

# k neighbours classifier

(k-Nearest Neighbors)

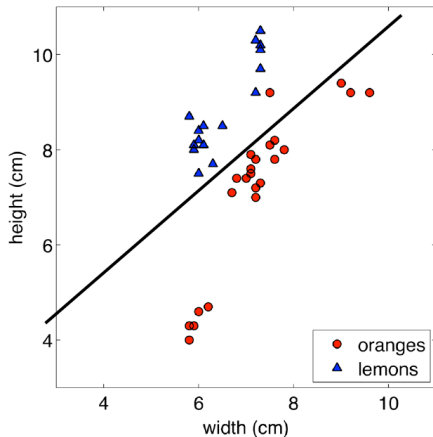
Predictive Analytics

Based on materials by **Fragkiskos D. Malliaros**.

École Polytechnique / CentraleSupélec (Université Paris–Saclay).

# Non-parametric learning

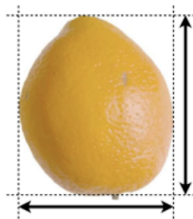
# Classification: Oranges and Lemons



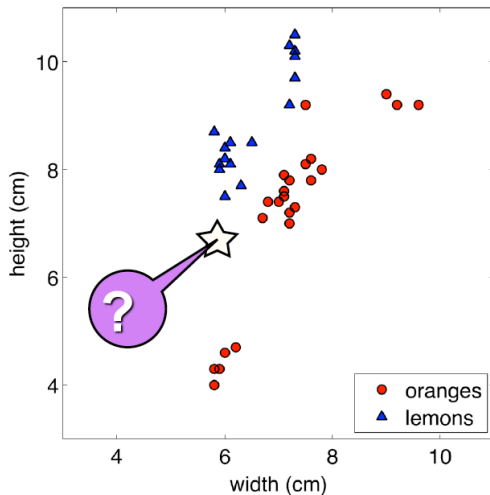
- We can construct a linear decision boundary:

$$y = \text{sign}(\theta_0 + \theta_1 x_1 + \theta_2 x_2)$$

- Parametric model
- Fixed number of parameters



# Classification as Induction

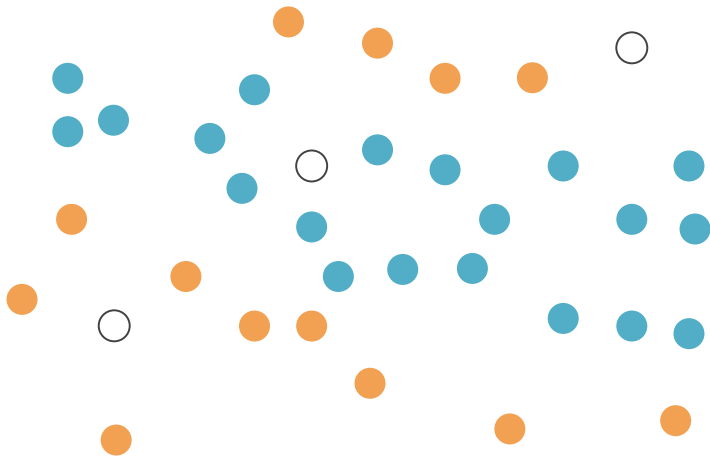


- Is there alternative way to formulate the classification problem?
- Classification as induction
  - Comparison to instances already seen in training
  - **Non-parametric learning**

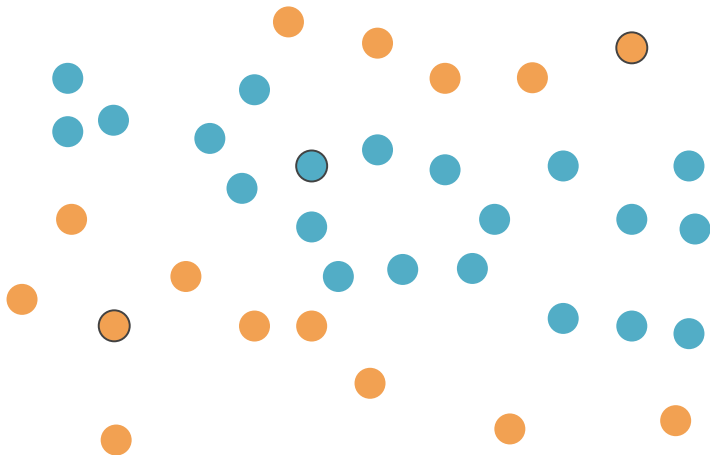
# Non-parametric Learning

- Non-parametric learning algorithm (does not mean NO parameters)
  - The complexity of the decision function grows with the number of data points
    - Contrast with linear regression ( $\approx$  as many parameters as features)
  - Usually: decision function is expressed directly in terms of the training examples
  - Examples:
    - k-nearest neighbors (today's lecture)
    - Tree-based methods (lecture 6)
    - Some cases of SVMs (lecture 7)

# How Would You Color the Blank Circles?

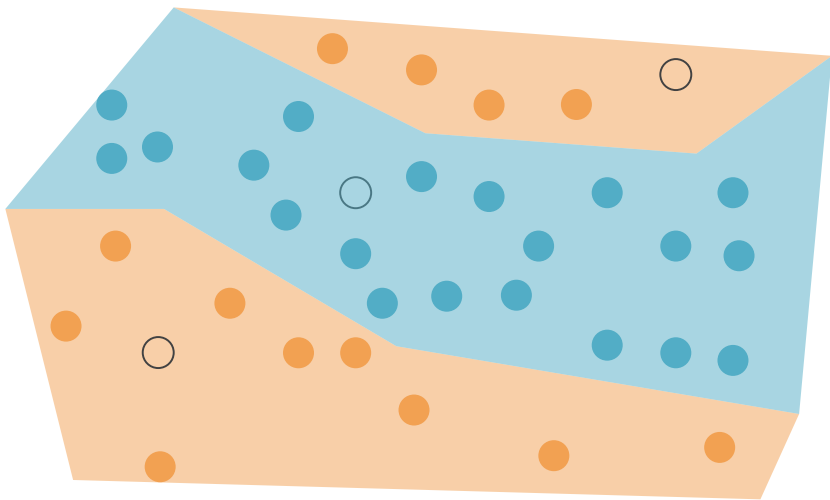


# How Would You Color the Blank Circles?





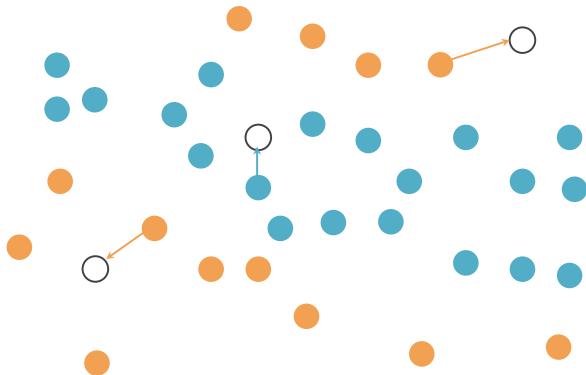
# Partitioning the Space



The training data partitions the entire space

# Nearest Neighbors – The Idea

- **Learning:**
  - Store all the training examples
- **Prediction:**
  - For a point  $x$ : assign the label of the training example closest to it



# Nearest Neighbors – The Idea

- Learning:
  - Store all the training examples
- Prediction:
  - For a point  $x$ : assign the label of the training example closest to it
  - Classification
    - Majority vote: predict the class of the most frequent label among the  $k$  neighbors
  - Regression
    - Predict the average of the labels of the  $k$  neighbors

# Instance-based Learning

- Learning
  - Store training instances
- Prediction
  - Compute the label for a new instance based on its similarity with the stored instances
- Also called lazy learning
- Similar to case-based reasoning
  - Doctors treating a patient based on how patients with similar symptoms were treated
  - Judges ruling court cases based on legal precedent

Where the magic happens!



similarity

# Computing distances and similarities

# Distance Function

- Distance function

$$d : \mathcal{X} \rightarrow \mathbb{R}_+$$

- Properties of a distance function (or metric)
  - $d(\mathbf{x}, \mathbf{z}) \geq 0$  non-negativity
  - $d(\mathbf{x}, \mathbf{x}) = 0$  identity of indiscernibles
  - $d(\mathbf{x}, \mathbf{z}) = d(\mathbf{z}, \mathbf{x})$  symmetry
  - $d(\mathbf{x}, \mathbf{z}) \leq d(\mathbf{x}, \mathbf{u}) + d(\mathbf{u}, \mathbf{z})$  triangle inequality

# Distance Between Instances

$$\mathbf{x} \in \mathbb{R}^n$$

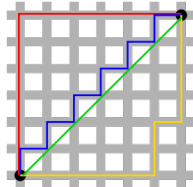
- Euclidean distance (L2)

$$d(\mathbf{x}^1, \mathbf{x}^2) = \|\mathbf{x}^1 - \mathbf{x}^2\|_2 = \sqrt{\sum_{j=1}^n (x_j^1 - x_j^2)^2}$$

- Manhattan distance (L1)

$$d(\mathbf{x}^1, \mathbf{x}^2) = \|\mathbf{x}^1 - \mathbf{x}^2\|_1 = \sum_{j=1}^n |x_j^1 - x_j^2|$$

Manhattan distance: The sum of the horizontal and vertical distances between points on a grid



Source: Wikipedia

- Lp-norm

$$d(\mathbf{x}^1, \mathbf{x}^2) = \|\mathbf{x}^1 - \mathbf{x}^2\|_p = \left( \sum_{j=1}^n |x_j^1 - x_j^2|^p \right)^{1/p}$$

# From Distance to Similarity

- Pearson's correlation

$$s = \frac{1}{1 + d}$$

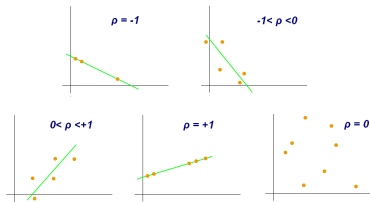
$$\rho(\mathbf{x}, \mathbf{z}) = \frac{\sum_{j=1}^n (x_j - \bar{x})(z_j - \bar{z})}{\sqrt{\sum_{j=1}^n (x_j - \bar{x})^2} \sqrt{\sum_{j=1}^n (z_j - \bar{z})^2}}$$

$$\bar{x} = \frac{1}{n} \sum_{j=1}^n x_j$$

- Assuming that the data is centered

$$\rho(\mathbf{x}, \mathbf{z}) = \frac{\sum_{j=1}^n x_j z_j}{\sqrt{\sum_{j=1}^n x_j^2} \sqrt{\sum_{j=1}^n z_j^2}}$$

Geometric interpretation?



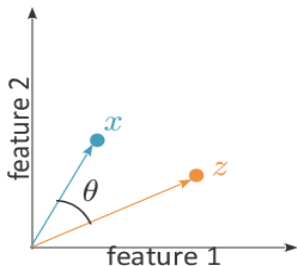


# Pearson's Correlation

- Pearson's correlation (centered data)

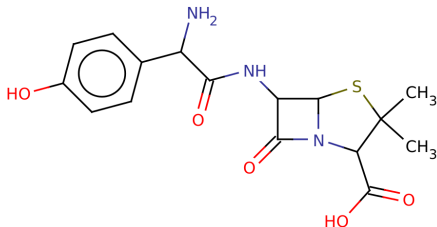
$$\rho(\mathbf{x}, \mathbf{z}) = \frac{\sum_{j=1}^n x_j z_j}{\sqrt{\sum_{j=1}^n x_j^2} \sqrt{\sum_{j=1}^n z_j^2}} = \frac{\overset{\text{inner product}}{\langle \mathbf{x}, \mathbf{z} \rangle}}{\|\mathbf{x}\| \|\mathbf{z}\|} = \cos \theta$$

- Cosine similarity:** the dot product can be used to measure similarities between vectors

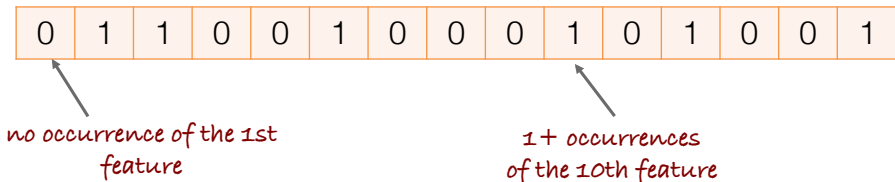


# Categorical Features

- Represent objects as the **list of presence/absence (or counts) of features** that appear in it
- **Example:** molecules
  - Features: atoms and bonds of a certain type
  - C, H, S, O, N, ...
  - O-H, O=C, C-N, ...



# Binary Representation (1/2)



- **Hamming distance** between two binary representations
  - Number of bits that are different

$$d(\mathbf{x}^1, \mathbf{x}^2) = \sum_{j=1}^n (x_j^1 \text{ XOR } x_j^2)$$

- Equivalent to the L1 distance

$$d(\mathbf{x}^1, \mathbf{x}^2) = \sum_{j=1}^n |x_j^1 - x_j^2|$$

XOR operator

Input		Output
A	B	
0	0	0
0	1	1
1	0	1
1	1	0

# Binary Representation (2/2)

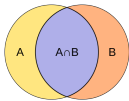


no occurrence of the 1st  
feature

1 + occurrences  
of the 10th feature

- Jaccard similarity (or Tanimoto similarity)
  - Number of shared features (normalized)

$$J(\mathbf{x}^1, \mathbf{x}^2) = \frac{\sum_{j=1}^n (x_j^1 \text{ AND } x_j^2)}{\sum_{j=1}^n (x_j^1 \text{ OR } x_j^2)}$$



AND operator

Input		Output
A	B	
0	0	0
0	1	0
1	0	0
1	1	1

OR operator

Input		Output
A	B	
0	0	0
0	1	1
1	0	1
1	1	1

# Example

$x = 010101001$

$y = 010011000$

- Hamming distance

$x = 010$ **1** $0100$ **1**

$y = 010$ **0** $11000$

Thus,  $d(x,y) = 3$

- Jaccard similarity

$$J = (\# \text{ of } 11) / (\# \text{ of } 01 + \# \text{ of } 10 + \# \text{ of } 11) \\ = (2) / (1 + 2 + 2) = 2 / 5 = 0.4$$

**Let's go back to the  
kNN classifier**

# Nearest Neighbor Algorithm

- Training examples in the Euclidean space  $\mathbf{x} \in \mathbb{R}^n$
- **Idea:** The label of a test data point is estimated from the known value of the **nearest training example**
  - The distance is typically defined to be the Euclidean one

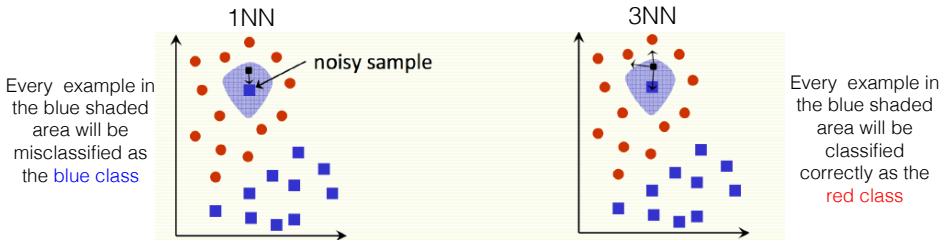
## Algorithm 1

1. Find example  $(\mathbf{x}^*, y^*)$  from the stored training set closest to the test instance  $\mathbf{x}$ . That is:

$$\mathbf{x}^* = \operatorname{argmin}_{\mathbf{x}^i \in \text{train. set}} d(\mathbf{x}^i, \mathbf{x})$$

2. Output  $y(\mathbf{x}) = y^*$  (The output label)

# k-Nearest Neighbors (kNN) Algorithm



- Algorithm 1 is sensitive to mis-labeled data ('class noise')
- Consider the **vote** of the **k** nearest neighbors (majority vote)

## Algorithm 2

- Find **k** examples  $(x^{*i}, y^{*i})$ ,  $i=1, \dots, k$  closest to the test instance **x**
- The output is the majority class

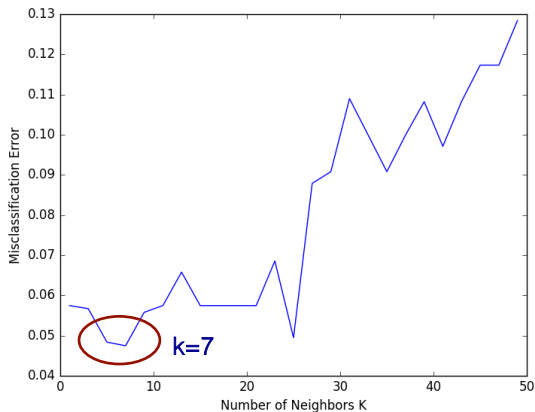


# Choice of Parameter $k$ (1/2)

- **Small  $k$ :** noisy decision
  - The idea behind using more than 1 neighbors is to average out the noise
- **Large  $k$** 
  - May lead to better prediction performance
  - If we set  $k$  too large, we may end up looking at samples that are not neighbors (are far away from the point of interest)
  - Also, computationally intensive. Why?
  - **Extreme case:** set  $k=m$  (number of points in the dataset)
    - For classification: the majority class
    - For regression: the average value

# Choice of Parameter k (2/2)

Set  $k$  by cross validation, by examining the misclassification error



Rule of thumb:

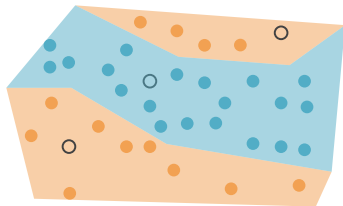
$$k = \sqrt{m}$$

$m$ : # of training instances

Source: <https://kevinzakka.github.io/2016/07/13/k-nearest-neighbor/>

# Advantages of kNN

- Training is very fast
  - Just store the training examples
  - Can use smart indexing procedures to speed-up testing
- The training data is part of the 'model'
  - Useful in case we want to do something else with it
- Quite robust to noisy data
  - Averaging  $k$  votes
- Can learn complex functions (implicitly)



# Drawbacks of kNN

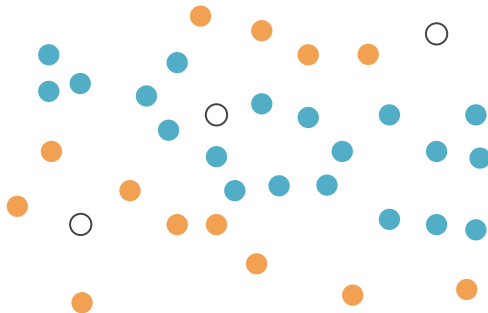
- Memory requirements
  - Must store all training data
- Prediction can be slow (will figure it out by yourself in the lab)
  - Complexity of labeling 1 new data point:  $O(knm)$
  - But kNN works best with lots of samples
  - Can we further improve the running time?
    - Efficient data structures (e.g., k-D trees)
    - Approximate solutions based on hashing
- High dimensional data and the curse of dimensionality
  - Computation of the distance in a high dimensional space may become meaningless
  - Need more training data
  - Dimensionality reduction

# kNN – Some More Issues

- Normalize the scale of the attributes
- Simple option: linearly scale the range of each feature to be, e.g., in the range of  $[0,1]$
- Linearly scale each dimension to have 0 mean and variance 1
  - Compute the mean  $\mu$  and variance  $\sigma^2$  for an attribute  $x_j$  and scale:  $(x_j - \mu)/\sigma$

# Decision Boundary of kNN

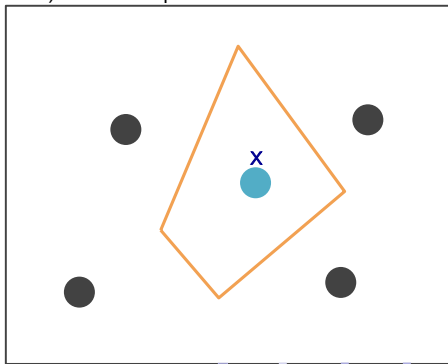
- Decision boundary in classification
  - Line separating the positive from negative regions
- What decision boundary is the kNN building?
  - The nearest neighbors algorithm does not explicitly compute decision boundaries, but those can be inferred



# Voronoi Tessellation

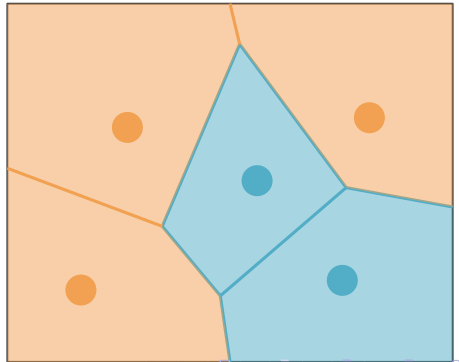
Consider the case of 1NN

- Voronoi cell of  $x$ :
  - Set of all points of the space closer to  $x$  than any other point of the training set
  - Polyhedron
- Voronoi tessellation (or diagram) of the space
  - Union of all Voronoi cells



# Voronoi Tessellation

- The Voronoi diagram defines the decision boundary of the 1NN
- The kNN algorithms also partitions the space but in a more complex way



Wikipedia: [https://en.wikipedia.org/wiki/Voronoi\\_diagram](https://en.wikipedia.org/wiki/Voronoi_diagram)



# kNN Variants

- Weighted kNN
  - Weight the vote of each neighbor  $x_i$  according to the distance to the test point  $x$

$$w_i = \frac{1}{d(x, x_i)^2}$$

- Other kernel functions can be used to weight the distance of neighbors

Source: [https://epub.ub.uni-muenchen.de/1769/1/paper\\_399.pdf](https://epub.ub.uni-muenchen.de/1769/1/paper_399.pdf)

# scikit-learn



<http://scikit-learn.org/stable/modules/generated/sklearn.neighbors.KNeighborsClassifier.html>