

\* Deep generative Models - (DGM)

- remarkable ability to learn underlying patterns in data.
- use knowledge to create entirely new data.
- understanding underlying data distribution.

Adv-Disadv-

- Data Discovery
- Data Generation
- Variability with Data
- Generative challenges
- Quality & Safety
- Training Complexity

\* Boltzmann Machine -

- unsupervised DL model; every node connected every other.
- connections are bidirectional; Boltzmanns are stochastic models.

Two nodes in BMS are -

- Visible Nodes - Nodes we can measure
- Hidden Nodes - Nodes that can't be or we can't measure
- type of probabilistic generative model  $\rightarrow$  based on statistical physics.
- type of ANN  $\rightarrow$  consists of misconnected binary unit (neurons)
- designed  $\rightarrow$  learn & model  $\rightarrow$  data trained
- adjusting & strengths of connections
- def how influential one neuron is on another

- Learning process of BM  $\rightarrow$  Upward pass

- activates updated com & p/p of the neuron

- Gibbs sampling  $\rightarrow$  determines activity of each connected neurons

## ② downward pass

- activities of neurons are used to reconstruct i/p data.

- gen samples  $\rightarrow$  repeatedly updating activities of neuron. generate new data  $\rightarrow$  resemble data
- capture complex dependencies & interactions of neurons.



\* appl<sup>n</sup> → Dim red<sup>n</sup>, collaborative filtering, collaborative filtering & feature learning.

- BM training → computationally expensive.
- Math func → reps energy → particular config of binary state of neurons.
- helps → prob of specific config occurring.
- each possible config → has an assoc. energy value.
- energy of config → connection b/w neurons & their wts.  
 energy is high → config less likely to occur.  
 energy is low → " " " " " "
- energy func of BM → sum of weights cons b/w neurons.  
 conn → same layer → b/w diff layers.  
 weights reps → strengths of connections → reps show influence.

$$E(x) = -\sum (w_{ij} * x_i * x_j) - \sum (b_i * x_i).$$

↑  
energy assoc  
with config

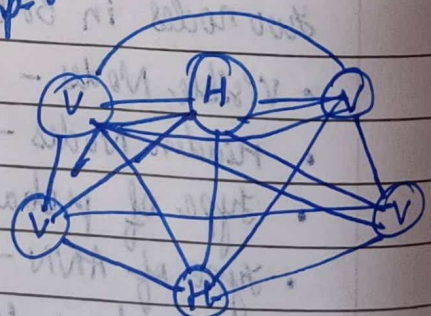
↑  
wt of  
conn b/w  
neurons

states of 2  
conn neurons

↪ bias term

- energy func in BM → prof of particular config → Boltzmann dist<sup>n</sup>  
 Prob of config → reg. energy / temp

$$P(x) = \frac{1}{Z} * e^{(-E(x)/T)}$$





## \* Deep Belief Networks - \*

- hybrid graphical model involving both directed & undirected connections with no intralayer connections like RBMs.
- has multiple hidden layers.
- first non-convolutional deep architecture.
- DBN = stack of RBMs + Fine tuning.
- DBN with only one hidden layer is an RBM.
- generative models with several layers of latent variables (hidden variable).
- connections b/w two layers are undirected while rest are directed.

### - Working of DBNs -

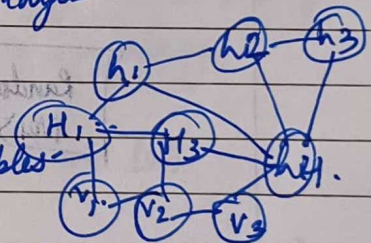
- Top two layers of DBNs. 1) Gibbs sampling.
- multiple iterations  $\rightarrow$  DBN generate samples.
- dependencies b/w top two hidden layers & exist. row.

### 2) Ancestral sampling -

- Gibbs, ancestral sampling is done on remaining layers.
- generates samples from visible units.

### 3) Greedy pretraining -

- used to determine values of hidden/latent variables.
- done layer by layer.
- Main adv of DBN  $\rightarrow$  Learn features in unsupervised manner.
- $\rightarrow$  DBNs resistant to overfitting.

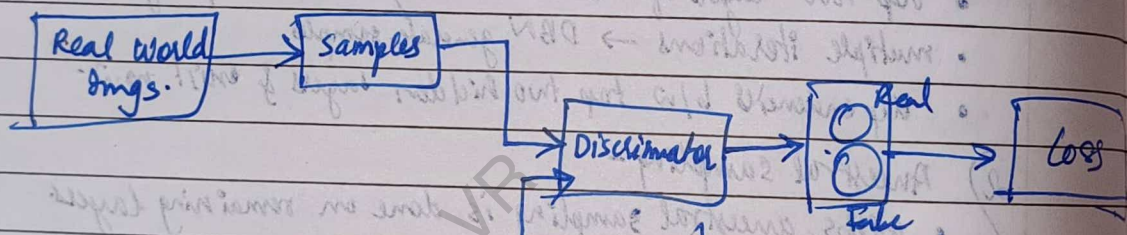


- designed to learn  $\rightarrow$  rep complex patterns & hierarchical in data.
- multiple learn  $\rightarrow$  rep complex patterns & hierarchical in data.
- each layer trained  $\rightarrow$  learn most imp features / patterns.
- RBM  $\rightarrow$  trained  $\rightarrow$  DBN goes through fine-tuning.
- Adv  $\rightarrow$  learns meaningful features  $\rightarrow$  raw data
  - eff in img recog & speech processing.
  - capture hierarchical reps.
  - gen models  $\rightarrow$  new data samples  $\rightarrow$  resemble training data.
- disadv  $\rightarrow$ 
  - computationally expensive.
  - KNN & CNN are pref due to eff & performance.



# \* Generative Adversarial Network [GAN] →

- way to make generative models by having two neural networks compete with each other.
- exceptionally potent neural networks → unsup learning.
- GAN → analyse → 2 neural h/w → compete with each other.
- GAN uses CNN → other DL techniques
- unsupervised learning technique → uses pattern in i/p data → find & learn time.
- applied to fresh instances.
- GAN training → former task as sup learning utilising GANs
- discriminator → compares images with real world exs to classify



- analyses data of decision
- acts as gatekeeper
- spotting fakes or genuine
- improves
- creates new data similar to training data.
- goal - to fool discriminator.
- learns & improves based on feedback from discriminator.



# \* How GANs work?

- ① Basic approach — gen modelling that generates a new set of data based on training data → looks like training data.
- ② 2 main blocks → NN → compete with each other (Gen & Discrim).
- ③ can copy, capture & analyze variations dataset.
- ④ GAN form breakup -
  - Generative — explains how data gen virtually (how data gen is form of probal model)
  - Adversarial — training of model is done in adv. setting.
  - Network — use deep NN for training purposes.
- ⑤ Generator → gives out fake samples of data (img, audio, etc) & tries to fool disc.
- ⑥ Discriminator → distinguish b/w real & fake samples.
- ⑦ Both G & D are NN → run in competition with each other in training.
- ⑧ repeated sev. times both G & D get better at their jobs.
- ⑨ Gen model → ① captures distn of data ② trained in manner that max. prob. of disc.
- ⑩ Discrim. model → ① estimates of prob that sample is real is entering.
- ⑪ GANs formulates as minimax game.

i.e.  $G \rightarrow \max. D's \text{ reward } V(D, G)$  i.e. minimise loss.  
 $\rightarrow \max V(G, D)$ .

$$V(D, G) = \mathbb{E}_{x \sim p_{data}(x)} [\log D(x)] + \mathbb{E}_{z \sim p_z} [\log (1 - D(G(z)))]$$

Training data → 2 sources → Real data → real pictures  
 → Fake data → instances created by G.

## \* Training the Disc-

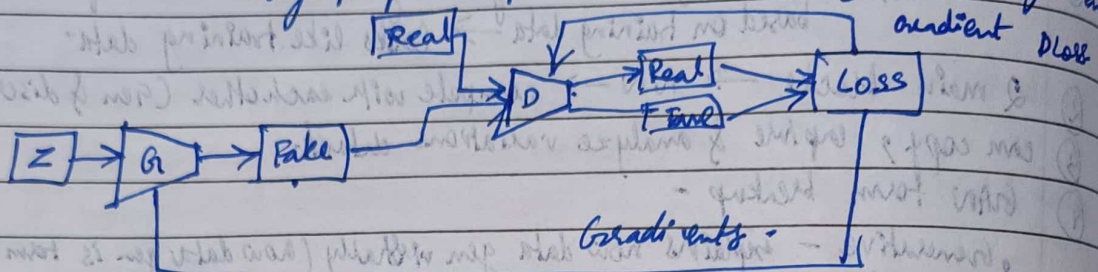
- ① connects 2 loss func.
- ② Syners loss & focus only on D loss
- ③ Loss used by G training.

During D training → ① classifies ② penalises ③ updates



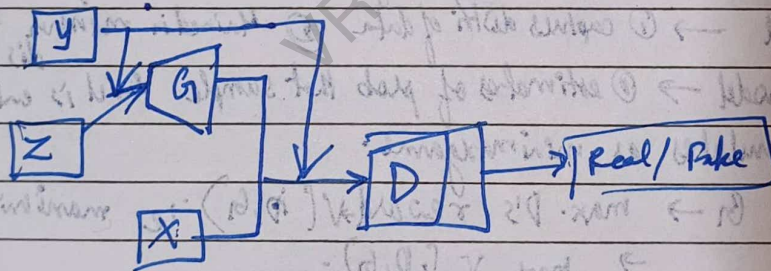
## \* TYPES OF GAN -

- ① Vanilla GAN - • simplest GAN • G & D are simple •  
 • algo simple  $\rightarrow$  optimizes max eqn using stochastic gradient



- ② Conditional GAN (CGAN) -

- DL method in which cond. params are considered.
- CGAN  $\rightarrow$  add "param  $y$ "  $\rightarrow$  added to G for gen corresponding data.
- Labels also put in D in order for D to help disting. b/w real data.



- ③ Deep Conditional GAN (DCGAN) -

- most popular + most successful implementation of GAN
- composed of convnets of multilayer preceptions
- convnets implemented w/o max pooling inst. replaced by convs
- layers not fully connected

- ④ Laplacian Pyramid GAN (LAPGAN).

- Laplacian Pyramid is linear invertible rep consisting of a set of band-pass imgs, spaced as octave apart + low freq. rep. that uses multiple Gs & Ds
- approach becoz it's produced high fidelity imgs.
- img is down-sampled at first at each layer of pyr.
- upsampled at each layer in backward pass when img requires

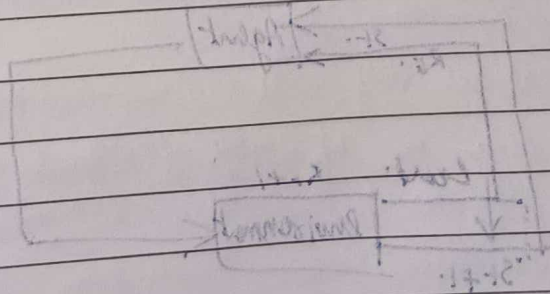


## ③ Super Resolution GAN (SR GAN) -

- DNN + adversarial network in order to produce higher res. imgs.
- useful in optimally scaling up native low-res. imgs. to enhance its details. minimises while doing so.

## Appln of GAN -

- img synthesis
- img editing & style transfer
- super resolution
- Data Augmentation
- Anomaly detection
- Text to img synthesis



- used to formalise reinforcement learning problems.
- MDP can be modelled as Markov Decision Process.
- state  $\rightarrow$  represents config / situation agent is in during decision making
- Actions  $\rightarrow$  decisions of what agent can be taken at each state
- "reward"  $\rightarrow$  tells immediate rewards
- "loss"  $\rightarrow$  tells cumulative loss