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import numpy as np

from .layers import *
from .layer_utils import *

class TwoLayerNet(object):
    """
    A two-layer fully-connected neural network with ReLU nonlinearity and
    softmax loss that uses a modular layer design. We assume an input dimension
    of D, a hidden dimension of H, and perform classification over C classes.

    The architecture should be affine - relu - affine - softmax.

    Note that this class does not implement gradient descent; instead, it
    will interact with a separate Solver object that is responsible for running
    optimization.

    The learnable parameters of the model are stored in the dictionary
    self.params that maps parameter names to numpy arrays.
    """

    def __init__(self, input_dim=3*32*32, hidden_dims=100, num_classes=10,
                 dropout=0, weight_scale=1e-3, reg=0.0):
        """
        Initialize a new network.

        Inputs:
        - input_dim: An integer giving the size of the input
        - hidden_dims: An integer giving the size of the hidden layer
        - num_classes: An integer giving the number of classes to classify
        - dropout: Scalar between 0 and 1 giving dropout strength.
        - weight_scale: Scalar giving the standard deviation for random
          initialization of the weights.
        - reg: Scalar giving L2 regularization strength.
        """
        self.params = {}
        self.reg = reg

        # ===== #
        # YOUR CODE HERE:
        # Initialize W1, W2, b1, and b2. Store these as self.params['W1'],
        # self.params['W2'], self.params['b1'] and self.params['b2']. The
        # biases are initialized to zero and the weights are initialized
        # so that each parameter has mean 0 and standard deviation weight_scale.
        # The dimensions of W1 should be (input_dim, hidden_dim) and the
        # dimensions of W2 should be (hidden_dims, num_classes)
        # ===== #
        self.params["W1"] = weight_scale * np.random.randn(input_dim, hidden_dims)
        self.params["b1"] = np.zeros(hidden_dims)
        self.params["W2"] = weight_scale * np.random.randn(hidden_dims, num_classes)
        self.params["b2"] = np.zeros(num_classes)

        # ===== #
        # END YOUR CODE HERE
        # ===== #

    def loss(self, X, y=None):
        """
        Compute loss and gradient for a minibatch of data.

        Inputs:
        - X: Array of input data of shape (N, d_1, ..., d_k)
        - y: Array of labels, of shape (N,). y[i] gives the label for X[i].

        Returns:
        If y is None, then run a test-time forward pass of the model and return:
        - scores: Array of shape (N, C) giving classification scores, where
          scores[i, c] is the classification score for X[i] and class c.

        If y is not None, then run a training-time forward and backward pass and
        return a tuple of:
        - loss: Scalar value giving the loss
        - grads: Dictionary with the same keys as self.params, mapping parameter
          names to gradients of the loss with respect to those parameters.
        """
        scores = None

        # ===== #

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# YOUR CODE HERE:
# Implement the forward pass of the two-layer neural network. Store
# the class scores as the variable 'scores'. Be sure to use the layers
# you prior implemented.
# ===== #

# Forward pass: affine - relu - affine - softmax
out1, cache1 = affine_forward(X, self.params['W1'], self.params['b1'])
relu_out, relu_cache = relu_forward(out1)
scores, cache2 = affine_forward(relu_out, self.params['W2'], self.params['b2'])

# ===== #
# END YOUR CODE HERE
# ===== #

# If y is None then we are in test mode so just return scores
if y is None:
    return scores

loss, grads = 0, {}
# ===== #
# YOUR CODE HERE:
# Implement the backward pass of the two-layer neural net. Store
# the loss as the variable 'loss' and store the gradients in the
# 'grads' dictionary. For the grads dictionary, grads['W1'] holds
# the gradient for W1, grads['b1'] holds the gradient for b1, etc.
# i.e., grads[k] holds the gradient for self.params[k].
#
# Add L2 regularization, where there is an added cost 0.5*self.reg*W^2
# for each W. Be sure to include the 0.5 multiplying factor to
# match our implementation.
#
# And be sure to use the layers you prior implemented.
# ===== #

loss, dscores = softmax_loss(scores, y)
loss += 0.5 * self.reg * (np.sum(self.params['W1'] ** 2) + np.sum(self.params['W2'] ** 2))

# Backward pass
dx2, dW2, db2 = affine_backward(dscores, cache2)
dW2 += self.reg * self.params['W2']

drelu = relu_backward(dx2, relu_cache)
dx1, dW1, db1 = affine_backward(drelu, cache1)
dW1 += self.reg * self.params['W1']

grads['W1'], grads['b1'] = dW1, db1
grads['W2'], grads['b2'] = dW2, db2

# ===== #
# END YOUR CODE HERE
# ===== #

return loss, grads

class FullyConnectedNet(object):
    """
    A fully-connected neural network with an arbitrary number of hidden layers,
    ReLU nonlinearities, and a softmax loss function. This will also implement
    dropout and batch normalization as options. For a network with L layers,
    the architecture will be

    {affine - [batch norm] - relu - [dropout]} x (L - 1) - affine - softmax

    where batch normalization and dropout are optional, and the {...} block is
    repeated L - 1 times.

    Similar to the TwoLayerNet above, learnable parameters are stored in the
    self.params dictionary and will be learned using the Solver class.
    """
    def __init__(self, hidden_dims, input_dim=3*32*32, num_classes=10,
                  dropout=0, use_batchnorm=False, reg=0.0,
                  weight_scale=1e-2, dtype=np.float32, seed=None):
        """
        Initialize a new FullyConnectedNet.

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Inputs:
- hidden_dims: A list of integers giving the size of each hidden layer.
- input_dim: An integer giving the size of the input.
- num_classes: An integer giving the number of classes to classify.
- dropout: Scalar between 0 and 1 giving dropout strength. If dropout=0 then
the network should not use dropout at all.
- use_batchnorm: Whether or not the network should use batch normalization.
- reg: Scalar giving L2 regularization strength.
- weight_scale: Scalar giving the standard deviation for random
initialization of the weights.
- dtype: A numpy datatype object; all computations will be performed using
this datatype. float32 is faster but less accurate, so you should use
float64 for numeric gradient checking.
- seed: If not None, then pass this random seed to the dropout layers. This
will make the dropout layers deterministic so we can gradient check the
model.
"""
self.use_batchnorm = use_batchnorm
self.use_dropout = dropout > 0
self.reg = reg
self.num_layers = 1 + len(hidden_dims)
self.dtype = dtype
self.params = {}

# ===== #
# YOUR CODE HERE:
# Initialize all parameters of the network in the self.params dictionary.
# The weights and biases of layer 1 are W1 and b1; and in general the
# weights and biases of layer i are Wi and bi. The
# biases are initialized to zero and the weights are initialized
# so that each parameter has mean 0 and standard deviation weight_scale.
# ===== #
self.params = {}
input_dim_current = input_dim

for i, hidden_dim in enumerate(hidden_dims):
    self.params[f'W{i+1}'] = weight_scale * np.random.randn(input_dim_current, hidden_dim)
    self.params[f'b{i+1}'] = np.zeros(hidden_dim)
    input_dim_current = hidden_dim

    if self.use_batchnorm:
        self.params[f'gamma{i+1}'] = np.ones(hidden_dim)
        self.params[f'beta{i+1}'] = np.zeros(hidden_dim)

self.params[f'W{len(hidden_dims)+1}'] = weight_scale * np.random.randn(input_dim_current, num_classes)
self.params[f'b{len(hidden_dims)+1}'] = np.zeros(num_classes)

# ===== #
# END YOUR CODE HERE
# ===== #

# When using dropout we need to pass a dropout_param dictionary to each
# dropout layer so that the layer knows the dropout probability and the mode
# (train / test). You can pass the same dropout_param to each dropout layer.
self.dropout_param = {}
if self.use_dropout:
    self.dropout_param = {'mode': 'train', 'p': dropout}
    if seed is not None:
        self.dropout_param['seed'] = seed

# With batch normalization we need to keep track of running means and
# variances, so we need to pass a special bn_param object to each batch
# normalization layer. You should pass self.bn_params[0] to the forward pass
# of the first batch normalization layer, self.bn_params[1] to the forward
# pass of the second batch normalization layer, etc.
self.bn_params = []
if self.use_batchnorm:
    self.bn_params = [{'mode': 'train'} for i in np.arange(self.num_layers - 1)]

# Cast all parameters to the correct datatype
for k, v in self.params.items():
    self.params[k] = v.astype(dtype)

def loss(self, X, y=None):
    """
    Compute loss and gradient for the fully-connected net.

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Input / output: Same as TwoLayerNet above.
"""
X = X.astype(self.dtype)
mode = 'test' if y is None else 'train'

# Set train/test mode for batchnorm params and dropout param since they
# behave differently during training and testing.
if self.dropout_param is not None:
    self.dropout_param['mode'] = mode
if self.use_batchnorm:
    for bn_param in self.bn_params:
        bn_param[mode] = mode

scores = None
caches = {}
layer_input = X

# ===== #
# YOUR CODE HERE:
# Implement the forward pass of the FC net and store the output
# scores as the variable "scores".
# ===== #

for i in range(1, self.num_layers):
    Wi, bi = self.params[f'W{i}'], self.params[f'b{i}']
    layer_input, caches[i] = affine_relu_forward(layer_input, Wi, bi)

# Last layer (affine only)
scores, caches[self.num_layers] = affine_forward(layer_input,
                                                    self.params[f'W{self.num_layers}'],
                                                    self.params[f'b{self.num_layers}'])

# ===== #
# END YOUR CODE HERE
# ===== #

# If test mode return early
if mode == 'test':
    return scores

loss, grads = 0.0, {}
# ===== #
# YOUR CODE HERE:
# Implement the backwards pass of the FC net and store the gradients
# in the grads dict, so that grads[k] is the gradient of self.params[k]
# Be sure your L2 regularization includes a 0.5 factor.
# ===== #

loss, dscores = softmax_loss(scores, y)
loss += 0.5 * self.reg * sum(np.sum(self.params[f'W{i}'])**2 for i in range(1, self.num_layers + 1))

dout, grads[f'W{self.num_layers}'], grads[f'b{self.num_layers}'] = affine_backward(dscores, caches[self.num_layers])
grads[f'W{self.num_layers}'] += self.reg * self.params[f'W{self.num_layers}']

for i in reversed(range(1, self.num_layers)):
    dout, grads[f'W{i}'], grads[f'b{i}'] = affine_relu_backward(dout, caches[i])
    grads[f'W{i}'] += self.reg * self.params[f'W{i}']

# ===== #
# END YOUR CODE HERE
# ===== #
return loss, grads

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