(a) Estimation of scale from field of view

Observed region

Estimated object scale



Estimated part scale

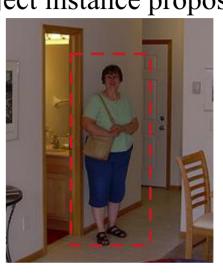


(b) Part parsing at proper object/part scales

Image



Object instance proposals



Part proposals

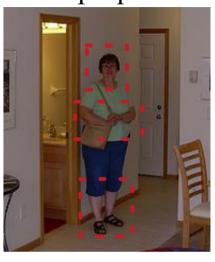
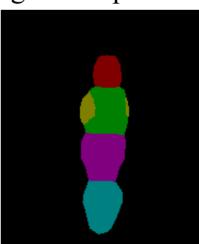
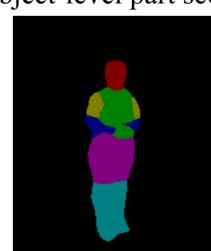


Image-level part scores



Object-level part scores



Part-level part scores

