

sheet3

November 7, 2017

```
In [2]: import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns
import random
% matplotlib inline
#x0 x1 y
training_data = pd.read_csv('regressionData.txt', delimiter=" ", header=None, names=["x1", "x0", "y"])
training_data["x0"] = training_data["x1"] / training_data["x1"]

x = training_data[["x0", "x1"]].values
y_t = training_data["y"].values

def h(w):
    def _h(x):
        return np.dot(w.T, x)
    return _h

def training_step(learning_rate):
    global i
    global w_21_00
    global w_21_01
    global w_21_02
    global w_21_03
    global w_10_00
    global w_10_01
    global w_10_10
    global w_10_11
    global w_10_20
    global w_10_21
    global E_T

    i += 1
    # Weight vectors
    w_10 = np.array([w_10_00, w_10_01])
    w_11 = np.array([w_10_10, w_10_11])
    w_12 = np.array([w_10_20, w_10_21])
    w_20 = np.array([w_21_00, w_21_01, w_21_02, w_21_03])
```

```

# compute hs of hidden layer ( $wT * x$ )
h_10 = np.apply_along_axis(h(w_10), 1, x)
h_11 = np.apply_along_axis(h(w_11), 1, x)
h_12 = np.apply_along_axis(h(w_12), 1, x)

# compute ss of hidden layer ( $f(h)$ )
s_10 = np.apply_along_axis(np.tanh, 0, h_10)
s_11 = np.apply_along_axis(np.tanh, 0, h_11)
s_12 = np.apply_along_axis(np.tanh, 0, h_12)

s_1 = np.array([training_data["x0"], s_10, s_11, s_12]).T

# compute input for last neuron (Add x0 for bias)
h_2 = np.apply_along_axis(h(w_20), 1, s_1)

# compute output ( $f(h_2)$ )
y_pred = h_2

# compute error
E_T = 0.5*np.sum(np.power(np.subtract(y_pred, training_data["y"]), 2))
#print("Error: "+str(E_T))

# compute local errors
# da die ableitung der identität 0 ist
delta_2_0 = np.array([1,1,1,1,1,1,1,1,1,1])

# da die ableitung von  $\tanh(x)$   $1/\cosh^2(x)$ 
delta_10 = np.multiply(np.power(np.cosh(h_10), -2), w_21_01)
delta_11 = np.multiply(np.power(np.cosh(h_11), -2), w_21_02)
delta_12 = np.multiply(np.power(np.cosh(h_12), -2), w_21_03)
# compute gradients

grad_10_00 = -0.1*np.sum(np.multiply(np.multiply(np.subtract(y_pred, y_t), delta_10),
grad_10_01 = -0.1*np.sum(np.multiply(np.multiply(np.subtract(y_pred, y_t), delta_10),

grad_10_10 = -0.1*np.sum(np.multiply(np.multiply(np.subtract(y_pred, y_t), delta_11),
grad_10_11 = -0.1*np.sum(np.multiply(np.multiply(np.subtract(y_pred, y_t), delta_11),

grad_10_20 = -0.1*np.sum(np.multiply(np.multiply(np.subtract(y_pred, y_t), delta_12),
grad_10_21 = -0.1*np.sum(np.multiply(np.multiply(np.subtract(y_pred, y_t), delta_12),

grad_21_00 = -0.1*np.sum(np.multiply(np.multiply(np.subtract(y_pred, y_t), delta_2_0),
grad_21_01 = -0.1*np.sum(np.multiply(np.multiply(np.subtract(y_pred, y_t), delta_2_0),
grad_21_02 = -0.1*np.sum(np.multiply(np.multiply(np.subtract(y_pred, y_t), delta_2_0),
grad_21_03 = -0.1*np.sum(np.multiply(np.multiply(np.subtract(y_pred, y_t), delta_2_0),

```

```

#adjust w
w_21_00 = w_21_00 + learning_rate * grad_21_00
w_21_01 = w_21_01 + learning_rate * grad_21_01
w_21_02 = w_21_02 + learning_rate * grad_21_02
w_21_03 = w_21_03 + learning_rate * grad_21_03

w_10_00 = w_10_00 + learning_rate * grad_10_00
w_10_01 = w_10_01 + learning_rate * grad_10_01

w_10_10 = w_10_10 + learning_rate * grad_10_10
w_10_11 = w_10_11 + learning_rate * grad_10_11

w_10_20 = w_10_20 + learning_rate * grad_10_20
w_10_21 = w_10_21 + learning_rate * grad_10_21

def plotNetwork(fig, pos):
    x = np.arange(0.01, 1, 0.05)
    x = np.array([x/x, x]).T
    # Weight vectors
    w_10 = np.array([w_10_00, w_10_01])
    w_11 = np.array([w_10_10, w_10_11])
    w_12 = np.array([w_10_20, w_10_21])
    w_20 = np.array([w_21_00, w_21_01, w_21_02, w_21_03])

    # compute hs of hidden layer (wT * x)
    h_10 = np.apply_along_axis(h(w_10), 1, x)
    h_11 = np.apply_along_axis(h(w_11), 1, x)
    h_12 = np.apply_along_axis(h(w_12), 1, x)

    # compute ss of hidden layer (f(h))
    s_10 = np.apply_along_axis(np.tanh, 0, h_10)
    s_11 = np.apply_along_axis(np.tanh, 0, h_11)
    s_12 = np.apply_along_axis(np.tanh, 0, h_12)

    s_1 = np.array([x[:,0], s_10, s_11, s_12]).T
    ax = fig.add_subplot(2,3,pos)
    pd.DataFrame(np.array([x[:,1], s_10, s_11, s_12]).T, columns=["x", "s1", "s2", "s3"])

    # compute input for last neuron (Add x0 for bias)
    h_2 = np.apply_along_axis(h(w_20), 1, s_1)
    # compute output (f(h_2))
    y_pred = h_2

    ax = fig.add_subplot(2,3,pos+1)
    ax = training_data.plot(x="x1", y="y", kind="scatter", ax=ax)
    pd.DataFrame(np.array([x[:,1], y_pred]).T, columns=["x", "y"]).plot(ax=ax, x="x", y="y")

```

```

def train(learning_rate, fig, figure_offset):
    global i
    global w_21_00
    global w_21_01
    global w_21_02
    global w_21_03
    global w_10_00
    global w_10_01
    global w_10_10
    global w_10_11
    global w_10_20
    global w_10_21
    global E_T

    w_10_00 = random.uniform(-0.5, 0.5)
    w_10_01 = random.uniform(-0.5, 0.5)

    w_10_10 = random.uniform(-0.5, 0.5)
    w_10_11 = random.uniform(-0.5, 0.5)

    w_10_20 = random.uniform(-0.5, 0.5)
    w_10_21 = random.uniform(-0.5, 0.5)

    w_21_00 = random.uniform(-0.5, 0.5)
    w_21_01 = random.uniform(-0.5, 0.5)
    w_21_02 = random.uniform(-0.5, 0.5)
    w_21_03 = random.uniform(-0.5, 0.5)

    i = 0

    learning_rate = 0.5
    errors = []
    E_T = 0
    E_T_last = 999999

    MAX_ITERATIONS = 3000

    while True:
        E_T_last = E_T
        training_step(learning_rate)
        errors.append(E_T)
        #if (i % 100 == 0):
        #     print(i)
        if (i > MAX_ITERATIONS or abs(E_T_last - E_T) <= 10 ** -5):
            break;

```

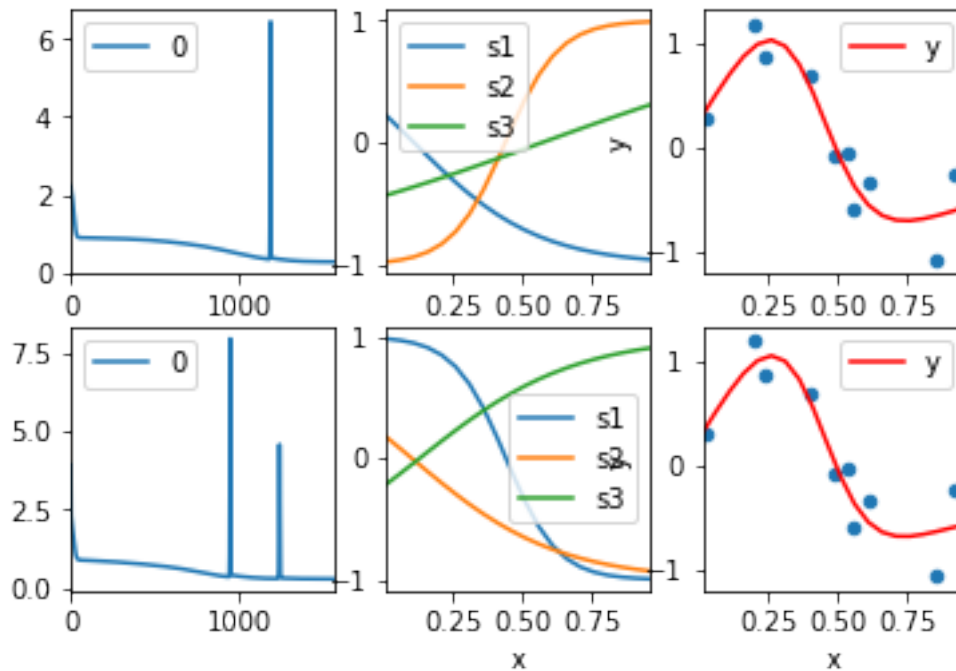
```

# print(errors)
errors = pd.DataFrame(errors)
ax = fig.add_subplot(2,3,figure_offset)
errors.plot(ax=ax)

plotNetwork(fig, figure_offset+1)

fig = plt.figure()
train(0.5, fig, 1)
train(0.5, fig, 4)

```



- d) Although the overall prediction of y is very similar in both MLPs, the output functions of the hidden neurons are completely different. This is caused by the random initialization of the weights: The weights are the starting point for gradient descent, which based on it finds different local optima.
- e) We know that the noise is Gaussian distributed, which makes big outliers very unlikely. Furthermore, the y_T values vary in $[-1, 1]$, thus quite strongly. Therefore, we want a cost functions that is strongly affected outliers.