

# DP on DAGs Strongly Connected Components

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#### Goal



To understand

Div2 D/E

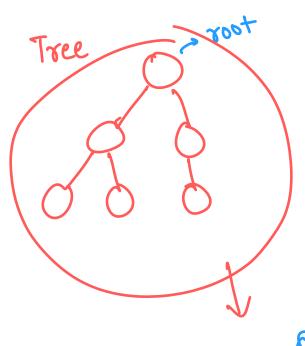
- DP on DAGs ✓
- Strongly Connected Components
- Condensation in Graphs

#### **DP on DAGs**



- **Dynamic Programming (DP) on DAGs** is a technique where we compute optimal values for nodes in a **topologically sorted** order.
- DAGs allow efficient DP state transitions since there are no cycles.
- **Common Applications:** longest paths, counting paths, and optimization problems.





# subtree de

$$dP[u] = dP[c_1] + dP[c_2] + a[u]$$

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DAGS

· no root

· we don't know the order inwhich we should calculate the dp states

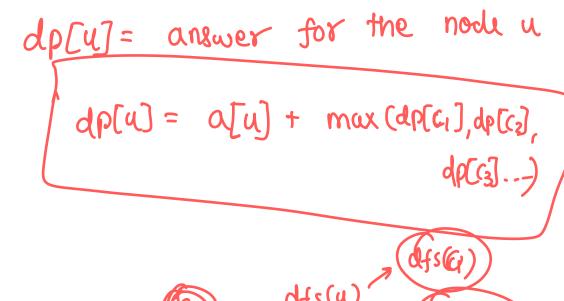
Given a DAG, each node u Problem:

has some value aty. score of path

score of path

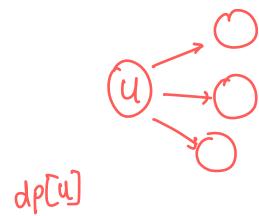
and all nodes

in the path For each node find the maximum score of any path stucting from that node



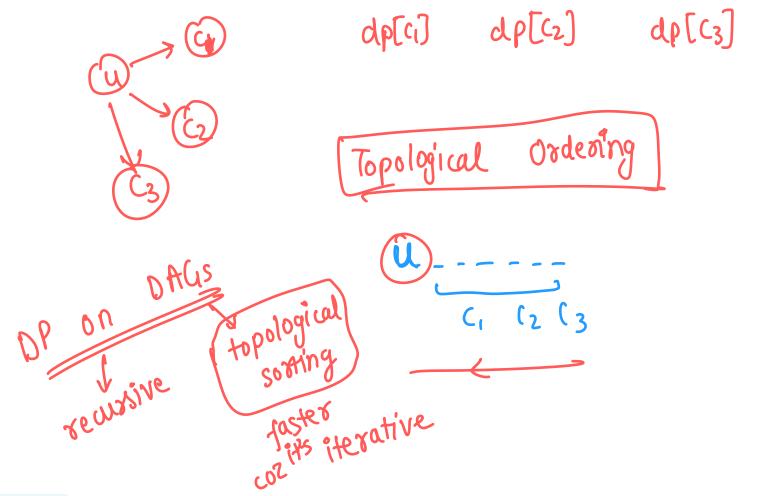


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Topological sorting dp[i] --- dp[0]



# **Key Steps in DP on DAGs**

- Topological Sorting
- 2. Define DP State
- 3. Iterate in Topological Order

dp state
topological ordering
do the transitions

#### **Problem: Longest Path in a DAG**



Find the heaviest path from a given source in a weighted DAG.

The weight of a path is defined as the sum of weights of all the edges on the path.

$$dp[u] = \max(\omega + (u, u) + dp[u], \dots)$$

$$\omega + (u, u) + dp[u], \dots)$$

$$\delta + (u, u) + dp[u], \dots)$$

$$\delta + (u, u) + dp[u], \dots$$

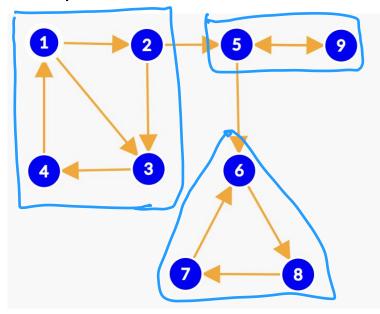
$$\delta + (u, u) + dp[u], \dots$$

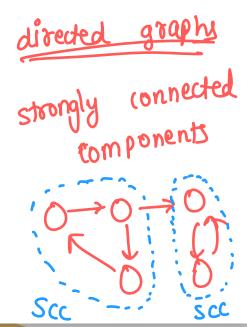


A strongly connected component in a directed graph is a maximal set of nodes such that there is a path from u to v and v to u for all the nodes in the

set.

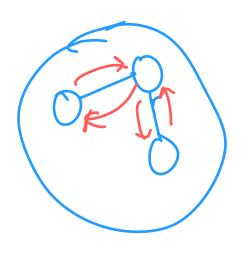
undirected

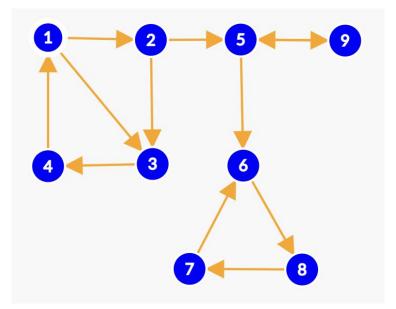






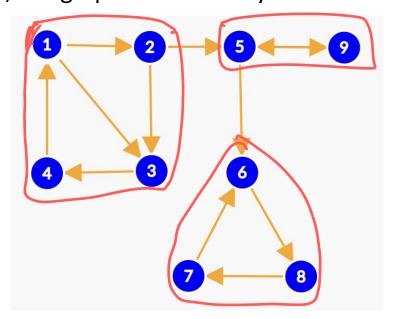
This is not a valid concept for Undirected graphs. There we talk about only connected components and there is no notion of strongly connected.

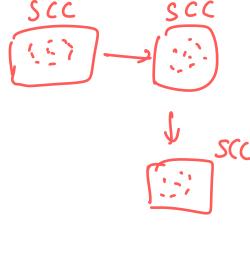


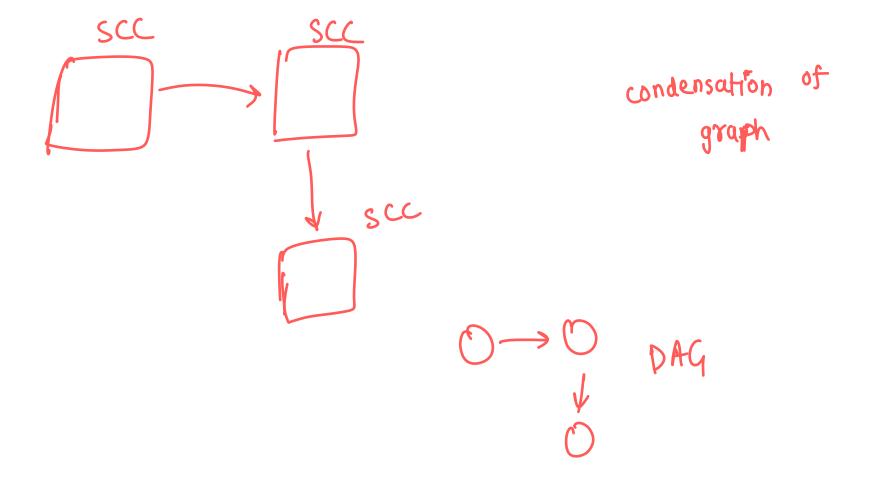




A graph can be decomposed into multiple strongly connected components. After decomposition, the graph becomes acyclic.



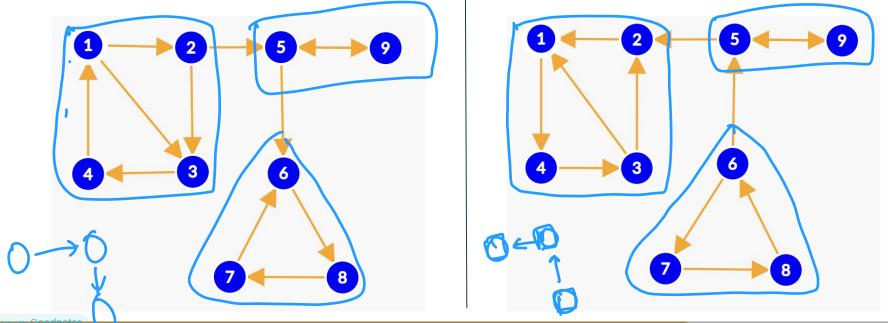






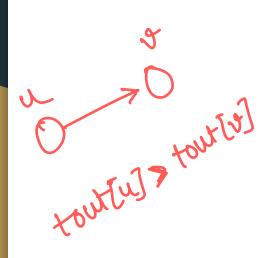
Strongly connected components of a graph don't change if the graph is

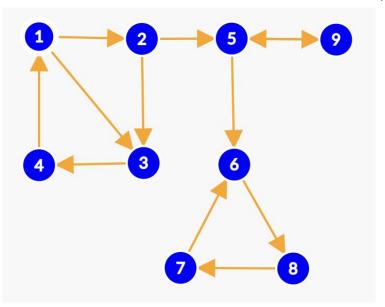
transposed.





If there is an edge from SCC<sub>i</sub> to SCC<sub>j</sub> then outTime[SCC<sub>i</sub>] > outTime[SCC<sub>j</sub>] irrespective of whether we start DFS from a node in SCC<sub>i</sub> or SCC<sub>i</sub>





#### How to find all SCCs



There are 2 famous algorithms:

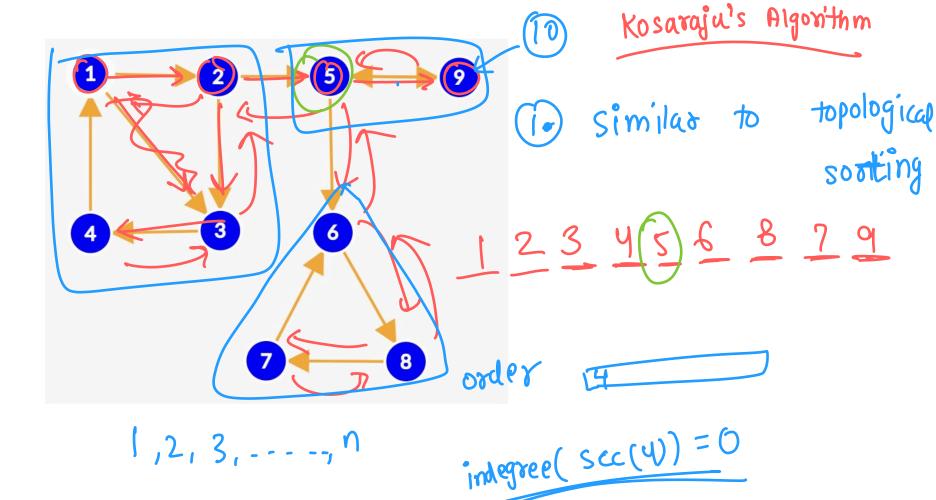
- Kosaraju's Algorithm
- Tarjan's Algorithm

#### Kosaraju's Algorithm

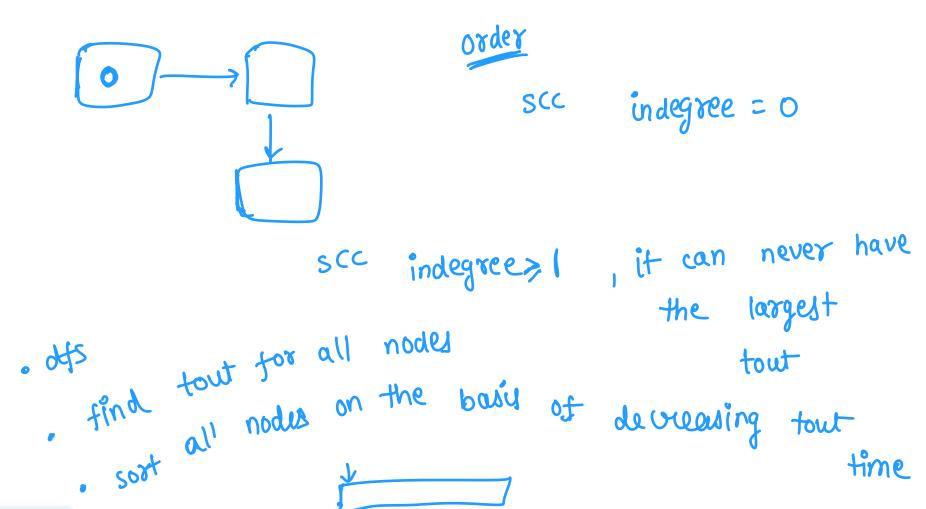


- Perform DFS and store nodes in a stack
  - Run DFS on the original graph.
  - Store nodes in a stack based on their finish time.
- Reverse all edges (Transpose Graph)
  - Reverse every directed edge.
  - Now, SCCs remain SCCs, but edges are flipped.
- Process nodes in stack order on the transposed graph
  - Run DFS using nodes in the stack order.
  - Each DFS call discovers an SCC.

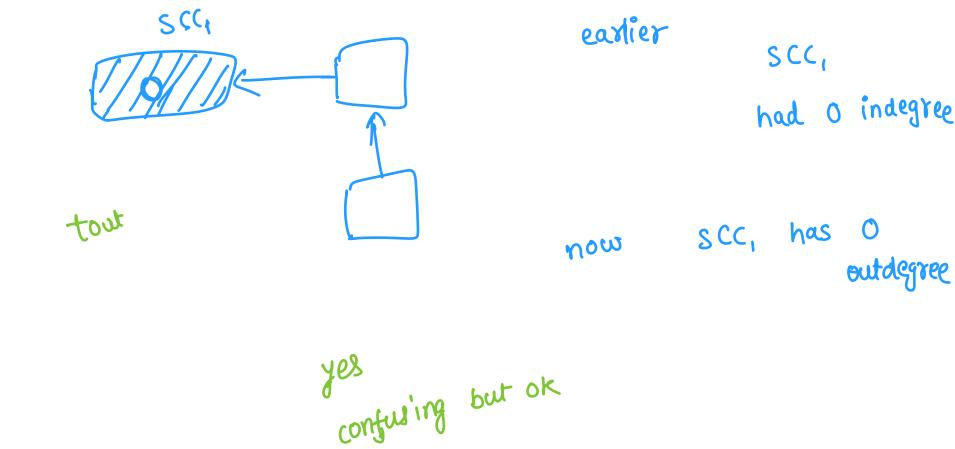
Time Complexity -> O(V + E)



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outdegree

no

# Implementation of Kosaraju's Algorithm



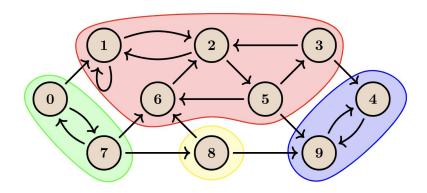
```
void kosaraju(vector<vector<int>> &adj, vector<vector<int>> &components,
                 vector<vector<int>> &adj_cond) {
     int n = adj.size();
     // Getting the order of vertices in decreasing order of their finishing
     vector<int> vis(n, 0), order;
     auto dfs = [&](auto &&dfs, int u) -> void {
       vis[u] = 1;
       for (int v : adj[u])
         if (!vis[v]) dfs(dfs, v);
10
11
       order.push_back(u);
12
     };
                                            similar to order
13
     for (int u = 0; u < n; u++)
14
       if (!vis[u]) dfs(dfs, u);
15
     fill(vis.begin(), vis.end(), 0);
16
     reverse(order.begin(), order.end());
17
18
19
     // Getting the transpose of the graph.
     vector<vector<int>> adj_rev(n);
20
     for (int u = 0; u < n; u++)
21
       for (int v : adj[u]) adj_rev[v].push_back(u);
22
23
```

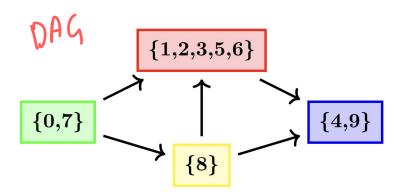
```
auto dfs_rev = [&](auto &&dfs_rev, int u) -> void {
       vis[u] = 1;
       components.back() push_back(u);
26
       for (int v : adj_rev[u])
28
         if (!vis[v]) dfs_rev(dfs_rev, v);
30
     vector<int> roots(n);
31
32
     // Getting the strongly connected components.
     for (int u : order) {
       if (vis[u]) continue;
                                                        SCC
       components.push_back({});
       dfs_rev(dfs_rev, u);
       vector<int> &component = components.back()
       int root = *min_element(component.begin(), component.end());
       for (int v : component) roots[v] = root;
41
42
     // Getting the condensed graph.
     adj_cond.resize(n);
     for (int u = 0; u < n; u++)
       for (int v : adj[u])
         if (roots[u] != roots[v]) adj_cond[roots[u]].push_back(roots[v]);
47
48 }
```

#### **Condensation of Directed Graphs**



Condensation of a directed graph refers to compressing Strongly Connected Components (SCCs) into single nodes, resulting in a Directed Acyclic Graph (DAG).



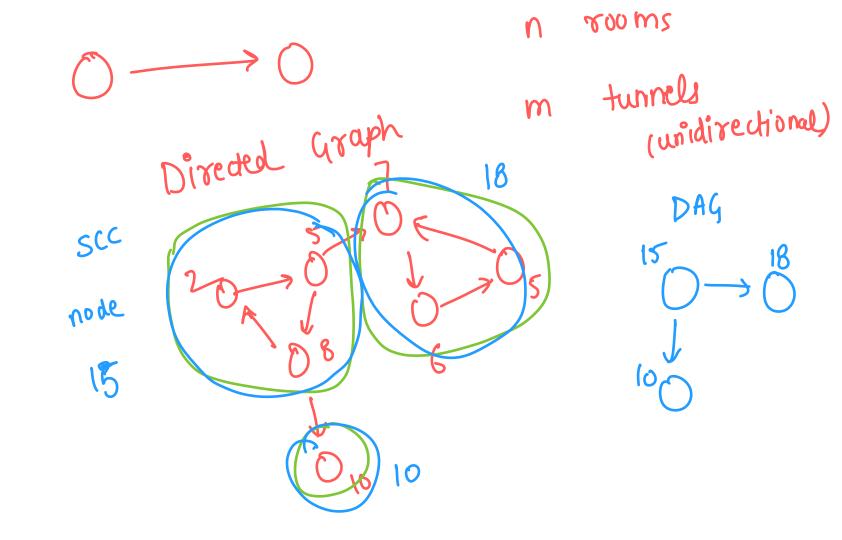


#### **Problem: Coin Collector**



A game has  $\mathbf{n}$  (1 <= n <=  $10^5$ ) rooms and  $\mathbf{m}$  (1 <= m <=  $2 * 10^5$ ) tunnels between them. Each room has a certain number of coins. What is the maximum number of coins you can collect while moving through the tunnels when you can freely choose your starting and ending room?

Problem Link - <a href="https://cses.fi/problemset/task/1686">https://cses.fi/problemset/task/1686</a>



( condense the graph => DAG

2. DP on DAG

#### Resources



• <a href="https://cp-algorithms.com/graph/strongly-connected-components.html">https://cp-algorithms.com/graph/strongly-connected-components.html</a>