

view_frames Result

Recorded at time: 1558.867

chassis

Broadcaster: /robot_state_publisher
Average rate: 10.211 Hz
Most recent transform: 1558.801 (0.066 sec old)
Buffer length: 4.701 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.211 Hz
Most recent transform: 1558.801 (0.066 sec old)
Buffer length: 4.701 sec

right_wheel

