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https://www.kaggle.com/c/dogs-vs-cats/data

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Dogs vs. Cats

Create an algorithm to distinguish dogs from cats

215 teams · 5 years ago

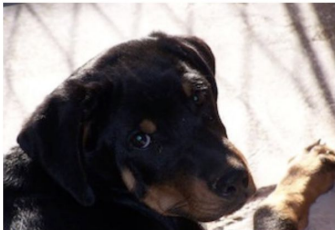
[Overview](#) [Data](#) [Kernels](#) [Discussion](#) [Leaderboard](#) [Rules](#) [Team](#)

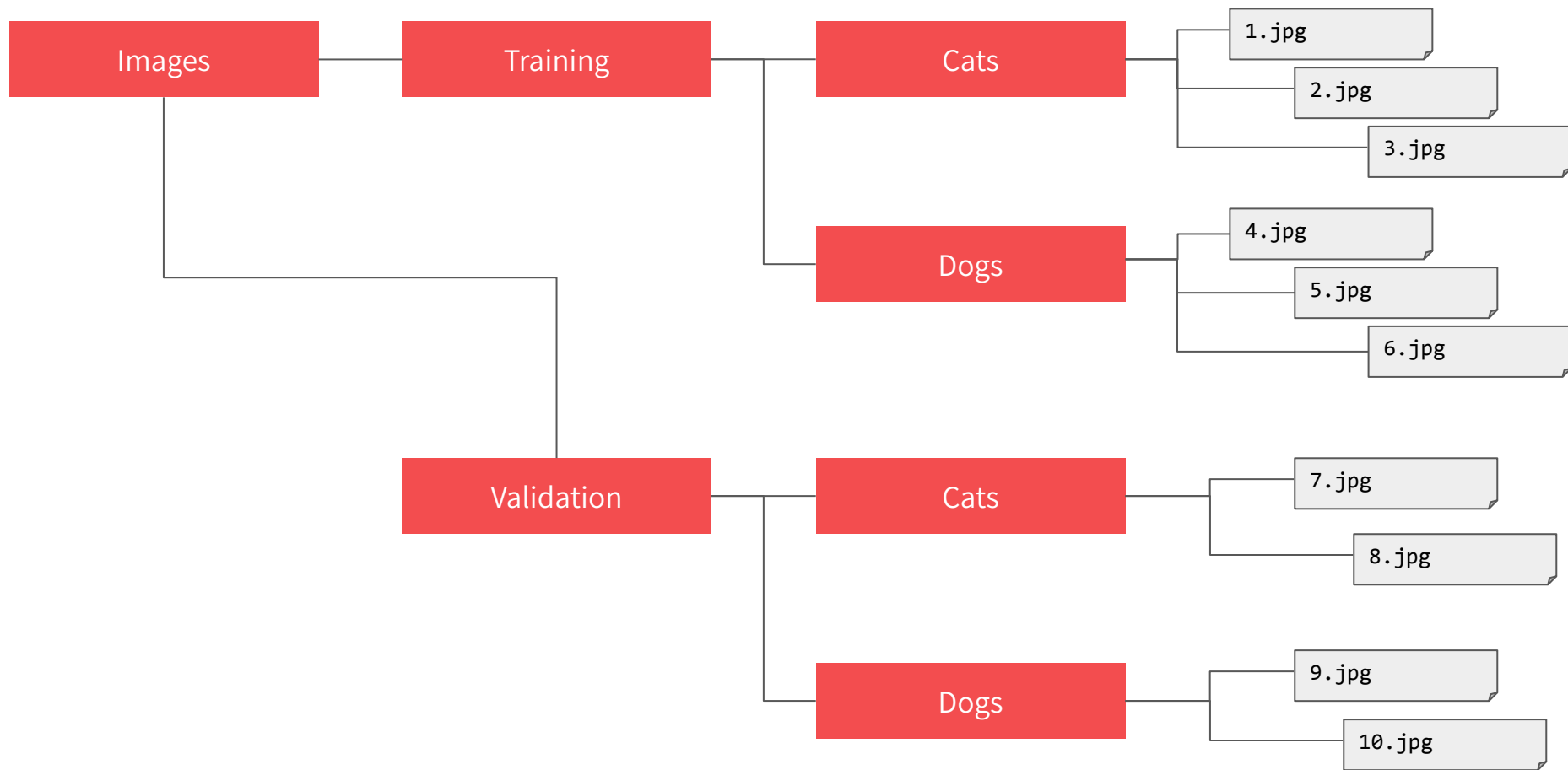
Data Description

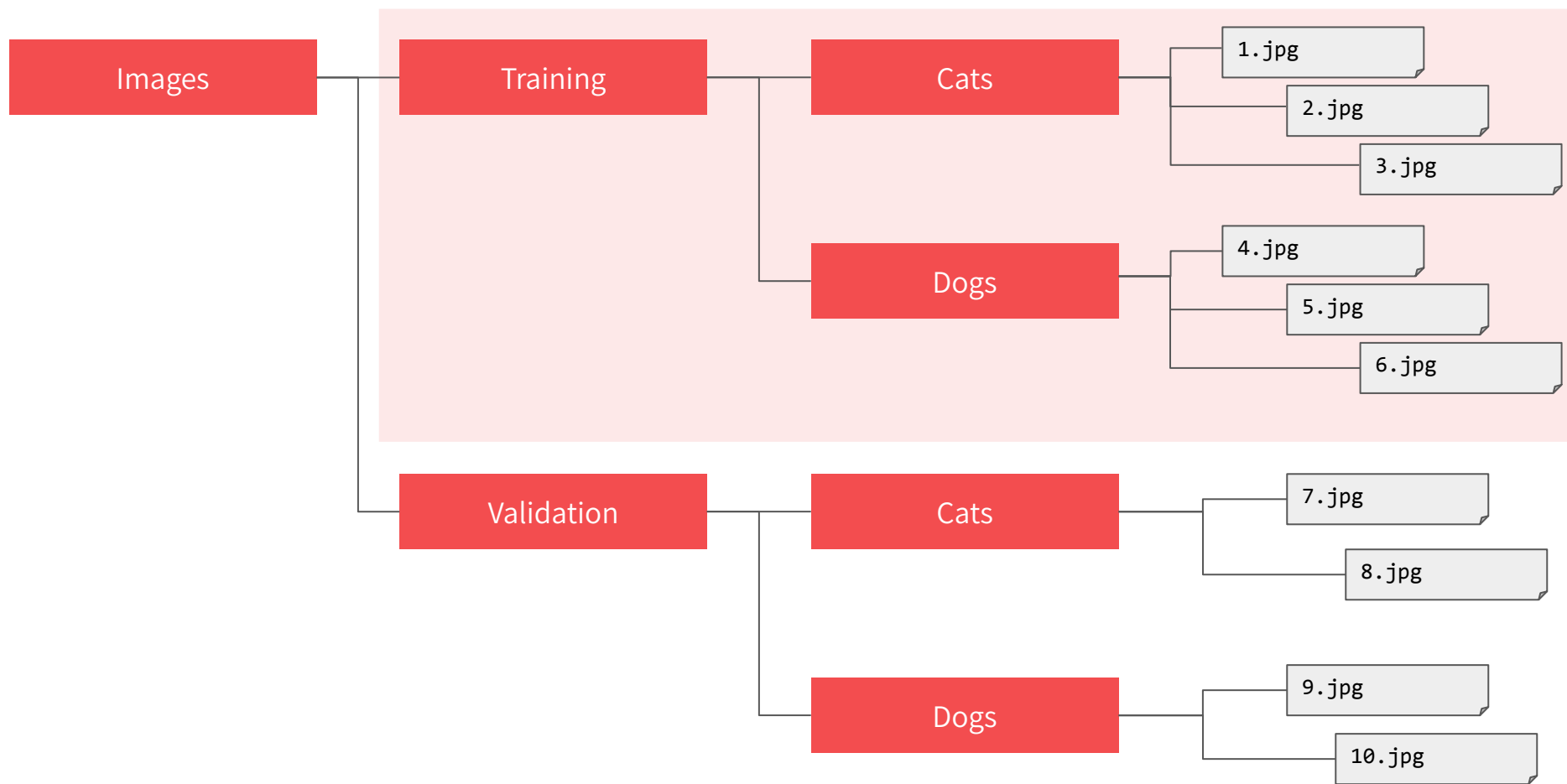
The training archive contains 25,000 images of dogs and cats. Train your algorithm on these files and predict the labels for test1.zip (1 = dog, 0 = cat).

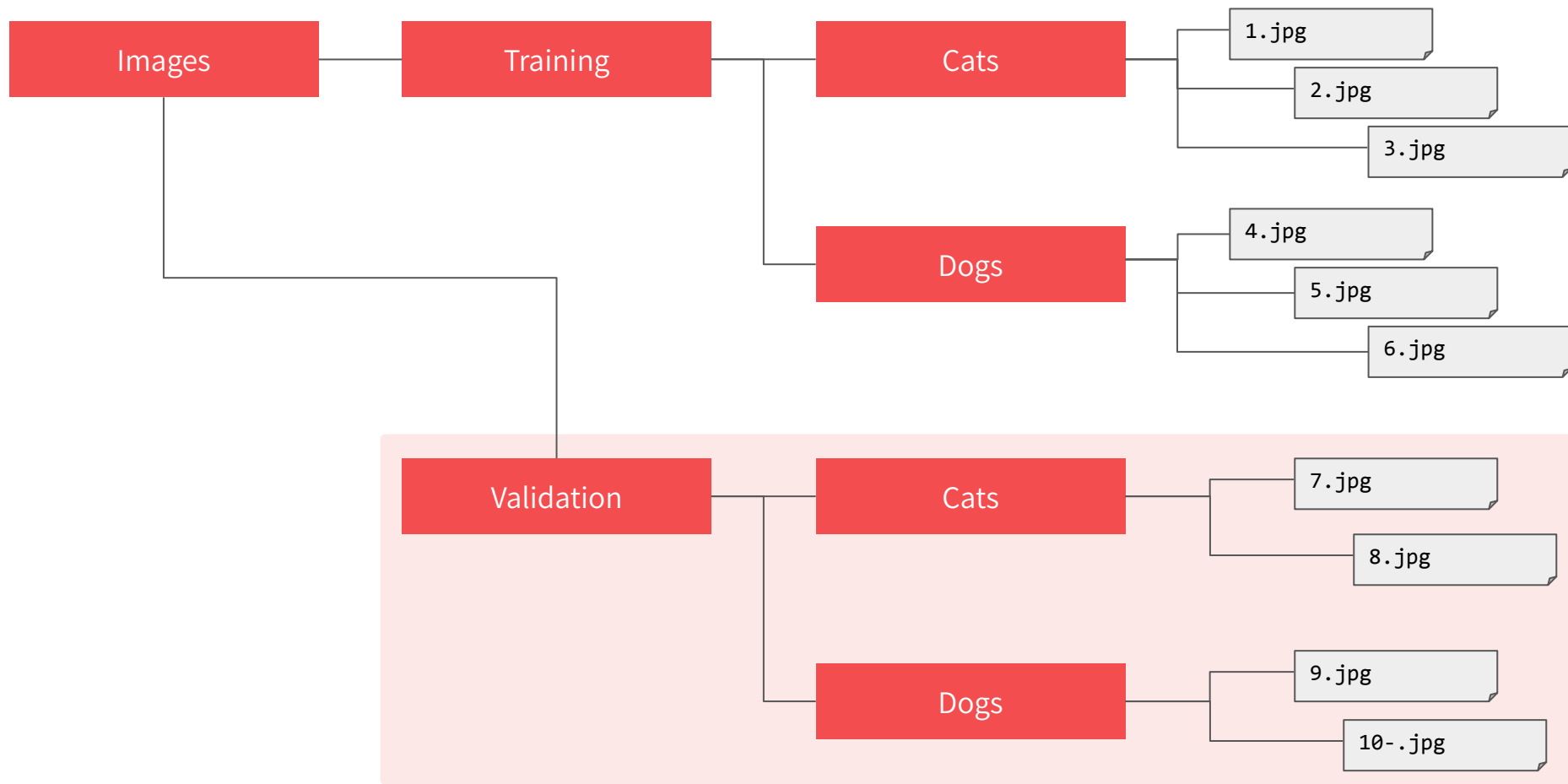
A note on hand labeling

Per the rules and spirit of this contest, please do not manually label your submissions. We work hard to fair and fun contests, and ask for the same respect in return.









```
train_dataset = tf.keras.utils.image_dataset_from_directory(  
    train_dir,  
    image_size=(150, 150),  
    batch_size=20,  
    label_mode='binary')
```



```
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    batch_size=20,  
    label_mode='binary')
```



```
validation_dataset = tf.keras.utils.image_dataset_from_directory(  
    validation_dir,  
    image_size=(150, 150),  
    batch_size=20,  
    label_mode='binary')
```



```
AUTOTUNE = tf.data.AUTOTUNE

train_dataset_final =
train_dataset_scaled.cache().shuffle(1000).prefetch(buffer_size=AUTOTUNE)

validation_dataset_final =
validation_dataset_scaled.cache().prefetch(buffer_size=AUTOTUNE)
```

```
model = tf.keras.models.Sequential([
    tf.keras.Input(shape=(150, 150, 3)),
    tf.keras.layers.Rescaling(1./255),
    tf.keras.layers.Conv2D(16, (3, 3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2, 2),
    tf.keras.layers.Conv2D(32, (3, 3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2, 2),
    tf.keras.layers.Conv2D(64, (3, 3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2, 2),
    tf.keras.layers.Flatten(),
    tf.keras.layers.Dense(512, activation='relu'),
    tf.keras.layers.Dense(1, activation='sigmoid')
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    tf.keras.layers.Dense(512, activation='relu'),
    tf.keras.layers.Dense(1, activation='sigmoid')
])
```



Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 148, 148, 16)	448
max_pooling2d (MaxPooling2D)	(None, 74, 74, 16)	0
conv2d_1 (Conv2D)	(None, 72, 72, 32)	4640
max_pooling2d_1 (MaxPooling2D)	(None, 36, 36, 32)	0
conv2d_2 (Conv2D)	(None, 34, 34, 64)	18496
max_pooling2d_2 (MaxPooling2D)	(None, 17, 17, 64)	0
flatten (Flatten)	(None, 18496)	0
dense (Dense)	(None, 512)	9470464
dense_1 (Dense)	(None, 1)	513

```

=====
Total params: 9,494,561
Trainable params: 9,494,561
Non-trainable params: 0

```

```
model.compile(loss='binary_crossentropy',  
              optimizer=tf.keras.optimizers.RMSprop(learning_rate=0.001),  
              metrics=['accuracy'])
```



```
history = model.fit(  
    train_dataset_final,  
    epochs=15,  
    validation_data=validation_dataset_final,  
    verbose=2)
```



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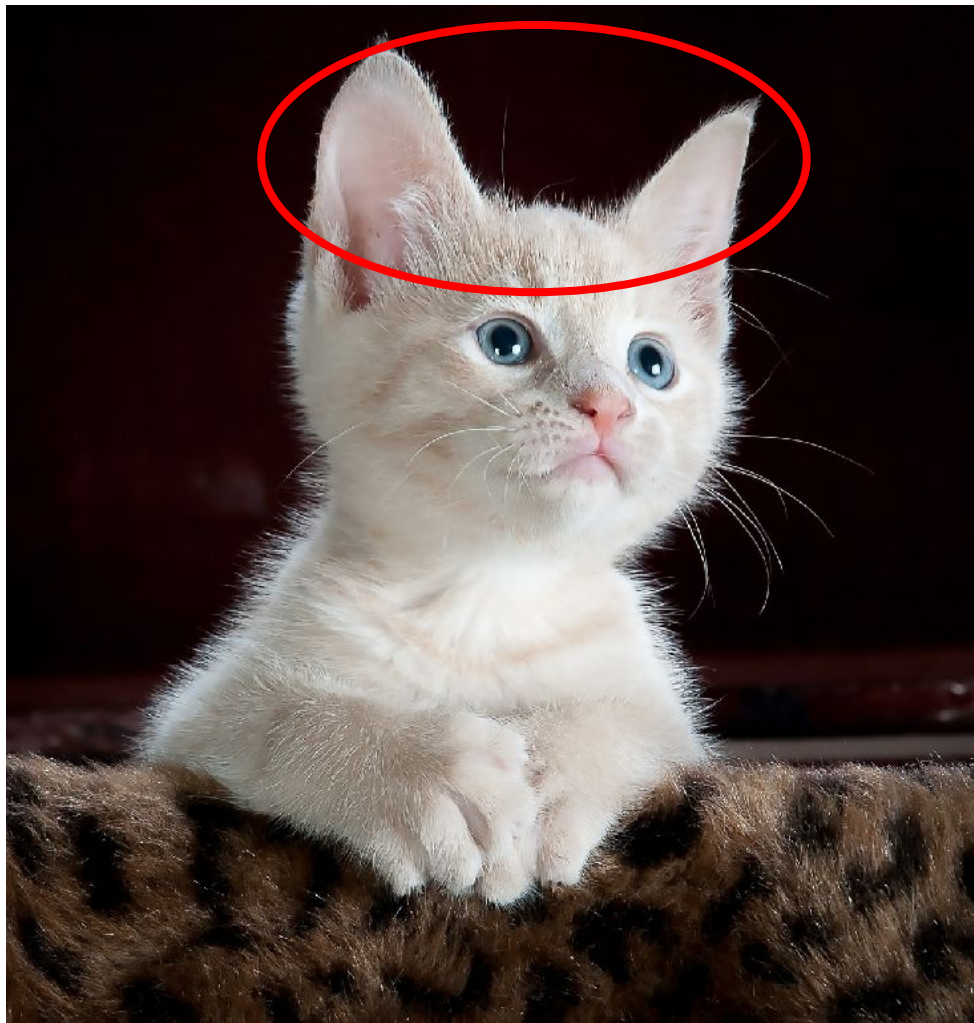
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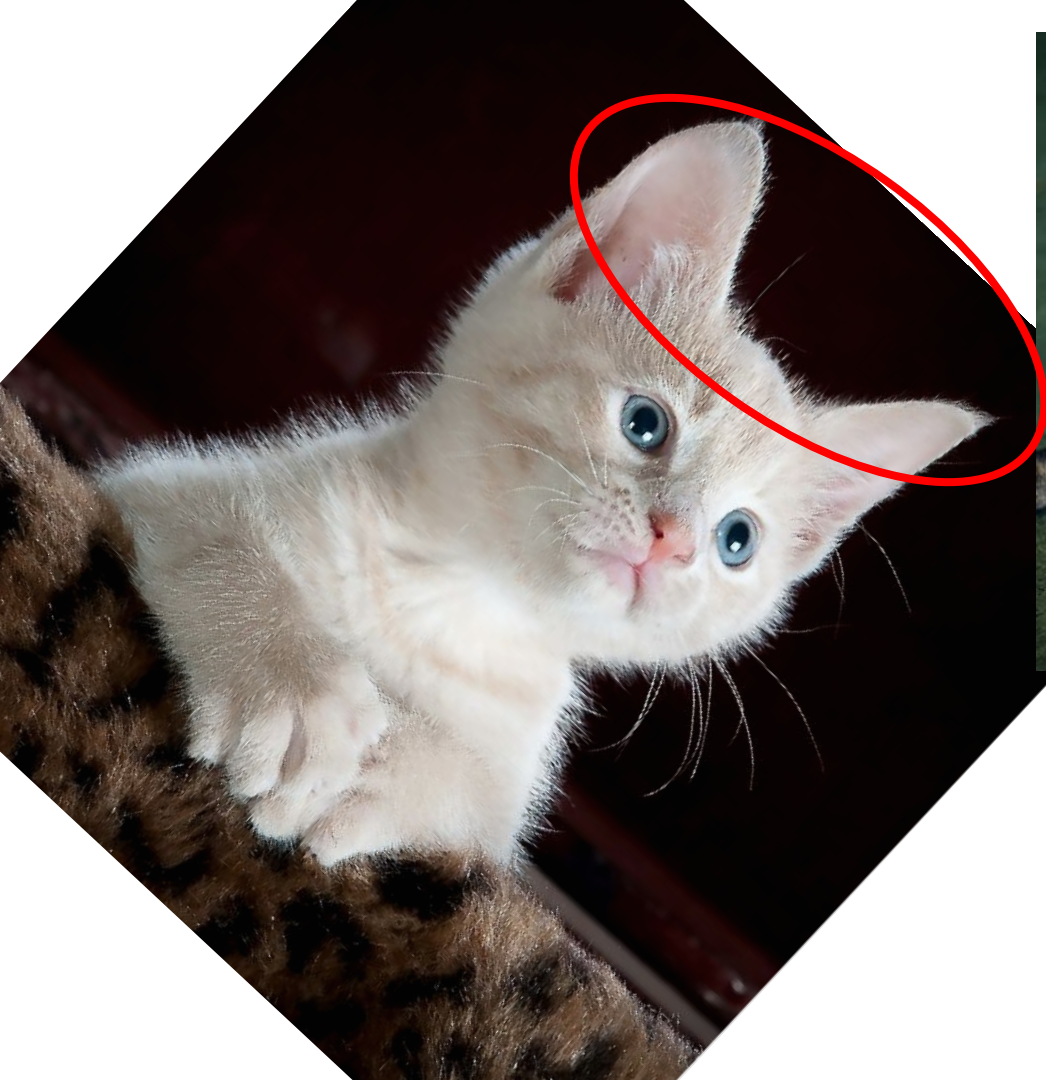
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```
train_dataset = tf.keras.utils.image_dataset_from_directory(  
    train_dir,  
    image_size=(150, 150),  
    batch_size=20,  
    label_mode='binary')
```

```
SHUFFLE_BUFFER_SIZE = 1000  
PREFETCH_BUFFER_SIZE = tf.data.AUTOTUNE
```

```
train_dataset_final = (train_dataset  
    .cache()  
    .shuffle(SHUFFLE_BUFFER_SIZE)  
    .prefetch(buffer_size=AUTOTUNE))
```



```
train_dataset = tf.keras.utils.image_dataset_from_directory(  
    train_dir,  
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train_dataset_final = (train_dataset  
    .cache()  
    .shuffle(SHUFFLE_BUFFER_SIZE)  
    .prefetch(buffer_size=AUTOTUNE))
```



```
data_augmentation = tf.keras.Sequential([
    tf.keras.Input(shape=(150, 150, 3)),
    tf.keras.layers.RandomFlip('horizontal'),
    tf.keras.layers.RandomRotation(0.2, fill_mode='nearest'),
    tf.keras.layers.RandomTranslation(0.2, 0.2, fill_mode='nearest'),
    tf.keras.layers.RandomZoom(0.2, fill_mode='nearest')
])
```

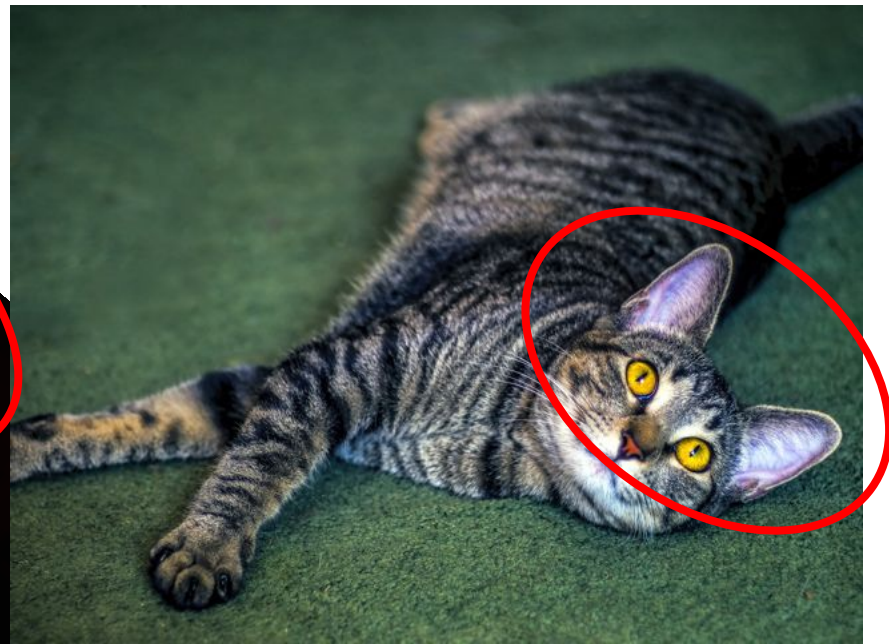
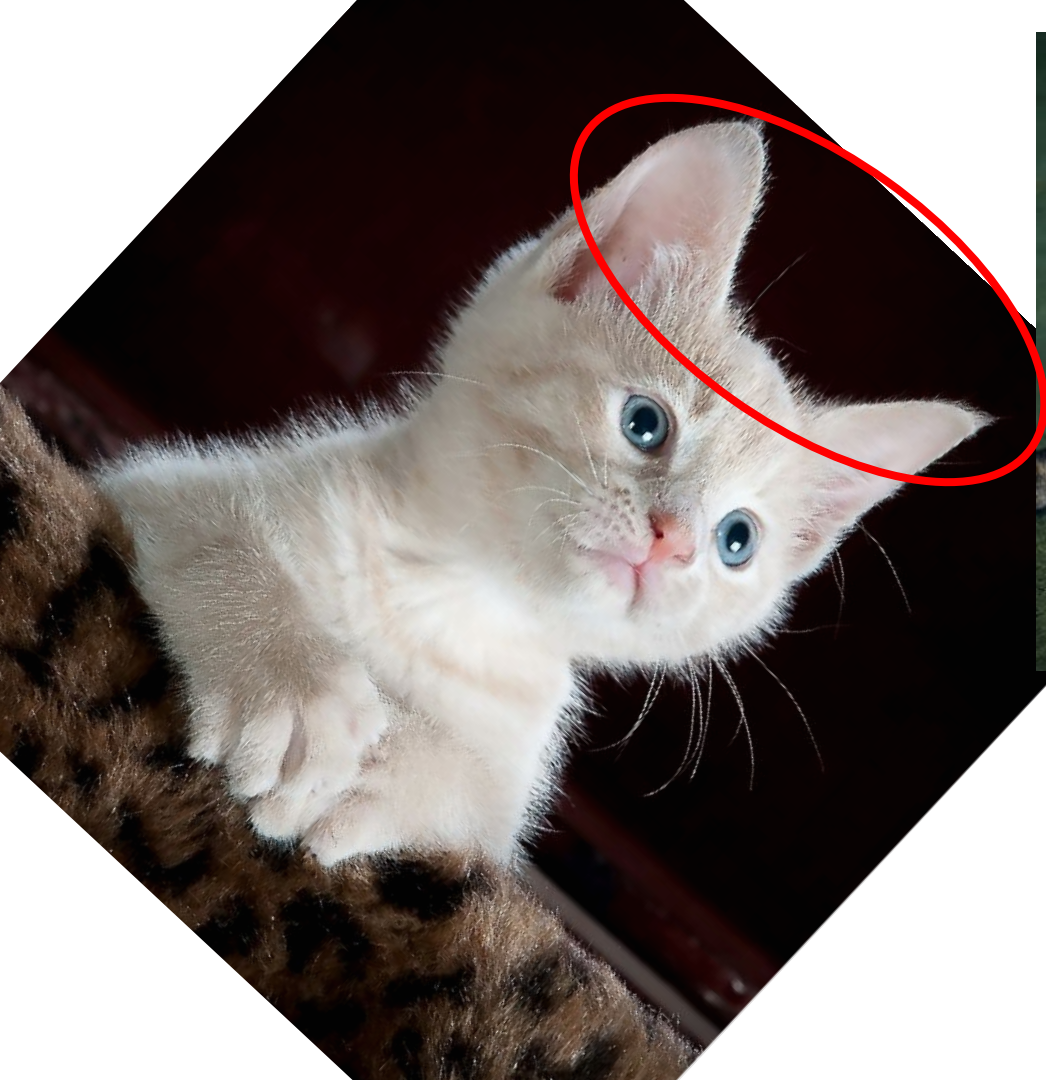







```
data_augmentation = tf.keras.Sequential([
    tf.keras.Input(shape=(150, 150, 3)),
    tf.keras.layers.RandomFlip('horizontal'),
    tf.keras.layers.RandomRotation(0.2, fill_mode='nearest'),
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```



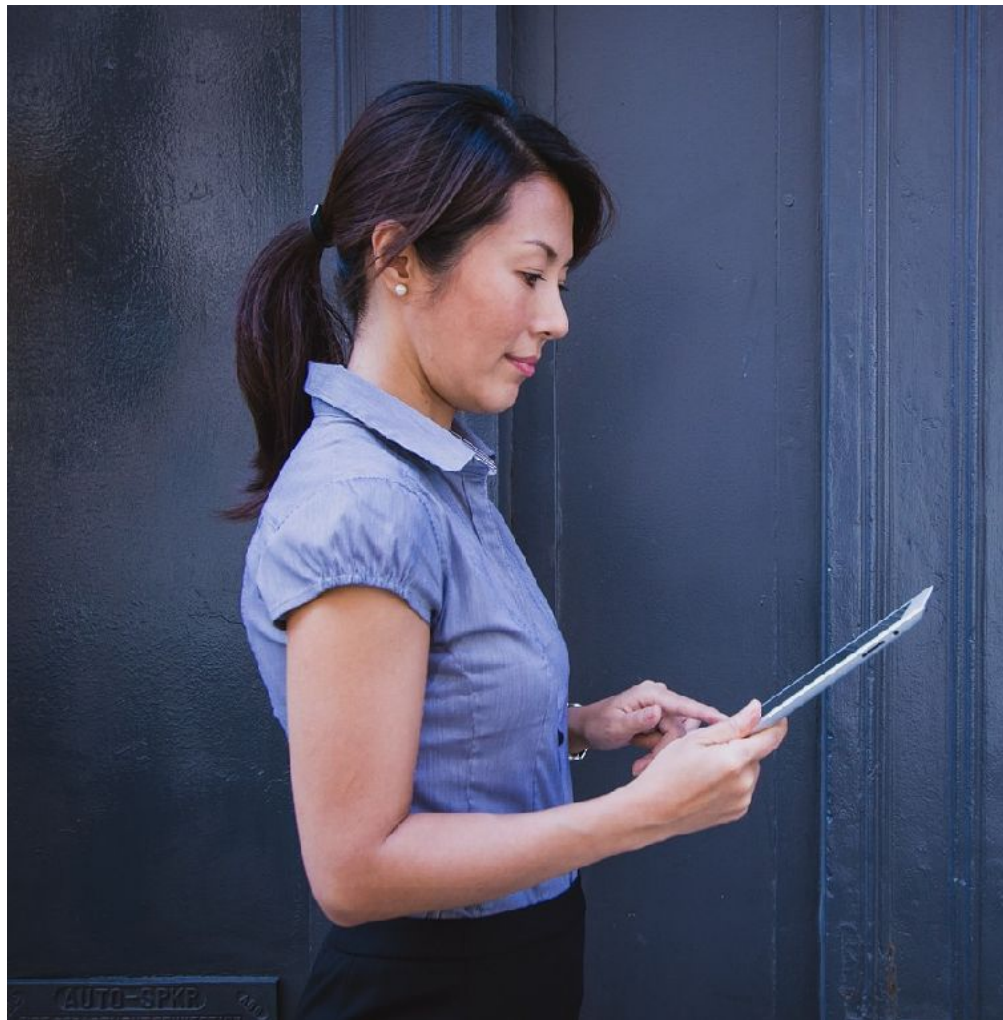


```
data_augmentation = tf.keras.Sequential([
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    tf.keras.layers.RandomZoom(0.2, fill_mode='nearest')
])
```




```
model_without_aug = create_model()
```

```
model_with_aug = tf.keras.models.Sequential([  
    data_augmentation,  
    model_without_aug  
])
```

```
model_with_aug.compile(  
    loss='binary_crossentropy',  
    optimizer=tf.keras.optimizers.RMSprop(learning_rate=1e-4),  
    metrics=['accuracy']
```



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Convolution



Convolution



Convolution



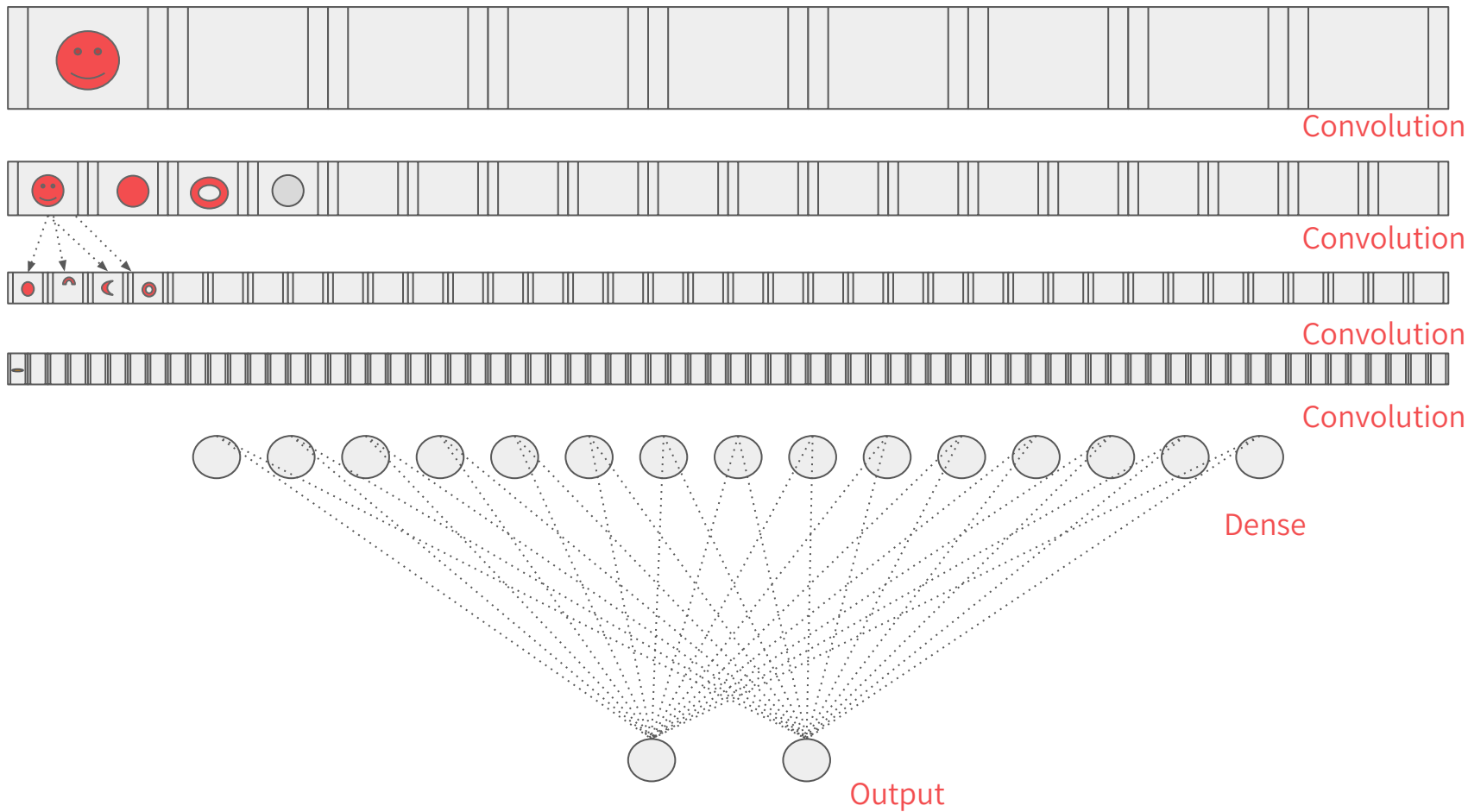
Convolution

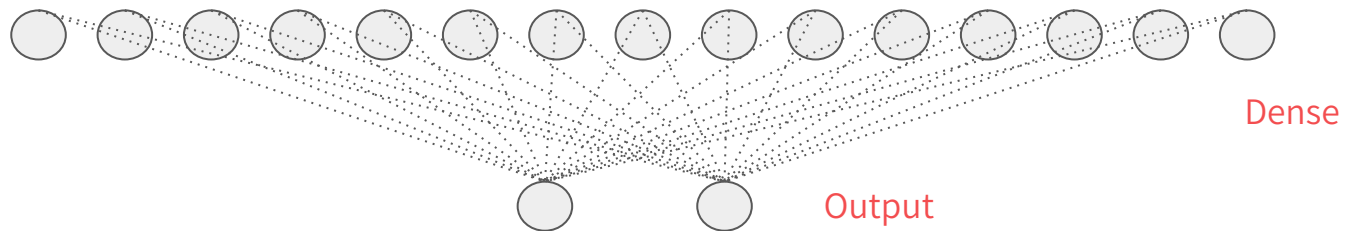
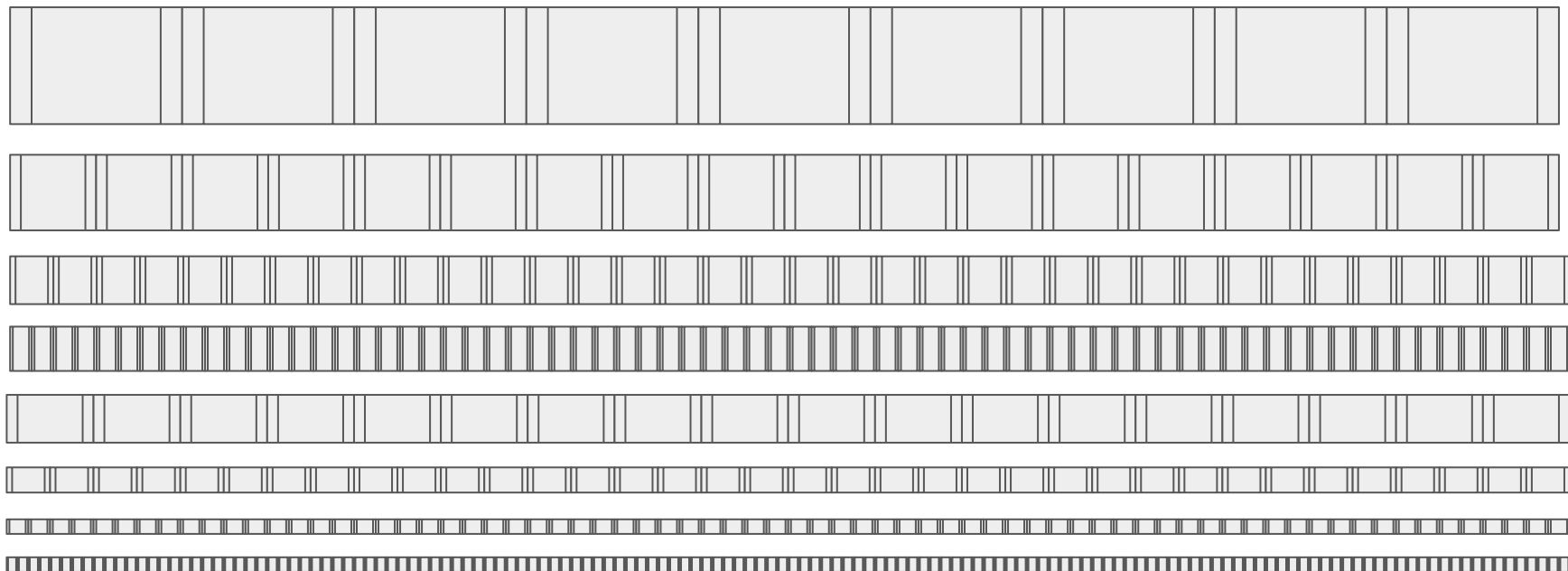


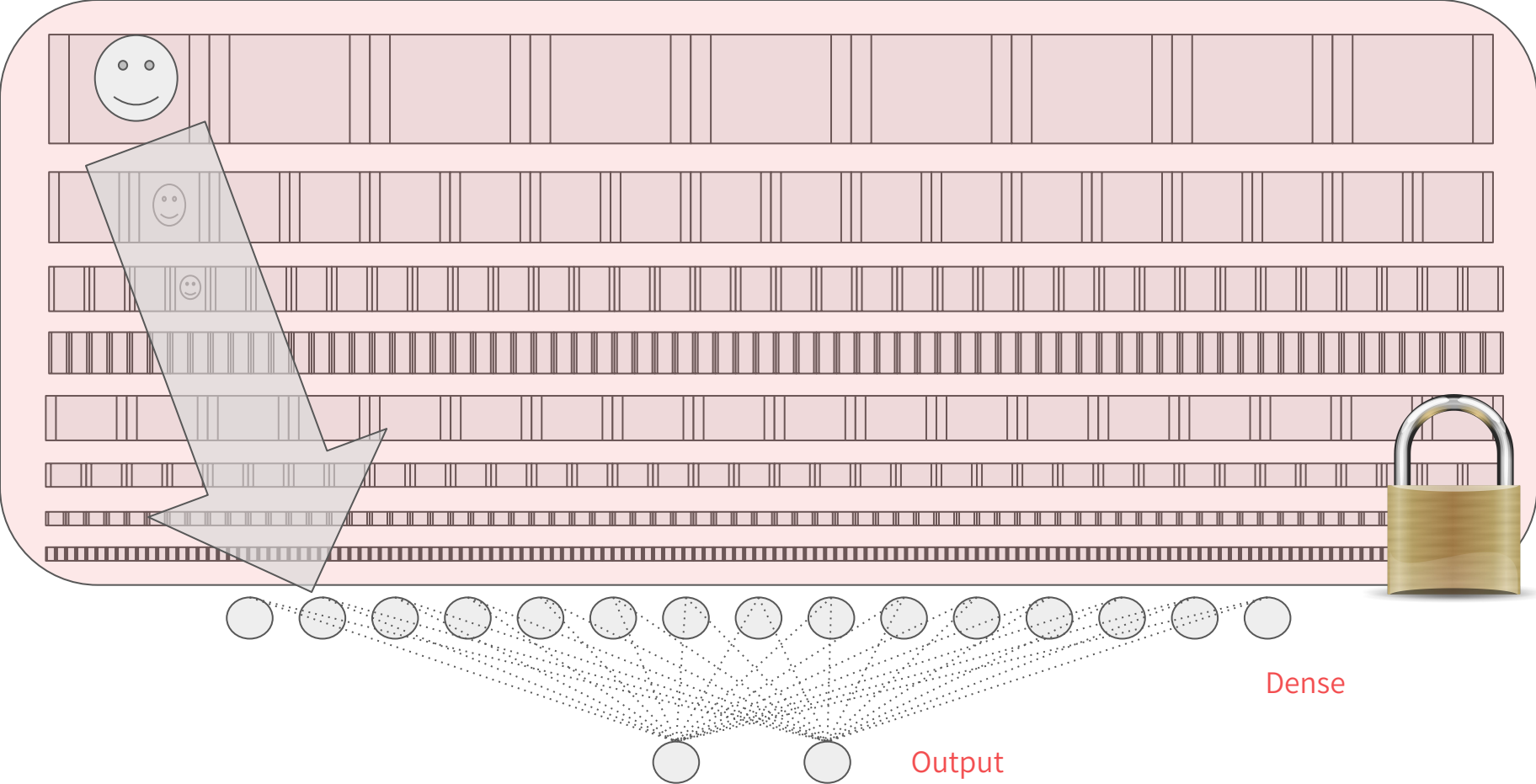
Dense

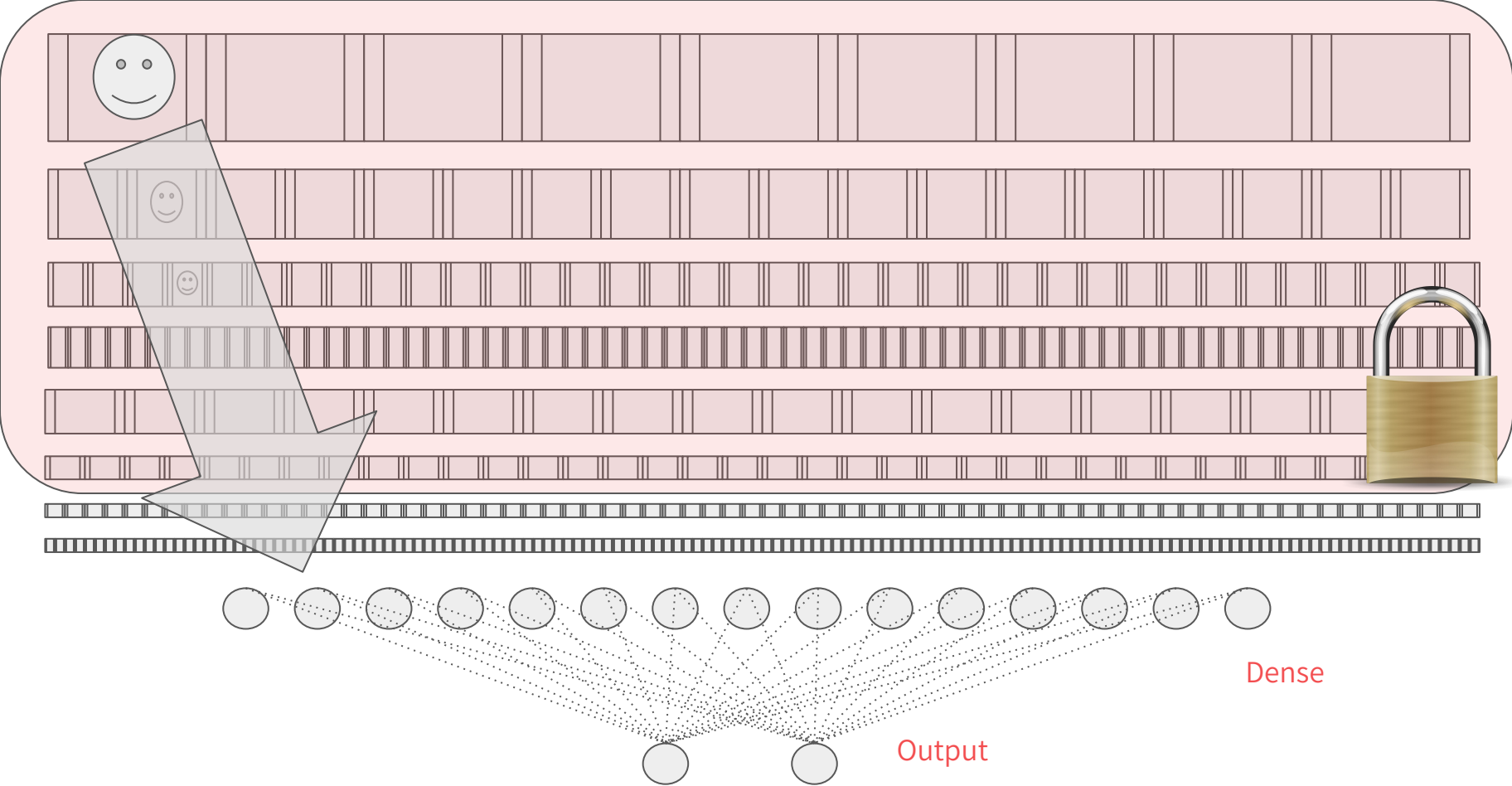


Output









https://arxiv.org/abs/1512.00567



We gratefully acknowledge support from the Simons Foundation and member institutions.

arXiv.org > cs > arXiv:1512.00567

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Computer Science > Computer Vision and Pattern Recognition

Rethinking the Inception Architecture for Computer Vision

Christian Szegedy, Vincent Vanhoucke, Sergey Ioffe, Jonathon Shlens, Zbigniew Wojna

(Submitted on 2 Dec 2015 (v1), last revised 11 Dec 2015 (this version, v3))

Convolutional networks are at the core of most state-of-the-art computer vision solutions for a wide variety of tasks. Since 2014 very deep convolutional networks started to become mainstream, yielding substantial gains in various benchmarks. Although increased model size and computational cost tend to translate to immediate quality gains for most tasks (as long as enough labeled data is provided for training), computational efficiency and low parameter count are still enabling factors for various use cases such as mobile vision and big-data scenarios. Here we explore ways to scale up networks in ways that aim at utilizing the added computation as efficiently as possible by suitably factorized convolutions and aggressive regularization. We benchmark our methods on the ILSVRC 2012 classification challenge validation set demonstrate substantial gains over the state of the art: 21.2% top-1 and 5.6% top-5 error for single frame evaluation using a network with a computational cost of 5 billion multiply-adds per inference and with using less than 25 million parameters. With an ensemble of 4 models and multi-crop evaluation, we report 3.5% top-5 error on the validation set (3.6% error on the test set) and 17.3% top-1 error on the validation set.

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[https://storage.googleapis.com/mledu-datasets/
inception_v3_weights_tf_dim_ordering_tf_kernels_notop.h5](https://storage.googleapis.com/mledu-datasets/inception_v3_weights_tf_dim_ordering_tf_kernels_notop.h5)



```
local_weights_file = '/tmp/inception_v3_weights_tf_dim_ordering_tf_kernels_notop.h5'

pre_trained_model = tf.keras.applications.inception_v3.InceptionV3(
    input_shape=(150, 150, 3),
    include_top=False,
    weights=None)

pre_trained_model.load_weights(local_weights_file)
```



```
for layer in pre_trained_model.layers:  
    layer.trainable = False
```



```
pre_trained_model.summary()
```

Model: "inception_v3"

Layer (type)	Output Shape	Param #	Connected to
input_layer_1 (InputLayer)	(None, 150, 150, 3)	0	-
conv2d_94 (Conv2D)	(None, 74, 74, 32)	864	input_layer_1[0]...
batch_normalizatio... (BatchNormalizatio...)	(None, 74, 74, 32)	96	conv2d_94[0][0]
activation_94 (Activation)	(None, 74, 74, 32)	0	batch_normalizat...
conv2d_95 (Conv2D)	(None, 72, 72, 32)	9,216	activation_94[0]...
batch_normalizatio... (BatchNormalizatio...)	(None, 72, 72, 32)	96	conv2d_95[0][0]

...




```
last_layer = pre_trained_model.get_layer('mixed7')
```

```
last_output = last_layer.output
```

```
x = tf.keras.layers.Flatten()(last_output)
x = tf.keras.layers.Dense(1024, activation='relu')(x)
x = tf.keras.layers.Dense(1, activation='sigmoid')(x)

model = tf.keras.Model(pre_trained_model.input, x)
model.compile(
    optimizer=RMSprop(learning_rate=0.0001),
    loss='binary_crossentropy',
    metrics=['accuracy'])
```



```
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```

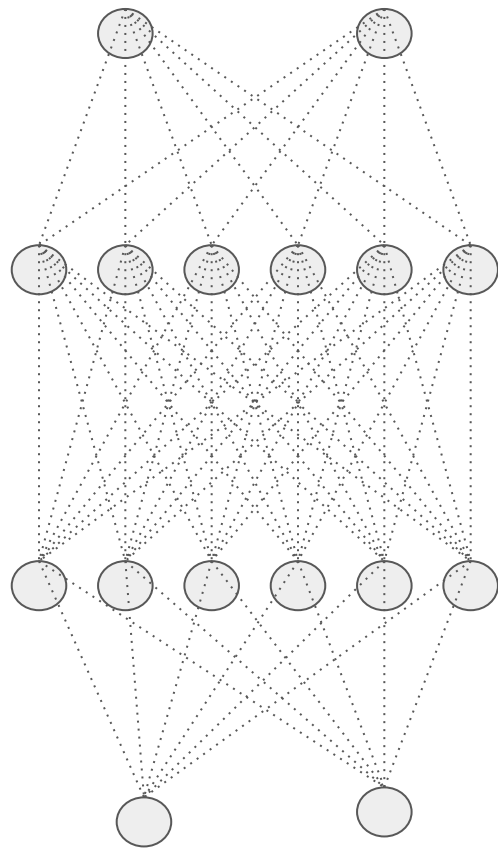


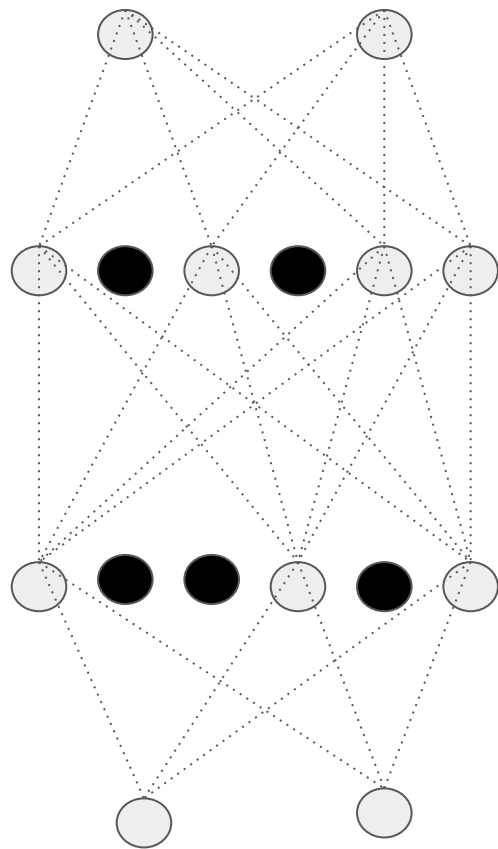
```
history = model_with_aug.fit(  
    train_dataset_final,  
    validation_data=validation_dataset_final,  
    epochs=20,  
    verbose=2)
```











```
x = tf.keras.layers.Flatten()(last_output)
x = tf.keras.layers.Dense(1024, activation='relu')(x)
x = tf.keras.layers.Dense(1, activation='sigmoid')(x)

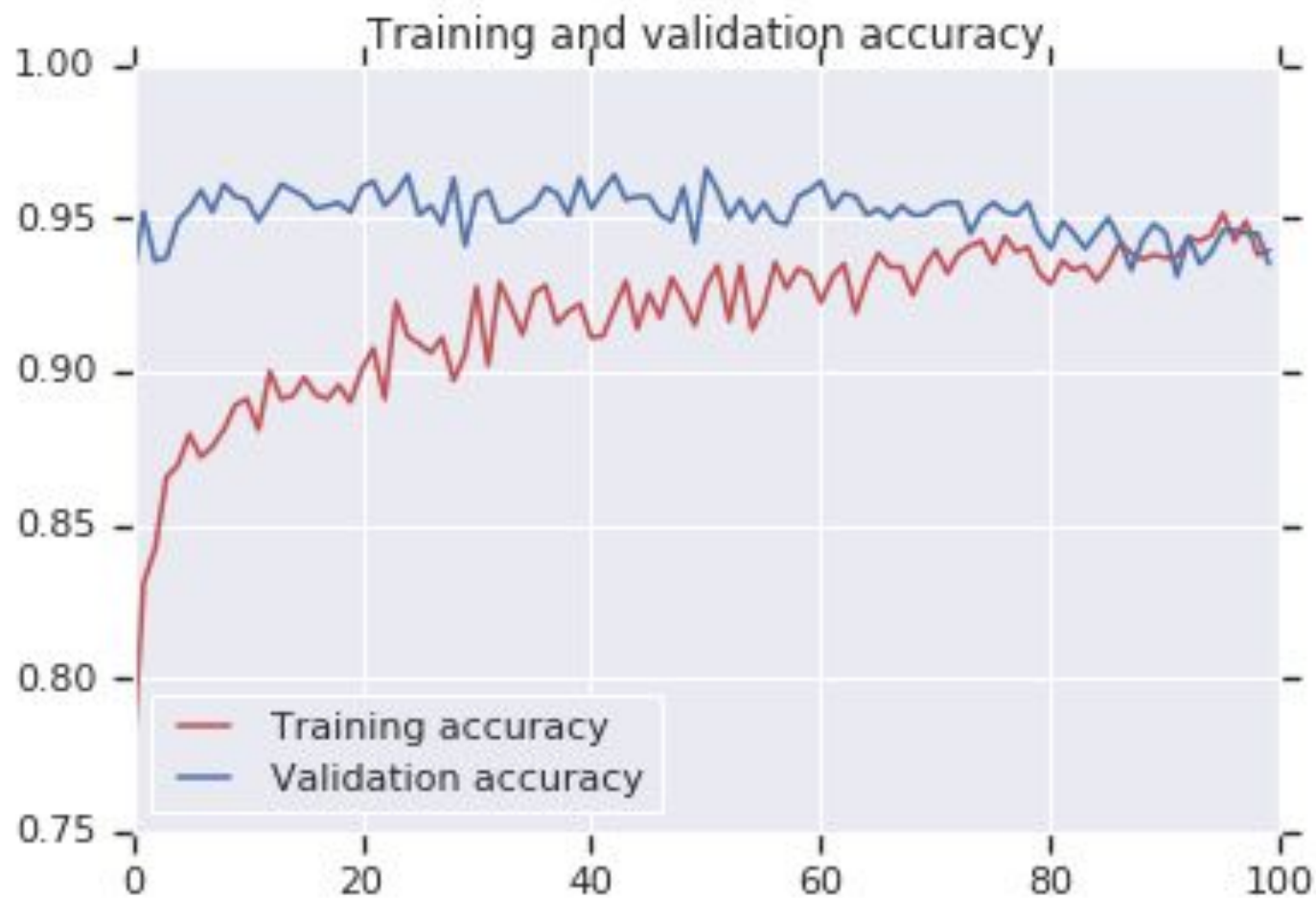
model = tf.keras.Model(pre_trained_model.input, x)
model.compile(
    optimizer=RMSprop(learning_rate=0.0001),
    loss='binary_crossentropy',
    metrics=['acc'])
```



```
x = tf.keras.layers.Flatten()(last_output)
x = tf.keras.layers.Dense(1024, activation='relu')(x)
x = tf.keras.layers.Dropout(0.2)(x)
x = tf.keras.layers.Dense(1, activation='sigmoid')(x)

model = tf.keras.Model(pre_trained_model.input, x)
model.compile(
    optimizer=RMSprop(learning_rate=0.0001),
    loss='binary_crossentropy',
    metrics=['acc'])
```



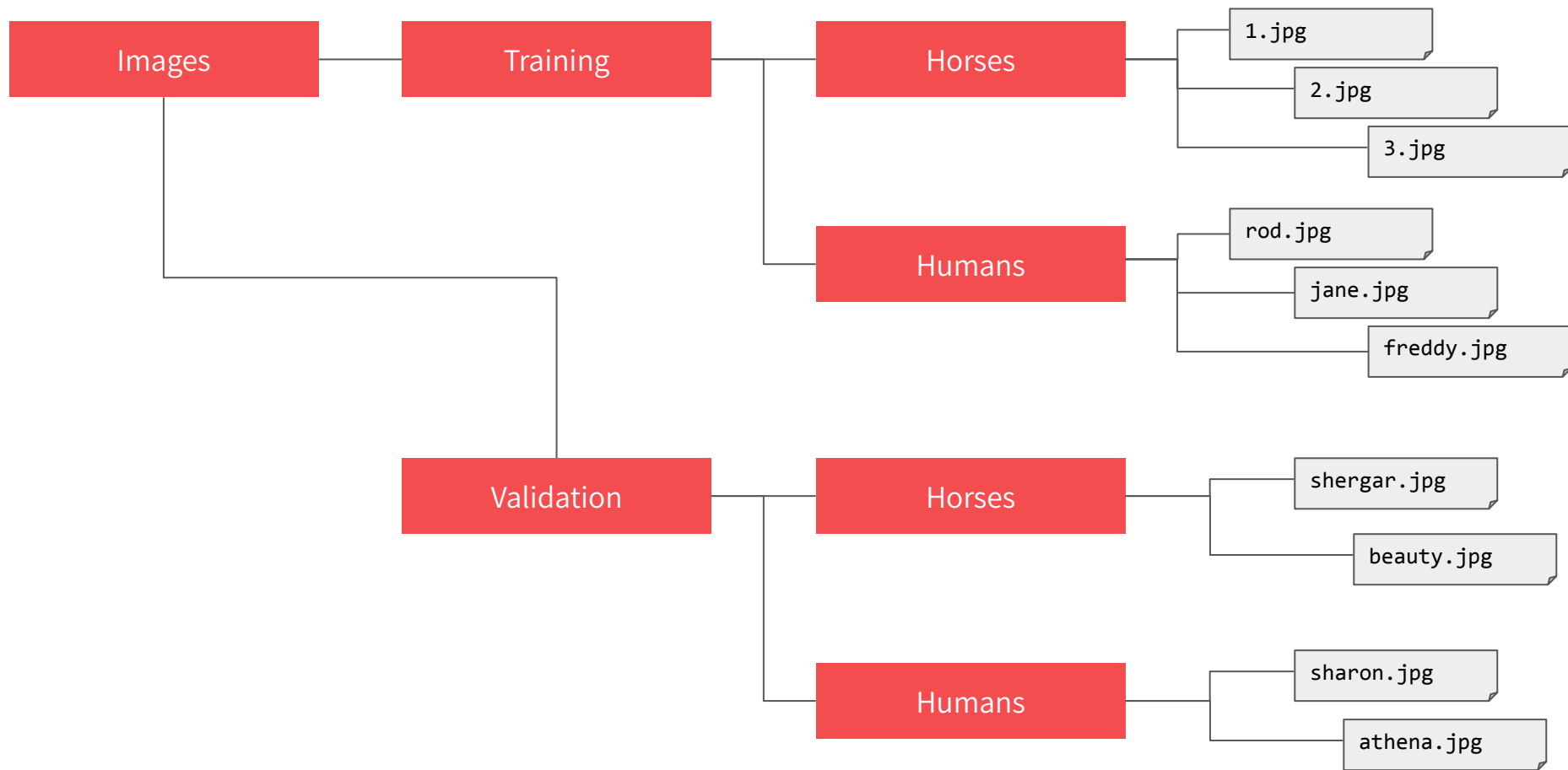


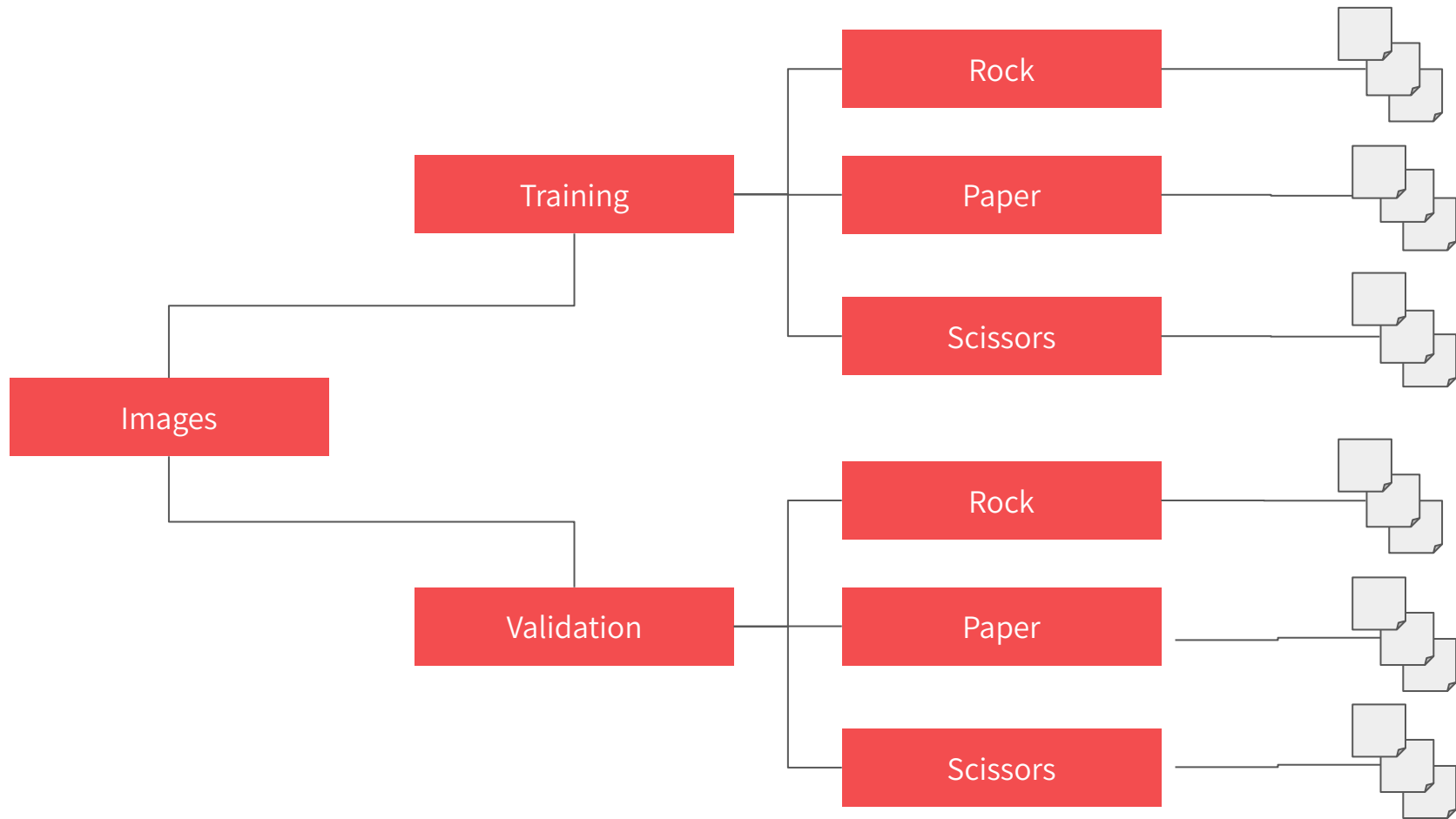
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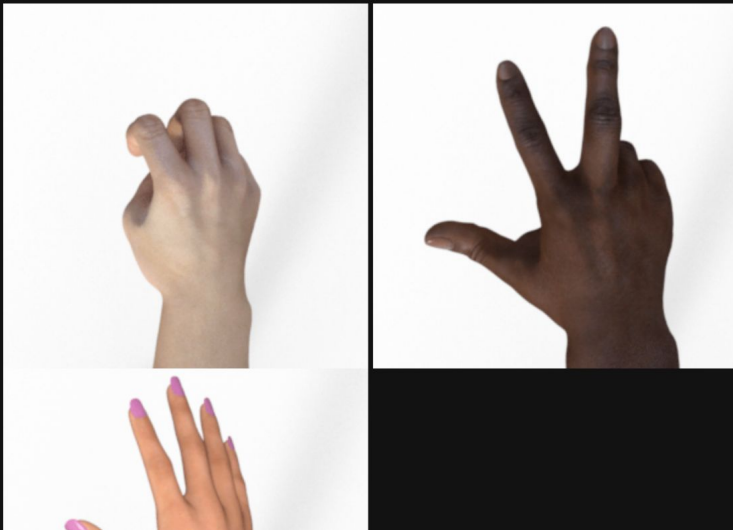


<https://laurencemoroney.com/datasets.html#rock-paper-scissors-dataset>

Rock Paper Scissors Dataset

Rock Paper Scissors contains images from various hands, from different races, ages, and genders, posed into Rock / Paper or Scissors and labeled as such. You can download the [training set here](#) and the [test set here](#). I created these images using CGI techniques as an experiment in determining if a model trained on a CGI-based dataset could classify real images. I also generated a few pictures that you can use for predictions. You can [find them here](#).

Note that all of these pictures use a plain white background. Each image is 300×300 pixels in 24-bit color. Examples Here are a few examples showing some of the poses and the diversity of hands used.



Horses or Humans Dataset
Rock Paper Scissors Dataset
Yoga Poses Dataset

```
train_dataset = tf.keras.utils.image_dataset_from_directory(  
    train_dir,  
    image_size=(150, 150),  
    batch_size=20,  
    label_mode='binary')
```



```
train_dataset = tf.keras.utils.image_dataset_from_directory(  
    train_dir,  
    image_size=(150, 150),  
    batch_size=20,  
    label_mode='categorical')
```



```
model = tf.keras.models.Sequential([
    tf.keras.Input(input_shape=(150, 150, 3)),
    tf.keras.layers.Conv2D(16, (3, 3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2, 2),
    tf.keras.layers.Conv2D(32, (3, 3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2, 2),
    tf.keras.layers.Conv2D(64, (3, 3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2, 2),
    tf.keras.layers.Flatten(),
    tf.keras.layers.Dense(512, activation='relu'),
    tf.keras.layers.Dense(1, activation='sigmoid')
])
```



```
model = tf.keras.models.Sequential([
    tf.keras.Input(input_shape=(150, 150, 3)),
    tf.keras.layers.Conv2D(16, (3, 3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2, 2),
    tf.keras.layers.Conv2D(32, (3, 3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2, 2),
    tf.keras.layers.Conv2D(64, (3, 3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2, 2),
    tf.keras.layers.Flatten(),
    tf.keras.layers.Dense(512, activation='relu'),
    tf.keras.layers.Dense(3, activation='softmax')
])
```





Rock: 0.001

Paper: 0.647

Scissors: 0.352

```
model.compile(loss='binary_crossentropy',  
              optimizer=tf.keras.optimizers.RMSprop(learning_rate=0.001),  
              metrics=['accuracy'])
```

```
model.compile(loss='categorical_crossentropy',  
              optimizer=tf.keras.optimizers.RMSprop(learning_rate=0.001),  
              metrics=['accuracy'])
```

