

# Kun Su

Ph.D. Student In NeuroAI Lab, University Of Washington

**Address** Seattle, WA, 98125

**WWW** <https://kun-su.netlify.app/>

**Phone** (518) 496-3100

**LinkedIn** <https://www.linkedin.com/in/kun-su-225933137/>

**E-mail** suk4@uw.edu



## Research Interests

**Audio-Visual Learning:** Latent representation and disentanglement of video/audio (music), transformation and generation from *video/audio* (music) to *audio* (music)/*video*.

**Computer Vision:** Human and animal 2D/3D pose, motion prediction, action recognition, temporal segmentation.

**Deep Learning:** Unsupervised learning, self-supervised learning, interpretable embeddings, generative models, incremental learning, meta learning.



## Education

**Apr 2019 - Ph.D.: Electrical & Computer Engineering**

**Current** *University Of Washington - Seattle, WA*

1. Current GPA: 3.90
2. Passed Quals: Fall 2020
3. Expected Graduation Date: Winter/Spring 2023

**Sep 2017 - Master of Science: Electrical & Computer Engineering**

**Mar 2019** *University Of Washington - Seattle, WA*

1. Graduated with 3.92 GPA

**Aug 2013 - Bachelor of Science: Electrical Engineering**

**May 2017** *Rensselaer Polytechnic Institute - Troy, NY*

1. Graduated magna cum laude
2. Graduated with 3.76 GPA



## Publications

**Conferences (CVPR, NeurIPS, ACC, URTC)**

1. Su, Kun, Xiulong Liu, and Eli Shlizerman. "Audeo: Audio generation for a silent performance video." *Advances in Neural Information Processing Systems (NeurIPS)* 33 (2020).

2. Su, Kun, Xiulong Liu, and Eli Shlizerman. "Predict & cluster: Unsupervised skeleton based action recognition." *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)*. 2020.

3. You, Jie, Yufei Zhang, Mingchen Li, Kun Su, Fumin Zhang, and Wencen Wu. "Cooperative parameter

identification of advection-diffusion processes using a mobile sensor network." In 2017 **American Control Conference (ACC)**, pp. 3230-3236. IEEE, 2017.

4. Li, M., **Su, K.**, Zhang, Y., You, J. and Wu, W., 2016, November. *Experimental validation of diffusion coefficient identification using a multi-robot system*. In 2016 **IEEE MIT Undergraduate Research Technology Conference (URTC)** (pp. 1-4). IEEE.

## Journal

5. **Su, Kun**, and Eli Shlizerman. "Clustering and Recognition of Spatiotemporal Features through Interpretable Embedding of Sequence to Sequence Recurrent Neural Networks." **Frontiers in Artificial Intelligence** 3 (2020): 70.

6. Wu, W., You, J., Zhang, Y., Li, M. and **Su, K.**, 2020. *Parameter Identification of Spatial–Temporal Varying Processes by a Multi-Robot System in Realistic Diffusion Fields*. **Robotica**, pp.1-20.

## Workshops

7. **Su, Kun**, and Eli Shlizerman. "Dimension reduction approach for interpretability of sequence to sequence recurrent neural networks." Understanding and Improving Generalization in Deep Learning, **ICML 2019 Workshop**.

## Submitted

8. **Su, Kun**, Xiulong Liu, and Eli Shlizerman. "How Does it Sound?" (2021)

9. **Su, Kun**, Xiulong Liu, and Eli Shlizerman. "Multi-instrumentalist Net: Unsupervised Generation of Music from Body Movements." (2020)

10. Zheng, Yang, Jinlin Xiang, **Kun Su**, and Eli Shlizerman. "BI-MAML: Balanced Incremental Approach for Meta Learning." *arXiv preprint arXiv:2006.07412* (2020).



## Media Coverage

1. University of Washington ECE News (Predict & Cluser)
2. University of Washington News (Audeo)
3. Tech Crunch (Audeo)



## Teaching

### Teaching Assistant

1. Practical Introduction to Neural Networks (**Graduate TA**), ECE 596, University of Washington, 2019
2. Computer Components and Operations (**Undergraduate TA**), ECSE 2610, Rensselaer Polytechnic Institute, 2016



## Peer-Review

**Reviewer (workshop):** Real Neurons & Hidden Units at NeurIPS 2019.



## Internships

**Audio Research Intern**, Adobe Research (Mentor: Xue Bai)

June – Sep 2021

1. Learning speech style from talking head videos.

**Robotic Simulation Intern**, SUNPRO Mechanical & Electrical Engineering Co., Ltd. June-August 2016

1. Design a visual system to evaluate the welded components in the Nissan assembly line.
2. Design an educational base for beginners to industrial robots.



## Skills

Comfortable with programming and deep learning development

**Deep Learning Frameworks:** PyTorch, TensorFlow

**Python Libraries:** NumPy, scikit-learn, OpenCV, Librosa, pretty-midi

**Other Tools:** Linux Shell Script, Matlab, C/C++, LabView

**Languages:** English, Chinese, Cantonese