## **Fully connected networks**

In the previous notebook, you implemented a simple two-layer neural network class. However, this class is not modular. If you wanted to change the number of layers, you would need to write a new loss and gradient function. If you wanted to optimize the network with different optimizers, you'd need to write new training functions. If you wanted to incorporate regularizations, you'd have to modify the loss and gradient function.

Instead of having to modify functions each time, for the rest of the class, we'll work in a more modular framework where we define forward and backward layers that calculate losses and gradients respectively. Since the forward and backward layers share intermediate values that are useful for calculating both the loss and the gradient, we'll also have these function return "caches" which store useful intermediate values.

The goal is that through this modular design, we can build different sized neural networks for various applications.

In this HW #3, we'll define the basic architecture, and in HW #4, we'll build on this framework to implement different optimizers and regularizations (like BatchNorm and Dropout).

### Modular layers

This notebook will build modular layers in the following manner. First, there will be a forward pass for a given layer with inputs (x) and return the output of that layer (out) as well as cached variables (cache) that will be used to calculate the gradient in the backward pass.

```
def layer_forward(x, w):
    """ Receive inputs x and weights w """
    # Do some computations ...
    z = # ... some intermediate value
    # Do some more computations ...
    out = # the output
    cache = (x, w, z, out) # Values we need to compute gradients
    return out, cache
```

The backward pass will receive upstream derivatives and the cache object, and will return gradients with respect to the inputs and weights, like this:

```
def layer_backward(dout, cache):
    """

Receive derivative of loss with respect to outputs and cache,
    and compute derivative with respect to inputs.
    """

# Unpack cache values
    x, w, z, out = cache

# Use values in cache to compute derivatives
    dx = # Derivative of loss with respect to x
    dw = # Derivative of loss with respect to w

return dx, dw
```

```
In [1]: | 1 ## Import and setups
         3 import time
         4 import numpy as np
         5 import matplotlib.pyplot as plt
         6 from nndl.fc_net import *
         7 from utils.data_utils import get_CIFAR10_data
         8 | from utils.gradient_check import eval_numerical_gradient, eval_numerical_gradient_array
         9 from utils.solver import Solver
        10
        11 %matplotlib inline
        12 plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
        13 plt.rcParams['image.interpolation'] = 'nearest'
        14 plt.rcParams['image.cmap'] = 'gray'
        16 # for auto-reloading external modules
        17 # see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
        18 %load ext autoreload
        19 %autoreload 2
        20
        21 def rel_error(x, y):
              """ returns relative error """
        22
              return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
In [4]: | 1 | # Load the (preprocessed) CIFAR10 data.
         2 data = get_CIFAR10_data()
         3 for k in data.keys():
             print('{}: {} '.format(k, data[k].shape))
        X_train: (49000, 3, 32, 32)
        y_train: (49000,)
        X_val: (1000, 3, 32, 32)
        y_val: (1000,)
        X_test: (1000, 3, 32, 32)
        y_test: (1000,)
```

### **Linear layers**

In this section, we'll implement the forward and backward pass for the linear layers.

The linear layer forward pass is the function affine forward in nndl/layers.py and the backward pass is affine backward.

After you have implemented these, test your implementation by running the cell below.

#### Affine layer forward pass

Implement affine\_forward and then test your code by running the following cell.

```
In [17]: 1 # Test the affine_forward function
           3 num_inputs = 2
           4 input_shape = (4, 5, 6)
           5 output_dim = 3
           7 input_size = num_inputs * np.prod(input_shape)
           8 weight_size = output_dim * np.prod(input_shape)
          10 | x = np.linspace(-0.1, 0.5, num=input_size).reshape(num_inputs, *input_shape)
          11 w = np.linspace(-0.2, 0.3, num=weight_size).reshape(np.prod(input_shape), output_dim)
          12 b = np.linspace(-0.3, 0.1, num=output_dim)
          13
          14 out, _ = affine_forward(x, w, b)
          15 correct_out = np.array([[1.49834967, 1.70660132, 1.91485297]]
16 [3.25553199, 3.5141327, 3.77273342]
                                                                        3.77273342]])
          17
          18 # Compare your output with ours. The error should be around 1e-9.
          19 print('Testing affine_forward function:')
20 print('difference: {}'.format(rel_error(out, correct_out)))
```

Testing affine\_forward function: difference: 9.769849468192957e-10

### Affine layer backward pass

Implement affine\_backward and then test your code by running the following cell.

```
In [18]: | 1 |# Test the affine_backward function
           3 \times = np.random.randn(10, 2, 3)
           4 w = np.random.randn(6, 5)
           5 b = np.random.randn(5)
           6 dout = np.random.randn(10, 5)
           8 \, dx_num = eval_numerical_gradient_array(lambda x: affine_forward(x, w, b)[0], x, dout)
           9 dw_num = eval_numerical_gradient_array(lambda w: affine_forward(x, w, b)[0], w, dout)
          10 db_num = eval_numerical_gradient_array(lambda b: affine_forward(x, w, b)[0], b, dout)
          11
          12
               _, cache = affine_forward(x, w, b)
          13 dx, dw, db = affine_backward(dout, cache)
          14
          15 # The error should be around 1e-10
          16 print('Testing affine_backward function:')
          17 print('dx error: {}'.format(rel_error(dx_num, dx)))
          18 print('dw error: {}'.format(rel_error(dw_num, dw)))
19 print('db error: {}'.format(rel_error(db_num, db)))
```

Testing affine\_backward function: dx error: 1.92096764519679e-09 dw error: 1.096709875458812e-10 db error: 5.0588919335003475e-11

### **Activation layers**

In this section you'll implement the ReLU activation.

#### ReLU forward pass

Implement the relu\_forward function in nndl/layers.py and then test your code by running the following cell.

Testing relu\_forward function: difference: 4.999999798022158e-08

#### **ReLU backward pass**

Implement the relu backward function in nndl/layers.py and then test your code by running the following cell.

```
In [20]:    1    x = np.random.randn(10, 10)
    dout = np.random.randn(*x.shape)

dx_num = eval_numerical_gradient_array(lambda x: relu_forward(x)[0], x, dout)

_, cache = relu_forward(x)
    dx = relu_backward(dout, cache)

# The error should be around 1e-12
    print('Testing relu_backward function:')
    print('dx error: {}'.format(rel_error(dx_num, dx)))
```

Testing relu\_backward function: dx error: 3.2756195039972447e-12

### Combining the affine and ReLU layers

Often times, an affine layer will be followed by a ReLU layer. So let's make one that puts them together. Layers that are combined are stored in nndl/layer\_utils.py.

#### Affine-ReLU layers

We've implemented affine\_relu\_forward() and affine\_relu\_backward in nndl/layer\_utils.py . Take a look at them to make sure you understand what's going on. Then run the following cell to ensure its implemented correctly.

```
In [21]: 1
    from nndl.layer_utils import affine_relu_forward, affine_relu_backward
2
    x = np.random.randn(2, 3, 4)
    w = np.random.randn(12, 10)
    b = np.random.randn(10)
    dout = np.random.randn(2, 10)

    out, cache = affine_relu_forward(x, w, b)
    dx, dw, db = affine_relu_backward(dout, cache)

10
    dx_num = eval_numerical_gradient_array(lambda x: affine_relu_forward(x, w, b)[0], x, dout)
    dw_num = eval_numerical_gradient_array(lambda w: affine_relu_forward(x, w, b)[0], w, dout)
    db_num = eval_numerical_gradient_array(lambda b: affine_relu_forward(x, w, b)[0], b, dout)

4
    print('Testing affine_relu_forward and affine_relu_backward:')
    print('dx error: {}'.format(rel_error(dx_num, dx)))
    print('dw error: {}'.format(rel_error(dw_num, dw)))
    print('db error: {}'.format(rel_error(db_num, db)))
```

Testing affine\_relu\_forward and affine\_relu\_backward: dx error: 2.1153280924652617e-10 dw error: 2.0913929148545147e-09 db error: 7.826653464481358e-12

#### Softmax loss

You've already implemented it, so we have written it in layers.py . The following code will ensure they are working correctly.

```
In [22]: 1    num_classes, num_inputs = 10, 50
    x = 0.001 * np.random.randn(num_inputs, num_classes)
    y = np.random.randint(num_classes, size=num_inputs)

d

d

d

d

d

d

d

f

dx_num = eval_numerical_gradient(lambda x: softmax_loss(x, y)[0], x, verbose=False)

loss, dx = softmax_loss(x, y)

# Test softmax_loss function. Loss should be 2.3 and dx error should be 1e-8

print('\nTesting softmax_loss:')

print('loss: {}'.format(loss))

print('dx error: {}'.format(rel_error(dx_num, dx)))
```

Testing softmax\_loss: loss: 2.30302268998151 dx error: 9.476234199045239e-09

### Implementation of a two-layer NN

In nndl/fc\_net.py , implement the class TwoLayerNet which uses the layers you made here. When you have finished, the following cell will test your implementation.

```
In [24]: | 1 | N, D, H, C = 3, 5, 50, 7
           2 X = np.random.randn(N, D)
           3 y = np.random.randint(C, size=N)
           5 \text{ std} = 1e-2
           6 | model = TwoLayerNet(input_dim=D, hidden_dims=H, num_classes=C, weight_scale=std)
           8 print('Testing initialization ... ')
           9 W1_std = abs(model.params['W1'].std() - std)
          10 b1 = model.params['b1']
          11 | W2_std = abs(model.params['W2'].std() - std)
          12 b2 = model.params['b2']
          13 | assert W1_std < std / 10, 'First layer weights do not seem right'
          14 | assert np.all(b1 == 0), 'First layer biases do not seem right'
          15 assert W2_std < std / 10, 'Second layer weights do not seem right'
16 assert np.all(b2 == 0), 'Second layer biases do not seem right'
          17
          18 print('Testing test-time forward pass ... ')
19 model.params['W1'] = np.linspace(-0.7, 0.3, num=D*H).reshape(D, H)
          20 model.params['b1'] = np.linspace(-0.1, 0.9, num=H)
          21 model.params['W2'] = np.linspace(-0.3, 0.4, num=H*C).reshape(H, C)
          22 model.params['b2'] = np.linspace(-0.9, 0.1, num=C)
          23 X = np.linspace(-5.5, 4.5, num=N*D).reshape(D, N).T
          24 scores = model.loss(X)
          25 correct_scores = np.asarray(
          26
                [[11.53165108, 12.2917344,
                                                 13.05181771, 13.81190102, 14.57198434, 15.33206765, 16.09215096],
                  [12.05769098, 12.74614105, 13.43459113, 14.1230412, 14.81149128, 15.49994135, 16.18839143], [12.58373087, 13.20054771, 13.81736455, 14.43418138, 15.05099822, 15.66781506, 16.2846319]])
          27
          28
          29 | scores_diff = np.abs(scores - correct_scores).sum()
          30 assert scores_diff < 1e-6, 'Problem with test-time forward pass'
          31
          32 print('Testing training loss (no regularization)')
          33 y = np.asarray([0, 5, 1])
          34 loss, grads = model.loss(X, y)
          35 correct_loss = 3.4702243556
          36 assert abs(loss - correct_loss) < 1e-10, 'Problem with training-time loss'
          37
          38 model.reg = 1.0
          39 loss, grads = model.loss(X, y)
          40 correct_loss = 26.5948426952
              assert abs(loss - correct_loss) < 1e-10, 'Problem with regularization loss'</pre>
          42
          43 for reg in [0.0, 0.7]:
          44
                print('Running numeric gradient check with reg = {}'.format(reg))
          45
                model.reg = reg
          46
                loss, grads = model.loss(X, y)
          47
          48
                for name in sorted(grads):
                   f = lambda _: model.loss(X, y)[0]
                   grad_num = eval_numerical_gradient(f, model.params[name], verbose=False)
          50
                   print('{} relative error: {}' format(name, rel_error(grad_num, grads[name])))
          51
          Testing initialization ...
          Testing test-time forward pass ...
          Testing training loss (no regularization)
```

```
Testing test-time forward pass ...
Testing training loss (no regularization)
Running numeric gradient check with reg = 0.0
W1 relative error: 1.5215703686475096e-08
W2 relative error: 3.2068321167375225e-10
b1 relative error: 8.368195737354163e-09
b2 relative error: 4.3291360264321544e-10
Running numeric gradient check with reg = 0.7
W1 relative error: 2.527915175868136e-07
W2 relative error: 2.8508510893102143e-08
b1 relative error: 1.5646801536371197e-08
b2 relative error: 7.759095355706557e-10
```

### **Solver**

We will now use the utils Solver class to train these networks. Familiarize yourself with the API in utils/solver.py . After you have done so, declare an instance of a TwoLayerNet with 200 units and then train it with the Solver. Choose parameters so that your validation accuracy is at least 50%.

```
In [32]:
        1 model = TwoLayerNet()
         2 solver = None
         3
         4 # ----- #
         5 # YOUR CODE HERE:
             Declare an instance of a TwoLayerNet and then train
         6 #
         7 #
             it with the Solver. Choose hyperparameters so that your validation
              accuracy is at least 50%. We won't have you optimize this further
         8 #
         9 #
              since you did it in the previous notebook.
        12
        13 | solver = Solver(model, data,
                         update_rule='sgd', optim_config={'learning_rate': 1e-3,},
        14
                            lr_decay=0.95,
num_epochs=10, batch_size=200,
        15
        16
        17
                            print_every=100)
        18
        19 solver.train()
        21 # ========== #
        22 # END YOUR CODE HERE
        (Iteration 1 / 2450) loss: 2.302087
        (Epoch 0 / 10) train acc: 0.144000; val_acc: 0.134000
        (Iteration 101 / 2450) loss: 1.757412
        (Iteration 201 / 2450) loss: 1.637018
        (Epoch 1 / 10) train acc: 0.403000; val_acc: 0.424000
        (Iteration 301 / 2450) loss: 1.526684
        (Iteration 401 / 2450) loss: 1.537290
        (Epoch 2 / 10) train acc: 0.476000; val_acc: 0.469000
        (Iteration 501 / 2450) loss: 1.541296
        (Iteration 601 / 2450) loss: 1.400074
        (Iteration 701 / 2450) loss: 1.424359
```

```
(Epoch 3 / 10) train acc: 0.493000; val_acc: 0.482000
(Iteration 801 / 2450) loss: 1.295249
(Iteration 901 / 2450) loss: 1.474847
(Epoch 4 / 10) train acc: 0.502000; val_acc: 0.486000
(Iteration 1001 / 2450) loss: 1.293859
(Iteration 1101 / 2450) loss: 1.499670
(Iteration 1201 / 2450) loss: 1.323325
(Epoch 5 / 10) train acc: 0.537000; val_acc: 0.494000
(Iteration 1301 / 2450) loss: 1.384211
(Iteration 1401 / 2450) loss: 1.290005
(Epoch 6 / 10) train acc: 0.533000; val_acc: 0.505000
(Iteration 1501 / 2450) loss: 1.324360
(Iteration 1601 / 2450) loss: 1.399059
(Iteration 1701 / 2450) loss: 1.288299
(Epoch 7 / 10) train acc: 0.572000; val_acc: 0.493000
(Iteration 1801 / 2450) loss: 1.161164
(Iteration 1901 / 2450) loss: 1.163402
(Epoch 8 / 10) train acc: 0.608000; val_acc: 0.511000
(Iteration 2001 / 2450) loss: 1.148272
(Iteration 2101 / 2450) loss: 1.139933
(Iteration 2201 / 2450) loss: 1.451878
(Epoch 9 / 10) train acc: 0.603000; val_acc: 0.533000
(Iteration 2301 / 2450) loss: 1.079785
(Iteration 2401 / 2450) loss: 1.288225
(Epoch 10 / 10) train acc: 0.571000; val_acc: 0.526000
```

/opt/homebrew/lib/python3.11/site-packages/IPython/core/pylabtools.py:152: MatplotlibDeprecationWarning: sa vefig() got unexpected keyword argument "orientation" which is no longer supported as of 3.3 and will become an error two minor releases later

fig.canvas.print\_figure(bytes\_io, \*\*kw)

/opt/homebrew/lib/python3.11/site-packages/IPython/core/pylabtools.py:152: MatplotlibDeprecationWarning: sa vefig() got unexpected keyword argument "dpi" which is no longer supported as of 3.3 and will become an err or two minor releases later

fig.canvas.print\_figure(bytes\_io, \*\*kw)

/opt/homebrew/lib/python3.11/site-packages/IPython/core/pylabtools.py:152: MatplotlibDeprecationWarning: sa vefig() got unexpected keyword argument "facecolor" which is no longer supported as of 3.3 and will become an error two minor releases later

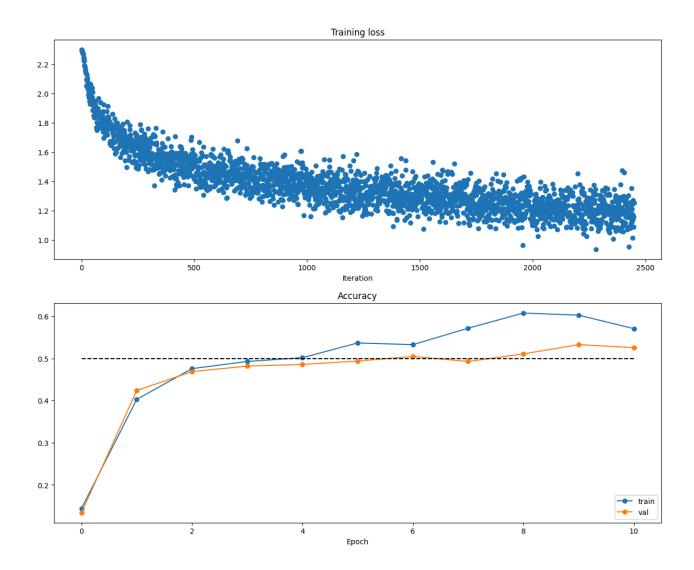
fig.canvas.print\_figure(bytes\_io, \*\*kw)

/opt/homebrew/lib/python3.11/site-packages/IPython/core/pylabtools.py:152: MatplotlibDeprecationWarning: sa vefig() got unexpected keyword argument "edgecolor" which is no longer supported as of 3.3 and will become an error two minor releases later

fig.canvas.print\_figure(bytes\_io, \*\*kw)

/opt/homebrew/lib/python3.11/site-packages/IPython/core/pylabtools.py:152: MatplotlibDeprecationWarning: sa vefig() got unexpected keyword argument "bbox\_inches\_restore" which is no longer supported as of 3.3 and will become an error two minor releases later

fig.canvas.print\_figure(bytes\_io, \*\*kw)



# **Multilayer Neural Network**

Now, we implement a multi-layer neural network.

Read through the FullyConnectedNet class in the file  $nndl/fc\_net.py$ .

Implement the initialization, the forward pass, and the backward pass. There will be lines for batchnorm and dropout layers and caches; ignore these all for now. That'll be in HW #4.

```
In [25]: 1 N, D, H1, H2, C = 2, 15, 20, 30, 10
            2 X = np.random.randn(N, D)
           3 y = np.random.randint(C, size=(N,))
            5 for reg in [0, 3.14]:
                 print('Running check with reg = {}'.format(reg))
            7
                 model = FullyConnectedNet([H1, H2], input_dim=D, num_classes=C,
            8
                                               reg=reg, weight_scale=5e-2, dtype=np.float64)
            9
           10
                 loss, grads = model.loss(X, y)
                 print('Initial loss: {}'.format(loss))
           11
           12
          13
                 for name in sorted(grads):
                   f = lambda _: model.loss(X, y)[0]
           14
                   grad_num = eval_numerical_gradient(f, model.params[name], verbose=False, h=1e-5)
print('{} relative error: {}'.format(name, rel_error(grad_num, grads[name])))
           15
          16
```

```
Running check with reg = 0
Initial loss: 2.2985850094266307
W1 relative error: 1.5638062961849955e-07
W2 relative error: 2.1676748168737265e-06
W3 relative error: 1.0089230525404633e-07
b1 relative error: 1.0382484882526912e-08
b2 relative error: 8.753554622271737e-10
b3 relative error: 1.602629914844274e-10
Running check with reg = 3.14
Initial loss: 7.22328144849468
W1 relative error: 4.403277559810739e-08
W2 relative error: 3.934021782261803e-08
W3 relative error: 2.2109530606580983e-08
b1 relative error: 1.8765746368643743e-08
b2 relative error: 1.2119045814856181e-08
b3 relative error: 2.410833343106932e-10
```

```
In [29]: 1 # Use the three layer neural network to overfit a small dataset.
          3 \text{ num\_train} = 50
          4 small_data = {
          5
                'X_train': data['X_train'][:num_train],
                'y_train': data['y_train'][:num_train],
          6
          7
               'X_val': data['X_val'],
          8
                'y_val': data['y_val'],
          9
          10
          11
          12 #### !!!!!!
          13 # Play around with the weight scale and learning rate so that you can overfit a small dataset.
          14 | # Your training accuracy should be 1.0 to receive full credit on this part.
          15 weight_scale = 2*1e-2
          16 | learning_rate = 1e-2
          17
          18 model = FullyConnectedNet([100, 100],
          19
                            weight_scale=weight_scale, dtype=np.float64)
          20 solver = Solver(model, small_data,
                              print_every=10, num_epochs=20, batch_size=25.
          21
          22
                              update_rule='sgd',
          23
                              optim_config={
          24
                                 'learning_rate': learning_rate,
          25
          26
                       )
          27 | solver.train()
          28
          29 plt.plot(solver.loss_history, 'o')
          30 plt.title('Training loss history')
          31 plt.xlabel('Iteration')
          32 plt.ylabel('Training loss')
         33 plt.show()
         (Iteration 1 / 40) loss: 3.182387
         (Epoch 0 / 20) train acc: 0.360000; val_acc: 0.123000
         (Epoch 1 / 20) train acc: 0.560000; val_acc: 0.121000
         (Epoch 2 / 20) train acc: 0.600000; val_acc: 0.126000
         (Epoch 3 / 20) train acc: 0.700000; val_acc: 0.173000
         (Epoch 4 / 20) train acc: 0.760000; val_acc: 0.141000
         (Epoch 5 / 20) train acc: 0.880000; val_acc: 0.146000
         (Iteration 11 / 40) loss: 0.870777
         (Epoch 6 / 20) train acc: 0.900000; val_acc: 0.132000
         (Epoch 7 / 20) train acc: 0.980000; val_acc: 0.169000
         (Epoch 8 / 20) train acc: 0.980000; val_acc: 0.158000 (Epoch 9 / 20) train acc: 1.000000; val_acc: 0.171000
         (Epoch 10 / 20) train acc: 1.000000; val_acc: 0.179000
         (Iteration 21 / 40) loss: 0.030894
         (Epoch 11 / 20) train acc: 1.000000; val_acc: 0.175000
         (Epoch 12 / 20) train acc: 1.000000; val_acc: 0.174000
         (Epoch 13 / 20) train acc: 1.000000; val_acc: 0.183000
         (Epoch 14 / 20) train acc: 1.000000; val_acc: 0.181000
         (Epoch 15 / 20) train acc: 1.000000; val_acc: 0.182000
         (Iteration 31 / 40) loss: 0.013713
         (Epoch 16 / 20) train acc: 1.000000; val_acc: 0.180000
         (Epoch 17 / 20) train acc: 1.000000; val_acc: 0.176000
         (Epoch 18 / 20) train acc: 1.000000; val_acc: 0.179000
         (Epoch 19 / 20) train acc: 1.000000; val_acc: 0.178000 (Epoch 20 / 20) train acc: 1.000000; val_acc: 0.176000
         /opt/homebrew/lib/python3.11/site-packages/IPython/core/pylabtools.py:152: MatplotlibDeprecationWarning: sa
         vefig() got unexpected keyword argument "orientation" which is no longer supported as of 3.3 and will becom
         e an error two minor releases later
            fig.canvas.print_figure(bytes_io, **kw)
         /opt/homebrew/lib/python3.11/site-packages/IPython/core/pylabtools.py:152: MatplotlibDeprecationWarning: sa
         vefig() got unexpected keyword argument "dpi" which is no longer supported as of 3.3 and will become an err
         or two minor releases later
           fig.canvas.print_figure(bytes_io, **kw)
         opt/homebrew/lib/python3.11/site-packages/IPython/core/pylabtools.py:152: MatplotlibDeprecationWarning: sa
         vefig() got unexpected keyword argument "facecolor" which is no longer supported as of 3.3 and will become
         an error two minor releases later
           fig.canvas.print_figure(bytes_io, **kw)
         /opt/homebrew/lib/python3.11/site-packages/IPython/core/pylabtools.py:152: MatplotlibDeprecationWarning: sa
         vefig() got unexpected keyword argument "edgecolor" which is no longer supported as of 3.3 and will become
         an error two minor releases later
           fig.canvas.print_figure(bytes_io, **kw)
         /opt/homebrew/lib/python3.11/site-packages/IPython/core/pylabtools.py:152: MatplotlibDeprecationWarning: sa
         vefig() got unexpected keyword argument "bbox_inches_restore" which is no longer supported as of 3.3 and wi
         ll become an error two minor releases later
           fig.canvas.print_figure(bytes_io, **kw)
```

