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304414410
SID
SUBJECT
                 MATHEMATICAL MODELLING & METHODS
HOMEWORK
                  #1
Mathematical Modeling & Methods - HW#1
Question 1:
(a) Standard basis vector of size 3 = 3*3 identity matrix
octave:1> eye (3)
ans =
Diagonal Matrix
       0
           0
   1
   0
       1
           0
   0
       0
           1
This needs to be transformed to matrix A which = [T(e1), T(e2), T(e3)] =
[a1,a2,a3]
octave:2> a1 = [3;-2;1]
a1 =
   3
  -2
octave:3 > a2 = [6;0;7]
a2 =
   6
   0
octave:5 > a3 = [5;4;-1]
a3 =
   5
   4
  -1
then T(e1) = a1
hence T(e1) = T(1;0;0) = a1
or T(e1) = T(x,y,z) = (3x;-2x;x)
T(e2) = a2
or T(e2) = T(x,y,z) = (6y;0;7y)
T(e3) = a3
or T(e3) = T(x,y,z) = (5z;4z;-z)
or A(x,y,z) = [(3x, 6y, 5z); (-2x,0,4z); (x,7y,-z)] assuming (x,y,z) are the
values of corresponding e<i> vector)
Given a identity matrix of size 2
octave:6> eye (2)
ans =
```

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NAME

```
Diagonal Matrix
```

1 0

[e1,e2] needs to be transformed into [4e2,-e1]

Hence A should be
octave:8> A = [0,-1;4,0]
A =

 $\begin{array}{ccc}
0 & -1 \\
4 & 0
\end{array}$

Identity matrix * Tranformation matrix = Resultant matrix A or transformation matrix is also = A

transformation matrix =

 $\begin{array}{ccc}
0 & -1 \\
4 & 0
\end{array}$

(c) octave:11> M = [1, 0; 1,1] M =

1 0 1 1

X axis is represented by the matrix C1 = [t; 0] where t is a variable definfing the value of x at that point in the x axis.

to transform X axis we need to : M * C1

The transformation is a matrix [t;t] which is represented by the line x=y. This is because for ex:

if t=4 the point which is defined by [t;t] = [4;4] if t=6.5 the point which is defined by [t;t] = [6.5;6.5] i.e

y = mx + c is the eqn of any staright line. where m = y2-y1/x2-x1 = 2.5/2.5 = 1; hence eqn => y = x + c

substitutitng $(4,6) \Rightarrow 4 = 4 + c \text{ or } c = 0$

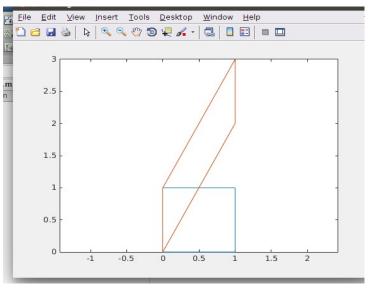
So the eqn of the line \Rightarrow y = x

Similarly the line y = 2 can be represented by the matrix c2 = [t;2]

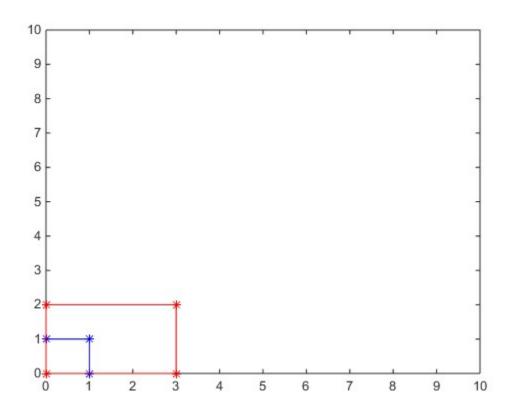
to transform X axis we need to : M * C1

The transformation is a matrix [t;t+2] which is represented by the line x+2=y. This is because for ex:

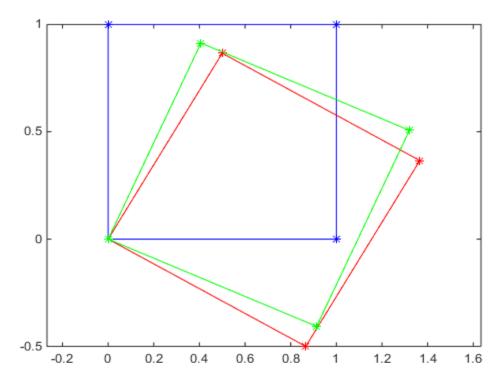
```
if t=4 the point which is defined by [t;t+2] = [4;6]
if t=6.5 the point which is defined by [t;t] = [6.5;8.5] i.e
y = mx + c is the eqn of any staright line.
where m = y2-y1/x2-x1 = 2/2 = 1; hence eqn => y = x + c
substitutitng (4,6) \Rightarrow 4 = 2 + c \text{ or } c = 2
So the eqn of the line \Rightarrow y = x + 2
d.
function [ ] = sheer( a,t )
  b = t * a;
  plot(a(1,:),a(2,:));
  hold on;
 plot(b(1,:),b(2,:));
 hold off;
  axis equal;
>> a = [0 1 1 0 0; 0 0 1 1 0]
>> t = [1 0; 2 1]
>> sheer(a,t)
```



```
(e)
function stretch_plot(pts)
figure
stretch = [3 0; 0 2]
plot(pts(1,:),pts(2,:),'b*-');
axis([0 10 0 10])
stretch_sqr = stretch * pts;
hold on
plot(stretch_sqr(1,:), stretch_sqr(2,:), 'r*-');
end
```



```
f) function ref_plot(pts)
ref = [cos(pi/3) sin(pi/3); sin(pi/3) -cos(pi/3)];
plot(pts(1,:),pts(2,:),'b*-');
ref_sqr = ref * pts;
hold on
axis equal
plot(ref_sqr(1,:),ref_sqr(2,:)
ref = [cos(pi/5) sin(pi/5); sin(pi/5) -cos(pi/5)];
ref_sqr = ref * ref_sqr;
hold on
plot(ref_sqr(1,:),ref_sqr(2,:)
end
```



```
QUESTION 2:
function I = id_mat(n)
X = 1 : n
Y = [1 : n]'
A = X' * X
A = A \cdot / A
Rows = X \cdot A
Cols = Y \cdot A
I = (Rows == Cols)
end
octave:2> id_mat(4)
X =
ans =
   1 0
          0
              0
   0 1
          0
              0
   0 0
           1
              0
   0
       0
              1
abs_func = @(X) -1 .* X .* (X<0) + X .* (X>0)
octave:4>
octave: 4 > x = [-1 \ 1]
x =
-1 1
octave:5> abs_func(x)
ans =
   1 1
3.function LT = ltri(X)
[n,p] = size(X)
I = 1 : n
J = [1 : p]'
A = X' * X
A = A \cdot / A
Rows = I \cdot A
Cols = J \cdot A
L = (Rows <= Cols)
LT = X .* L
end
octave:13> x
x =
   1
       2
   3
       4
octave:14> ltri(x)
ans =
   1
       0
   3
       4
```

```
QUESTION 3:
a.
%interpolate function
function [ C ] = interpolate(A, B, t )
  C = (1-t).*A + t.*B
end
%code to show interpolation and extrapolation
[x2, map] =
imread('/home/kami/Documents/FALL/modelling/hw1/nikki_minaj.jpg');
load mandrill;
mandrill_cropped = Mandrill(1:252,1:228,1:3)
C = interpolate(double(x2), mandrill_cropped, 0.25);
imshow(C)
C = interpolate(mandrill_cropped, double(x2), 1.25);
imshow(C)
%code for the movie
function [] = mov(A,B,n)
    F(n) = struct('cdata',[],'colormap',[]);
    for j = 1:n
        \bar{C} = interpolate(double(A), double(B), j-1/n);
        imshow(C);
        F(j) = getframe;
    end
    movie(F);
end
```

A: B:





C: 0.25

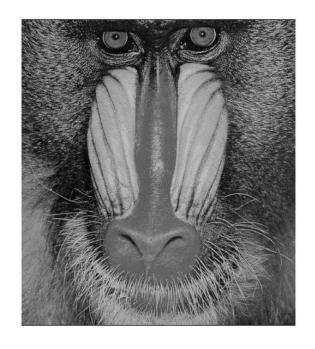




```
3b.

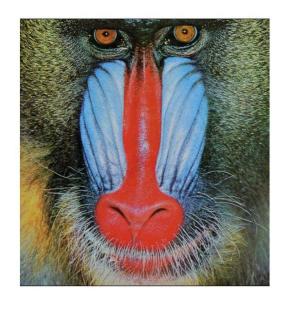
1.
%grayscale
function [ G ] = grayscale( A )
%Converts an image to gray scale
% R = G = B
    [R,G,B] = image2rgb(A);
    G = cat(3, (R+G+B)/3, (R+G+B)/3, (R+G+B)/3);
end

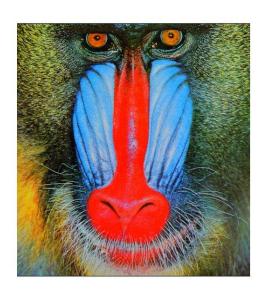
C = grayscale(mandrill)
imshow(C)
```



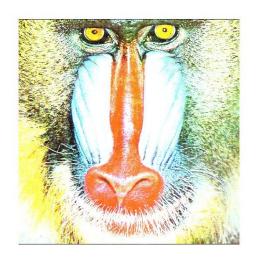
```
2.
%saturate
function [ S ] = saturate( A,t )
%changes image saturation
   grayScale = grayscale(A);
   S = interpolate(A, grayScale,t);
end
```

t = 0.25 t = -0.25





3.
%brigten
function [B] = brighten(A,t)
%brightens the image
 B = t.* A;
end
C = brighten(mandrill, 0.25)
imshow(C)
C = brighten(mandrill, -0.25)
imshow(C)





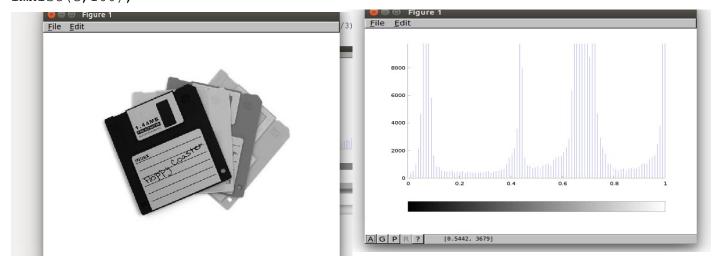
```
%darken
function [ D ] = darken(A,t )
% darkens the image
    hsvConverted = rgb2hsv(A);
    H = double(hsvConverted(:,:,1));
    S = double(hsvConverted(:,:,2));
    V = double(hsvConverted(:,:,3));
    V = t.* V;
    hsvDarkened = cat(3,H,S,V);
    D = hsv2rgb(hsvDarkened);
end

D = darken(mandrill,0.25)
imshow(D);
```

4.



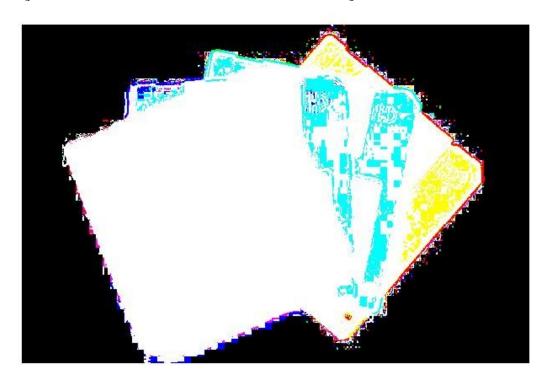
```
3c.
y = mat2gray(X);
imshow(y);
[R,G,B] = image2rgb(y);
G = cat(3, (R+G+B)/3, (R+G+B)/3, (R+G+B)/3);
imshow(G);
imhist(G,100);
```



```
color_inversion
function [ Y ] = color_inversion( A )
% inverts the color in the image
    [R,G,B] = image2rgb(A);
    R1 = 255 - R;
    G1 = 255 - G;
    B1 = 255 - B;
    Y = rgb2image(R1,G1,B1);
end

Y = color_inversion(X)
imshow(Y)
```

% Using the floppy image instead of Mandrill because the Mandrill image has r,g,b in the range 0-1. And to convert it to 1-255 range we need Image processing toolkit which is not available on my MATLAB.



```
3d2.
%Color transform
function [ Y ] = YCbCr( A )
%YCbCr
    T = [0.29900, 0.58700, 0.11400; -0.16874,-0.33126,0.50000;0.50000,-
0.41869,-0.08131];
    v = [0;128;128];
    [R,G,B] = image2rgb(A);
    [rows,cols] = size(R);
    for r = 1:rows
        for c = 1:cols
```

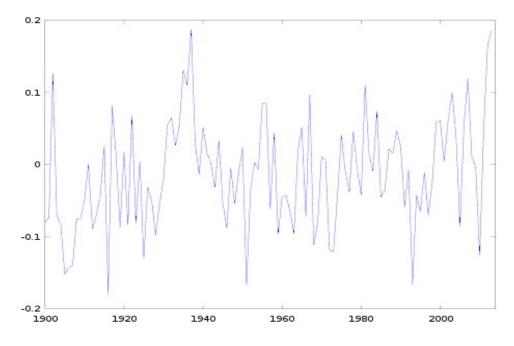
```
color = [R(r,c);G(r,c);B(r,c)];
color = T*color;
color = color + v;
R1(r,c) = round(color(1));
G1(r,c) = round(color(2));
B1(r,c) = round(color(3));
end
end
Y = rgb2image(R1,G1,B1);
end
```



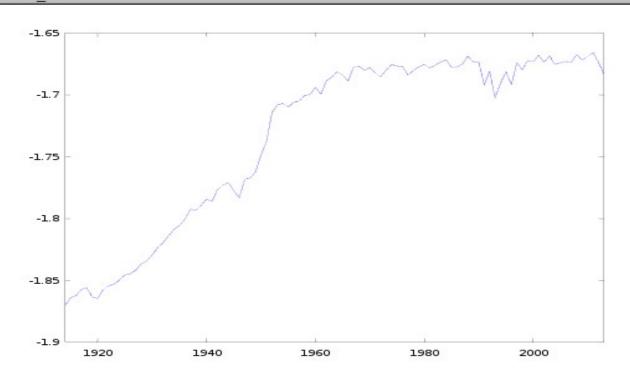
```
3d3.
>> T = [0.29900, 0.58700, 0.11400; -0.16874, -0.33126, 0.50000; 0.50000, -0.16874]
0.41869, -0.08131;
>> min_value
min_value =
     0
     0
     0
>> max_value =
   255
   255
   255
>> T*max_value + v
ans =
   255
   128
   128
```

```
>> T*min value + v
ans =
     0
   128
   128
Since for both max and min values of R,G,B components of color matrrix the
resultant is positive, for values in between it will be positive.
4. OVERHEATING
Problem 4:
a. Code to generate a plot of average temperature anamoly in July for the
years 1900-2014 for United States
GHCN = csvread('ghcn.csv');
GHCN in centigrade = (GHCN(:, 3:74) - 2500) / 100;
temperature_anomaly = reshape( GHCN_in_centigrade, [36, 12, 135, 72] );
US_latitude = 9:12
US_longitude = 15:20
my_years = 1900:2013
my_slice = temperature_anomaly( US_latitude, :, my_years - 1880,
US longitude );
total_number_of_grid_squares = length(US_latitude) * length(US_longitude) *
12;
N = total_number_of_grid_squares;
monthly_anamoly = sum(sum(my_slice, 4),1);
for n = 1:114
  yearly_matrix(1:12) = monthly_anamoly(:,:,n);
  july_anomaly(n) = yearly_matrix(7)/N;
plot( my_years, july_anomaly )
xlim([1900, 2014])
```





```
generate a plot of average temperature anamoly in July for the years 1900-
2014 for entire world
GHCN = csvread('ghcn.csv');
GHCN_in_centigrade = (GHCN(:, 3:74) - 2500) / 100;
temperature_anomaly = reshape( GHCN_in_centigrade, [36, 12, 135, 72] );
US_latitude = 1:36
US longitude = 1:72
my_years = 1900:2013
my_slice = temperature_anomaly( US_latitude, :, my_years - 1880,
US_longitude );
total_number_of_grid_squares = length(US_latitude) * length(US_longitude) *
N = total_number_of_grid_squares;
monthly_anamoly = sum(sum(my_slice, 4),1);
for n = 1:114
  yearly_matrix(1:12) = monthly_anamoly(:,:,n);
  july_anomaly(n) = yearly_matrix(7);
plot( my_years, july_anomaly )
xlim([1914,2013])
```

```
G P R ? [1966, -1.687]
```

```
c. function [] = ghcn_hotplot()
GHCN =
```

```
csvread('/home/kami/Documents/FALL/modelling/hw1/Homework1/ghcn.csv');
    GHCN_in_centigrade = (GHCN(:, 3:74) - 2500) / 100;
    temperature_anomaly = reshape(GHCN_in_centigrade, [36, 12, 135, 72]);
   US_latitude = 1:36;
   US_longitude = 1:72;
   my_years = 1880:2014;
   my_slice = temperature_anomaly( US_latitude, :, my_years - 1880,
US_longitude );
    colormap(hot)
   F(114) = struct('cdata',[],'colormap',[]);
   total_number_of_grid_squares = length(US_latitude) *
length (US longitude) * 12;
   N = total_number_of_grid_squares;
   monthly_anamoly = sum(sum(my_slice, 4),1);
    for n = 1:110
      yearly_matrix(1:12) = monthly_anamoly(:,:,n);
      july_anomaly(n) = yearly_matrix(7);
      plot( my_years(1:n), july_anomaly );
      F(n) = getframe;
    end
   xlim([1880,2014]);
    %movie(F);
end
```

