## **HOMEWORK 3**

```
3.10
```

```
import numpy as np
def calc poly(x,roots):
  Computes polynomial
  p = 1
  for i in range(len(roots)):
     p *= (x - roots[i])
  return p
def test poly(x,roots):
  Test function for poly
  p=1
  assert calc poly(x, roots) == np.prod([p*(x-roots[i]) for i in range(len(roots))]), "Calculation is wrong"
def main():
  roots = [1,2,5]
  x = 3
  p=1
  exp = np.prod([p*(x-roots[i]) for i in range(len(roots))])
  print("Expected polynomial:",exp)
  print("Polynomial calculated by the function:",calc poly(x,roots))
  test poly(x,roots)
main()
import numpy as np
def calc poly(x,roots):
  Computes polynomial
******
  p = 1
  for i in range(len(roots)):
     p *= (x - roots[i])
  return p
def test poly(x,roots):
```

```
Test function for poly
  p=1
  assert calc poly(x, roots) == np.prod([p*(x-roots[i]) for i in range(len(roots))]), "Calculation is wrong"
def main():
  roots = list(map(int,input("\nEnter roots : ").strip().split()))
  x = int(input("Enter value of x:"))
 p=1
  exp = np.prod([p*(x-roots[i]) for i in range(len(roots))])
  print("Expected polynomial:",exp)
  print("Polynomial calculated by the function:",calc poly(x,roots))
  test poly(x,roots)
main()
Output
Enter roots : 3 4 7
Enter value of x: 8
 Expected polynomial: 20
Polynomial calculated by the function : 20
3.17
import math
#definition of the pathlength() function...
def pathlength(x,y):
```

```
nport math

definition of the pathlength() function...

ef pathlength(x,y):

#declare the L and set it to 0...

L = 0

#find the length of x and y...

lenX = len(x)

lenY = len(y)

#use the for loop to find the expression...

for i in range(1,lenX):

L += math.sqrt( (x[i] - x[i-1]) ** 2 + (y[i] - y[i-1]) ** 2 )

#handle the last pair of distance...

L += math.sqrt( (x[lenX - 1] - x[lenX - 2]) ** 2 + (y[lenY - 1] - y[lenY - 2]) ** 2 )
```

```
#return the L...
  return L
#definition of the test_pathlength() to test the above function...
def test_pathlength():
  #set some dummy data in the lists, x and y...
  x = [10,20,30,40]
  y = [10,20,30,40]
  #call the pathlength() function and store the returned value...
  result = pathlength(x,y)
  #print the final result...
  print("The total length L is = {:.3f}".format(result))
test_pathlength()
output:
PS C:\homework> python pathlength.txt
The total length L is = 56.569
PS C:\homework>
3.18
import math
def pathlength(x,y):
  #declare the L and set it to 0...
  L = 0
  #find the length of x and y...
  lenX = len(x)
  len Y = len(y)
  #use the for loop to find the expression...
  for i in range(1,lenX):
    L += math.sqrt((x[i] - x[i-1]) ** 2 + (y[i] - y[i-1]) ** 2)
  #handle the last pair of distance...
  L += math.sqrt( (x[lenX - 1] - x[lenX - 2]) ** 2 + (y[lenY - 1] - y[lenY - 2]) ** 2)
  #return the L...
```

```
return L
```

```
def test_pathlength():

for k in range(2,11):

#declare empty x and y lists...
x = []
y = []

#find the value of n...
n = 2**k

#generate the points as per the given formula...
for i in range(n):
    x.append( (1/2) * math.cos( 2 * math.pi * i / n))
    y.append( (1/2) * math.sin( 2 * math.pi * i / n))

result = pathlength(x,y)

#print the final result...
print("The Error in the approximation of pi when n = '{:4d}' is = {:.9f}".format(n, math.pi - result))
```

## test\_pathlength()

## Output

```
PS C:\homework> python pi_approx.txt

The Error in the approximation of pi when n = ' 4' is = 0.313165529

The Error in the approximation of pi when n = ' 8' is = 0.080125195

The Error in the approximation of pi when n = ' 16' is = 0.020147501

The Error in the approximation of pi when n = ' 32' is = 0.005044163

The Error in the approximation of pi when n = ' 64' is = 0.001261497

The Error in the approximation of pi when n = ' 128' is = 0.000315403

The Error in the approximation of pi when n = ' 256' is = 0.000078852

The Error in the approximation of pi when n = ' 512' is = 0.000019713

The Error in the approximation of pi when n = '1024' is = 0.000004928
```