player)

```
/** Return a best move for minimizing player from POSN, searching
 * to depth DEPTH. Any move with value <= ALPHA is also
 * "good enough". */
Move findMin(Position posn, int depth, double alpha, double beta) {
    if (depth == 0 || gameOver(posn))
       return simpleFindMin(posn, alpha, beta);
    Move bestSoFar = artificial "Move" with value +\infty;
    for (each M = a legal move for minimizing player from posn) {
         Position next = posn.makeMove(M);
         Move response = findMax(next, depth-1, alpha, beta);
         if (response.value() <= bestSoFar.value()) {</pre>
               bestSoFar = next;
               next.setValue(response.value());
               beta = min(beta, response.value());
               if (beta <= alpha) break;</pre>
    return bestSoFar;
Last modified: Thu Oct 11 15:10:22 2018
                                                     CS61B: Lecture #22 14
```