

Qualifications

- Proficient with SolidWorks, Rhinoceros surface modelling, rendering with Keyshot and post processing with Photoshop
- Extensive experience with rapid prototyping through SLA, SLS, and FDM 3D printing for professional presentation
- Project Management skills developed through co-ordinating product manufacturing trials in both mould injection and decorative finishing
- Experienced with material testing procedures for various interior automotive parts that would need to be tested for compression, adhesive strength, tensile strength, impact testing, and marring

Work Experience

Mitchell Plastics *Decorative ENG. Intern Jan-Apr '16*

- Worked within R&D department on conceptual interior products and parts for Toyota, FCA, and Ford
- Conceptualized and created new interior decorative designs through the use of industry production processes (eg. painting, hydrographic, wrapping, and laser etching)
- Knowledgeable with Injection Moulding and basic Tool Design from work with prototype plastic part design for R&D projects, for example the Dodge Ram tambour door project done during my last term

Current Projects

- Member of mechanical engineering team helping start up the Waterloo Autonomous Sailboat team, our objective is to build a autonomous sailboat which will compete against other university teams across Canada and America
- Prototyping a silicone sport wristband for the Apple watch which will meet Apple's design specifications for third party wristbands
- Working under the supervision of professor Behrad Khamsee on a new electromagnetic spherical wheel design which uses maglev propulsion to drive forward levitating wheels

Previous Projects

- Have run my own 3D Print service using my own FDM Printer completing orders for more than 70 clients, made a return on investment and now expanded to a new Form 2 SLA Printer
- Designed and built a 250cc Dune Buggy out of a steel chassis and developed skills in metal work, welding, automobile painting, and high strength 3D Printing
- Designed and built a all electric Segway made of a aluminum base chassis and powered by twin 12V lead batteries powering 300 Watt Scooter Electric Motors balanced by a 6 axis Analog Accelerometer Arduino Combo