

# Machine Intelligence 1 - Exercise 1: Math Primer

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## 1 Distributions and expected values (2 Points)

### 1.1 (a)

As  $p$  is obviously piecewise continuous, it is measurable for every  $c \in \mathbb{R}$ . One has

$$\int_{\mathbb{R}} p(t) dt = \int_0^{\pi} c \cdot \sin(t) dt = c \cdot \int_0^{\pi} \sin(t) dt = c(-\cos(t)) \Big|_{t=0}^{\pi} = -c(-1 - 1) = 2c.$$

Therefore the condition  $\int_{\mathbb{R}} p(t) dt = 1$  is satisfied if and only if  $c = \frac{1}{2}$ .

As  $\sin(x) \geq 0$  holds for all  $x \in [0, \pi]$ ,  $\frac{1}{2}\sin(x) \geq 0$  is satisfied for all  $x \in [0, \pi]$ , so  $p$  is truly a probability density for  $c = \frac{1}{2}$ .

### 1.2 (b)

For  $c = \frac{1}{2}$  we obtain

$$\langle X \rangle_p = \int_{\mathbb{R}} t \cdot p(t) dt = \frac{1}{2} \int_0^{\pi} t \cdot \sin(t) dt = \frac{1}{2} \left( -t \cos(t) \Big|_{t=0}^{\pi} - \int_0^{\pi} -\cos(t) dt \right) = \frac{\pi}{2} + \frac{1}{2} \sin(t) \Big|_{t=0}^{\pi} = \frac{\pi}{2}.$$

### 1.3 (c)

We have

$$\begin{aligned} \langle X^2 \rangle_p &= \int_{\mathbb{R}} t^2 \cdot p(t) dt = \int_0^{\pi} t^2 \cdot p(t) dt = \frac{1}{2} \int_0^{\pi} t^2 \cdot \sin(t) dt = \\ &= -t^2 \cos(t) \Big|_{t=0}^{\pi} - 2 \int_0^{\pi} -t \cdot \cos(t) dt = \frac{1}{2} \left( -\pi^2(-1) + 0 + 2 \int_0^{\pi} t \cdot \cos(t) dt \right) = \\ &= \frac{\pi^2}{2} + \left( t \sin(t) \Big|_{t=0}^{\pi} - \int_0^{\pi} \sin(t) dt \right) = \frac{\pi^2}{2} + \cos(t) \Big|_{t=0}^{\pi} = \frac{\pi^2}{2} - 1 - 1 = \frac{\pi^2}{2} - 2 \end{aligned}$$

and consequently  $V(X) = \langle X^2 \rangle_p - \langle X \rangle_p^2 = \frac{\pi^2}{2} - 2 - \left(\frac{\pi}{2}\right)^2 = \frac{\pi^2 - 8}{4}$ .

## 2 Marginal densities (2 Points)

### 2.1 (a)

$$p_X(x) = \int_{\mathbb{R}} p_{X,Y}(x,y) dy \text{ for } x \in [0, 2]$$

$$\begin{aligned} p_X(x) &= \int_0^1 \frac{3}{7}(2-x)(x+y) dy = \frac{3}{7} \int_0^1 (2x + 2y - x^2 - xy) dy \\ &= \frac{3}{7} (2xy + y^2 - x^2y - \frac{xy^2}{2}) \Big|_{y=0}^1 = -\frac{3}{7}x^2 + \frac{9}{14}x + \frac{3}{7} \end{aligned}$$

$$p_X(x) = -\frac{3}{7}x^2 + \frac{9}{14}x + \frac{3}{7} \text{ for } x \in [0, 2]$$

$$p_Y(y) = \int_{\mathbb{R}} p_{X,Y}(x,y) dx \text{ for } y \in [0, 1]$$

$$\begin{aligned} p_Y(y) &= \int_0^2 \frac{3}{7}(2-x)(x+y) dx = \frac{3}{7} \int_0^2 (2x + 2y - x^2 - xy) dx \\ &= \frac{3}{7} (x^2 + 2xy - \frac{x^3}{3} - \frac{x^2y}{2}) \Big|_{x=0}^2 = \frac{6}{7}y + \frac{4}{7} \end{aligned}$$

$$p_Y(y) = \frac{6}{7}y + \frac{4}{7} \text{ for } y \in [0, 1]$$

### 2.2 (b)

If random variables  $X$  and  $Y$  are independent,  $p_{X,Y}(x,y) = p_X(x)p_Y(y)$  yields. Let's check:

$$p_X(x)p_Y(y) = (-\frac{3}{7}x^2 + \frac{9}{14}x + \frac{3}{7})(\frac{6}{7}y + \frac{4}{7}) \text{ for } x \in [0, 2], y \in [0, 1]$$

For  $x = y = 0$ ,

$$p_Y(0)p_X(0) = \frac{12}{49} \neq 0 = p_{X,Y}(0,0)$$

Hence, **not independent**.

Let's check uncorrelatedness:

If two random variables  $X$  and  $Y$  are uncorrelated,  $E(XY) = E(X)E(Y)$  yields.

$$\begin{aligned} E(X) &= \int_{\mathbb{R}} x \cdot p_X(x) dx = \int_0^2 x \cdot \frac{3}{7}(-x^2 + \frac{3}{2}x + 1) dx \\ &= \frac{3}{7}(-\frac{1}{4}x^4 + \frac{1}{2}x^3 + \frac{1}{2}x^2) \Big|_{x=0}^2 = \frac{6}{7} \end{aligned}$$

$$E(Y) = \int_{\mathbb{R}} y \cdot p_Y(y) dy = \frac{3}{7} \int_0^1 (2y^2 + \frac{4}{3}y) dy = \frac{3}{7}(\frac{2}{3}y^3 + \frac{2}{3}y^2) \Big|_{y=0}^1 = \frac{4}{7}$$

$$\begin{aligned} E(XY) &= \int_0^2 \int_0^1 x \cdot y \cdot \frac{3}{7}(2-x)(x+y) dy dx = \frac{3}{7} \int_0^2 x \{ \int_0^1 2xy - x^2y + 2y^2 - xy^2 dy \} dx \\ &= \frac{3}{7} \int_0^2 x \cdot [xy^2 - \frac{1}{2}x^2y^2 + \frac{2}{3}y^3 - \frac{1}{3}xy^3] \Big|_0^1 dx = \frac{3}{7} \int_0^2 (\frac{2}{3}x^2 - \frac{1}{2}x^3 + \frac{2}{3}x) dx \end{aligned}$$

$$= \frac{3}{7} \left\{ \frac{16}{9} - \frac{16}{9} + \frac{4}{3} \right\} = \frac{10}{21}$$

So,  $E(XY) \neq E(X)E(Y)$ . Then, **not uncorrelated**.

### 3 Taylor expansion (1 Point)

Let  $t_0(x)$  be the Taylor expansion to the third degree at  $x_0 = 0$  for  $f(x) = \sqrt{1+x}$

Using the definition of the Taylor expansion we know that

$$\begin{aligned} t_0(x) &= \sum_{n=1}^3 \frac{f^{(n)}(0) \cdot (x-0)^n}{n!} = \frac{1}{0!} f(0)x^0 + \frac{1}{1!} f'(0)x^1 + \frac{1}{2!} f''(0)x^2 + \frac{1}{3!} f'''(0)x^3 \\ &= f(0) + f'(0)x + \frac{1}{2} f''(0)x^2 + \frac{1}{6} f'''(0)x^3 \end{aligned}$$

The derivatives of  $f(x)$  can be computed using the chain rule:

$$f'(x) = \frac{1}{2\sqrt{1+x}} \implies f'(0) = \frac{1}{2}$$

$$f''(x) = -\frac{1}{4(1+x)^{3/2}} \implies f''(0) = -\frac{1}{4}$$

$$f'''(x) = \frac{3}{8(1+x)^{5/2}} \implies f'''(0) = \frac{3}{8}$$

Therefore:

$$\begin{aligned} t_0(x) &= 1 + \frac{1}{2}x + \frac{1}{2} \left(-\frac{1}{4}\right)x^2 + \frac{1}{6} \left(\frac{3}{8}\right)x^3 \\ &= 1 + \frac{1}{2}x - \frac{1}{8}x^2 + \frac{1}{16}x^3 \end{aligned}$$

### 4 Determinant of a matrix (1 Point)

We define

$$A := \begin{bmatrix} 5 & 8 & 16 \\ 4 & 1 & 8 \\ -4 & -4 & -11 \end{bmatrix}$$

Then the rule of Sarrus delivers

$$\begin{aligned} \det(A) &= 5 \cdot 1 \cdot (-11) + 8 \cdot 8 \cdot (-4) + 16 \cdot 4 \cdot (-4) - (-4) \cdot 1 \cdot 16 - (-4) \cdot 8 \cdot 5 - (-11) \cdot 4 \cdot 8 \\ &= -55 - 256 - 256 + 64 + 160 + 352 = -567 + 576 = 9. \end{aligned}$$

Furthermore we have  $\text{trace}(A) = 5 + 1 - 11 = -5$

### 5 Critical points (2 Points)

#### 5.1 (a)

First, we compute the gradients

$$\nabla f(x) = \begin{pmatrix} 2x \\ 2y \end{pmatrix}, \nabla g(x) = \begin{pmatrix} 2x \\ -2y \end{pmatrix}$$

and find their roots:

$$\nabla f(x, y) = 0 \Leftrightarrow (x, y) = (0, 0) = \underline{a}$$

$$\nabla g(x, y) = 0 \Leftrightarrow (x, y) = (0, 0) = \underline{a}$$

This shows that  $\underline{a}$  is indeed a critical point for  $f$  and  $g$ .

## 5.2 (b)

Computing the Hessian matrices yields:

$$H_f(x, y) = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}, H_g(x, y) = \begin{bmatrix} 2 & 0 \\ 0 & -2 \end{bmatrix}$$

We can immediately see, that  $H_f$  is positive definite (both eigenvalues bigger than zero) and  $H_g$  is indefinite (one eigenvalue bigger than zero, one less than zero). We deduce, that  $\underline{a}$  is a minimum for  $f$  but a saddle point for  $g$ .

## 6 Bayes rule (2 Points)

We know that:

$$\begin{aligned} P(D) = 0.01 &\implies P(\overline{D}) = 0.99 \\ P(+|D) = 0.95 &\implies P(-|D) = 0.05 \\ P(-|\overline{D}) = 0.999 &\implies P(+|\overline{D}) = 0.001 \end{aligned}$$

Therefore we can calculate

$$P(+) = P(D) \times P(+|D) + P(\overline{D}) \times P(+|\overline{D}) = 0.01 \times 0.95 + 0.99 \times 0.001 = 0.01049$$

Therefore  $P(-) = 1 - P(+) = 0.98951$

### 6.1 (a)

$$\begin{aligned} P(D|+) &= \frac{P(D \cap +)}{P(+)} = \frac{P(+|D) \times P(D)}{P(+)} = \frac{0.95 \times 0.01}{0.01049} \approx 0.9056 \\ P(\overline{D}|+) &= 1 - P(D|+) \approx 0.09438 \end{aligned}$$

### 6.2 (b)

$$\begin{aligned} P(\overline{D}|-) &= \frac{P(-|\overline{D}) \times P(\overline{D})}{P(-)} = \frac{0.99 \times 0.999}{0.98951} \approx 0.9995 \\ P(D|-) &= 1 - P(\overline{D}|-) \approx 0.0005053 \end{aligned}$$