



Graph Travserals and Bipartite Graphs

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Goal

- Depth First Search ✓
- Breadth First Search ✓
- Problems on Traversals ✓
- Grids as Graphs → *
- Bipartite Graphs → cool !



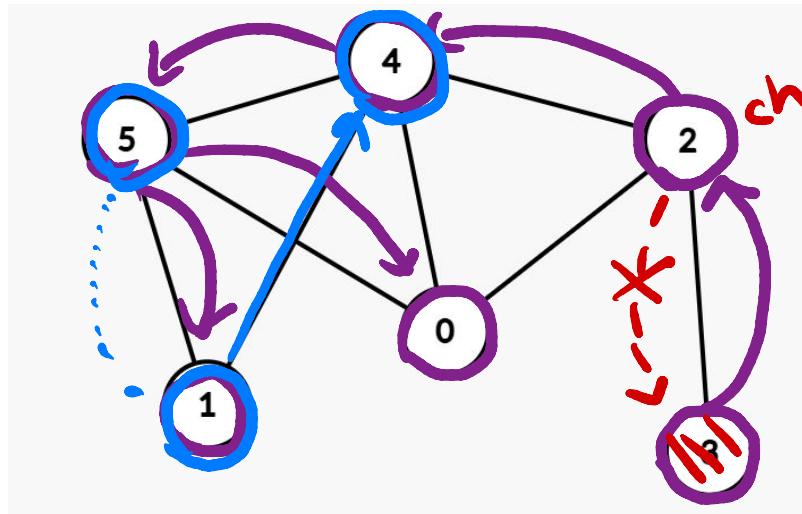
Depth First Search

In Depth First Search (or DFS) for a graph, we traverse all adjacent vertices one by one. When we traverse an adjacent vertex, we completely finish the traversal of all vertices reachable through that adjacent vertex.

*** Note: DFS Traversal is not unique for a graph, multiple traversal orders exist**



Depth First Search Example



Tree's dfs (— , par)

DFS Traversal : [3, 2, 4, 5, 1, 0]



	↓	✗
0	1	1
1	1	1
2	2	2
2	2	2

Visited array : $\text{vis}[i]$



→ 0

→ 1

node i
is vis



Depth First Search Implementation

↗ (D, O, OO)

```
void dfs(int node, vector<vector<int>>&adj, vector<int>&vis) {  
    vis[node] = 1; → mark it as vis ↳ n  
    cout << node << " ";  
    for(auto &neigh : adj[node]) {  
        if(!vis[neigh]) { vis[neigh] = 0 } →  
        dfs(neigh, adj, vis); } } }
```

— : changes from trees

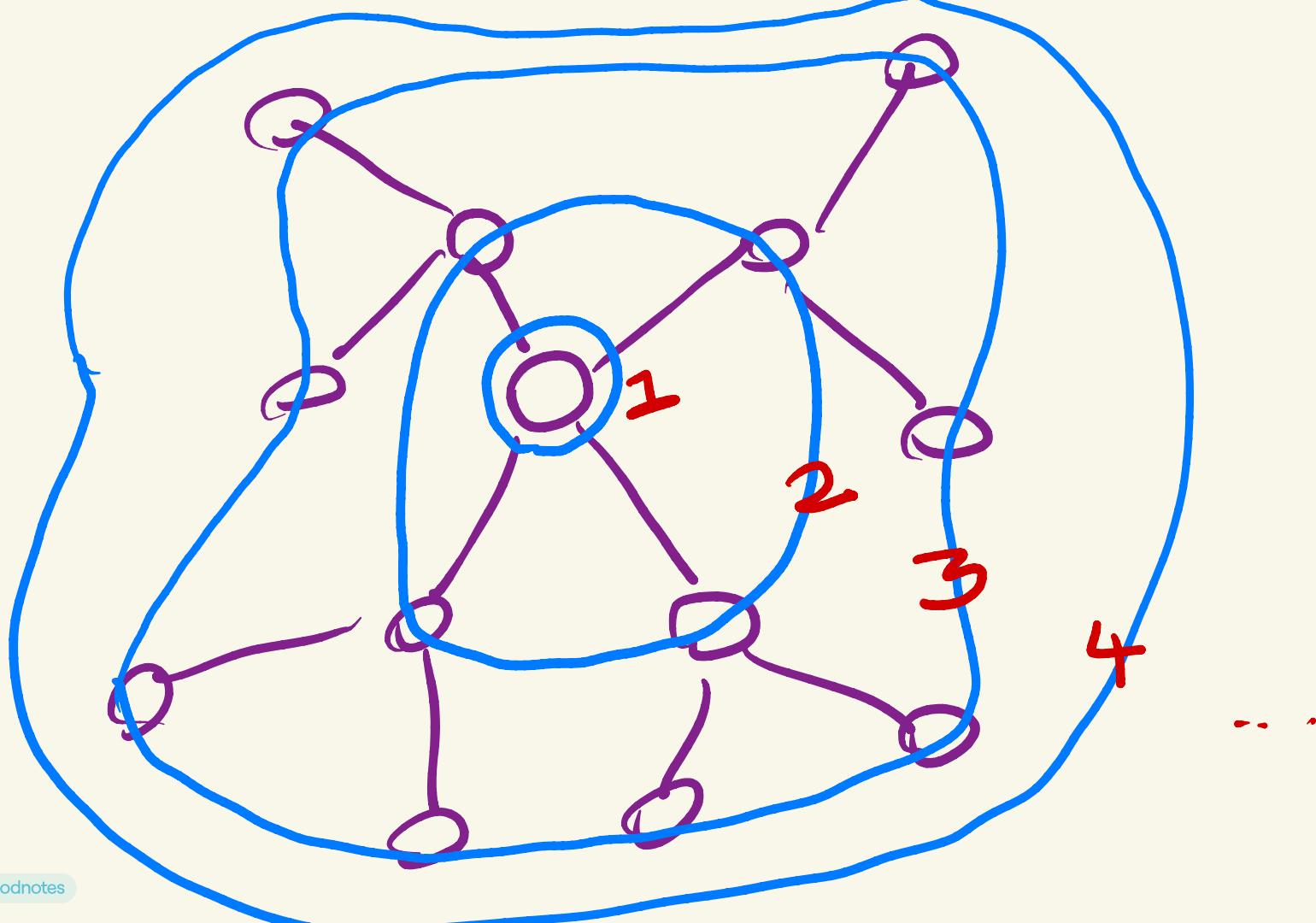


Breadth First Search

Breadth First Search (BFS) expands its breadth one by one. It first visits an entire level, then visits the next entire level and so on.

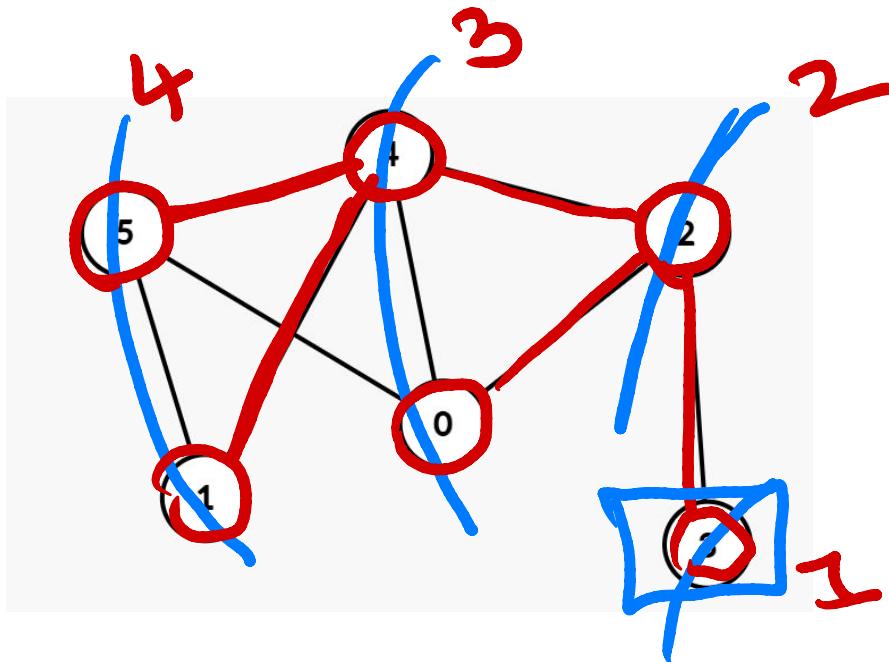
We use a queue to implement the traversal since we want to visit all nodes in a level and then its children and so on, so forth.

Note: Just like DFS, BFS Traversal is not unique for a given graph.





Breadth First Search Example



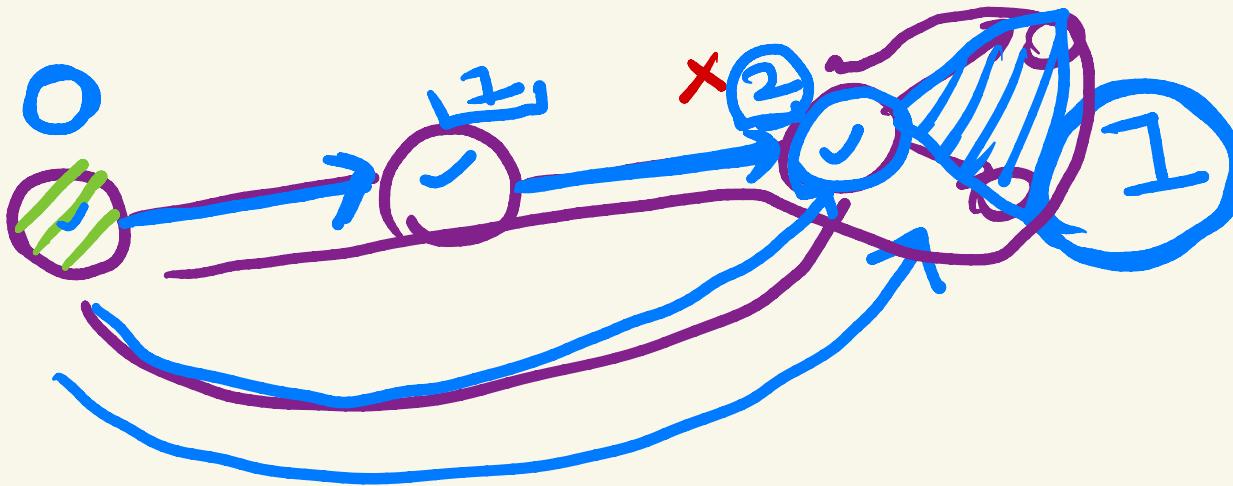
BFS Traversal: [3, 2, 0, 4, 5, 1]

Consider an undirected
unweighted graph.



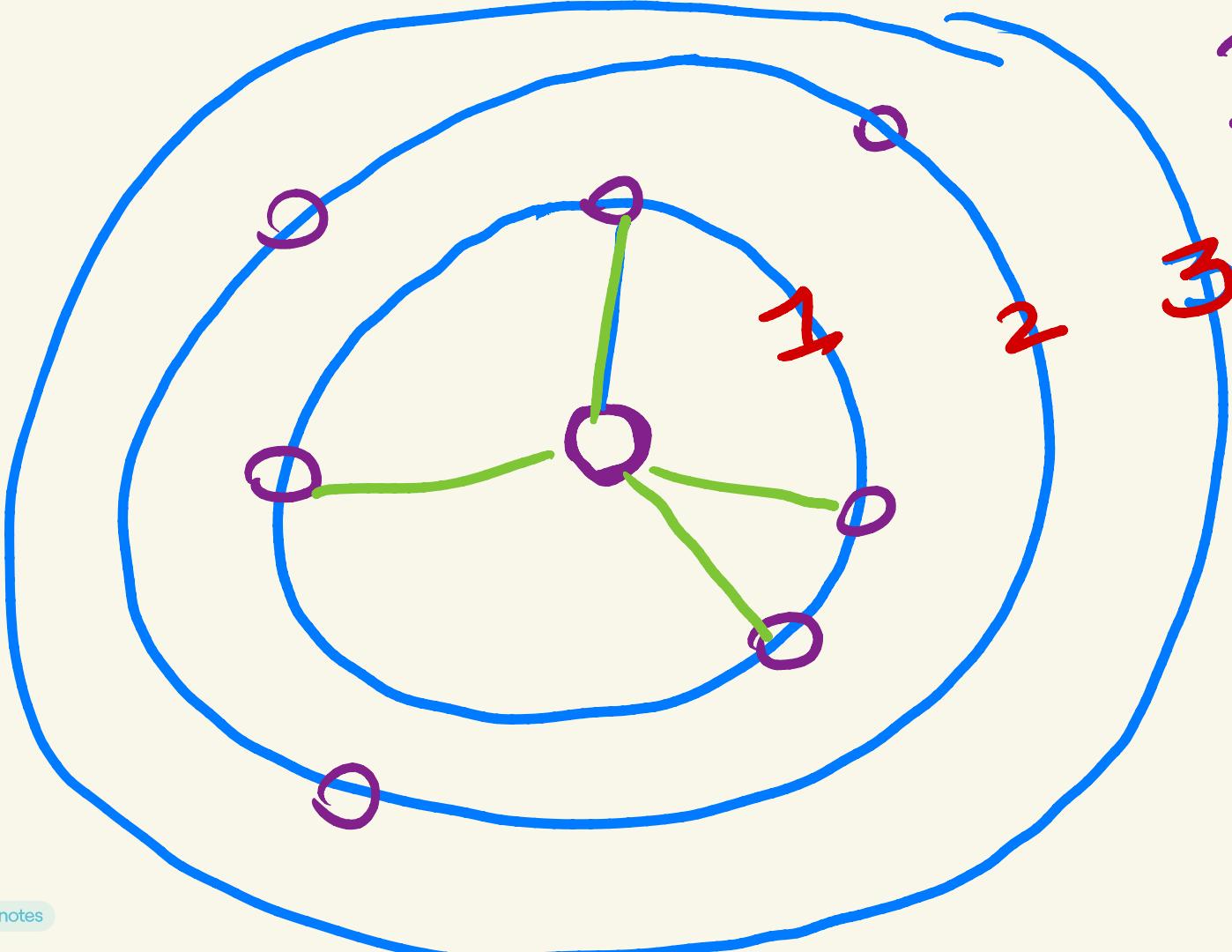
given

→ shortest distance
from to all
other nodes

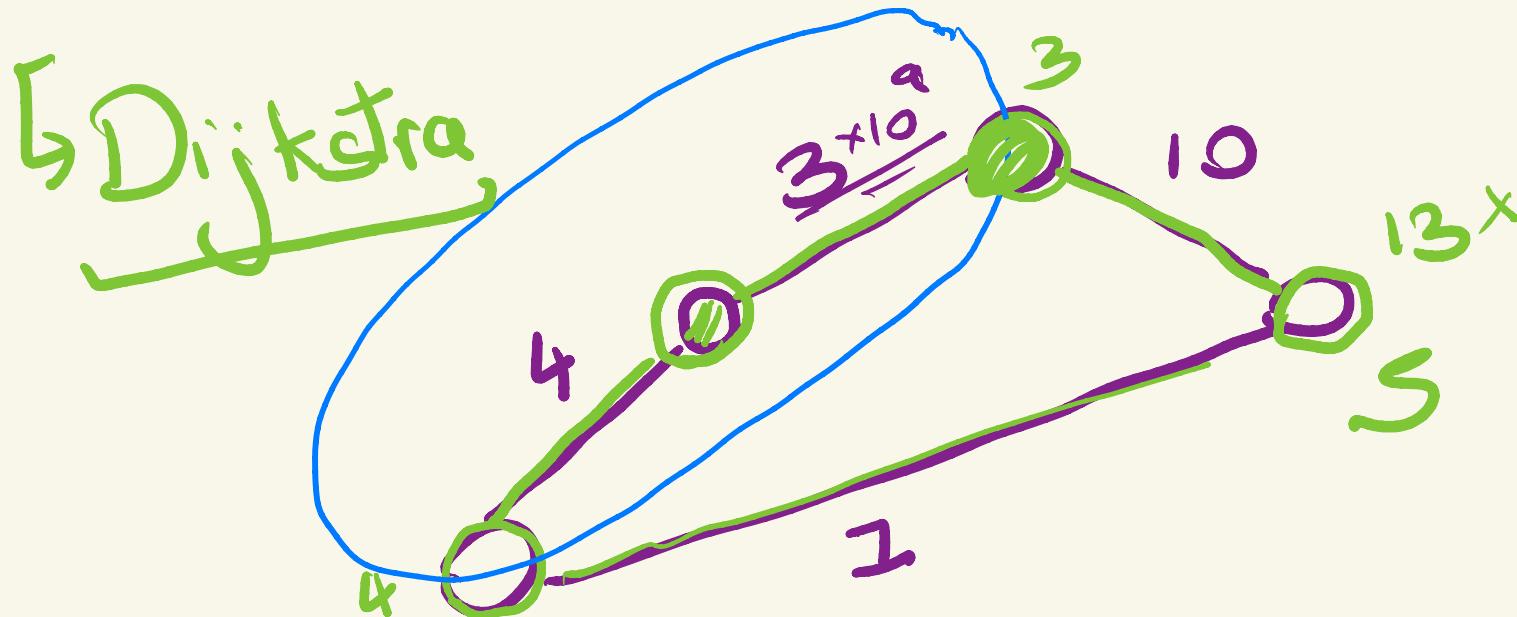


Why DFS fails?

BFS



Why not weighted graphs
as well??



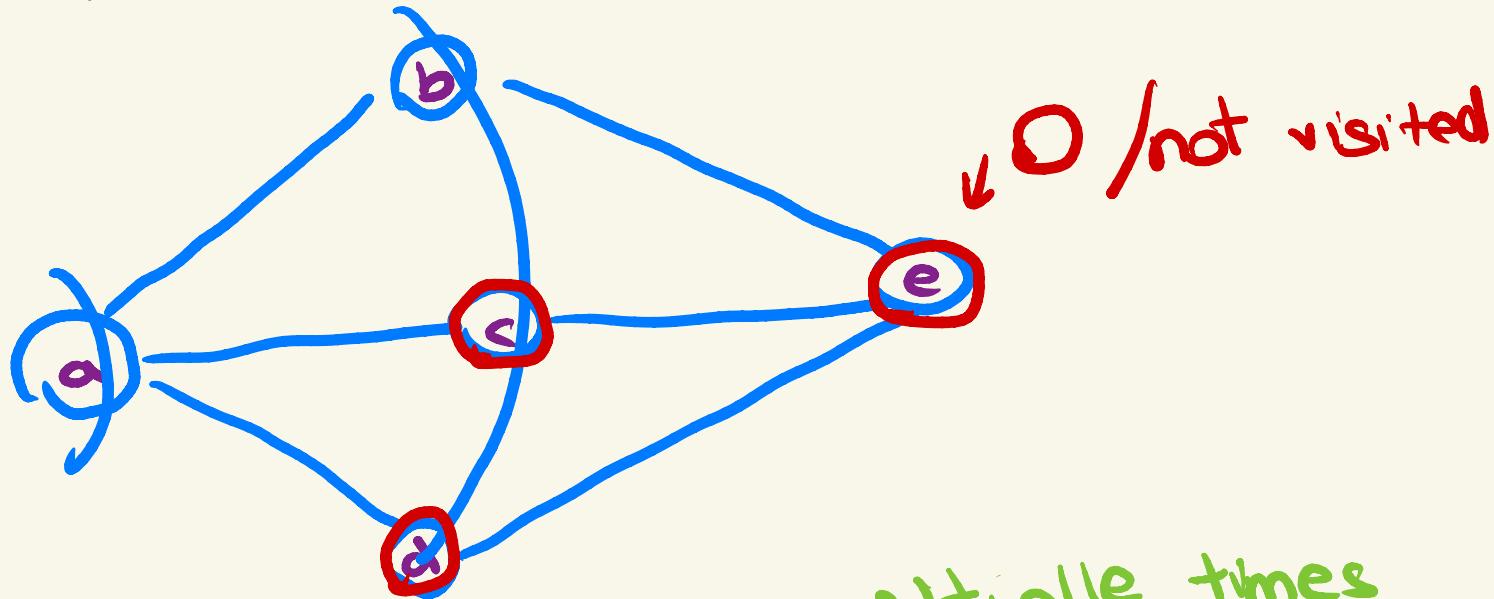


Breadth First Search Implementation

```
void bfs(int node, vector<vector<int>>&adj) {
    vector<int> vis(adj.size());
    queue<int> q; q.push(node); vis[node] = 1;

    while(!q.empty()) {
        int u = q.front(); q.pop();
        cout << u << " ";
        for(auto &v : adj[u]) {
            if(!vis[v]) {
                vis[v] = 1;
                q.push(v);
            }
        }
    }
}
```

Why not mark visited later?



$\{ \cancel{a}, \cancel{b}, \cancel{c}, \cancel{d}, e, e, e \}$ } multiple times

Time complexity: $O(n \underline{tm})$

\nearrow \uparrow

nodes edges

Space complexity: $O(n)$

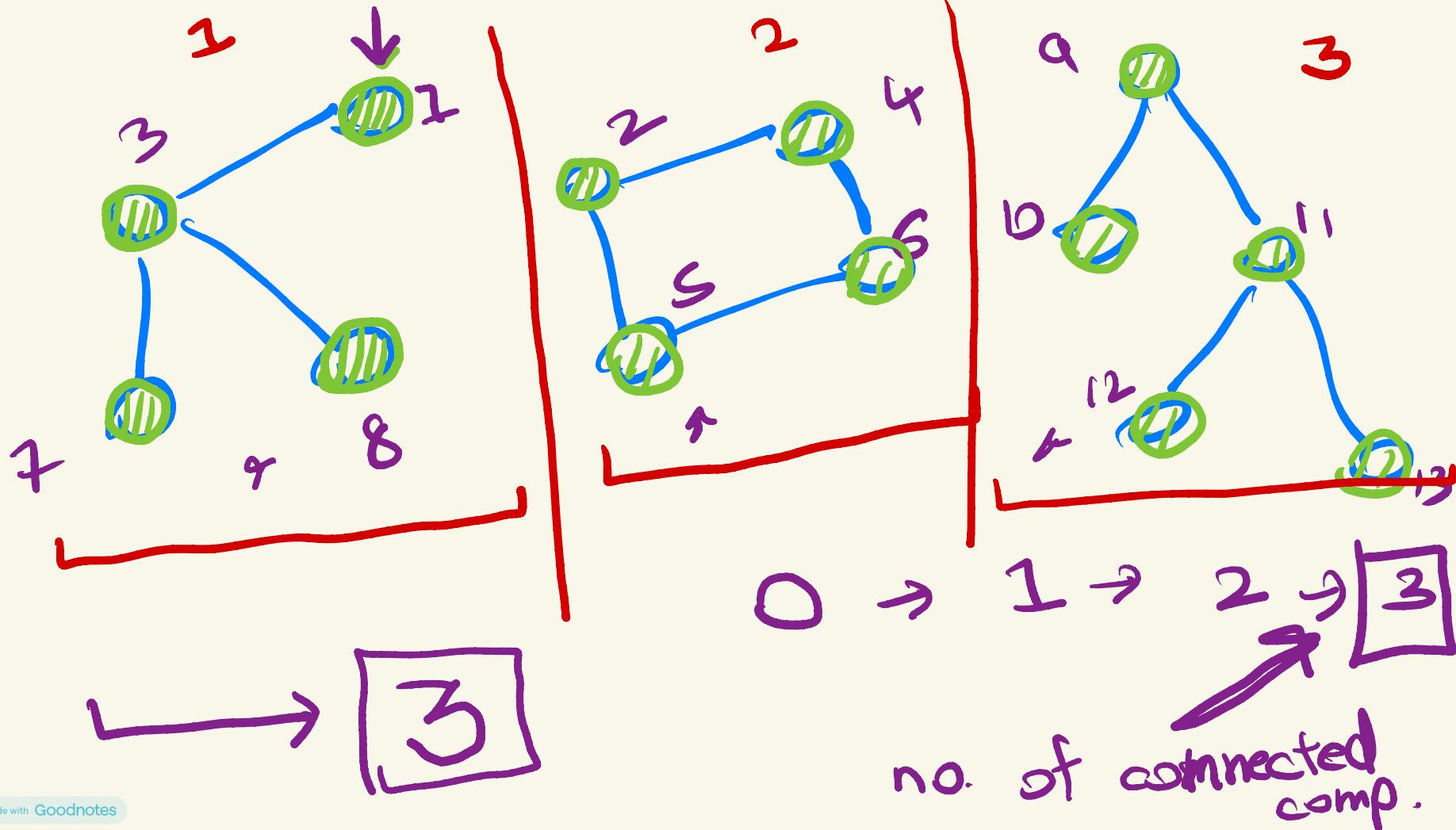
1000 nodes

$\lceil 10^6 \rceil$ edges



Problems to Consider:

- * 1. Given a Graph, Find the Number of Connected Components.
- * 2. Given a Graph, Find the Size of each Connected Component.
- * 3. Minimum Time to Reach each cell from a source node in an unweighted graph. → BFS



int count = 0; $O(n+m)$ ✓

for (int i = 1; i <= n; i++) {
 if (!vis[i]) {
 count++;
 → dfs(i);
 }
}

Printing size of each cc.

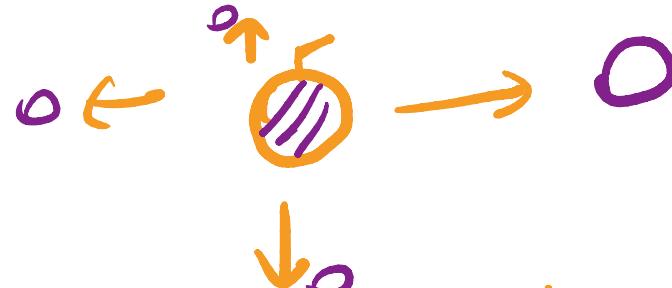
```
for (int i = 1; i <= n; i++) {  
    if (!vis[i]) {  
        int count = 0; color  
        → dfs(i, count);  
        cout < count << " ";  
    }  
}
```

dfs (node, & count) {

 vis[node] = 1 = color
 [count++;] ← only change

}

Graphs as Grids



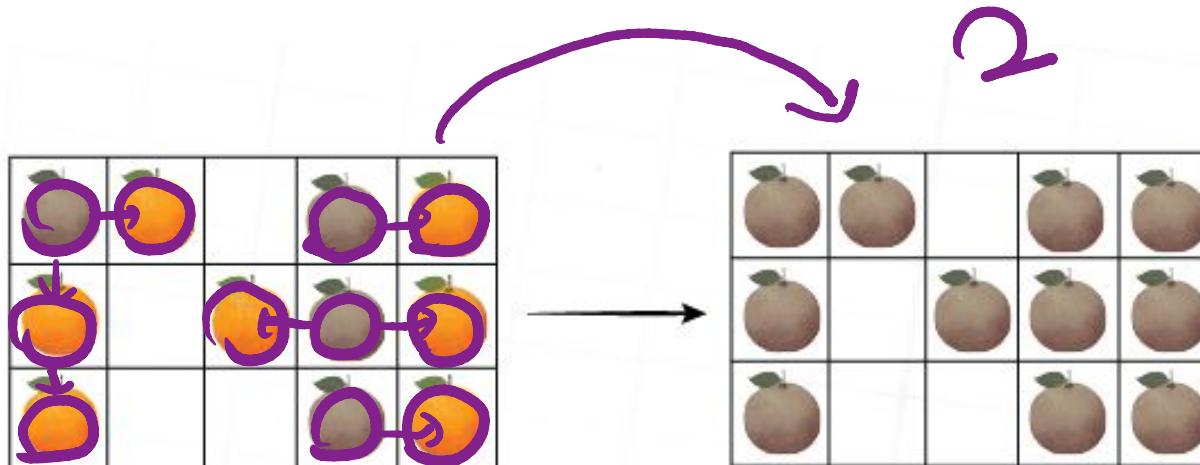
Consider this problem:

Rotten oranges Leetcode

You are given an $n * m$ grid where each cell is initially empty, or has a fresh or rotten orange. Each rotten orange every second infects its neighbouring oranges and they also become rotten. What is the minimum time required to make all oranges rotten in the grid



Example: (Answer is 2 seconds)



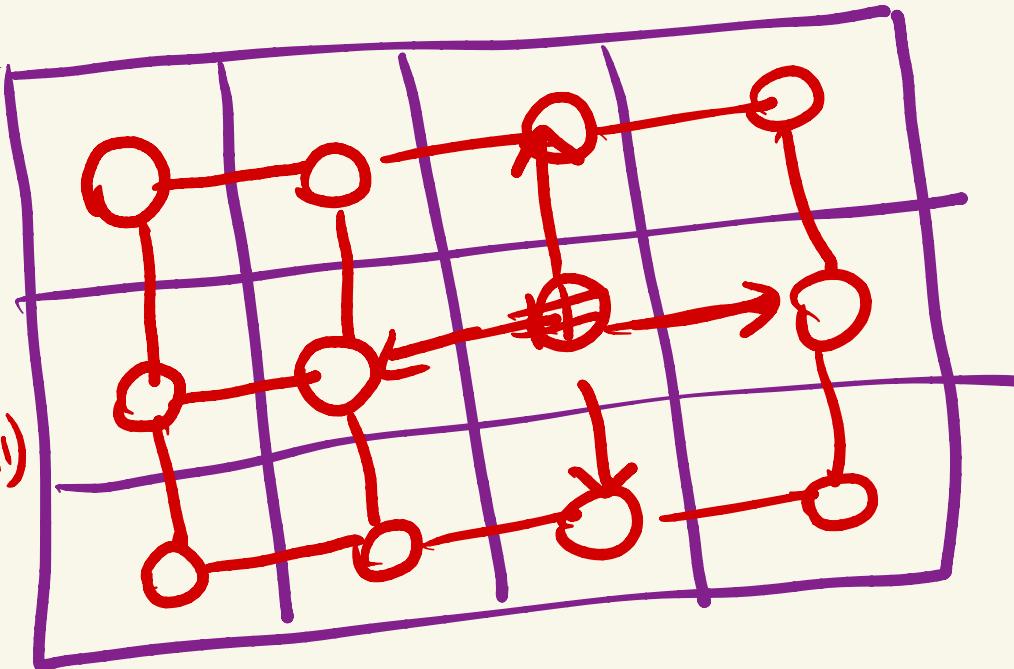
$(i-1, j)$

\uparrow

$\leftarrow (i, j-1) \quad (i, j) \rightarrow (i, j+1)$

\downarrow

$(i+1, j)$





Correlation Between Graphs and Grids



You can notice that a grid, is a just a graph where cell (i, j) is adjacent with cells $(i - 1, j)$, $(i + 1, j)$, $(i, j - 1)$, $(i, j + 1)$.

Now the task is just given some “special” nodes on the graph, to find the minimum time to visit all nodes via this “special” nodes.

We can use BFS, but insert all “special” nodes in the queue.

Concept of DxDy Arrays

```
[ Int dx[] = {-1, 1, 0, 0};  
  Int dy[] = {0, 0, 1, -1}; ]
```

↓ ↓ ↓
↑ ↑ ↑

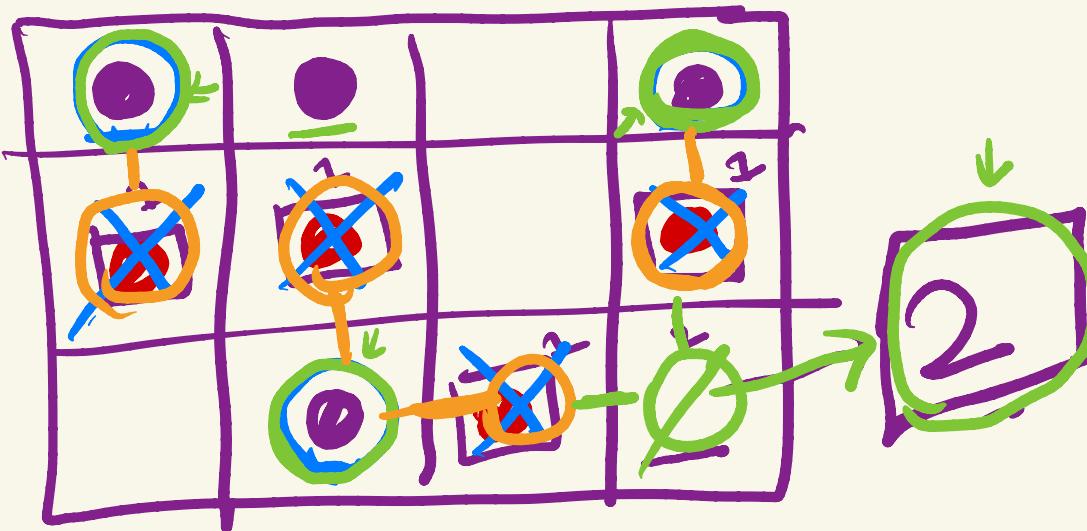
```
[ for(i=0; i<4; i++) {  
    newx = x + dx[i];  
    newy = y + dy[i]; } ]
```

If you iterate over indices i from 0, 1, 2, 3 and add $dx[i]$ to x and $dy[i]$ to y , you will notice that you are iterating over the adjacent cells of a cell in a grid.

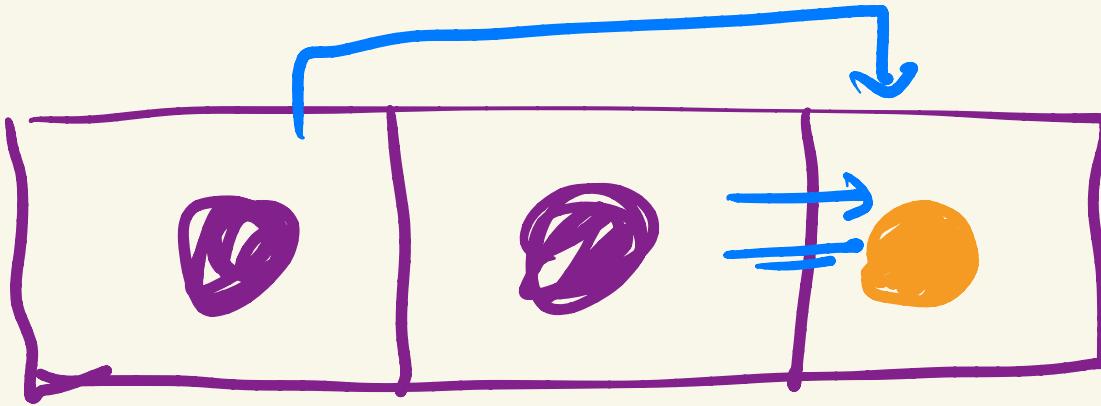
For Example for (x, y) : $(x - 1, y)$, $(x + 1, y)$, $(x, y + 1)$, $(x, y - 1)$

Find max ^{min} distance of an orange from rotten

$$n \times m \leq 10^6$$



$$\xrightarrow[1]{\text{BFS}} O(n^2 m^2) \xrightarrow[\text{Multisource}]{\text{BFS}} O(\underline{n}, \underline{m})$$



Brute Force : X wont work TLE

For each rotten orange do

BFS call

$O(n \cdot m) \rightarrow O(n \cdot m)$ BFS

[rotten or]

Multisource BFS :



Implementation (Continued on Next Page)

```
int minutes = 0, number0fOrangesLeft = 0;  
int dx[] = {1, -1, 0, 0};  
int dy[] = {0, 0, -1, 1}; ]dx dy  
queue<pair<int,int>>q;  
  
for(int i = 0; i < grid.size(); i++)  
{  
    for(int j = 0; j < grid[0].size(); j++)  
    {  
        if(grid[i][j] == 2) q.push({i, j});  
        if(grid[i][j] == 1) number0fOranges++;  
    } → rotten  
}  
}
```



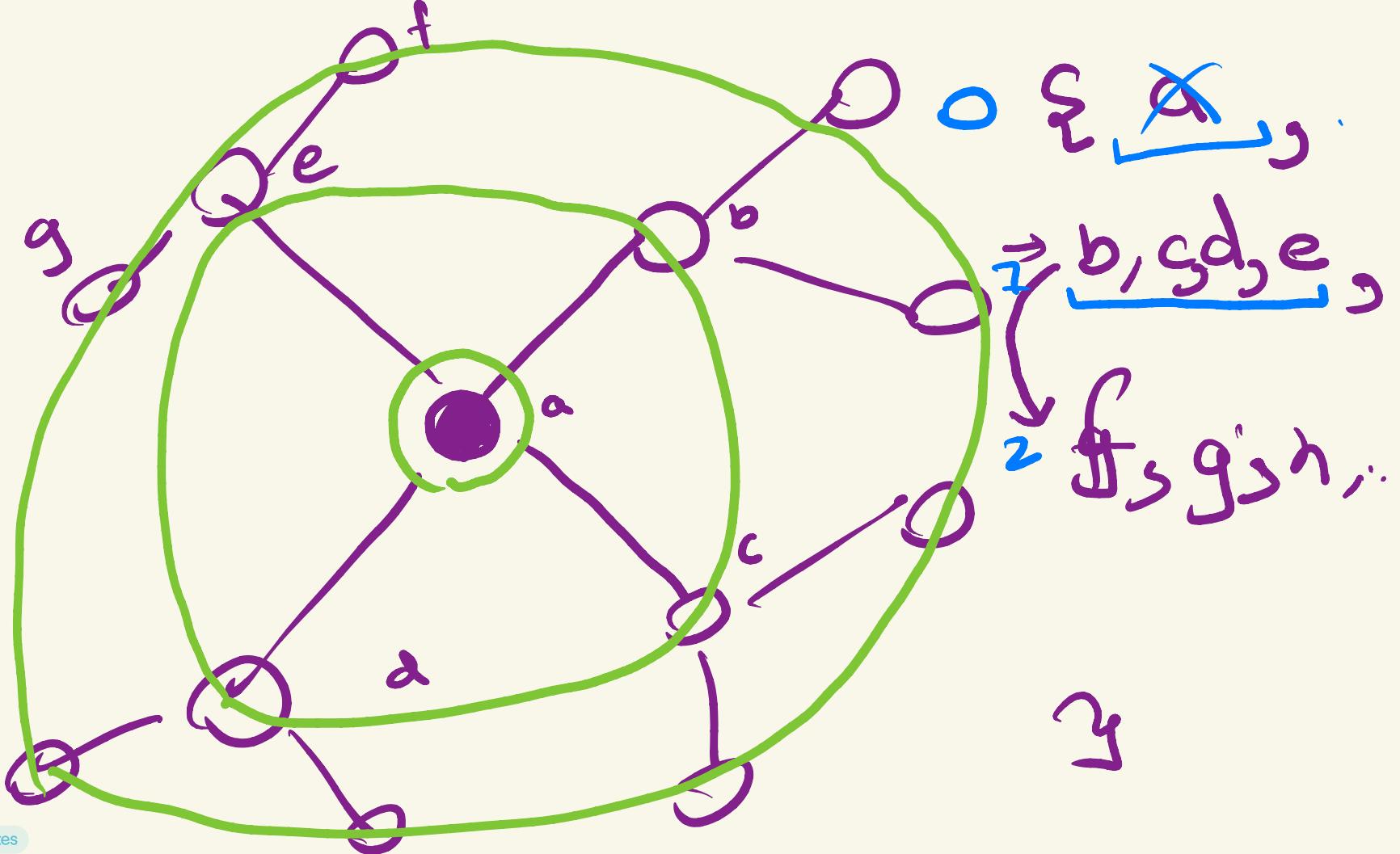
```
while(!q.empty()) {
    if(numberOfOrangesLeft == 0) break;
    minutes++;
    int n = q.size();
    for(int i = 0; i < n; i++)
    {
        auto [x, y] = q.front(); q.pop();
        for(int k = 0; k < 4; k++)
        {
            int X = x + dx[k];
            int Y = y + dy[k];
            if(X >= 0 && Y >= 0 && X < grid.size() && Y < grid.size() && grid[X][Y] == 1)
            {
                numberofOrangesLeft--;
                q.push({X, Y});
                grid[X][Y] = 2;
            }
        }
    }
}
```

Break

pair<int, int> cord = q.front()

check if inside
grid

→ minute

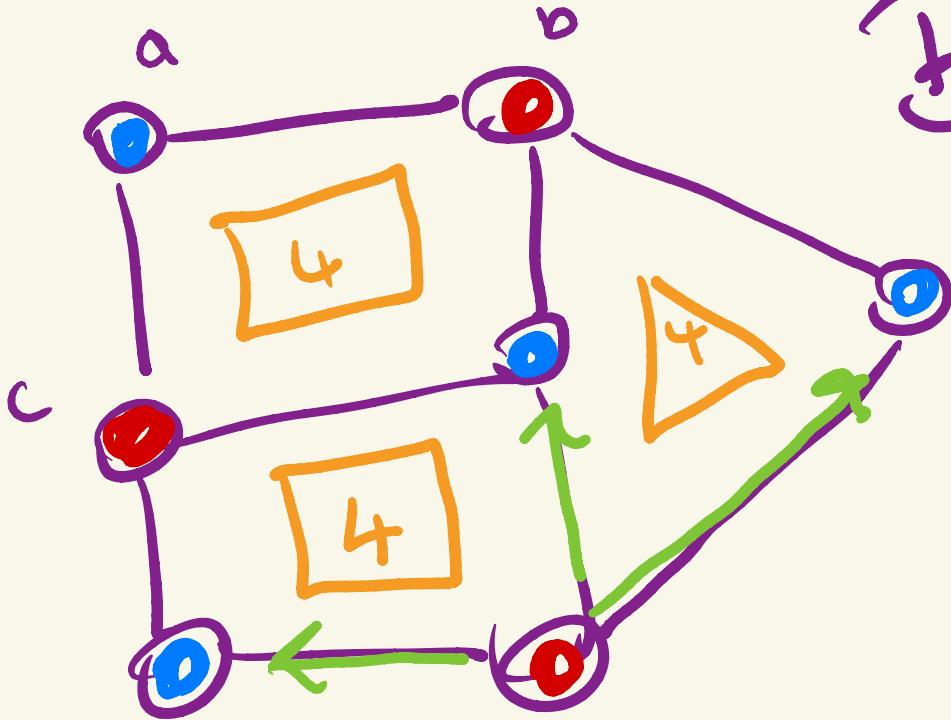




Bipartite Graphs

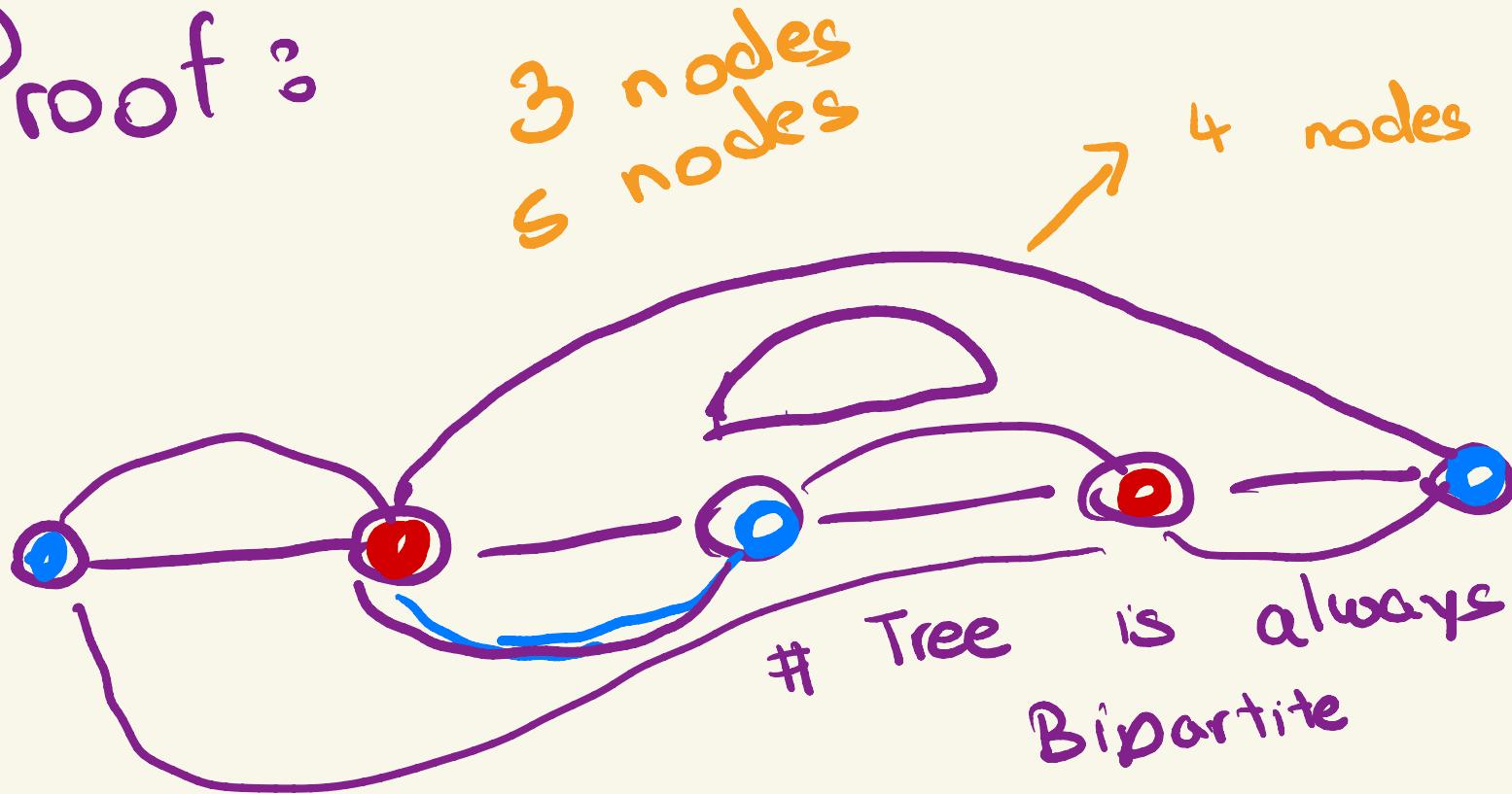
A graph is said to be bipartite, if and only if you colour the nodes with white or black and in the end for every node, its neighbour is collected in a different color.

Bipartite Graph



check if bipartite or not

Proof :



[# even len/ odd cycle] → Always Bipartite
no cycles not bipartite

node → all adj should be
diff colors. bool isB...

```
dfs (node, color) {  
    vis[node] = color.  
    for (v : adj[node]) {  
        if (vis[v] == 0) dfs(v, otherColor);  
        else {  
            if (vis[v] != otherColor)  
                is Bipartite = false.  
        }  
    }  
}
```

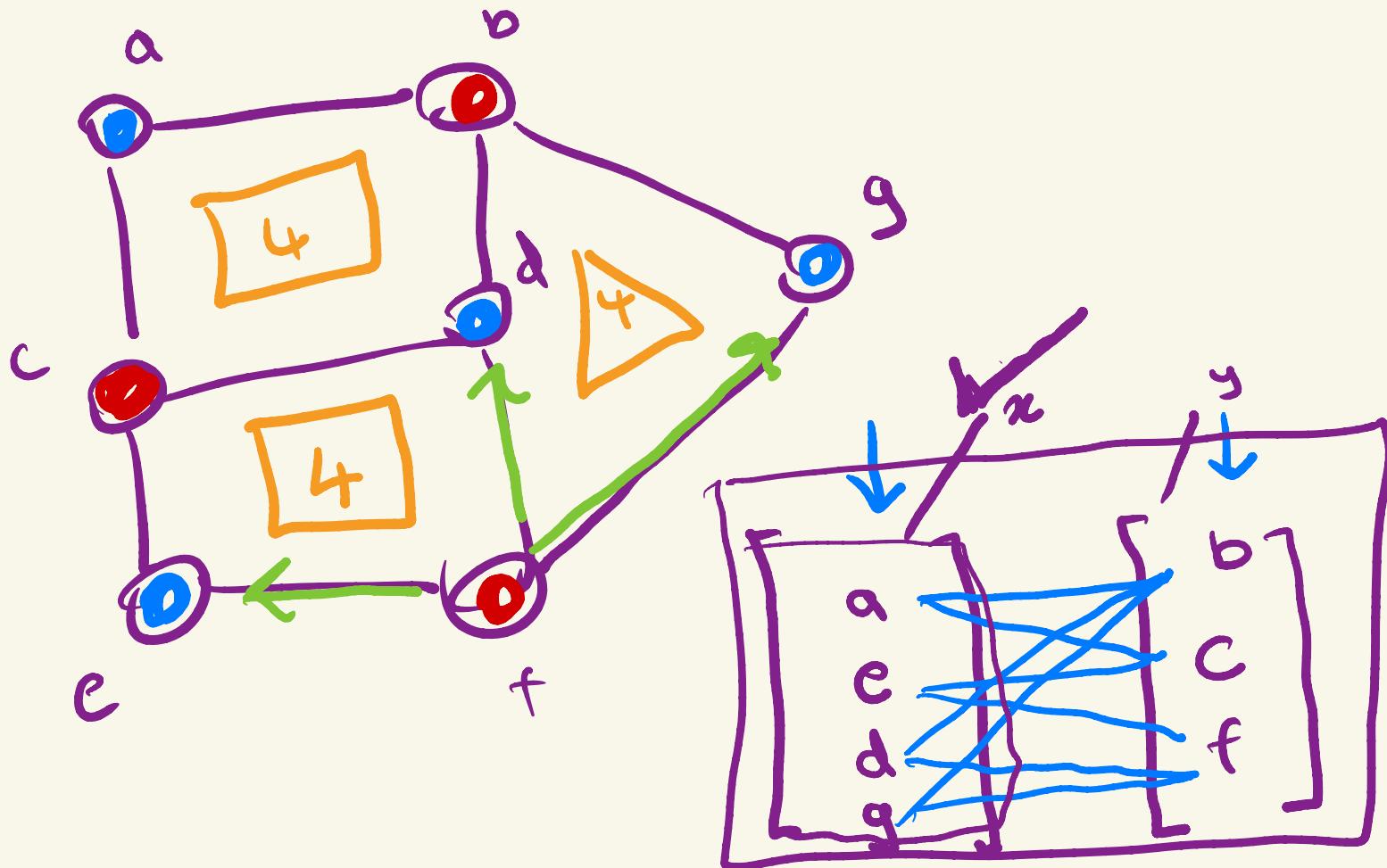
check if graph has
odd length cycle.

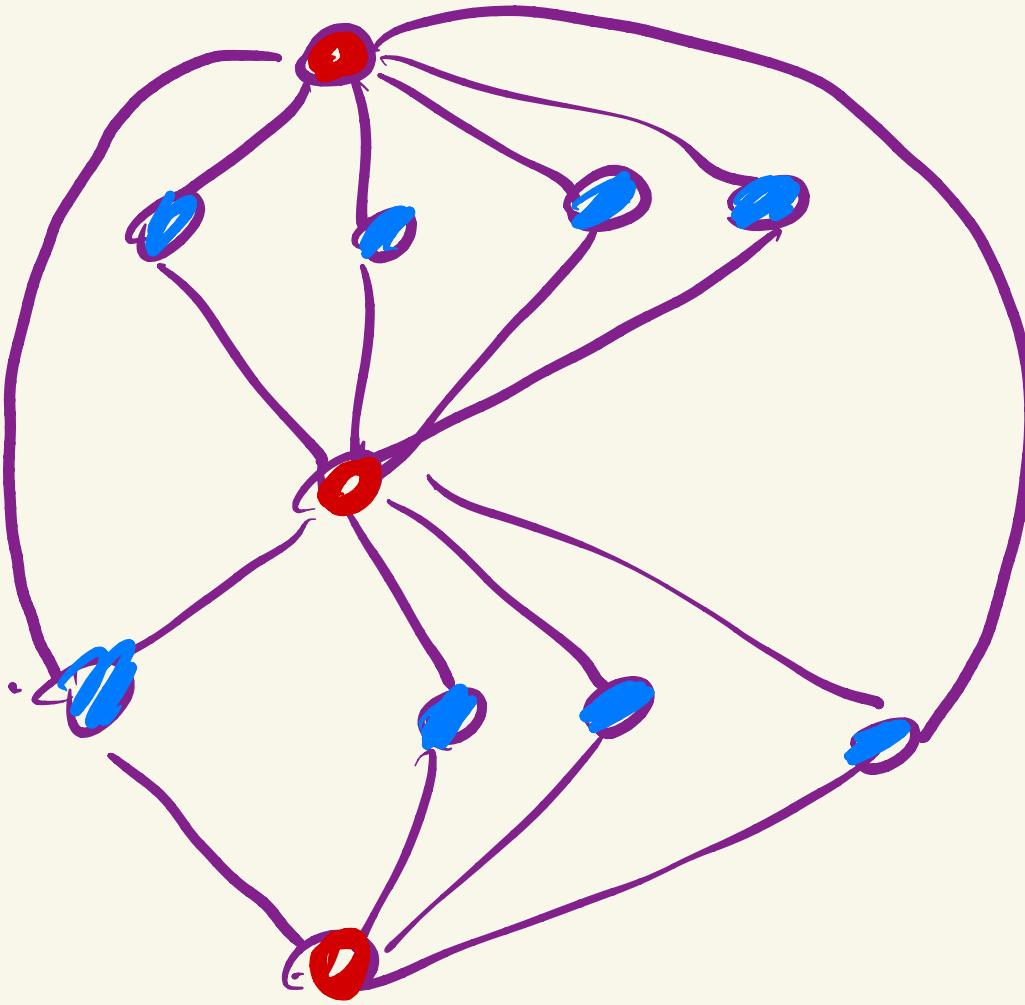
↳ Checking if graph is
Bipartite



Important Observation

- * Bipartite Graphs do not have odd length Cycles
- * Bipartite Graphs can be split exhaustively into 2 sets, where each set contains nodes of a particular color. Then edges in the graph will only go from one set to the other set.







Problem:

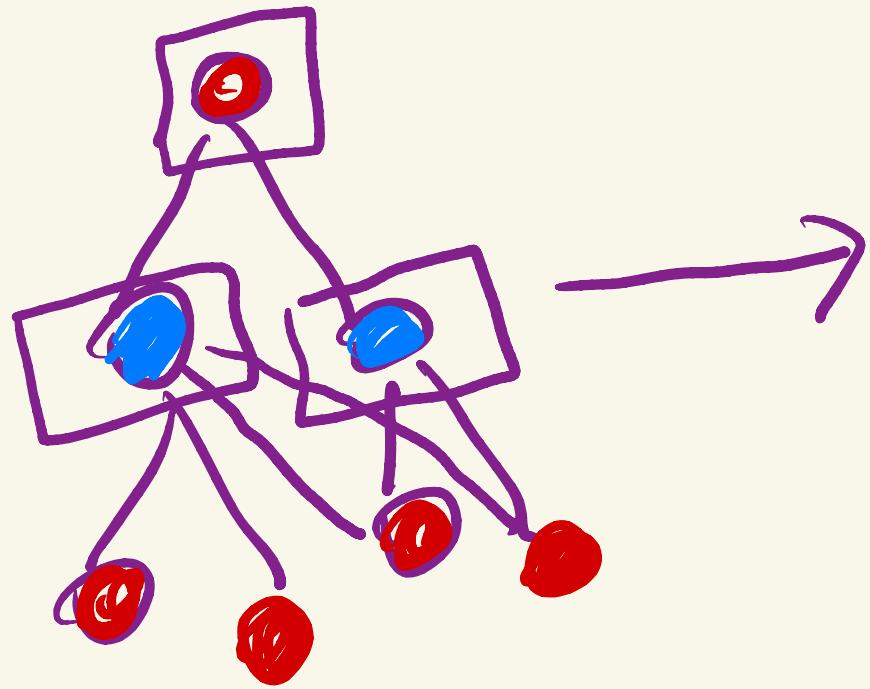
<https://codeforces.com/problemset/problem/862/b>

Mahmoud and Ehab continue their adventures! As everybody in the evil land knows, Dr. Evil likes bipartite graphs, especially trees.

A tree is a connected acyclic graph. A bipartite graph is a graph, whose vertices can be partitioned into 2 sets in such a way, that for each edge (u, v) that belongs to the graph, u and v belong to different sets. You can find more formal definitions of a tree and a bipartite graph in the notes section below.

Dr. Evil gave Mahmoud and Ehab a tree consisting of n nodes and asked them to add edges to it in such a way, that the graph is still bipartite. Besides, after adding these edges the graph should be simple (doesn't contain loops or multiple edges). What is the maximum number of edges they can add?

A loop is an edge, which connects a node with itself. Graph doesn't contain multiple edges when for each pair of nodes there is no more than one edge between them. **A cycle and a loop aren't the same .**



blue red Max number of edges
↓ ↓ you can add ??
 $x \cdot y - (n - 1)$

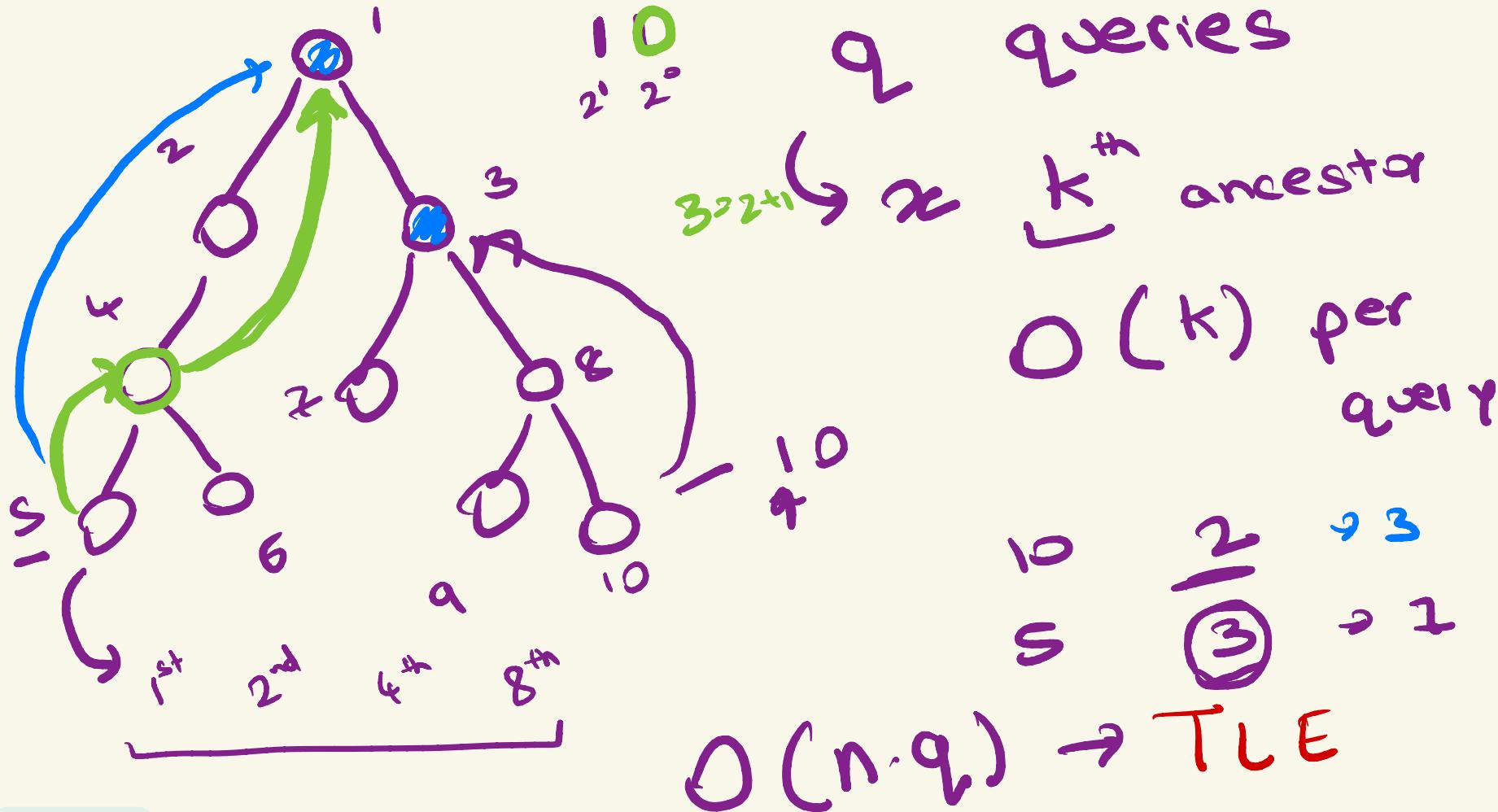
Implementation

```
int col[2] = {0, 0};  
void dfs(int node, int parent, int color, vector<vector<int>>&adj) {  
    col[color]++;  
    for(auto &i : adj[node]) {  
        if(i != parent) {  
            dfs(i, node, color ^ 1, adj);  
        }  
    }  
}  
  
int main() {  
    ios_base::sync_with_stdio(false);  
    cin.tie(NULL);  
  
    int n; cin >> n;  
  
    vector<vector<int>>adj(n + 1);  
  
    for(int i = 1; i < n; i++) {  
        int u, v; cin >> u >> v;  
        adj[u].push_back(v);  
        adj[v].push_back(u);  
    }  
  
    dfs(1, 1, 0, adj);  
    cout << 1ll * col[0] * col[1] - (n - 1) << "\n";  
}
```

Tree



initial nodes



$x \rightarrow \sum \text{powers of } 2$

$n^{2^k} \text{ parent}$

$O(\log_2 n)$

node $\rightarrow O(\log_2 r)$

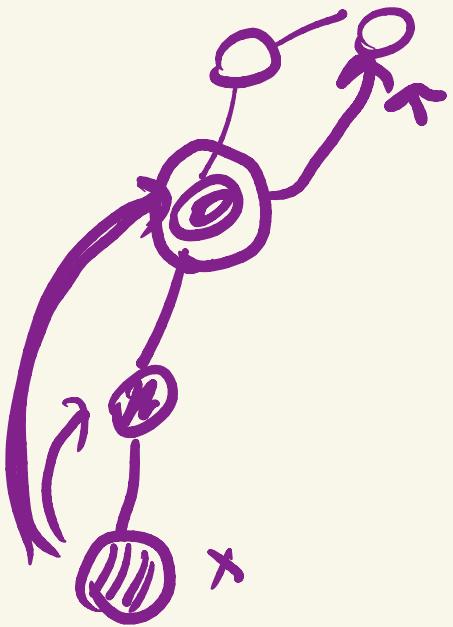
parents

$i \in \{0, 1\}$

$$17 \rightarrow 16 + 1$$

$$2^4 + 2^0$$

$O(q \cdot \log(n))$



2^0
 \downarrow
 P

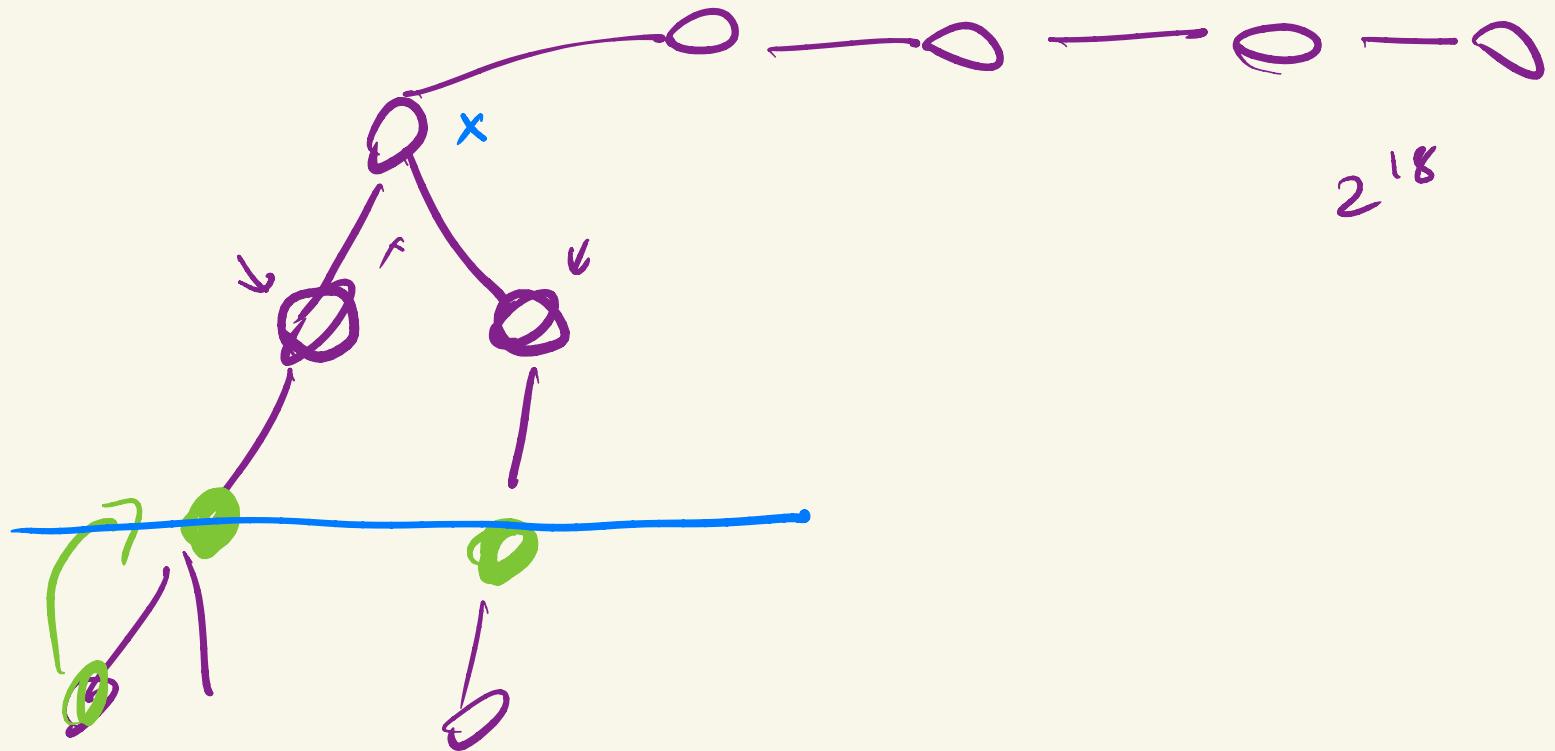
2^1
 2^2

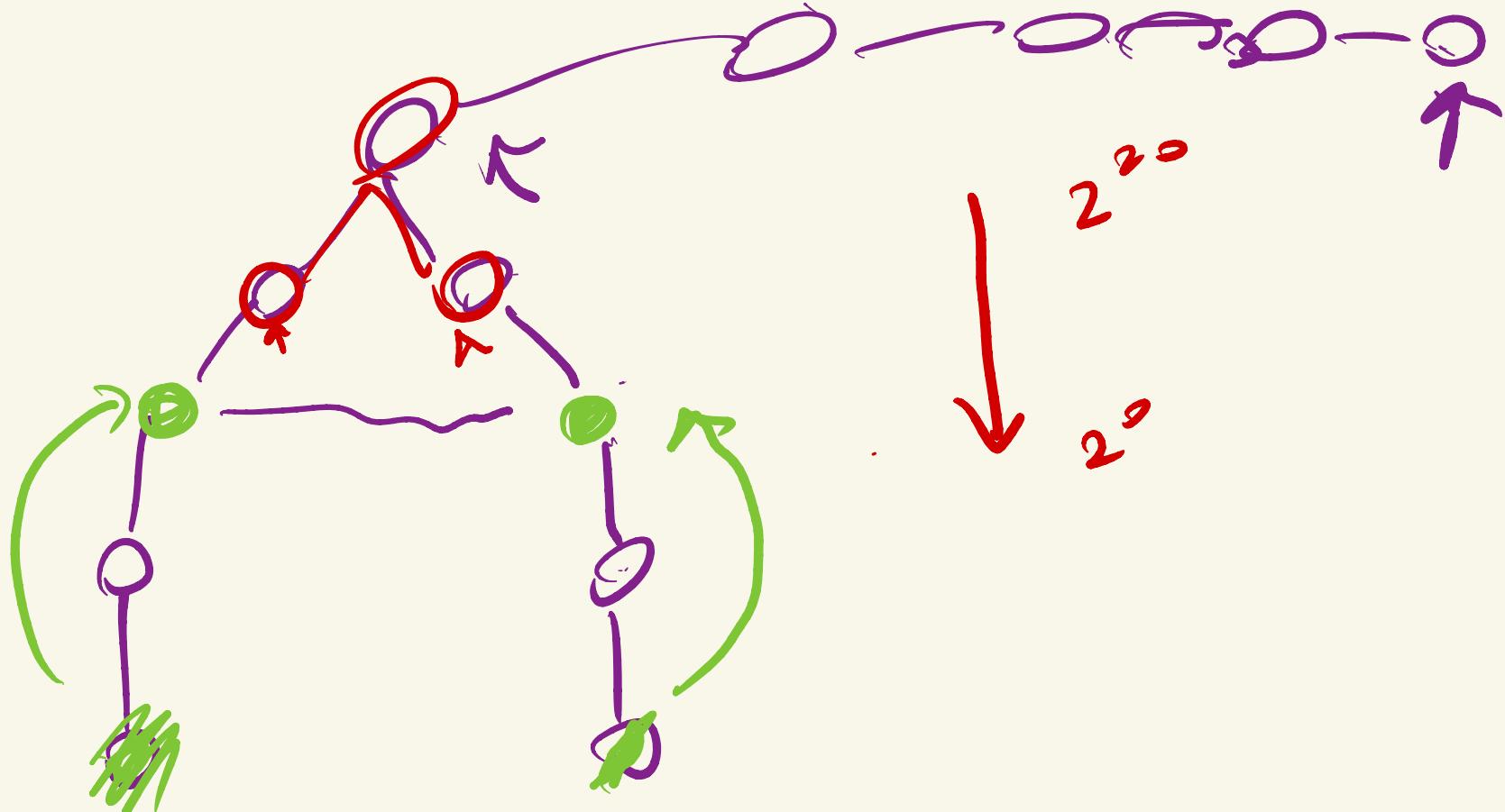
2^0 "parent of
 your 2^0 th parent

$$2^i = 2^{i-1} + 2^{i-1}$$

\searrow
 parent $[x][i] = \text{parent}[\text{par}[x][i-1]][i-1]$

$O(n \log n + q \log n)$





8^{th}

7^{th}

parent

$$(2^3) - 1 = 2^2 + 2^1 + 2^0$$

$$2^2 + 2^1 + 2^0 \rightarrow 7$$

Binary Lifting =
Binary Exp